

(This is the coversheet for the homework. The actual solutions should be worked out neatly on single-sided with each problem labeled (for example: Problem 1, 1.1 #14) and the answer boxed. Those additional sheets are then to be stapled with a metal staple in the upper left corner in such a way that no work is obscured. Failure to follow the style outlined here will result in a loss of credit. The problems refer to Anton and Rorres 10th ed. of *Elementary Linear Algebra: applications version.*)

Problem 28 Suppose $M \in \mathbb{R}^{m \times m}$ and $N \in \mathbb{R}^{n \times n}$ such that x_1, x_2 are solutions $Mx_1 = y_1$ and $Nx_2 = y_2$. Let A be a block-diagonal matrix of the form:

$$A = \left[\begin{array}{c|c} M & 0 \\ \hline 0 & N \end{array} \right]$$

If $\det(M), \det(N) \neq 0$ then solve $Az = w$ where $w = [2y_1, 3y_2]^T$.

Problem 29 § 2.1 # 10 (arrow-technique to calculate 3×3 determinant)

Problem 30 § 2.1 # 16 (equation given by determinant, solve it)

Problem 31 § 2.1 # 32 (determinant by inspection)

Problem 32 § 2.2 # 12 (row-reduction to calculate det)

Problem 33 § 2.2 # 20 (properties of det calculation)

Problem 34 The matrix $A = \begin{bmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{bmatrix}$ is an example of a **Vandermonde matrix**. Use properties about row and column operations to show that $\det(A) = (b-a)(c-a)(c-b)$.

Problem 35 Define a **Vandermonde matrix** $V(t)$ as follows:

$$V(t) = \begin{bmatrix} 1 & t & t^2 & t^3 \\ 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_2 & x_2^2 & x_2^3 \\ 1 & x_3 & x_3^2 & x_3^3 \end{bmatrix}$$

This matrix provides us a convenient way of creating a cubic polynomial that passes through distinct zeros $(x_1, 0)$, $(x_2, 0)$, $(x_3, 0)$. Define $f(x) = \det(V(x))$ and explain why $f(x_1) = f(x_2) = f(x_3) = 0$. Based on an analogy to the preceding problem state an explicit formula for $f(t)$.

Problem 36 § 2.3 # 8 (invertible? use det to decide)

Problem 37 § 2.3 # 18 (choose k to make matrix invertible)

Problem 38 Supplementary exercises, page 117 #26 (Cramer's rule for symbolic problem)

Problem 39 Let $A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$.

(a.) let $p(t) = \det(A - tI)$. Calculate the formula for $p(t)$

(b.) show that $p(A) = 0$

Problem 40 Let $\vec{v}_1 = \langle 1, 2, 3 \rangle$, $\vec{v}_2 = \langle 1, 1, 0 \rangle$ and $\vec{v}_3 = \langle 2, 1, 3 \rangle$. Find the volume of a parallel-piped with edges $\vec{v}_1, \vec{v}_2, \vec{v}_3$. Is $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ a right-handed triple?

\vec{v}_2

(typo)

Problem 28 Given $M \in \mathbb{R}^{m \times m}$, $N \in \mathbb{R}^{n \times n}$

with solⁿs x_1, x_2 such that $Mx_1 = y_1$ and $Nx_2 = y_2$.

If $A = \left[\begin{array}{c|c} M & 0 \\ \hline 0 & N \end{array} \right] \in \mathbb{R}^{(m+n) \times (m+n)}$ and $\det M, \det N \neq 0$

then solve $Az = w$ where $w = [2y_1, 3y_2]^T$

Let z_1, z_2 be such that Mz_1, Nz_2 are defined,

$$Az = \begin{bmatrix} M & 0 \\ 0 & N \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} Mz_1 \\ Nz_2 \end{bmatrix} = \begin{bmatrix} 2y_1 \\ 3y_2 \end{bmatrix}$$

We must solve $Mz_1 = 2y_1$ and $Nz_2 = 3y_2$

Note $Mx_1 = y_1$ & $Nx_2 = y_2 \Rightarrow M^{-1}y_1 = x_1$ & $N^{-1}y_2 = x_2$

since $\det M, \det N \neq 0$ and we know M^{-1}, N^{-1} exist.

We find $z_1 = 2M^{-1}y_1 = 2x_1$ & $z_2 = 3N^{-1}y_2 = 3x_2$

Thus $\boxed{z = [2x_1, 3x_2]^T}$

Problem 29 (§2.1#10)

$$\det \begin{bmatrix} -2 & 7 & 6 \\ 5 & 1 & -2 \\ 3 & 8 & 4 \end{bmatrix} = (-8)(-42)(240) - 18(32)(140) = \boxed{0}$$

$$\begin{array}{ccc|ccc} -2 & 7 & 6 & -2 & 7 \\ 5 & 1 & -2 & 5 & 1 \\ 3 & 8 & 4 & 3 & 8 \end{array}$$

Problem 30 (§2.1#16) find solⁿs of $\det(A) = 0$.

$$\begin{aligned} \det \begin{bmatrix} \lambda-4 & 0 & 0 \\ 0 & \lambda & 2 \\ 0 & 3 & \lambda-1 \end{bmatrix} &= (\lambda-4) [\lambda(\lambda-1) - 6] \\ &= (\lambda-4) (\lambda^2 - \lambda - 6) \\ &= (\lambda-4) (\lambda-3) (\lambda+2) = 0 \end{aligned}$$

$$\therefore \boxed{\lambda = 3, 4, -2}$$

Problem 31 (§2.1#32) find det. by inspection.

The matrix $A = \begin{bmatrix} -3 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 40 & 10 & -1 & 0 \\ 100 & 200 & -23 & 3 \end{bmatrix}$ is lower triangular

$$\therefore \det(A) = -3(2)(-1)(3) = \boxed{18}$$

Problem 32 (§2.2#12) use row-reduction to calculate determinant.

$$A = \begin{bmatrix} 1 & -3 & 0 \\ -2 & 4 & 1 \\ 5 & -2 & 2 \end{bmatrix} \xrightarrow[\underline{r_3 - 5r_1}]{\underline{r_2 + 2r_1}} \begin{bmatrix} 1 & -3 & 0 \\ 0 & -2 & 1 \\ 0 & 13 & 2 \end{bmatrix} \xrightarrow{\underline{r_2 + \frac{2}{13}r_3}} \begin{bmatrix} 1 & -3 & 0 \\ 0 & 0 & \frac{17}{13} \\ 0 & 13 & 2 \end{bmatrix}$$

$$\xrightarrow{\underline{r_2 \leftrightarrow r_3}} \begin{bmatrix} 1 & -3 & 0 \\ 0 & 13 & 2 \\ 0 & 0 & \frac{17}{13} \end{bmatrix} \dots \rightarrow \begin{bmatrix} 1 & -3 & 0 \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 1 \end{bmatrix} = \det(A)$$

$$\det(A) = - (13) \left(\frac{17}{13} \right) = \boxed{-17}$$

because I only did row additions and a row-swap.

Maybe you'll like this notation $\det A = |A|$

$$\left| \begin{array}{ccc} 1 & -3 & 0 \\ -2 & 4 & 1 \\ 5 & -2 & 2 \end{array} \right| \xrightarrow[\underline{r_3 - 5r_1}]{\underline{r_2 + 2r_1}} \left| \begin{array}{ccc} 1 & -3 & 0 \\ 0 & -2 & 1 \\ 0 & 13 & 2 \end{array} \right| \xrightarrow{\underline{r_2 + \frac{2}{13}r_3}} \left| \begin{array}{ccc} 1 & -3 & 0 \\ 0 & 0 & \frac{17}{13} \\ 0 & 13 & 2 \end{array} \right| \rightarrow$$

$$\xrightarrow{\underline{r_2 \leftrightarrow r_3}} \left| \begin{array}{ccc} 1 & -3 & 0 \\ 0 & 13 & 2 \\ 0 & 0 & \frac{17}{13} \end{array} \right| \xrightarrow{\frac{1}{13}r_2} \frac{-1}{13} \left| \begin{array}{ccc} 1 & -3 & 0 \\ 0 & 1 & \frac{2}{13} \\ 0 & 0 & \frac{17}{13} \end{array} \right| \rightarrow$$

$$\xrightarrow{\frac{13}{17}r_3} \frac{13}{17} \left(\frac{-1}{13} \right) \left| \begin{array}{ccc} 1 & -3 & 0 \\ 0 & 1 & \frac{2}{13} \\ 0 & 0 & 1 \end{array} \right| = -17 (1)(1)(1) = \boxed{-17}$$

PROBLEM 33 (§ 2.2 # 20)

$$\begin{vmatrix} g & h & i \\ d & e & f \\ a & b & c \end{vmatrix} = - \underbrace{\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix}}_{\text{given to be } -6} = -(-6) = \boxed{6}$$

PROBLEM 34 You could use row op. to do the whole calculation. This is easier.

$$\begin{aligned} \det \begin{pmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{pmatrix} &= \det \begin{pmatrix} 1 & a & a^2 \\ 0 & b-a & b^2-a^2 \\ 0 & c-a & c^2-a^2 \end{pmatrix} \\ &= 1 \cdot [(b-a)(c^2-a^2) - (c-a)(b^2-a^2)] \\ &= (b-a)(c-a)(c+a) - (c-a)(b+a)(b-a) \\ &= (b-a)(c-a)[c+a - (b+a)] \\ &= \underline{(b-a)(c-a)(c-b)}. \end{aligned}$$

PROBLEM 35

$$V(t) = \det \begin{bmatrix} 1 & t & t^2 & t^3 \\ 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_2 & x_2^2 & x_2^3 \\ 1 & x_3 & x_3^2 & x_3^3 \end{bmatrix}$$

Show $f(x_1) = f(x_2) = f(x_3) = 0$ and find formula for $f(t)$

Clearly $f(x_1) = f(x_2) = f(x_3) = 0$ since

$$V(x_1) = \det \begin{bmatrix} 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_2 & x_2^2 & x_2^3 \\ 1 & x_3 & x_3^2 & x_3^3 \end{bmatrix} = 0 \quad \begin{array}{l} \text{repeated} \\ \text{row} \\ \Rightarrow \text{zero det.} \end{array}$$

Likewise for x_2 & x_3 . We've found

$f(t) = A(x_1-t)(x_2-t)(x_3-t)$, need to find A.

$$f(0) = x_1 x_2 x_3 A = V(0) = \det \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_2 & x_2^2 & x_2^3 \\ 1 & x_3 & x_3^2 & x_3^3 \end{bmatrix}$$

$$\begin{aligned} V(0) &= \begin{vmatrix} x_1 & x_1^2 & x_1^3 \\ x_2 & x_2^2 & x_2^3 \\ x_3 & x_3^2 & x_3^3 \end{vmatrix} = x_1(x_2^2 x_3^3 - x_2^3 x_3^2) - x_1^2(x_2 x_3^2 - x_3 x_2^2) + x_1^3(x_2 x_3^2 - x_3 x_2^2) \\ &= x_1 x_2 x_3 [x_2^2 x_3^3 - x_2^3 x_3^2 - x_1 x_2 x_3^2 + x_1 x_2^2 x_3 + x_1^2 x_2 x_3 - x_1^3 x_2^2] \end{aligned}$$

$$\therefore f(t) = x_2 x_3 (x_2 x_3^2 - x_2^2 x_3 - x_1 x_3^2 + x_1 x_2^2 + x_1^2 - x_1^2 x_2) \cdot A \cdot (x_1-t)(x_2-t)(x_3-t)$$

PROBLEM 36 (§2.3 #8)

$$\det \underbrace{\begin{bmatrix} 2 & 0 & 3 \\ 0 & 3 & 2 \\ -2 & 0 & -4 \end{bmatrix}}_A = 2(-12) + 3(6) = \underline{-6 \neq 0}$$

$\therefore A^{-1}$ exists

PROBLEM 37 (§2.3 #18)

$$A = \begin{bmatrix} 1 & 2 & 0 \\ k & 1 & k \\ 0 & 2 & 1 \end{bmatrix} \quad \text{find } k \text{ for which } A^{-1} \text{ exists.}$$

we need $\det(A) \neq 0$. Consider,

$$\det(A) = 1(1-2k) - 2(k) = 1-4k = 0 \Rightarrow \underline{k = \frac{1}{4}}$$

We find A^{-1} exists for all $k \neq \frac{1}{4}$

PROBLEM 38 (pg. 117 #26)

Solve
$$\begin{aligned} x &= x' \cos \theta - y' \sin \theta \\ y &= x' \sin \theta + y' \cos \theta \end{aligned}$$
 for x', y' .
By Cramer's Rule

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x' \\ y' \end{pmatrix}$$

$$x' = \frac{\det \begin{bmatrix} x & -\sin \theta \\ y & \cos \theta \end{bmatrix}}{\det \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}} = \frac{x \cos \theta + y \sin \theta}{\cos^2 \theta + \sin^2 \theta}$$

$$y' = \frac{\det \begin{bmatrix} \cos \theta & x \\ \sin \theta & y \end{bmatrix}}{1} = y \cos \theta - x \sin \theta$$

\therefore

$$\boxed{\begin{aligned} x' &= x \cos \theta + y \sin \theta \\ y' &= y \cos \theta - x \sin \theta \end{aligned}}$$

PROBLEM 39 | Let $A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$

(a.) $P(t) = \det(A - tI)$. find formula,

$$P(t) = \det \begin{bmatrix} 1-t & 1 \\ 1 & 2-t \end{bmatrix}$$

$$= (1-t)(2-t) - 1$$

$$= (t-1)(t-2) - 1$$

$$= t^2 - 3t + 2 - 1$$

$$= \boxed{t^2 - 3t + 1 = P(t)}$$

(b.) $A^2 = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix}$

$$A^2 - 3A + I = \begin{bmatrix} 2 & 3 \\ 3 & 5 \end{bmatrix} - \begin{bmatrix} 3 & 3 \\ 3 & 6 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \neq \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

($P(A) = \det(A - AI) = \det(\mathbf{0}) = 0$ also good)

PROBLEM 40 | edges $\vec{v}_1, \vec{v}_2, \vec{v}_3$ give what 11-piped volume?
is $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ right-handed?

$$\det(\vec{v}_1/\vec{v}_2/\vec{v}_3) = \det \begin{pmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ 3 & 0 & 3 \end{pmatrix} = -6 \quad \therefore \boxed{\text{Vol} = 6}$$

this $\det(\vec{v}_1/\vec{v}_2/\vec{v}_3) < 0 \Rightarrow \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is
not right-handed.