

4/1/2

Group Actions:

Ex (1): $GL(n)$ acts on $T^p_g \mathbb{R}^n$

(i) We first define an action of $GL(n)$ on $(\mathbb{R}^n)^*$ (right regular rep.)

$A \in GL(n)$, $\alpha \in (\mathbb{R}^n)^*$ by:

$$(A \cdot \alpha)(x) = \alpha(A^{-1}x)$$

note: $(A \cdot (B \cdot \alpha))(x) = \alpha(B^{-1}A^{-1}x) = \alpha((AB)^{-1}x) = (AB \cdot \alpha)(x)$

$(I \cdot \alpha)(x) = \alpha(Ix) = \alpha(x) \therefore$ is an action.

(ii) $GL(n)$ acts on $\mathbb{R}^n$ by matrix mult.

(iii) Combine: $A \in GL(n)$ $Z \in T^p_g \mathbb{R}^n$ define

$A \cdot Z \in T^p_g \mathbb{R}^n$ by

$$A \cdot Z(v_1, \dots, v_q, \theta^1, \dots, \theta^p) = Z(A^{-1}v_1, \dots, A^{-1}v_q, A^{-1}\theta^1, \dots, A^{-1}\theta^p)$$

$$A \cdot Z(e_{i_1}, \dots, e_{i_q}, e^{j_1}, \dots, e^{j_p}) = Z(A^{-1}_{i_1} e_{j_1}, \dots, A^{-1}_{i_q} e_{j_q}, A^{j_1}_{k_1} e^{k_1}, \dots)$$

b/c

$$A^{-1} e^{j_1}(e_k) = e^{j_1}(A^m_k e_m) = A^m_k \delta^j_1_m = A^{j_1}_k$$

$$(A \cdot Z)^{j_1 \dots j_p}_{i_1 \dots i_q} = A^{-1}_{i_1}{}^{l_1} \dots A^{-1}_{i_q}{}^{l_q} A^{j_1}_{k_1} \dots A^{j_p}_{k_p} Z^{k_1 \dots k_p}_{l_1 \dots l_q}$$

Extra Credit Check out...

$$\begin{array}{ccc} GL(n) \times V & \xrightarrow{\text{frame bundle}} & V \\ \pi \downarrow & \searrow \varphi & \\ M & \xleftrightarrow{\Delta \varphi} & FM \times V / G \end{array}$$

equivariant mapping:
 $\varphi(u \cdot g) = g^{-1} \varphi(u)$
 $(T^p_g M)$

Ex (2): $GL(n)$ acts on FM on the right.

Let $(p, \{e_i\}) \in FM$ and $A \in GL(n)$ define:

$$(p, \{e_i\}) \cdot A = (p, \{e_i A^j_i\})$$

Should check if action is smooth:

use chart (U, x) , $FM = \{(p, \{e_i\}) \mid p \in U, e_i \in T_p M \text{ a basis}\}$

$$Fx(p, \{e_i\}) = (x(p), (d_p x^j(e_i))_{j,i})$$

$$\begin{aligned} Jx((p, \{e_i\}) \cdot A) &= Jx(p, \{e_i A_i^\dagger\}) = (x(p), (dx^k e_i A_i^\dagger)_{k,i}) \\ &= (x(p), (A_i^\dagger dx^k e_i)_{k,i}) = (x(p), (dx^k e_i)(A_i^\dagger)) \end{aligned}$$

$$= [Jx(p, \{e_i\})] \cdot A \quad \therefore \text{smooth (after some details)}$$

$$\in Jx(u) \stackrel{\text{right}}{\subseteq} \stackrel{\text{right}}{\text{open}} \mathbb{R}^n$$

$$\Rightarrow \varphi(u \underset{\text{right action}}{g}) = \underset{\text{right action}}{\varphi(u)} g \leftarrow \text{equivariant.}$$

$$\varphi(u \underset{\text{right action}}{g}) = \underset{\text{left action}}{g^{-1}} \varphi(u)$$

Def If G acts on the left of a manifold M (G a Lie group and the action smooth) $x \in M$ then the orbit of x is

$$G \cdot x = \{g \cdot x \mid g \in G\}$$

Note:

$G \cdot x$ and $G \cdot y$ are disjoint or equal (ie partition)

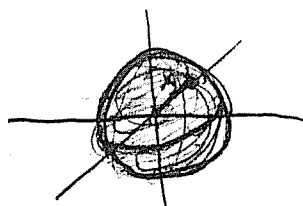
$$\begin{aligned} x \in G \cdot x, \quad x \in G \cdot y &\Rightarrow x = g \cdot y \Rightarrow g^{-1} \cdot x = y \in G \cdot x \\ &\Rightarrow x \sim y \Leftrightarrow y \sim x \end{aligned}$$

+ transitive...

The isotropy subgroup of G determined by $x \in M$ is

$$G_x = \{g \in G \mid g \cdot x = x\} \quad (\text{stabilizer})$$

Ex: $G = SO(3)$ acts on $\mathbb{R}^3$ by mult, If $x \neq 0$ then $G \cdot x$ is the set of all rotations of x = Sphere of radius $\|x\|$



$G_x \cong SO(2)$ (fixes the line through the origin which also goes through x)

$$S^2 = G \cdot x = G/G_x = \frac{SO(3)}{SO(2)}$$

$SU(2) \xrightarrow{P} SO(3)$
 $\Rightarrow$ we induce an action of $SU(2)$ on $\mathbb{R}^3$... Hopf bundle

4/3/2

(topologically)

Thm If H is a closed subgroup of a Lie group G then,

(1) H is a Lie subgroup of G .

(2) There exists a unique differentiable structure on $G/H \ni$

(i) $\eta: G \rightarrow G/H$ is smooth (natural def)

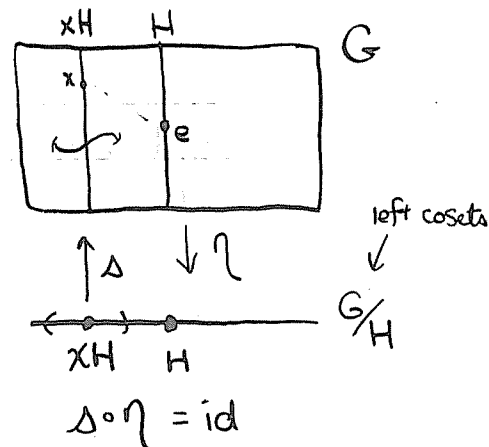
(ii) At each point of $G/H \ni$ a local section of η which is smooth.

proof

(1) See Warner OR Olver

(2) See Warner (maybe Olver also)

Note: We can also use right cosets for G/H etc.



There are 2 natural actions of H on G

$$(h, g) \mapsto hg \quad H \times G \rightarrow G$$

$$\& (g, h) \mapsto gh \quad G \times H \rightarrow G$$

for a principle fiber bundle we want to act on the right

Def G acts transitively on M iff $\exists x \in M \ni G \cdot x = M$.

Thm If a Lie group G acts transitively on a manifold M then the mapping $\beta: G/G_x \rightarrow G \cdot x = M$

defined by $\beta(gG_x) = g \cdot x$ is a diffeomorphism. $\forall x \in M$.

(likewise $\beta: G/G_x \rightarrow x \cdot G = M$ def by $\beta(gG_x) = x \cdot g$)

Ex: $SO(3) \times S^2 \rightarrow S^2 \quad S^2 = \{v \in \mathbb{R}^3 \mid \|v\| = 1\}$
 $\{A \cdot v \mid A \in SO(3)\} = S^2 \quad S^2 = SO(3) \cdot v$

$\beta: G/G_x \rightarrow G \cdot x$ makes sense since $gG_x = hG_x$ then

$$g = hg_x \therefore \beta(gG_x) = g \cdot x = hg_x \cdot x = h \cdot (g_x \cdot \overset{\text{fixed}}{x}) = h \cdot x$$

$\therefore \beta(gG_x) = \beta(hG_x)$ hence well def.

= (proof of Thm see Warner...) =

Remark: If $\tilde{f}: G/H \rightarrow Q$ is smooth (Q a manifold)

then $\exists!$ smooth mapping $f: G \rightarrow Q \ni f = \tilde{f} \circ \eta$ $\tilde{f}$ const. on cosets.

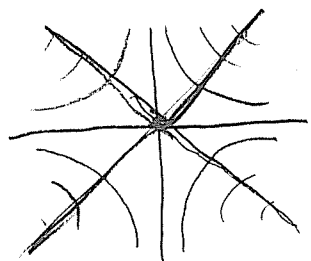
And If $f: G \rightarrow Q$ is smooth $\ni f$ is const. on cosets

then $\exists! \tilde{f}: G/H \rightarrow Q$ smooth $\ni f = \tilde{f} \circ \eta$

Ex: $\frac{dx}{dt} = x \quad \frac{dx}{x} = dt \Rightarrow x = Ae^t$

$$\frac{dy}{dt} = -y \quad \frac{dy}{y} = -dt \Rightarrow y = Be^{-t} = B \frac{1}{e^t}$$

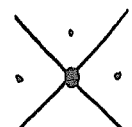
$$\Rightarrow \frac{x}{A} = e^t \text{ \& } \frac{B}{y} = e^t \Rightarrow x = \frac{AB}{y}$$



$(\mathbb{R}, +)$ acts on $\mathbb{R}^2$
 $\varphi: \mathbb{R} \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$

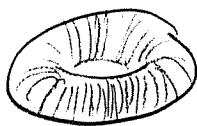
$\varphi(t, (x, y)) =$ flow of the vector through (x, y)

$$\varphi(t, (x, y)) = \begin{pmatrix} \cosh t & \sinh t \\ \sinh t & \cosh t \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \leftarrow \text{something like this}$$

quotient looks like  not Hausdorff !!

must be careful with non-transitive actions

Ex:



dense wind on torus is another counterexample
 ?

Def Let G a Lie group act on a manifold M . The action is called an effective action iff $g \cdot x = x \ \forall x \in M$ then $g = e$

The action is free iff $g \cdot x = x$ for some $x \in M$ then $g = e$,
(no fixed points $\leftarrow$)

• Effective says, $\bigcap_{x \in M} G_x = \{e\}$

• Free says, $\bigcup_{x \in M} G_x = \{e\}$ (ie Free $\Rightarrow$ Effective)

$$G \times M \xrightarrow{\sigma} M$$

$$\tilde{\sigma}: G \rightarrow \text{Diff } M \quad \tilde{\sigma}(g)(x) = \sigma(g, x)$$

$$\text{Effective: } g \in \text{Ker}(\tilde{\sigma}) \Leftrightarrow \tilde{\sigma}(g) = \text{id}_M$$

$$\Leftrightarrow \tilde{\sigma}(g)(x) = x \ \forall x \in M \Leftrightarrow g \cdot x = x \ \forall x \in M$$

$$\Leftrightarrow g = e$$

$\therefore \tilde{\sigma}$ is a monomorphism iff action is effective

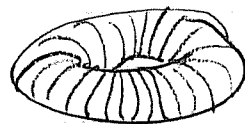
free: means $\exists x \ni G_x = \{e\} \Rightarrow G/G_x \cong G \cdot x \Rightarrow G \cong G \cdot x$
(ie the orbit is diffeomorphic to the group.)

4/5/2

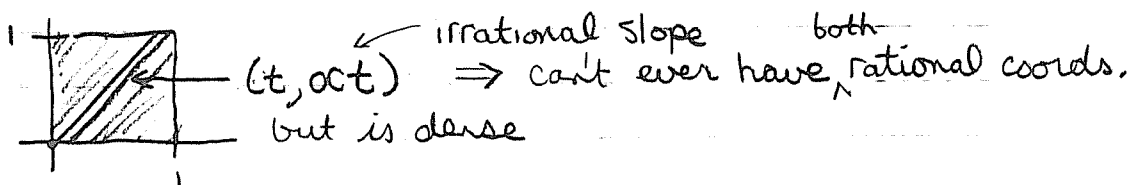
$G \cdot x$ = orbit of x

G_x = stabilizer of x =

Ex: $T^2 = \{(e^{2\pi i \theta}, e^{2\pi i \varphi}) \mid \theta, \varphi \in \mathbb{R}\} \cong \mathbb{C} \times \mathbb{C}$



$t \in (\mathbb{R}, +)$
 $t \cdot (e^{2\pi i \theta}, e^{2\pi i \varphi}) = (e^{2\pi i \theta t}, e^{2\pi i \varphi t})$ where $\alpha \in \mathbb{R} \setminus \mathbb{Q}$



∴ we can't get a smooth section (a smooth curve that intersects each orbit in exactly one point).

Assume the Lie group G acts on a manifold M . for $A \in \mathfrak{g}$ (the Lie algebra of G) define a vector field δ_A by

$$\delta_A(x) = \left. \frac{d}{dt} [x \cdot \exp(tA)] \right|_{t=0} \quad \forall x \in M$$

The mapping $\delta: \mathfrak{g} \rightarrow \mathcal{X}(M)$ defined by $\delta(A) = \delta_A$ is called the infinitesimal generator of the action.

$t \mapsto x \cdot \exp(tA)$ is smooth, since $tA \checkmark$, $\exp \checkmark$, action $\checkmark$ are smooth. $0 \mapsto x \cdot \exp(0) = x \cdot e = x$

∴ this is a curve through x , $\Rightarrow \left. \frac{d}{dt} [x \cdot \exp(tA)] \right|_{t=0} \in T_x M$
 $\delta_A(x) \in T_x(M)$ also $x \mapsto \delta_A(x)$ is smooth $\checkmark$ (skip)

Note:

$t \mapsto x \cdot \exp(tA)$ is in $x \cdot G$ if $x \cdot G$ is a submanifold then $\delta_A(x) \in T_x(x \cdot G)$

∴ (when it makes sense) δ_A is everywhere tangent to the orbits of the action.

Thm G a Lie group which acts on the right of the manifold M .
Then the infinitesimal generator, $\delta: \mathfrak{g} \rightarrow \mathfrak{X}(M)$, is a Lie algebra homomorphism, which is:

- injective when the action is effective.
- δ_A is never zero $\forall A \neq 0$ when the action is free.

proof:

(maybe homework)

If G acts on the right then $M \times G \xrightarrow{\sim} M$ then we have a map $\sigma: G \rightarrow \text{Diff}(M)$ where $\sigma(g)(x) = \tilde{\sigma}(x, g)$ then σ is a homomorph. if $\text{Diff}(M)$ were finite dim'd we would have

$$d_e \sigma: T_e G \rightarrow T_{\mathbb{I}}(\text{Diff} M) = \mathfrak{X}(M)$$

$\varphi: G \rightarrow H \leftarrow$ Lie group hom. $\Downarrow$ Thm works (but we assumed finite dim.)

$d_e \varphi: T_e G \rightarrow T_e H \leftarrow$ Lie alg. hom.

$$T_{\mathbb{I}}(\text{Diff} M) \stackrel{?}{=} \mathfrak{X}(M)$$

⌈ A tangent vector to $\text{Diff}(M)$ at $\mathbb{I}_M$ should be the derivative of a curve through $\mathbb{I}_M$ at 0.

Let $C: (-a, a) \rightarrow \text{Diff}(M)$ $C(t): M \rightarrow M$

$t \mapsto C(t)(x)$ is a curve in $M \ni C(0)(x) = x$

$$\left. \frac{d}{dt} C(t) \right|_{t=0}: M \rightarrow TM \quad \left. \frac{d}{dt} (C(t)(y)) \right|_{t=0} = \left. \frac{d}{dt} (C(t)(y)) \right|_{t=0} \in T_y M$$

Sketch:

$$\delta_A(x) = \left. \frac{d}{dt} (x \cdot \exp(tA)) \right|_{t=0} \quad x \in M, \sigma_x: G \rightarrow M \text{ def by } \sigma(x) = x \cdot g$$

$$\delta_A(x) = \left. \frac{d}{dt} [\sigma_x \circ \exp(tA)] \right|_{t=0} = d_e \sigma_x \left(\left. \frac{d}{dt} (\exp(tA)) \right|_{t=0} \right)$$

$$= d_e \sigma_x(A) \text{ (obviously linear)} \Rightarrow \delta_{A+B} = \delta_A + \delta_B, \delta_{cA} = c\delta_A$$

$\nexists A \in \text{Ker}(\delta)$

$$\delta_A = 0 \Rightarrow \delta_A(x) = 0 \quad \forall x \quad R_g(x) = x \cdot g \therefore d_x R_g(\delta_A(x)) = 0$$

$$= d_x R_g \left(\left. \frac{d}{dt} (x \cdot \exp(tA)) \right|_{t=0} \right) = \left. \frac{d}{dt} [\dots] \right|_{t=0} \text{ finish later,}$$

4/8/2 finish Thm:

$$M \times G \rightarrow M$$

$$\mathfrak{g} = \text{Lie } G$$

$$A \in \mathfrak{g} \text{ and } x \in M \ni \delta_A(x) = 0$$

Then, $\frac{d}{dt} [x \cdot \exp(tA)]|_{t=0} = 0$, then $\overset{\text{use}}{R_g(x)} = x \cdot g \Rightarrow$

$$dx R_{\exp(sA)} \left(\frac{d}{dt} [x \cdot \exp(tA)]|_{t=0} \right) = 0 \quad \forall s$$

linear map sends $0 \rightarrow 0$

$$\frac{d}{dt} [x \cdot \exp(tA) \exp(sA)]|_{t=0} = 0 \quad \forall s$$

$$\frac{d}{dt} [x \cdot \exp((t+s)A)]|_{t=0} = 0 \quad \forall s$$

$$u = s+t$$

$$\frac{d}{du} [x \cdot \exp(uA)]|_{\substack{t=0 \\ u=s}} \cdot \frac{du}{dt}(0) \overset{1}{=} 0$$

$$\frac{d}{ds} [x \cdot \exp(sA)] = 0 \quad \Delta \mapsto x \cdot \exp(\Delta A) \text{ const.}$$

• If $\delta_A(x) = 0 \quad \forall x \in M$ and the action is effective:

$$\text{we have } x \cdot \exp(\Delta A) = x \quad \forall \Delta$$

$$\Rightarrow x \cdot g = x \Rightarrow g = e$$

$$\Rightarrow \Delta A = \exp^{-1}(e) \text{ for small } \Delta \text{ (exp is a local diffeom.)}$$

$$\Rightarrow \Delta A = 0 \Rightarrow A = 0$$

hence $\delta_A(x) = 0 \quad \forall x \in M$ action effective $\Rightarrow A = 0$

• If $\exists x \ni \delta_A(x) = 0$ then

$$x \cdot \exp(\Delta A) = x \quad \forall \Delta \quad x \cdot g = x \text{ free action} \Rightarrow$$

$$g = e \Rightarrow A = 0 \text{ hence}$$

$$\delta_A(x) = 0 \text{ for some } x \in M \text{ action free} \Rightarrow A = 0$$

• if the action is free, $A \neq 0$ then δ_A is never zero.

(P.F.B.)

Def $P \xrightarrow{\pi} M$ is a principal fiber bundle iff

- (1) $\pi: P \rightarrow M$ is a fiber bundle with fiber G which is a Lie group.
- (2) G acts freely on the right of P
- (3) $\exists$ local trivializing maps $\{\psi_u\} \ni \psi_u(u \cdot g) = \psi_u(u) \cdot g$
 $\psi_u: \pi^{-1}(U) \rightarrow U \times G$
(where $(u, g) \in U \times G$ then $h \in G$ define $(u, g) \cdot h = (u, gh)$)

Note: $U \times G$ is a principal fiber in its own right.

$\downarrow$
 U

Thm Assume $P \xrightarrow{\pi} M$ is a P.F.B. with fiber G , and trivializing maps as in (3) (i.e. equivariant) then the corresponding transition functions $\varphi_{uv}: U \cap V \rightarrow \text{Diff } G$ have the property that $\varphi_{uv}(x)(g) = g_{uv}(x)g$ for some set of functions $\{g_{uv}\}$
 $g_{uv}: U \cap V \rightarrow G$ $\varphi_{uv}(x) = L_{g_{uv}(x)}$

proof

$$(x, \varphi_{uv}(x)(g)) = (\Psi_u \circ \Psi_v^{-1})(x, g) = \Psi_u \circ \Psi_v^{-1}(x, e)g$$

note: $\Psi_u(u \cdot g) = \Psi_u(u) \cdot g \Rightarrow \Psi_u(\Psi_u^{-1}(u) \cdot g) = \Psi_u(\Psi_u^{-1}(u)) \cdot g$
 $= u \cdot g \Rightarrow \Psi_u^{-1}(u) \cdot g = \Psi_u^{-1}(u \cdot g)$ Ψ_u^{-1} has prop. (3)

$$= \Psi_u[\Psi_v^{-1}(x, e) \cdot g] = (\Psi_u \circ \Psi_v^{-1})(x, e) \cdot g$$

$$\pi_G \circ \Psi_u \circ \Psi_v^{-1}(x, e) \in G \text{ call this } g_{uv}(x)$$

$$\Rightarrow \varphi_{uv}(x)(g) = g_{uv}(x)g$$

4/10/2

Structure group
↓

$P \xrightarrow{\pi} M$ Principal Fiber Bundle (PFB) with group G

• $\psi_u: \pi^{-1}(u) \rightarrow U \times G$ are equivariant in the 2nd factor
(ie $\psi_u(u \cdot g) = \psi_u(u) \cdot g$) then we have that $\exists g_{uv}: M \rightarrow G$

$\varphi_{uv}(x)(g) = g_{uv}(x)g$ where φ_{uv} is a transition function
 φ_{uv} satisfy co-cycle condition $\Rightarrow g_{uv}(x)$ do too.

(ie $g_{uv}g_{vw} = g_{uw}$)

thus $g_{uu}(x) = e \quad \forall x \in M$

Thm Let M a manifold, G a Lie group, $\{U_\alpha\}_{\alpha \in \Lambda}$ an open covering of $M \ni \forall \alpha, \beta \in \Lambda$ for which $U_\alpha \cap U_\beta \neq \emptyset$ one has a mapping $g_{\beta\alpha}: U_\alpha \cap U_\beta \rightarrow G$. If $\{g_{\alpha\beta}\}$ satisfy the cocycle condition then $\exists$ a P.F.B. $\pi: P \rightarrow M$ w/t group G . with transition functions $\{\varphi_{\alpha\beta}\}$.

Sketch proof

$\varphi_{\alpha\beta}: U_\alpha \cap U_\beta \rightarrow G \quad \varphi_{\alpha\beta}(x) = g_{\alpha\beta}(x)g$

then $\{\varphi_{\alpha\beta}\}$ are transition functions which satisfy the cocycle cond.

thus we get $\psi_\alpha: \pi^{-1}(U_\alpha) \rightarrow U_\alpha \times G$ define action of P

$u \cdot g = \psi_\alpha^{-1}(\psi_\alpha(u) \cdot g)$

need to check on overlap (action well def.)

proof 2: detailed

See handout / notes from library.

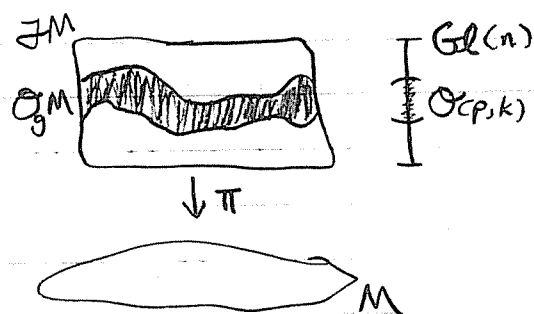
Ex: $\mathcal{F}M = \{(p, \{e_i\}) \mid \{e_i\} \text{ a basis of } T_p M\}$ is the frame bundle over M this is a PFB w/t group $GL(n)$

choose some metric g

$\mathcal{O}_g M = \{(p, \{e_i\}) \mid \{e_i\} \text{ an orthogonal basis of } T_p M\}$
 $g_p(e_i, e_j) = \delta_{ij}$

is the orthogonal frame bundle over M is a PFB w/t group $O(p, k)$.

This is a reduced bundle



$\varphi: P \rightarrow V$ P a P.F.B., V a vector space.

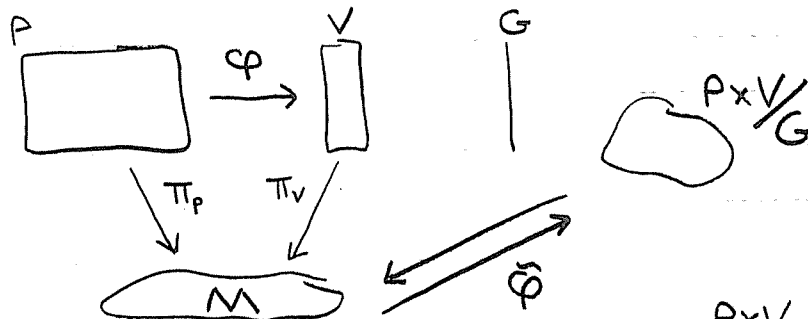
where $G \times V \rightarrow V$ is an action on V

φ is equivariant iff $\varphi(u \cdot a) = \bar{a} \cdot \varphi(u)$

$$\frac{P \times V}{G} \quad (u, x) \cdot g = (u \cdot g, \bar{g}^{-1} \cdot x)$$

"
 {orbit space}

$\frac{P \times V}{G}$ is a vector bundle with fiber V .



given equivariant $\varphi \exists! \tilde{\varphi}: M \rightarrow \frac{P \times V}{G}$ section & conversely,

4/12/2

$$TM \xrightarrow{L} \mathbb{R} \quad \leftarrow \text{Lagrangian}$$

$$T^*M \xrightarrow{H} \mathbb{R} \quad \leftarrow \text{Hamiltonian}$$

- An internal theory is modeled by a vector bundle

$$E \xrightarrow{\pi} M$$

M is spacetime

On many theories you have a state-space parameterized by state vectors are not (definable in terms of tangent vectors) is not tensor bundles,

So E is a vector bundle and $\pi^{-1}(x) = E_x$ for $x \in M$ is the set of all states of the given theory.

If M is Minkowski then $E = M \times V$, V a finite dim'l vector space.

(*) Example: (like isospin) $\begin{pmatrix} p \\ n \end{pmatrix} \begin{matrix} \leftarrow \text{proton} \\ \leftarrow \text{neutron} \end{matrix} + \rightsquigarrow \text{nucleon}$

$$E = M \times \mathbb{C}^2$$

$$\downarrow \pi$$

M

$$\text{then } E_x \cong \mathbb{C}^2$$

$$p \equiv \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad n \equiv \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\psi: M \rightarrow \mathbb{C}^2 \quad \psi(x) = \begin{pmatrix} \psi_1(x) \\ \psi_2(x) \end{pmatrix} \begin{matrix} \leftarrow \text{protonness} \\ \leftarrow \text{neutronness} \end{matrix}$$

$$g_x(z, w) = z_1 \bar{w}_1 + z_2 \bar{w}_2$$

[**Def**] A fiber metric is a map $g \ni \forall x \in M \quad g_x$ is a metric on E_x .

$$\hat{\psi}(x) = (x, \psi(x))$$

→ Math types associate fields with sections of E .

Def $\mathcal{F}E$ is the frame bundle of the vector bundle $E \xrightarrow{\pi} M$
 $\mathcal{F}E = \{(p, \{e_i\}) \mid p \in M, \{e_i\} \text{ is a basis for } E_p (= \pi^{-1}\{p\})\}$

$\mathcal{F}E \xrightarrow{\pi} M$ is a principal fiber bundle with group $GL(k)$
 $(k = \dim V)$

$$(p, \{e_i\}) \cdot A = (p, \{e_j A_i^j\})$$

could
be R_{ij}
↓

If $\exists$ a fiber metric g we can define $\mathcal{O}_g E = \{(p, \{e_i\}) \mid g_p(e_i, e_j) = \delta_{ij}\}$

$\mathcal{O}_g E \xrightarrow{\pi} M$ orthogonal frame bundle.

• back to example (*) $g(z, w) = z_1 \bar{w}_1 + z_2 \bar{w}_2$
 then the group of $\mathcal{O}_g E$ is $U(2)$

$$\text{where } U(2) = \{A \in GL(2, \mathbb{C}) \mid \bar{A}^t A = I\}$$

When M is Minkowski space, then E is trivial ($E = M \times \mathbb{C}^2$)
 then $\mathcal{O}_g E = \{(p, z, w) \mid z, w \in \mathbb{C}^2 \ni g_p(z, w) = \delta_{ij}\}$
 $= M \times U(2)$

These are trivial:

$$\bullet \mathcal{O}_g E \xleftarrow{\quad} M \times U(2) \quad \gamma(p, A) = (p, (1, 0)A, (0, 1)A)$$

$$\bullet \mathcal{F}E \xleftarrow{\quad} M \times GL(m) \quad \gamma(p, A) = (p, (A_i^j, 1) \Sigma_j(p))$$

(at each pt.)

Def if $\exists$ m linear independent vector fields on M ($\dim(M) = m$)
 then we say M is parallelizable.

Thm M parallelizable then TM & $\mathcal{F}M$ are trivial bundles.

Thm If $\exists$ a global section of a principal fiber bundle then it must be trivial

Thm If $\exists$ n lin. indep. sections of a vector bundle it is trivial (where $\dim V = n$)

Isospin Case:

$\exists$ sections Δ_1, Δ_2 of $E = M \times \mathbb{C}^2$

$$\Delta_1(x) = (x, (1, 0))$$

$$\Delta_2(x) = (x, (0, 1))$$

$\exists$ a section $\Delta: M \rightarrow \mathcal{O}_g M$

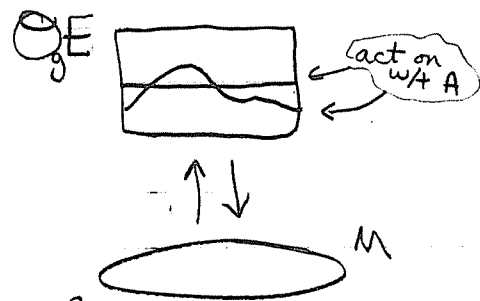
$$\Delta(x) = (x, \{(1, 0), (0, 1)\})$$

Let $A: M \rightarrow U(2)$

$$\bar{\Delta}(x) = (x, \{(1, 0), (0, 1)\}) \cdot A = (x, \{(1, 0)A, (0, 1)A\})$$

In general M a manifold, $E \xrightarrow{\pi} M$
a vector bundle, g a fiber metric
we can consider $\mathcal{O}_g E \rightarrow M$

it has group $G = \{\text{orthogonal w/t resp. to } g\}$



4/15/2

Lemma 239 If $\pi: P \rightarrow M$ is a PFB w/t group G , and $U \subseteq M$ open then $\exists \Delta: U \rightarrow P$ a section (ie $\pi \circ \Delta = \text{id}_U$) iff $\exists$ local trivializing map $\psi_u: \pi^{-1}(u) \rightarrow U \times G$

Sketch proof

$\supset$ $\Delta: U \rightarrow P$ is a section (note: $\Delta(u) \in \pi^{-1}(u)$)

Define $\Phi: U \times G \rightarrow \pi^{-1}(u)$ by $\Phi(x, g) = \Delta(x) \cdot g$

$\supset \Delta(x) \cdot g_1 = \Delta(x) \cdot g_2 \Rightarrow g_1 = g_2$ by freeness of action $\Rightarrow 1-1$ onto by transitivity. Hence Φ is a bijection, smooth since Δ is smooth & the action is smooth.

Using the inverse function theorem we get locally smooth inverse

... and it has a global inverse $\Phi^{-1} = \psi_u$ hence must agree

w/t local inverse hence smooth. Also $\psi_u(z) \cdot g = \psi_u(z \cdot g) \checkmark \checkmark$

$\psi_u: \pi^{-1}(u) \rightarrow U \times G$ given then

define $\Delta: U \rightarrow \pi^{-1}(u)$ by $\Delta(x) = \psi_u^{-1}(x, e)$

(note: ψ_u^{-1} smooth & $\text{id}_U \times e$ is smooth ($e(x) \equiv e$))

$\Rightarrow \Delta$ smooth, $\pi \circ \Delta(x) = \pi \circ \psi_u^{-1}(x, e) = \pi_u(x, e) = x \checkmark \checkmark$

Cor P has a global section iff it is trivial

proof

$\Delta: M \rightarrow P \Leftrightarrow \psi_u: P \rightarrow M \times G$ diffeomorphism,

Thm Let $\pi: P \rightarrow M$ be principal G -bundle, and let

$\{U_\alpha\}$ be an open cover of M . $\exists$ local trivializing maps $\psi_\alpha: \pi^{-1}(U_\alpha) \rightarrow U_\alpha \times G$ iff $\exists$ sections $\Delta_\alpha: U_\alpha \rightarrow \pi^{-1}(U_\alpha)$

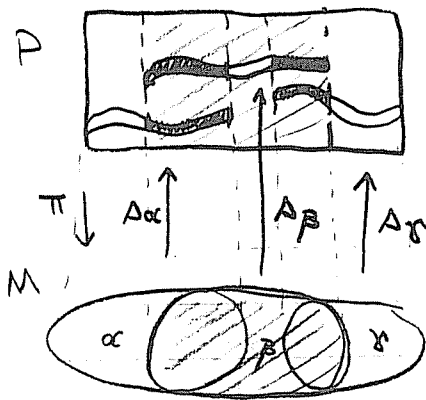
If one has $\{\psi_\alpha\}$ & $\{\Delta_\alpha\}$ and transition maps $\{g_{\alpha\beta}\}$ (of ψ_α 's)

then

$$\Delta_\alpha(x) = \Delta_\beta(x) g_{\beta\alpha}(x)$$

where

$$g_\alpha(y) = \pi_G(\psi_\alpha(\Delta_\alpha(y)))$$



proof

first part is immed. from Lemma.

• again $g_\gamma(y) = \pi_G \circ \psi_\gamma \circ \Delta_\gamma(y)$

$$\Leftrightarrow \psi_\gamma \circ \Delta_\gamma(y) = (y, g_\gamma(y))$$

$$\begin{aligned} \psi_\beta \circ \Delta_{\alpha\beta}(x) &= \psi_\beta \circ \psi_\alpha^{-1}(x, g_{\alpha\beta}(x)) = \psi_\beta \circ \psi_\alpha^{-1}(x, e) \circ g_{\alpha\beta}(x) \\ &= (x, g_{\beta\alpha}(x)) \circ g_{\alpha\beta}(x) = (x, e) \circ g_{\beta\alpha}(x) g_{\alpha\beta}(x) \end{aligned}$$

$$\begin{aligned} \Rightarrow \Delta_{\alpha\beta}(x) &= \psi_\beta^{-1}(x, e) \circ g_{\beta\alpha}(x) g_{\alpha\beta}(x) = \psi_\beta^{-1}(x, g_\beta(x)) \circ g_\beta(x)^{-1} \cdot \\ &= \Delta_\beta(x) g_\beta(x)^{-1} g_{\beta\alpha}(x) g_{\alpha\beta}(x) // \end{aligned}$$

Ex 2.6 (c)

surj

G

$\boxed{\text{Thm}}$

$\exists$ unique manifold structure on $G/H \dots$

S^2

G/H

$$\psi_\alpha^{-1}(x, gh) = \Delta_\alpha(x) gh = \psi_\alpha^{-1}(x, g) h$$

$$G_x \subseteq G$$

closed subgroup & $G/G_x \cong x \cdot G$

Handout:

"Lemma of AEG and ...
& "Definition To say that
 $P \xrightarrow{\pi} M$ is a ...

4/17/2

Let $E \xrightarrow{\pi} M$ be a vector bundle with fiber V (a finite dim'd vector space). Let $\{n_i\}_{i=1}^N$ be a basis for V .

Define $GL(N) \times V \rightarrow V$ by $A \cdot n_j = A_j^i n_i$.
(ie $v = v^i n_i$ then $A \cdot v = v^i A_j^i n_j = n^i(v) A_j^i n_j$)
 $\Rightarrow A \cdot v = (A_j^i n^i)(v) n_j$ where $\{n^i\}$ is the dual basis.

$$\mathcal{F}E = \{ (x, \{e_i\}) \mid \{e_i\} \text{ is a basis of } \pi^{-1}\{x\} (= E_x) \}$$

(ie $\mathcal{F}M = \mathcal{F}(TM)$ from before)
Bad Notation

Thm $\exists$ 1-1 correspondence between sections φ of $E \xrightarrow{\pi} M$ and equivariant maps $\hat{\varphi}: \mathcal{F}E \rightarrow V$

(note: $(x, \{e_i\}) \cdot A = (x, \{e_i A_j^i\})$ the fibers are $GL(N)$)
 $\hat{\varphi}((x, \{e_i\}) \cdot A) = A^i_j \hat{\varphi}(x, \{e_i\}) \leftarrow \text{equivariance}$

Physicists start with $\varphi: M \rightarrow V$ from this we induce
 $\tilde{\varphi}: M \rightarrow M \times V$ def by $\tilde{\varphi}(x) = (x, \varphi(x))$ from which we
can induce $\hat{\varphi}: \mathcal{F}(M \times V) \rightarrow V$

Note: This Thm can be generalized to

$\begin{matrix} P & \xrightarrow{\pi} & M \\ \downarrow & & \downarrow \\ G \times F & \rightarrow & F \end{matrix}$ principal then sections of $P \times F$ are in 1-1
 $\searrow \quad \quad \quad \nearrow M$

correspondence w/ equiv. maps from P to F .

proof

Let $\varphi: M \rightarrow E$ be a section of π . Define $\hat{\varphi}: \mathcal{F}E \rightarrow V$

by $\hat{\varphi}(x, \{e_i\}) = e^i(\varphi(x)) n_i$ (this is ok because $\varphi(x) \in E_x$)

$$\hat{\varphi}[(x, \{e_i\}) \cdot A] = \hat{\varphi}(x, \{e_i A_j^i\}) = f^i(\varphi(x)) n_i$$

$\underbrace{\quad}_{f^i}$

$$\text{but } f^i = (\bar{A}^{-1})^i_j e^j \therefore f^i(\varphi(x)) \omega_i = ((\bar{A}^{-1})^i_j e^j)(\varphi(x)) \omega_i$$

$$= \bar{A}^{-1} \cdot e^i(\varphi(x)) \omega_i \quad (\text{from before})$$

$\therefore \hat{\varphi}$ is equivariant

Given $\hat{\varphi}: TE \rightarrow V$ define $\varphi: M \rightarrow E$ a section of π as follows:

$x \in M$ then choose $\{e_i\}$ a basis of E_x then
 $\varphi(x) = \omega^i(\hat{\varphi}(x, \{e_i\})) e_i$

$\{f_j\}$ is another basis then $\exists A \ni e_i = A^j_i f_j$
 and $e^i = \bar{A}^i_j f^j$

$$\omega^i(\hat{\varphi}(x, \{e_i\})) e_j = \omega^i(\hat{\varphi}(x, \{f_k\}) \cdot A) A^j_i f_j$$

$$= \omega^i(\bar{A}^{-1} \cdot \hat{\varphi}(x, \{f_k\})) A^j_i f_j = \omega^i(\bar{A}^{-1}_\ell \omega^\ell(\hat{\varphi}(x, \{f_k\})) \omega^\ell_k) A^j_i f_j$$

$$= \bar{A}^{-1}_\ell \omega^\ell(\hat{\varphi}(x, \{f_k\})) \delta^\ell_k A^j_i f_j = \bar{A}^{-1}_\ell A^j_k \omega^\ell(\hat{\varphi}(x, \{f_k\})) f_j$$

$$= \omega^j(\hat{\varphi}(x, \{f_j\})) f_j \therefore \text{well defined}$$

$$\text{finally } \pi \circ \varphi(x) = \pi(\omega^i(\hat{\varphi}(x, \{e_i\})) e_i) = x \checkmark$$

Skip: $\varphi, \hat{\varphi}$ smooth and 1-1-ness of this correspondence

=

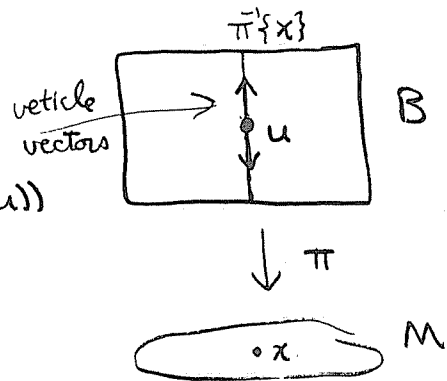
Skip Exercise 2.7 for Now

? See Ex 2.8 do for T^*M ?

Connections

Def Let $B \xrightarrow{\pi} M$ be a fiber bundle with fiber F .
It is possible to select a subspace from $T_u B$ for $u \in B$ which we call vertical vectors. These vertical vectors are tangent to the fiber of π at u .

If $X \in T_u B$ is tangent to $\pi^{-1}(\pi(u))$ then $\exists$ a curve $\gamma: (-a, a) \rightarrow \pi^{-1}(\pi(u))$
 $\exists \gamma(0) = u$ & $\gamma'(0) = X$



Also, note that

$$d_u \pi: T_u B \rightarrow T_{\pi(u)} M$$

$$d_u \pi(X) = d_u \pi(\gamma'(0)) = \frac{d}{dt} (\pi \circ \gamma(t)) \Big|_{t=0} = \frac{d}{dt} (\pi \circ \text{const.}) \Big|_{t=0} = \frac{d}{dt} (u) \Big|_{t=0} = 0$$

denote the set of vertical vectors by

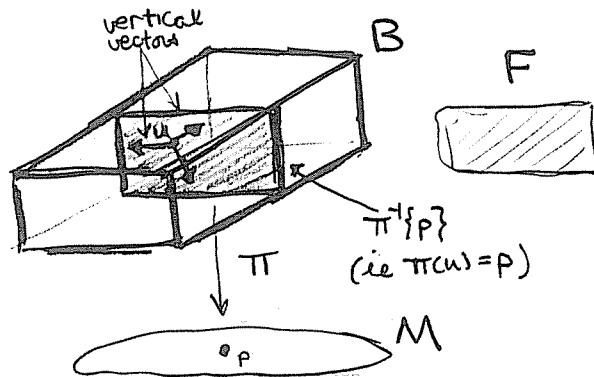
$$VT_u B = \{X \in T_u B \mid d_u \pi(X) = 0\}$$

Our choice of complement: $VT_u B \oplus \underline{\hspace{1cm}} = T_u B$
will give rise to our connection

$$\begin{array}{c} \uparrow \qquad \qquad \uparrow \qquad \qquad \uparrow \\ \dim M + \dim F = \dim B \end{array}$$

$$\dim F \neq 0 \Rightarrow VT_u B \subsetneq T_u B$$

4/19/2



$B \xrightarrow{\pi} M$ with fiber F

$$VT_u B = \{X \in T_u B \mid d_u \pi(X) = 0\} = \text{vertical vectors.}$$

Def An Ehresmann connection on B is a mapping $H: B \rightarrow \{\text{subspaces of } T_u B \text{ where } u \in B\}$

- (1) $\forall u \in B$ $H(u) = H|_{T_u B}$ is a subspace of $T_u B$
 $\oplus T_u B = H(u) \oplus VT_u B = H|_{T_u B} \oplus VT_u B$

we write $X_u = hX_u + vX_u = X_u + Z_u$

- (2) The mapping H is "smooth" $\equiv \forall$ vector field X on B the vector fields hX & vX are smooth.

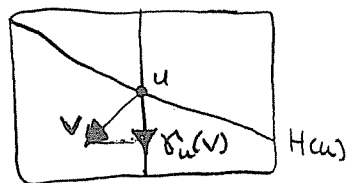
If $B \xrightarrow{\pi} M$ is a P.F.B. with group G , then H is called a (principal) connection iff H is an Ehresmann connection $\exists$

- (3) $d_u \rho_g(H(u)) = H(u \cdot g) \forall u \in B, g \in G$
 where $\rho_g: B \rightarrow B$ defined by $\rho_g(x) = x \cdot g$

note: $d_u \rho_g: T_u B \rightarrow T_{u \cdot g} B \because d_u \rho_g(H(u)) \in T_{u \cdot g} B$

- $\dim(B) = \dim(M \times F) = \dim(M) + \dim(F)$
 and $\dim(VT_u B) = \dim(F)$ & $\dim(H(u)) = \dim(M)$

$\mathcal{F}(TM)$ group is $GL(n)$ where $n = \dim(M)$
 (note: prev; we wrote $\mathcal{F}M$ instead of $\mathcal{F}(TM)$)
 $\downarrow$
 M
connections in Riemannian geometry live here



Let H be an Ehresmann connection we can define a map $\gamma_u: T_u B \rightarrow T_u B \ni \gamma_u(X_u) = vX_u + hX_u$ just keep the vert. part.

(i) γ_u is a projection and $\gamma_u(T_u B) = VT_u B$

(ii) $\text{Ker}(\gamma_u) = H(u)$

γ is smooth since it sends smooth vector fields to smooth v.f.'s and conversely,

given a projection γ_u onto $VT_u B \ni \gamma$ is smooth. we get $H(u) \equiv \text{Ker}(\gamma_u)$ a connection.

If $\pi: B \rightarrow M$ is principal and H is a prin. connection we can induce a projection γ which induces a $\mathfrak{g}$ -valued 1-form.

$\gamma_u: T_u B \rightarrow VT_u B \xleftarrow{\delta_u^{-1}} \mathfrak{g}$
this induced form is the "connection form"

note: VTB is a vector bundle
 $\downarrow$
 B

4/22/2

Thm

$\pi: P \rightarrow M$ is a P.F.B. with structure group G .
 If $H: P \rightarrow \{\text{subspaces of } T_u P \text{ for } u \in P\}$ is a principal connection then $\exists \mathfrak{g}$ -valued one form ω on P s.t.

- ① $\ker(\omega_u) = H(u) \quad \forall u \in P$
- ② $\omega_u(\delta_A(u)) = A \quad \forall u \in P, A \in \mathfrak{g}$
- ③ $\iota_g^* \omega_u = \text{Ad}(g^{-1}) \omega_u, \quad \forall g \in G$

proof

Let H be a connection. For $A \in \mathfrak{g}, u \in P$ $\sigma(u, g) = u \cdot g$

$$\delta_A(u) = \left. \frac{d}{dt} [u \cdot \exp(tA)] \right|_{t=0} = \left. \frac{d}{dt} [\sigma_u(\exp(tA))] \right|_{t=0}$$

$$= d_{\sigma_u} \left(\left. \frac{d}{dt} (\exp(tA)) \right|_{t=0} \right) = d_{\sigma_u}(A) \quad (\delta_A(u) \text{ linear in } A)$$

Since the action is free: $\delta_A(u) = 0$ for some u then $A = 0$

If we define $\delta_u: \mathfrak{g} \rightarrow VT_u P$ by $\delta_u(A) = \delta_A(u)$

Note: δ_u is linear & injective ($\delta_u(A) = 0 \Rightarrow A = 0$)

$$\dim VT_u P = \dim T_u \pi^{-1}(\pi(u)) = \dim(\pi^{-1}(\pi(u))) = \dim(G) = \dim(\mathfrak{g})$$

hence δ_u is an isomorphism (vector space) $\forall u \in P$.

Let $\omega_u = \delta_u^{-1} \gamma_u$ where γ_u is the E. connection induced by H .

$$X \in \ker(\omega_u) \Leftrightarrow \omega_u(X) = \delta_u^{-1} \gamma_u(X) = 0 \Leftrightarrow \gamma_u(X) = 0 \Leftrightarrow X \in H(u)$$

① $\therefore \ker(\omega_u) = H(u) \checkmark$

Since γ_u is a projection of $T_u P$ onto $VT_u P$, we have $\gamma_u|_{\text{Im}(\delta_u)}$

$$= \gamma_u|_{VT_u P} = \text{id}_{VT_u P} \text{ and so, } \omega_u(\delta_A(u)) = \delta_u^{-1} \gamma_u(\delta_A(u)) = \delta_u^{-1}(\delta_A(u))$$

② (since $\delta_A(u) \in VT_u P$) $= \delta_u^{-1} \delta_u(A) = A \checkmark$

Since H is principal $d_u \iota_g(H(u)) = H(u \cdot g) \quad \forall u \in P, g \in G$.

$$\iota_g^*(\omega)(h) = \omega(\iota_g(h)) = 0 \text{ since } d_u \iota_g(h) \in H(u \cdot g) = \ker(\omega_{u \cdot g})$$

$$\forall h \in H(u) \text{ hence } \text{Ad}(g^{-1})\omega_u(h) = \text{Ad}(g^{-1})(0) = 0 \checkmark$$

$$\iota_g^*(\omega_u)(\delta_A(u)) = \omega_{u \cdot g}(d_u \iota_g(\delta_A(u))) \stackrel{\text{lemma pg 256}}{=} \omega_{u \cdot g}(\delta_{\text{Ad}(g^{-1})A}(u \cdot g))$$

$$= \text{Ad}(g^{-1})(A) = \text{Ad}(g^{-1})\omega_u(\delta_A(u)) \Rightarrow \iota_g^* \omega_{u \cdot g} = \text{Ad}(g^{-1})\omega_u \text{ on } VT_u P$$

$$\Rightarrow X \in T_u P \quad r_g^* \omega(vX + hX) = r_g^* \omega(vX) + \cancel{r_g^* \omega(hX)}^0 \\ = \text{Ad}(g^{-1})\omega(vX) + \text{Ad}(g^{-1})\omega(hX) = \text{Ad}(g^{-1})\omega(vX + hX) \checkmark$$

Converse:

Thm Let ω be a Lie algebra valued 1-form on $TP \Rightarrow$

$$\textcircled{1} \omega_u(\delta_A(u)) = A \quad \forall u \in P, A \in \mathfrak{g}$$

$$\textcircled{2} r_g^* \omega = \text{Ad}(g^{-1})\omega$$

then

$$\textcircled{3} H(u) \equiv \text{Ker}(\omega_u) \text{ is a principal connection.}$$

proof

First show $T_u P = H(u) + VT_u P$ then show sum is direct:

Let $w \in T_u P$ and let $w_v \equiv \delta_{\omega_u(w)}(u) \in VT_u P$

need $w - w_v \in H(u) = \text{Ker}(\omega_u): \omega_u(w - w_v) =$

$$\omega_u(w) - \omega(\delta_{\omega_u(w)}(u)) = \omega_u(w) - \omega_u(w) = 0 \checkmark$$

$\S w \in H(u) \cap VT_u P \Rightarrow \omega_u(w) = 0$ & $\delta_A(u) = w$ some $A \in \mathfrak{g}$

$$\Rightarrow \omega_u(\delta_A(u)) = A = 0 \Rightarrow w = 0 \therefore T_u P = H(u) \oplus VT_u P$$

Note: $vX_u = \delta_u(\omega_u(X_u))$ is smooth b/c δ & ω are.

and $hX_u = X_u - vX_u$ is smooth $\checkmark$

$$\text{Ad}(g)^* = \text{Ad}(g^{-1})^* \quad \text{invertible map}$$

$$w \in H(u) \Leftrightarrow w \in \text{Ker}(\omega_u) \Leftrightarrow \omega_u(w) = 0 \Leftrightarrow \text{Ad}(g^{-1})\omega_u(w) = 0$$

$$\Leftrightarrow \omega_{ug}(d_u r_g w) = 0 \Leftrightarrow d_u r_g(w) \in \text{Ker}(\omega_{ug}) = H(ug)$$

$\Rightarrow$ The connection is principal

Handout!

"Theorem Assume that $\varphi: G \rightarrow H$ is a ...

4/24/2

Physics

A gauge potential is a Lie algebra valued 1-form on a space-time (Some must be modified if the space-time is not contractible.)

M be a space-time manifold (say Minkowski)

Two such potentials $A, \bar{A}$ are gauge equivalent $(G \subseteq \mathfrak{gl}(n))$

$$\Leftrightarrow \exists g: M \rightarrow G \quad \exists \bar{A} = g^{-1} A g + g^{-1} dg, \quad (= g^{-1} [A g + dg g^{-1}] g)$$

$$\Leftrightarrow \bar{A}_x(v) = g^{-1}(x) A_x(v) g(x) + g^{-1}(x) d_x g(v)$$

Math

A connection ω on a P.F.B. $P \xrightarrow{\pi} M$ with structure group G .

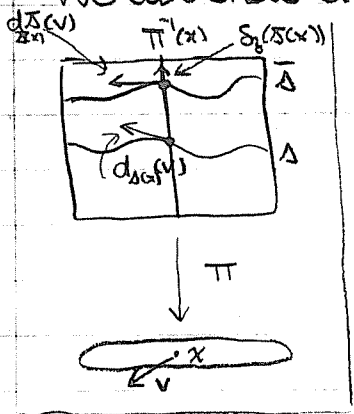
If Δ & $\bar{\Delta}$ are sections of π define $A = \Delta^* \omega$ & $\bar{A} = \bar{\Delta}^* \omega$

(think global for now)

$$\Delta(x), \bar{\Delta}(x) \in \pi^{-1}\{x\} = P_x = \Delta(x) \cdot G \Rightarrow \Delta(x) \cdot g_x = \bar{\Delta}(x)$$

$g: M \rightarrow G$ is smooth (skip)

We can show $d_x \bar{\Delta} = d_{\Delta(x)} \eta_{g(x)} \circ d_x \Delta + \delta_z(\bar{\Delta}(x))$ for some $z \in \mathfrak{g}$



$$\text{ie } d_{\Delta(x)} (d_x \bar{\Delta}(v) - d_{\Delta(x)} \eta_{g(x)} \circ d_x \Delta(v)) = 0$$

$$z = d \eta_{g(x)^{-1}} \circ d_x g$$

$$\omega_{\Delta(x)}(d_x \bar{\Delta}(v)) = \omega_{\Delta(x)}(d_{\Delta(x)} \eta_{g(x)} \circ d_x \Delta(v)) + \omega_{\Delta(x)}(\delta_z(\bar{\Delta}(x)))$$

$\parallel$ $(\bar{\Delta}^* \omega)_x(v)$ $\parallel$ $\omega_{\Delta(x)}(\delta_z(\bar{\Delta}(x)))$

$$\Rightarrow \bar{A}_x(v) = \text{Ad}(g(x)^{-1}) A_x(v) + g(x)^{-1} d_x g(v)$$

$\text{Ad}(g(x)^{-1}) (\Delta^* \omega)_x(v) + d \eta_{g(x)^{-1}} \circ d_x g(v)$

$\Rightarrow$ so our P.F.B. & Connection ... encode the gauge equiv.

Next Semester:

$$\mathcal{G} = \{g: M \rightarrow G\} \quad \mathcal{A} = \{\text{gauge potentials}\}$$

$$\mathcal{A} \times \mathcal{G} \rightarrow \mathcal{A} \text{ by } g \cdot A = g^{-1} A g + g^{-1} dg$$

→ work to get an ∞ -dim'd P.F.B.

$$\mathcal{A} \xrightarrow{\text{w/ fiber } \mathcal{G}} \mathcal{A}/\mathcal{G}$$

Gets messy b/c ∞ -dim'd.

Thm $\pi: P \rightarrow M$ P.F.B. with group G ,

ω a connection.

$\Delta: U \rightarrow P$ & $\bar{\Delta}: \bar{U} \rightarrow P$ $U \cap \bar{U} \neq \emptyset$ are local sections

then $\exists g: U \cap \bar{U} \rightarrow G$ $\exists \bar{\Delta}(x) = \Delta(x) \cdot g(x)$ with g smooth &
 $(\bar{\Delta}^* \omega)_x = \text{Ad}(g(x)^{-1})(\Delta^* \omega)_x + d_{\text{geom}} \log_{\text{geom}} \circ dx g$

proof (Rough Sketch)

$$\gamma(0) = p \quad \bar{\Delta}(\gamma(t)) = \Delta(\gamma(t)) g(\gamma(t))$$

$$\gamma'(0) = v \quad d_{\gamma(0)} \bar{\Delta}(\gamma'(t)) = \frac{d}{dt} [\Delta(\gamma(t)) g(\gamma(t))]$$

define $f(t_1, t_2) = \Delta(\gamma(t_1)) \cdot g(\gamma(t_2))$ look for $\frac{d}{dt} f(t, t) \Big|_{t=0}$

$$= \frac{\partial}{\partial t_1} f(0, 0) + \frac{\partial}{\partial t_2} f(0, 0) = d_{\gamma(0)} \Delta(d_{\gamma(0)} \gamma'(0)) + \dots$$

details in notes pg 264 etc. //

We can define equivalence classes of gauge potentials

$$A_\alpha = \Delta_\alpha^* \omega \quad A_\beta = \Delta_\beta^* \omega \quad U_\alpha \cap U_\beta \neq \emptyset \text{ then}$$

$$A_\alpha = g^{-1} A_\beta g + g^{-1} dg \text{ some } g \text{ then } A_\alpha \sim A_\beta$$

Given an open cover $\{U_\alpha\}$ with local sections $\{\Delta_\alpha\}$

and we have $\{A_\alpha\} \ni A_\alpha = g_{\alpha\beta}^{-1} A_\beta g_{\alpha\beta} + g_{\alpha\beta}^{-1} dg_{\alpha\beta}$ some $g_{\alpha\beta}$

we get a unique connection ω

we also have enough data to both the P.F.B. & ω .

4/26/2 How to Build a Connection:

Given $A: TU \rightarrow \mathfrak{g}$ where U is the domain of a section $\Delta: U \rightarrow P$ of some PFB $\pi: P \rightarrow M$.
How do you define a connection on $\pi^{-1}(U)$?

Define ω at points of $\Delta(U)$ first.

Let $x \in U$ and $w \in T_{\Delta(x)}\Delta(U)$ $w = d_x \Delta(v)$ for some $v \in T_x M$

Vectors
tangent
to
 $\Delta(U)$

Define $\omega_{\Delta(x)}(w) = \omega_{\Delta(x)}(d_x \Delta(v)) = A_x(v)$ ($\Delta^* \omega = A$)
Let $\hat{w} \in T_{\Delta(x)}\pi^{-1}(U) \in T_{\Delta(x)}P$ since $\pi^{-1}(U)$ is an open submanifold of P
 $\hat{v} = d_{\Delta(x)}\pi(\hat{w}) \in T_x M$ $d_{\Delta(x)}[\hat{w} - d_x \Delta(\hat{v})] = d_{\Delta(x)}\pi(\hat{w}) -$

$$d_{\Delta(x)}\pi(d_x \Delta(\hat{v})) = \hat{v} - d_x \pi \circ \Delta^* d(\hat{v}) = \hat{v} - \hat{v} = 0$$

$$\Rightarrow \hat{w} - d_x \Delta(\hat{v}) \in VT_{\Delta(x)}P$$

$$\therefore \hat{w} - d_x \Delta(\hat{v}) = \delta_{\Delta(x)}(z) \text{ some } z \in \mathfrak{g}$$

Vectors
at
points in
 $\Delta(U)$

$$\omega_{\Delta(x)}(\hat{w}) = \omega_{\Delta(x)}(d_x \Delta(\hat{v}) + \delta_{\Delta(x)}(z)) \equiv A_x(v) + z$$

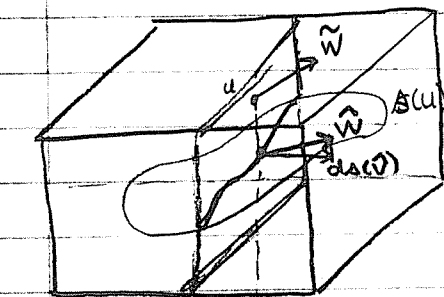
Now let $u \in \pi^{-1}(x)$, $x \in U$ then $u = \Delta(x) \circ g$ some $g \in G$

In general

$\nexists \tilde{w} \in T_u P$ where $\pi(u) \in U$ then

$$\omega_u(\tilde{w}) \equiv \text{Ad}(g^{-1})\omega_{\Delta(x)}(d_u \pi_{g^{-1}}(\tilde{w}))$$

($= \Delta(x) \circ g$)



Magnetic Monopole ... (see Neighbors)

QFT & Anomalies by Bertlemann

$$A_\mu^a dx^\mu \otimes T_a \leftarrow \text{basis for Lie algebra}$$

↑ Lie algebra-valued 1-form on (U, x)

What is the horizontal lift of a vector?

$x \in M$

Def

$u \in \pi^{-1}(x)$ & $v \in T_x M$ the horizontal lift of v to u is $\tilde{v} \in T_u P$, $\tilde{v} = [d_u \pi|_{H(u)}]^{-1}(v) \in H(u) \subseteq T_u P$

$\S d_u \pi(\tilde{v}) = 0 \Rightarrow \tilde{v} \in V T_u P \cap H(u) = \{0\} \Rightarrow d_u \pi|_{H(u)}$ is 1-1.
 $\dim(H(u)) = \dim(M) = \dim(T_x M)$ hence $d_u \pi|_{H(u)}$ is a linear isomorphism. ✓

Alt.
Def.

properties

$$\textcircled{1} d_u \pi(\tilde{v}) = d_u \pi([d_u \pi|_{H(u)}]^{-1}(v)) = v$$

$$\textcircled{2} \omega_n(\tilde{v}) = 0$$

$\S \tilde{v} \in T_u P \ni d_u \pi(\tilde{v}) = v$ & $\omega_n(\tilde{v}) = 0$
 $\Rightarrow \tilde{v} \in H(u) \therefore [d_u \pi|_{H(u)}]^{-1}(v) = \tilde{v}$

look at Prop on pg 2 of Handout

Prop

X is v.f. on M then horizontal lift of X is a v.f. $\exists$ at $u \in P$ it is $[d_u \pi|_{H(u)}]^{-1}(X_{\pi(u)})$
this is smooth ✓

$\vdots$
Will use horizontal lift to talk about covariant derivative.

4/29/2

$P \xrightarrow{\pi} M$ P.F.B., with connection
 $G \times V \rightarrow V$, V a finite dimensional vector space.
 $\hat{\phi}: P \rightarrow V$ equivariant

Def

$$D\hat{\phi}: TP \rightarrow V$$

$$(D\hat{\phi})_u(\Upsilon_u) = d_u \hat{\phi}(h(\Upsilon_u))$$

horizontal comp.

(dim M = n)

$$\underline{\alpha}: P = \mathcal{Z}(TM) = \{(p, \{e_i\}) \mid p \in M, \{e_i\} \text{ a basis of } T_p M\}$$

$$\mathbb{R}(n) \times (\mathbb{R}^n)^* \rightarrow (\mathbb{R}^n)^* \quad (g \circ f)(x) \equiv f(g^{-1}x)$$

$$\hat{\phi}: \mathcal{Z}(TM) \rightarrow (\mathbb{R}^n)^* \quad \alpha \in (\mathbb{R}^n)^*, \alpha = \alpha_i n^i \quad \left\{ \begin{array}{l} \{n^i\} \text{ dual standard} \\ \text{basis of } \mathbb{R}^n \end{array} \right.$$

$$\phi: M \rightarrow T^*M$$

$$\phi(p) = \phi_i(p) dp^i$$

equivariant maps.

↖ equivariant map

$$\hat{\phi}((p, \{e_i\})) = \hat{\phi}_j(p, \{e_i\}) n^j$$

$$\phi(p) = \hat{\phi}_j(p, \{e_i\}) e^j \in (T_p^*M)$$

↗ section of the bundle TM

↕ section of the bundle.

Prop $D_u \hat{\phi}(\Upsilon) = d_u \hat{\phi}(\Upsilon_u) + \omega_u(\Upsilon_u) \cdot \hat{\phi}(u)$

(better formula for covariant derivative) →

Def $\mathfrak{g} \times V \rightarrow V$ by $(\xi, x) \mapsto \frac{d}{dt}(\exp(t\xi) \cdot x)|_{t=0}$
 ↖ (Lie algebra)

If $\{e_a\}$ is a basis of $\mathfrak{g}$ and $\{V_b\}$ is a basis of V

then $e_a \cdot V_b = h_{acb}^c V_c$ where h_{acb}^c are constants.

where $b, c = 1, \dots, \dim V$ ↗ $a = 1, \dots, \dim \mathfrak{g}$

Weinberg "1" vol. 2

↖ representation of Lie algebra on V

$$\omega(\Upsilon) = \omega^\alpha(\Upsilon) e_\alpha \quad \hat{\Phi}(u) = \hat{\Phi}^a(u) V_a$$

then

$$D_u \hat{\Phi}(\Upsilon_u) = d_u \hat{\Phi}(\Upsilon_u) + \omega_u^\alpha(\Upsilon) e_\alpha \cdot (\hat{\Phi}^a(u) V_a)$$

$$D_u \hat{\Phi}(\Upsilon_u) = (d_u \hat{\Phi}^b)(\Upsilon_u) V_b + \omega_u^\alpha(\Upsilon) \hat{\Phi}^b(u) h_{\alpha c}^b V_c$$

$$\therefore D_u \hat{\Phi} = (d_u \hat{\Phi}^b + \omega_u^\alpha \hat{\Phi}^c h_{\alpha c}^b) V_b$$

$$D_u \hat{\Phi}^c = d_u \hat{\Phi}^c + h_{\alpha c}^b \hat{\Phi}^b(u) \omega_u^\alpha$$

covariant derivative components

Prop $D_u \hat{\Phi}(\Upsilon) = d_u \hat{\Phi}(\Upsilon_u) + \omega_u(\Upsilon_u) \cdot \hat{\Phi}(u)$

Proof

$$\Upsilon_u \in T_u P \Rightarrow \forall \Upsilon_u \in V T_u P \text{ and so } (v \Upsilon)_u = \delta_u(A(u))$$

for some $A(u) \in \mathfrak{g}$

$$\omega_u(\Upsilon(u)) = \omega(\cancel{A \Upsilon_u}) + \omega(v \Upsilon_u) = \omega(\delta_u(A(u))) = A(u)$$

$$v \Upsilon_u = \delta_u(\omega(\Upsilon_u)) = \left. \frac{d}{dt} [u \cdot \exp(t \omega(\Upsilon_u))] \right|_{t=0}$$

$$d_u \hat{\Phi}(v \Upsilon_u) = d_u \hat{\Phi} \left(\left. \frac{d}{dt} [u \cdot \exp(t \omega(\Upsilon_u))] \right|_{t=0} \right)$$

$$= \left. \frac{d}{dt} [\hat{\Phi}(u \cdot \exp(t \omega(\Upsilon_u)))] \right|_{t=0} = \text{use equivariant prop of } \hat{\Phi} \Rightarrow$$

$$\left. \frac{d}{dt} [\exp(-t \omega(\Upsilon_u)) \cdot \hat{\Phi}(u)] \right|_{t=0} \stackrel{\text{by def}}{=} -\omega(\Upsilon_u) \cdot \hat{\Phi}(u)$$

$$\Rightarrow D_u \hat{\Phi}(\Upsilon) = d_u \hat{\Phi}(h \Upsilon_u) = d_u \hat{\Phi}(\Upsilon_u) - d_u \hat{\Phi}(v \Upsilon_u) \\ = d_u \hat{\Phi}(\Upsilon_u) + \omega(\Upsilon_u) \cdot \hat{\Phi}(u) //$$

$$\begin{array}{ccc}
 P & \xrightarrow{\hat{\varphi}} & V \\
 \pi \downarrow & & \downarrow \\
 M & & M
 \end{array}
 \quad
 \begin{array}{l}
 P \times_G V = \{ (u, v)G \mid (u, v) \in P \times V \} \\
 (u, v) \cdot g = (ug, g^{-1}v)
 \end{array}$$

$\swarrow$ G-orbit

$\nwarrow$ vector field on M

$$\begin{array}{ccc}
 \hat{\varphi} \in \Gamma_M(P \times_G V) & \xleftarrow{\text{sections}} & \tilde{X} \in \Gamma_M(TM) \\
 \downarrow & & \downarrow \\
 \hat{\varphi} \in \text{Equivariant Maps}_G(P, V) & & \tilde{X} \text{ horizontal lift} \\
 \downarrow & & \downarrow \\
 D\hat{\varphi}: TP \rightarrow V & \longrightarrow & D\hat{\varphi}(\tilde{X}) \in \text{Equivar. Maps}_G(P, V) \\
 & & \downarrow \\
 & & \nabla_{\tilde{X}} \hat{\varphi} \text{ covar. der.}
 \end{array}$$

Wed.: Curvature
 Fri.: Holonomy

5/1/2

1. Find a formula for the horizontal lift of a vector field.

$P \xrightarrow{\pi} M$ P.F.B., X a vector field on M , $\omega: TP \rightarrow \mathfrak{g}$ a connection
 Let $\Delta: U \rightarrow P$ be a local section. Then,
 $\tilde{X}(\Delta(x)) = d_x \Delta(X_x) - \delta_{\Delta(x)}(A_x(X_x))$ where $A = \Delta^* \omega$

Proof

$$d_{\Delta(x)} \pi (\tilde{X}(\Delta(x)) - d_x \Delta(X_x))$$

$$= X_{\pi \Delta(x)} - d_{\Delta(x)} \pi (d_x \Delta(X_x))$$

$$= X_x - d_x \pi \xrightarrow{\text{id}} \Delta(X_x) = X_x - X_x = 0$$

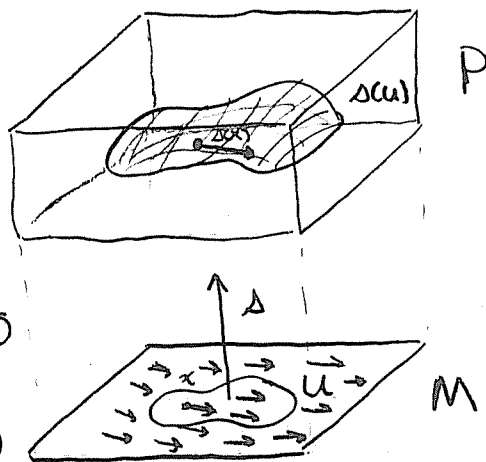
$$\therefore \tilde{X}(\Delta(x)) = d_x \Delta(X_x) + \delta_{\Delta(x)}(z)$$

$$\omega(\tilde{X}(\Delta(x))) = \omega(d_x \Delta(X_x)) + \omega(\delta_{\Delta(x)}(z))$$

$\parallel$

$\parallel$

$$0 = \Delta^* \omega(X_x) + z \Rightarrow z = \Delta^* \omega(X_x) = A_x(X_x)$$



Assume (x^μ) are coordinates on U . We can lift ∂_μ :

$$\tilde{\partial}_\mu(x) = d_x \Delta(\partial_\mu(x)) - \delta_{\Delta(x)}(A_x(\partial_\mu(x)))$$

$$\therefore \tilde{\partial}_\mu(x) = (\partial_\mu \Delta)(x) - \delta_{\Delta(x)}(A_\mu(x)) \text{ where } A_x = A_\mu(x) dx^\mu$$

• So $\Delta: U \rightarrow P$ is horizontal if $\tilde{\partial}_\mu(x) = (\partial_\mu \Delta)(x)$
 that is $\delta_{\Delta(x)}(A_\mu(x))$ is $A_\mu = 0$ ie $A = 0$

2. If $P \xrightarrow{\pi} M$ is a P.F.B w/ group G , $G \times V \rightarrow V$ is an action on a finite dim'l vector space V .

then $\tilde{X}(\hat{\varphi}) \in \text{Maps}_G(P, V)$ (= Equivariant Maps from P to V)

$\forall \hat{\varphi} \in \text{Maps}_G(P, V)$ and $\forall X$ a vector field on M .

$$\begin{array}{ccccc} \text{section} & & \text{(equiv. map)} & & \text{section} \\ \varphi & \xleftarrow[\text{corresp.}]{1-1} & \hat{\varphi} & \xrightarrow{\quad} & \tilde{X}(\hat{\varphi}) \xleftarrow[\text{corresp.}]{1-1} \nabla_X \varphi \end{array}$$

covariant derivative

different notations:

$$L_{\tilde{X}}(\hat{\varphi}) = \tilde{X}(\hat{\varphi}) = d\hat{\varphi}(\tilde{X}) = D\hat{\varphi}(\tilde{X}) = d\hat{\varphi}(h\tilde{X})$$

note:

$$d\pi \circ d\pi_g(\tilde{X}(u)) = \tilde{X}(u_g) \quad \& \quad d\pi \circ d\pi_g = d\pi$$

Lemma $\tilde{X}(\hat{\varphi}) \in \text{Maps}_G(P, V)$ (ie $\tilde{X}(\hat{\varphi})$ is equivariant)

proof see notes

3. If $\varphi \in T'_M(P \times_G V)$ and X is a vector field on M , we define $\nabla_X \varphi$ to be the element of $T'_M(P \times_G M) \ni (\nabla_X \varphi)(x) = (u_x, \tilde{X}(\hat{\varphi})(u_x)) \cdot G$ $u_x \in \pi^{-1}(x)$
 (well defined b/c equivar.)
 $= (u_x, D\hat{\varphi}(\tilde{X}(u_x))) \cdot G$

Let $\{V_a\}$ be a basis for V , $\{e_\alpha\}$ a basis for $\mathfrak{g}$, and $\Delta: U \rightarrow P$ a local section of π ,

Define:

$$W_a(x) = (\Delta(x), V_a) \cdot G$$

$$\begin{aligned} \varphi(x) &= (\Delta(x), \hat{\varphi}(\Delta(x))) \cdot G = (\Delta(x), \hat{\varphi}^a(\Delta(x)) V_a) \cdot G \\ &= \hat{\varphi}^a(\Delta(x)) (\Delta(x), V_a) \cdot G = \hat{\varphi}^a(\Delta(x)) W_a(x) \end{aligned}$$

$$\therefore \varphi^a(x) = \hat{\varphi}^a(\Delta(x)) \text{ where } \varphi^a(x) W_a(x) = \varphi(x), \hat{\varphi}^a(\Delta(x)) V_a = \hat{\varphi}(\Delta(x))$$

$$\Rightarrow \boxed{\varphi^a = \hat{\varphi}^a \circ \Delta}$$

Claim: If $(\nabla_X \varphi)(x) = (\nabla_X \varphi)^a(x) W_a(x)$, then

$$\begin{aligned} (\nabla_X \varphi)^a(x) &= d\varphi^a(X_x) + h_{ac}^a A^c(X_x) \varphi^c(x), \quad A = \Delta^* \omega \\ e_\alpha \cdot V_a &= h_{\alpha a}^b V_b \end{aligned}$$

$$(\nabla_{\partial_\mu} \varphi)^a(x) = (\partial_\mu \varphi^a)(x) + h_{\alpha c}^a A_{\mu}^{\alpha}(x) \varphi^c(x) \text{ where } A^{\alpha} = A_{\mu}^{\alpha} dx^{\mu} \\ A = A^{\alpha} e_{\alpha}$$

$$(\nabla_{\tilde{X}} \varphi)(x) = (\Delta(x), d\hat{\varphi}(\tilde{X}(\Delta(x)))) \cdot G = (\Delta(x), d\hat{\varphi}^a(\tilde{X}(\Delta(x))) v_a) G$$

$$= d\hat{\varphi}^a(\tilde{X}(\Delta(x))) (\Delta(x), v_a) \cdot G = d\hat{\varphi}^a(\tilde{X}(\Delta(x))) W_a(x)$$

$$= d\hat{\varphi}^a(d_x \Delta(\tilde{X}_x) - \delta_{\Delta(x)}(\Delta^* \omega)(\tilde{X}_x)) W_a(x)$$

$$= d_x \hat{\varphi}^a \circ \Delta(\tilde{X}_x) - d\hat{\varphi}^a(\delta_{\Delta(x)}(\Delta^* \omega)(\tilde{X}_x)) W_a(x)$$

→
(use (*))
↪

$$= (d\varphi^a(\tilde{X}_x) + [(\Delta^* \omega)(\tilde{X}_x) \cdot \hat{\varphi}(\Delta(x))]^a) W_a(x)$$

$$(\nabla_{\tilde{X}} \varphi)(x) = (d\varphi^a(\tilde{X}_x) + [(\Delta^* \omega)(\tilde{X}_x) \cdot \varphi(x)]^a) W_a(x) \quad \dots$$

Problem #2: Uses $T^*M \cong \mathcal{F}(TM) \times (\mathbb{R}^n)^*$
 $\hookrightarrow$ identify: $\alpha_i e_i = ((p, \{e_i\}), \alpha_i n_i) \in \mathfrak{gl}(n)$

$$\begin{aligned} \nabla_{\partial_\mu} \alpha &= (d\alpha_v)(\partial_\mu) + (\Gamma_\mu \cdot \alpha)_v dx^\nu \\ &= \partial_\mu \alpha_v + \dots \end{aligned}$$

$$= (d\varphi^a(\tilde{X}_x) + [A(\tilde{X}_x) \cdot \varphi(x)]^a) W_a(x)$$

$$= (d\varphi^a(\tilde{X}_x) + (A^a(\tilde{X}_x) e_a \cdot \varphi^b(x) v_b))^a W_a(x)$$

$$= (d\varphi^a(\tilde{X}_x) + [A^a(\tilde{X}_x) \varphi^b(x) h_{ab}^c v_c]^a) W_a(x)$$

$$= (d\varphi^a(\tilde{X}_x) + \underbrace{A^a(\tilde{X}_x)}_{\text{Connection stuff}} \varphi^b(x) \underbrace{h_{ab}^a}_{\text{Lie algebra action}}) W_a(x) \quad \checkmark$$

Connection
stuff

Lie algebra action

5/3/2

Def $\varphi \in \Lambda^p(M, \mathfrak{g}), \psi \in \Lambda^q(M, \mathfrak{g})$ (ie $\varphi(X_1, \dots, X_p) \in \mathfrak{g}$ for $X_i \in T_x M$)
 Define $[\varphi, \psi] \in \Lambda^{p+q}(M, \mathfrak{g})$ by

$$[\varphi, \psi]_x(X_1, \dots, X_{p+q}) = \frac{1}{p!} \frac{1}{q!} \sum_{\sigma \in S_{p+q}} (-1)^\sigma [\varphi(X_{\sigma(1)}, \dots, X_{\sigma(p)}), \psi(X_{\sigma(p+1)}, \dots, X_{\sigma(p+q)})]$$

$$\forall x \in M \text{ \& } X_i \in T_x M$$

Aside:

$$\left. \begin{aligned} \iota_g^* \varphi &= \varphi \quad \checkmark \text{ vertical} \\ \varphi(\dots, v, \dots) &= 0 \end{aligned} \right\} \text{ Tensorial form}$$

$$\omega(\delta_A) = A \leftarrow \text{Pseudo-Tensorial}$$

Note: ω_1, ω_2 connections $\Rightarrow \omega_1 - \omega_2$ is tensorial

$\mathcal{C} = \{\text{connections}\}$ is an affine space

$$\mathcal{C} = \omega_0 + \{\text{Tensorial Stuff}\}$$

$$[\omega, \omega](X, Y) = \frac{1}{1!} \frac{1}{1!} ([\omega(X), \omega(Y)] - [\omega(Y), \omega(X)])$$

$$\Rightarrow [\omega, \omega](X, Y) = 2[\omega(X), \omega(Y)]$$

Def ω is a connection on a P.F.B. $P \xrightarrow{\pi} M$ w/t group G ,

then the curvature of ω is $\Omega = D\omega$

$$(D\omega)(X, Y) = d\omega(hX, hY)$$

$\uparrow$ Exterior Covariant Derivative

Thm $\Omega = D\omega = d\omega + \frac{1}{2}[\omega, \omega]$

proof

Lemma $[\delta_A, \tilde{X}] = 0$

$$[\delta_A, \tilde{X}]_u = (L_{\delta_A} \tilde{X})_u = \frac{d}{dt} [d_u \varphi_t(\tilde{X}_{\varphi_t(u)})] \Big|_{t=0}$$

where φ is the flow of δ_A

$$\text{now use } d\eta_g(\tilde{X}) = \tilde{X}_u g$$

$$\begin{aligned}
 \varphi_t(u) &= \mathcal{L}_{\exp(tA)}(u) \Rightarrow d_u \varphi_{-t} = d_u \mathcal{L}_{\exp(tA)} \\
 \Rightarrow \frac{d}{dt} [d_u \varphi_{-t}(\tilde{X}_{\varphi_t(u)})] \Big|_{t=0} &= \frac{d}{dt} [d_u \mathcal{L}_{\exp(-tA)} \tilde{X}_{\varphi_t(u)}] \Big|_{t=0} \\
 &= \frac{d}{dt} [\tilde{X}_{\varphi_t(u) \circ \exp(-tA)}] \Big|_{t=0} = \frac{d}{dt} [\tilde{X}_{\varphi_{-t} \circ \varphi_t(u)}] \Big|_{t=0} = \frac{d}{dt} [\tilde{X}_u] \Big|_{t=0} \xrightarrow{0} 0
 \end{aligned}$$

($\varphi_{t-t}(u) = \varphi_0(u) = u$)

$$Y, Z \text{ horizontal. } D\omega(Y, Z) = d\omega(hY, hZ) = d\omega(Y, Z)$$

$$\begin{aligned}
 (d\omega + \frac{1}{2}[\omega, \omega])(Y, Z) &= d\omega(Y, Z) + \frac{1}{2}[\omega, \omega](Y, Z) \\
 &= d\omega(Y, Z) + [\omega(Y), \omega(Z)] \xrightarrow{0} 0
 \end{aligned}$$

$$Y = \delta_A, Z = \delta_B \text{ where } Y, Z \text{ vertical}$$

$$D\omega(\delta_A, \delta_B) = d\omega(h\delta_A, h\delta_B) \xrightarrow{0} 0$$

$$d\omega(\delta_A, \delta_B) + \frac{1}{2}[\omega, \omega](\delta_A, \delta_B) = d\omega(\delta_A, \delta_B) + [\omega\delta_A, \omega\delta_B]$$

$$= \delta_A \omega(\delta_B) - \delta_B \omega(\delta_A) - \omega([\delta_A, \delta_B]) + [A, B]$$

$$\begin{aligned}
 &= \delta_A \omega(\delta_B) - \delta_B \omega(\delta_A) - \omega \delta_{[A, B]} + [A, B] \xrightarrow{\text{Lie hom. } \delta} 0 \\
 &= \delta_A \omega(\delta_B) - \delta_B \omega(\delta_A) - \omega \delta_{[A, B]} + [A, B] = -[A, B] + [A, B] = 0
 \end{aligned}$$

[vector field acting on constants] $\Rightarrow$ Curvature kills vertical vectors

$$\text{Mixed Case: } Y = \delta_A, Z = \tilde{X} \text{ 1-vert. 1-horz.}$$

$$D\omega(Y, Z) = d\omega(h\delta_A, h\tilde{X}) \xrightarrow{0} 0$$

$$\begin{aligned}
 d\omega(\delta_A, \tilde{X}) + \frac{1}{2}[\omega, \omega](\delta_A, \tilde{X}) &= d\omega(\delta_A, \tilde{X}) + [\omega\delta_A, \omega\tilde{X}] \xrightarrow{0} 0 \\
 &= \delta_A(\omega(\tilde{X})) - \tilde{X}(\omega\delta_A) - \omega([\delta_A, \tilde{X}]) \xrightarrow{\text{Const}} 0 \checkmark
 \end{aligned}$$

$$\Omega = d\omega + \frac{1}{2}[\omega, \omega]$$

$$(\Delta^* \Omega)(X, Y) = \Omega(ds(X), ds(Y)) =$$

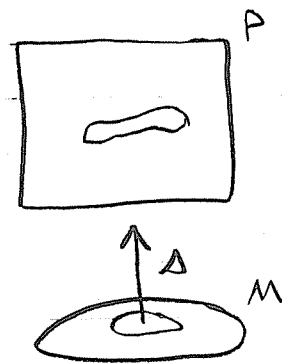
$$d\omega(ds(X), ds(Y)) + [\omega(ds(X)), \omega(ds(Y))]$$

$$= \Delta^*(d\omega)(X, Y) + [(\Delta^*\omega)(X), (\Delta^*\omega)(Y)]$$

$$= d(\Delta^*\omega)(X, Y) + [(\Delta^*\omega)(X), (\Delta^*\omega)(Y)]$$

We call $\Delta^*\omega = A$ thus

$$= dA(X, Y) + [A(X), A(Y)]$$



Also call $F = \Delta^* \Omega$ then $F = dA + \frac{1}{2}[A, A]$

now use $\partial_\mu = X, \partial_\nu = Y$:

$$F(\partial_\mu, \partial_\nu) = dA(\partial_\mu, \partial_\nu) + [A(\partial_\mu), A(\partial_\nu)]$$

write:

$$F_{\mu\nu} = \partial_\mu(A\partial_\nu) - \partial_\nu(A\partial_\mu) - A[\partial_\mu, \partial_\nu] + [A\partial_\mu, A\partial_\nu]$$

$$= \partial_\mu A_\nu - \partial_\nu A_\mu + [A_\mu, A_\nu]$$

Lie algebra valued function
 $F_{\mu\nu}: M \rightarrow \mathfrak{g}$

$\S A_\mu^a e_a$ where e_a is a basis of $\mathfrak{g}$

then

$$F_{\mu\nu} = (\partial_\mu A_\nu^a) e_a - (\partial_\nu A_\mu^a) e_a + A_\mu^a A_\nu^b [e_a, e_b]$$

$$\Rightarrow \text{If } [e_a, e_b] = f_{ab}^c e_c$$

$$\therefore F_{\mu\nu}^c = \partial_\mu A_\nu^c - \partial_\nu A_\mu^c + A_\mu^a A_\nu^b f_{ab}^c$$

$$P = \mathbb{F}(TM) \quad G = \mathcal{GL}(n) \quad \mathfrak{g} = \mathfrak{gl}(n)$$

$$\text{then } F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu + [A_\mu, A_\nu]$$

$$\downarrow^k \quad R_{\mu\nu\lambda}^k = (F_{\mu\nu})_\lambda^k = \partial_\mu A_{\nu\lambda}^k - \partial_\nu A_{\mu\lambda}^k + [A_\mu, A_\nu]_\lambda^k$$

$$A_\nu = \Gamma_\nu^k \Rightarrow R_{\mu\nu\lambda}^k = \partial_\mu \Gamma_{\nu\lambda}^k - \partial_\nu \Gamma_{\mu\lambda}^k + \Gamma_{\mu\lambda}^a \Gamma_{\nu a}^k - \Gamma_{\nu\lambda}^a \Gamma_{\mu a}^k$$

Like Riemannian Curvature ✓
(is R-Curvature if $\Gamma_{\nu\lambda}^k$ are Christoffel Symbols)