

Ex 1.1: $\mu \in \wedge^n V^* \Rightarrow \mu_{i_1, \dots, i_n} e^{i_1} \wedge \dots \wedge e^{i_n}$ (but if we are choosing n strictly inc. indices from n integers they must be $i_1=1, \dots, i_n=n. \Rightarrow \mu = c e^1 \wedge \dots \wedge e^n$)

$$\mu(e_1, \dots, e_n) = 1 \text{ \& } e^1 \wedge \dots \wedge e^n(e_1, \dots, e_n) =$$

$$\left(\frac{1}{n!} \sum_{\sigma \in S_n} (-1)^\sigma e^{\sigma(1)} \otimes \dots \otimes e^{\sigma(n)} \right)(e_1, \dots, e_n) =$$

$$\frac{1}{n!} \sum_{\sigma \in S_n} (-1)^\sigma e^{\sigma(1)}(e_1) \dots e^{\sigma(n)}(e_n) = \frac{1}{n!} \sum_{\sigma \in S_n} (-1)^\sigma \delta_1^{\sigma(1)} \dots \delta_n^{\sigma(n)}$$

the only non-zero term would be where $\sigma(1)=1, \dots, \sigma(n)=n$ (ie $\sigma=1$) $\therefore e^1 \wedge \dots \wedge e^n(e_1, \dots, e_n) = \frac{1}{n!} \Rightarrow c = n!$

$$\therefore \mu = n! e^1 \wedge \dots \wedge e^n$$

$$\text{by definition } e^1 \wedge \dots \wedge e^n = \left(\frac{1}{n!} \sum_{\sigma \in S_n} (-1)^\sigma e^{\sigma(1)} \otimes \dots \otimes e^{\sigma(n)} \right)$$

$$= \frac{1}{n!} \sum_{\sigma \in S_n} \epsilon_{\sigma(1) \dots \sigma(n)} e^{\sigma(1)} \otimes \dots \otimes e^{\sigma(n)} = \frac{1}{n!} \sum_{i_1, \dots, i_n} \epsilon_{i_1 \dots i_n} e^{i_1} \otimes \dots \otimes e^{i_n}$$

(because if $i_1, \dots, i_n$ is not a permutation $\Rightarrow i_s = i_t$ some $s \neq t$ but this means $\epsilon_{i_1 \dots i_n} = 0 \checkmark$)

$$\therefore \mu = n! e^1 \wedge \dots \wedge e^n = n! \frac{1}{n!} \epsilon_{i_1 \dots i_n} e^{i_1} \otimes \dots \otimes e^{i_n}$$

$$= \epsilon_{i_1 \dots i_n} e^{i_1} \wedge \dots \wedge e^{i_n} \text{ (as in notes)}$$

my error!
the $\frac{1}{n!}$ should not be part of definition of $e^1 \wedge \dots \wedge e^n$

OK

Ex 1.2: $\tilde{g}: \Lambda^p V^* \times \Lambda^p V^* \rightarrow \mathbb{R}$ defined by $\tilde{g}(\alpha, \beta) = \frac{1}{p!} \alpha^{i_1 \dots i_p} \beta_{i_1 \dots i_p}$
 where $\alpha = \alpha_{i_1 \dots i_p} e^{i_1} \wedge \dots \wedge e^{i_p}$ and $\beta = \beta_{i_1 \dots i_p} e^{i_1} \wedge \dots \wedge e^{i_p} \in \Lambda^p V^*$

• $\forall c \in \mathbb{R}$ and $\gamma = \gamma_{i_1 \dots i_p} e^{i_1} \wedge \dots \wedge e^{i_p} \in \Lambda^p V^*$ then

$$\begin{aligned} \tilde{g}(\alpha, c\beta + \gamma) &= \frac{1}{p!} \alpha^{i_1 \dots i_p} (c\beta_{i_1 \dots i_p} + \gamma_{i_1 \dots i_p}) = \\ &= \frac{1}{p!} \alpha^{i_1 \dots i_p} (c\beta_{i_1 \dots i_p}) + \frac{1}{p!} \alpha^{i_1 \dots i_p} \gamma_{i_1 \dots i_p} = c\tilde{g}(\alpha, \beta) + \tilde{g}(\alpha, \gamma) \end{aligned}$$

$$\begin{aligned} \tilde{g}(\alpha, \beta) &= \frac{1}{p!} \alpha^{i_1 \dots i_p} \beta_{i_1 \dots i_p} = \frac{1}{p!} \alpha^{i_1 \dots i_p} \beta^{j_1 \dots j_p} g_{i_1 j_1} \dots g_{i_p j_p} \\ &= \frac{1}{p!} \alpha_{k_1 \dots k_p} g^{i_1 k_1} \dots g^{i_p k_p} \beta^{j_1 \dots j_p} g_{i_1 j_1} \dots g_{i_p j_p} \\ &= \frac{1}{p!} \beta^{j_1 \dots j_p} \alpha_{k_1 \dots k_p} (g^{i_1 k_1} g_{i_1 j_1}) \dots (g^{i_p k_p} g_{i_p j_p}) \\ &= \frac{1}{p!} \beta^{j_1 \dots j_p} \alpha_{k_1 \dots k_p} \delta_{j_1}^{k_1} \dots \delta_{j_p}^{k_p} = \frac{1}{p!} \beta^{j_1 \dots j_p} \alpha_{j_1 \dots j_p} = \tilde{g}(\beta, \alpha) \end{aligned}$$

$\Rightarrow \tilde{g}$ is symmetric & bilinear

$\forall \tilde{g}(\alpha, \beta) = 0 \forall \beta \in \Lambda^p V^*$ choose $j_1, \dots, j_p \in \{1, \dots, n\}$

let $\beta = \delta_{i_1}^{j_1} \dots \delta_{i_p}^{j_p} e^{i_1} \wedge \dots \wedge e^{i_p} (\in \Lambda^p V^*)$ then

these are not shown in $i_1, i_2, \dots, i_p$ ~~in the definition~~

$$\tilde{g}(\alpha, \beta) = \frac{1}{p!} \alpha^{i_1 \dots i_p} \delta_{i_1}^{j_1} \dots \delta_{i_p}^{j_p} = \frac{1}{p!} \alpha^{j_1 \dots j_p} = 0 \Rightarrow \alpha^{j_1 \dots j_p} = 0 \Rightarrow \alpha = 0$$

hence $\tilde{g}$ is non-degenerate.

need a little extra work here!

$\therefore \tilde{g}$ is a metric ✓

Ex 1.3: $\nexists \alpha \in \wedge^p V^*$ and $\alpha \wedge \gamma = 0 \forall \gamma \in \wedge^{n-p} V^*$
 where $\dim(V) = n$. let $\{e_i\}$ be a basis for V

Write $\alpha_{i_1, \dots, i_p} e^{i_1} \wedge \dots \wedge e^{i_p}$. Let $k_1 < \dots < k_p$ be indices ($1 \leq k_i \leq n$)
 let $j_1 < \dots < j_{n-p}$ be the remaining $n-p$ integers between 1 and n . (ie $\{k_1, \dots, k_p\} \cup \{j_1, \dots, j_{n-p}\} = \{1, \dots, n\}$)

Now $e^{j_1} \wedge \dots \wedge e^{j_{n-p}} \in \wedge^{n-p} V^* \therefore \alpha \wedge (e^{j_1} \wedge \dots \wedge e^{j_{n-p}}) = 0$
 but $(e^{i_1} \wedge \dots \wedge e^{i_p}) \wedge (e^{j_1} \wedge \dots \wedge e^{j_{n-p}}) = 0$ if $i_s = j_t$ some s, t
 $\therefore (e^{i_1} \wedge \dots \wedge e^{i_p}) \wedge (e^{j_1} \wedge \dots \wedge e^{j_{n-p}}) \neq 0$ if $i_s \neq j_t \forall s, t$
 if we also requires $i_1 < \dots < i_p$ this forces $i_1 = k_1, \dots, i_p = k_p$

$$\Rightarrow \alpha_{i_1, \dots, i_p} e^{i_1} \wedge \dots \wedge e^{i_p} \wedge e^{j_1} \wedge \dots \wedge e^{j_{n-p}} = \alpha_{k_1, \dots, k_p} e^{k_1} \wedge \dots \wedge e^{k_p} \wedge e^{j_1} \wedge \dots \wedge e^{j_{n-p}}$$

Now, $e^{k_1} \wedge \dots \wedge e^{k_p} \wedge e^{j_1} \wedge \dots \wedge e^{j_{n-p}} \neq 0$ since k_s, j_t 's are all distinct hence $\alpha \wedge (e^{j_1} \wedge \dots \wedge e^{j_{n-p}}) = 0 \Rightarrow \alpha_{k_1, \dots, k_p} = 0$
 but the $k_1 < \dots < k_p$ were arbitrary (set of inc. indices)
 $\Rightarrow \alpha = 0 //$

Exercise 1.1

Let $\mu = \mu_g$ be induced by a metric g and let $\{e_i\}$ be a g -orthonormal basis such that $\mu(e_1, e_2, \dots, e_n) = 1$. Show that

$$\mu = e^1 \wedge e^2 \wedge \dots \wedge e^n = \left(\frac{1}{n!}\right) \sum_{i_1, \dots, i_n} \epsilon_{i_1, \dots, i_n} (e^{i_1} \wedge \dots \wedge e^{i_n})$$

where

$$\epsilon_{i_1, \dots, i_n} = \begin{cases} 1 & \text{if } i \text{ is even permutation} \\ 0 & \text{if } i_k = i_l \text{ for } k \neq l \\ -1 & \text{if } i \text{ is odd permutation} \end{cases}$$

Exercise 1.2 Show that the natural:

bilinear mapping $\tilde{g}: \wedge^p V^* \times \wedge^p V^* \rightarrow \mathbb{R}$ induced by a metric g on a finite dimensional vector space V is itself a metric.

$$\tilde{g}(\alpha, \beta) \equiv \frac{1}{p!} \alpha^{i_1 i_2 \dots i_p} \beta_{i_1 i_2 \dots i_p}$$

Exercise 1.3 If $\alpha \in \wedge^p V^*$ and $\alpha \wedge \gamma = 0$

for every $\gamma \in \wedge^{n-p} V^*$ where $n = \dim V$, then show that $\alpha = 0$.

Exercise 1.4 Let x, y, z be coordinates on all $\mathbb{R}^3$ and $x = x^1, y = x^2$, and $z = x^3$. for ∂_{x^i} write ∂_i . Let $\mathbf{X}$ be a vector field with $\mathbf{X} = X^i \partial_i$

(1) Let $\omega_{\mathbf{X}} = X^1 dx + X^2 dy + X^3 dz$ then

$$d\omega_{\mathbf{X}} = d(X^1 dx) + d(X^2 dy) + d(X^3 dz) \quad (d \text{ is linear})$$

$$= \partial_1 X^1 dx \wedge dx + \partial_2 X^1 dy \wedge dx + \partial_3 X^1 dz \wedge dx + \partial_1 X^2 dx \wedge dy + \partial_2 X^2 dy \wedge dy + \partial_3 X^2 dz \wedge dy + \partial_1 X^3 dx \wedge dz + \partial_2 X^3 dy \wedge dz + \partial_3 X^3 dz \wedge dz$$

now we use:
 $dx^i \wedge dx^i = -dx^i \wedge dx^i = 0$

$$= (\partial_2 X^3 - \partial_3 X^2) dy \wedge dz + (\partial_3 X^1 - \partial_1 X^3) dz \wedge dx + (\partial_1 X^2 - \partial_2 X^1) dx \wedge dy$$

$$= (\text{Curl } \mathbf{X})^1 dy \wedge dz + (\text{Curl } \mathbf{X})^2 dz \wedge dx + (\text{Curl } \mathbf{X})^3 dx \wedge dy$$

(2) Let $\tau_{\mathbf{X}} = X^1 dy \wedge dz + X^2 dz \wedge dx + X^3 dx \wedge dy$ then

$$d\tau_{\mathbf{X}} = d(X^1 dy \wedge dz) + d(X^2 dz \wedge dx) + d(X^3 dx \wedge dy)$$

$$= \partial_1 X^1 dx \wedge dy \wedge dz + \partial_2 X^1 dy \wedge dz \wedge dx + \partial_3 X^1 dz \wedge dx \wedge dy + \partial_1 X^2 dx \wedge dz \wedge dx + \partial_2 X^2 dy \wedge dz \wedge dx + \partial_3 X^2 dz \wedge dx \wedge dx + \partial_1 X^3 dx \wedge dx \wedge dy + \partial_2 X^3 dy \wedge dx \wedge dy + \partial_3 X^3 dz \wedge dx \wedge dy$$

$$= \partial_1 X^1 dx \wedge dy \wedge dz + \partial_2 X^1 dy \wedge dz \wedge dx + \partial_3 X^1 dz \wedge dx \wedge dy + \partial_1 X^2 dx \wedge dx \wedge dy + \partial_2 X^2 dy \wedge dx \wedge dy + \partial_3 X^2 dz \wedge dx \wedge dy + \partial_1 X^3 dx \wedge dx \wedge dy + \partial_2 X^3 dy \wedge dx \wedge dy + \partial_3 X^3 dz \wedge dx \wedge dy$$

$(-1)^2 = 1 \checkmark \quad (-1)^2 = 1 \checkmark$

$$= (\partial_1 X^1 + \partial_2 X^2 + \partial_3 X^3) dx \wedge dy \wedge dz = (\text{Div } \mathbf{X}) dx \wedge dy \wedge dz$$

(3) Define a metric g by $g(\partial_i, \partial_j) = \delta_{ij}$

(a) $\hat{g}(dx^i, dx^j) = \hat{g}(\delta_a^i dx^a, \delta_b^j dx^b) = \frac{1}{1!} (g^{ak} \delta_k^i) \cdot \delta_a^j$

but $g_{ij} = \delta_{ij}$ hence $g^{ij} = \delta^{ij}$

$$\hat{g}(dx^i, dx^j) = \delta^{ak} \delta_k^i \delta_a^j = \delta_a^i \delta_a^j = \delta^{ij} \checkmark$$

(b) $g^b(\mathbf{X})(\partial_j) = g(X^i \partial_i, \partial_j) = X^i g(\partial_i, \partial_j) = X^i \delta_{ij} = X^j$

$$\Rightarrow g^b(\mathbf{X}) = X^1 dx^1 + X^2 dx^2 + X^3 dx^3 \quad (= \omega_{\mathbf{X}})$$

(3) (b) continued...

$$\text{Curl } \mathbf{X} = (\partial_2 X^3 - \partial_3 X^2) \partial_1 + (\partial_3 X^1 - \partial_1 X^3) \partial_2 + (\partial_1 X^2 - \partial_2 X^1) \partial_3$$

hence $g^b(\text{Curl } \mathbf{X}) = (\text{Curl } \mathbf{X})^1 dx^1 + (\text{Curl } \mathbf{X})^2 dx^2 + (\text{Curl } \mathbf{X})^3 dx^3$

$$\Rightarrow *g^b(\text{Curl } \mathbf{X}) = \sqrt{|\det I|} \sum_{j < k} \sum_{i, l} (\text{Curl } \mathbf{X})^i g^{il} \epsilon_{ijk} dx^j \wedge dx^k$$

note: $I = (g_{ij}) = (\delta_{ij})$ hence $\sqrt{|\det I|} = \sqrt{1} = 1$ and $(\text{Curl } \mathbf{X})^i g^{il} = (\text{Curl } \mathbf{X})^i \delta^{il}$

$$*g^b(\text{Curl } \mathbf{X}) = \sum_{j < k} \sum_i (\text{Curl } \mathbf{X})^i \epsilon_{ijk} dx^j \wedge dx^k$$

We need i, j, k distinct for $\epsilon_{ijk} \neq 0$ but $j < k \therefore$ we have

$$\begin{aligned} &= (\text{Curl } \mathbf{X})^1 \epsilon_{123}^{-1} dx^2 \wedge dx^3 + (\text{Curl } \mathbf{X})^2 \epsilon_{213}^{-1} dx^1 \wedge dx^3 \\ &\quad + (\text{Curl } \mathbf{X})^3 \epsilon_{312}^{-1} dx^1 \wedge dx^2 \quad \text{use } -dx^1 \wedge dx^3 = dx^3 \wedge dx^1 \\ &= (\text{Curl } \mathbf{X})^1 dx^2 \wedge dx^3 + (\text{Curl } \mathbf{X})^2 dx^3 \wedge dx^1 + (\text{Curl } \mathbf{X})^3 dx^1 \wedge dx^2 \\ &= d(\omega_{\mathbf{X}}) = d(g^b \mathbf{X}) \checkmark \end{aligned}$$

$$\begin{aligned} \text{(c)} * \omega_{\mathbf{X}} &= \sqrt{|\det I|} \sum_{j < k} \sum_{i, l} X^i \delta^{il} \epsilon_{ijk} dx^j \wedge dx^k \quad (\text{as before}) \\ &= X^1 dx^2 \wedge dx^3 + X^2 dx^3 \wedge dx^1 + X^3 dx^1 \wedge dx^2 = \tau_{\mathbf{X}} \end{aligned}$$

and $d\tau_{\mathbf{X}} = (\text{Div } \mathbf{X}) dx^1 \wedge dx^2 \wedge dx^3$

$$\Rightarrow d(*g^b(\mathbf{X})) = (\text{Div } \mathbf{X}) dx^1 \wedge dx^2 \wedge dx^3$$

$$\begin{aligned} *(\text{Div } \mathbf{X}) &= \sqrt{|\det I|} \sum_{i < j < k} (\text{Div } \mathbf{X}) \epsilon_{ijk} dx^i \wedge dx^j \wedge dx^k \\ &= (\text{Div } \mathbf{X}) \epsilon_{123} dx^1 \wedge dx^2 \wedge dx^3 \\ &= (\text{Div } \mathbf{X}) dx^1 \wedge dx^2 \wedge dx^3 = d(*g^b(\mathbf{X})) \checkmark \end{aligned}$$

Exercise 4

Let X be a vector field on $\mathbb{R}^3$,

$$X = X^1 \frac{\partial}{\partial x} + X^2 \frac{\partial}{\partial y} + X^3 \frac{\partial}{\partial z}.$$

(1) Show that if

$$\omega_X = X^1 dx + X^2 dy + X^3 dz$$

then

$$d\omega_X = (\text{Curl } X)^1 (dy \wedge dz) + (\text{Curl } X)^2 (dz \wedge dx) + (\text{Curl } X)^3 (dx \wedge dy)$$

(2) Show that if

$$\tau_X = X^1 (dy \wedge dz) + X^2 (dz \wedge dx) + X^3 (dx \wedge dy)$$

then

$$d\tau_X = (\text{Div } X) (dx \wedge dy \wedge dz)$$

(3) Let $x^1 = x, x^2 = y, x^3 = z$ and define a metric g by

$$g\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) = \delta_{ij}$$

(a) Show that

$$\hat{g}(dx^i, dx^j) = \delta^{ij}$$

(b) Show that

$$g^b(X) = X^1 dx^1 + X^2 dx^2 + X^3 dx^3$$

and that

$$d(g^b(X)) = *(g^b(\text{Curl } X))$$

$$(c) \quad d(*(g^b(X))) = *(\text{Div } X)$$

Exercise 1.5: Let M be a manifold with $\dim(M) = n$, a metric g , and a metric compatible volume μ_g .

$$(1) \delta\Delta - \Delta\delta = \delta(d\delta + \delta d) - (d\delta + \delta d)\delta = \delta d\delta + \delta^2 d - d\delta^2 - \delta d\delta = \delta d\delta - \delta d\delta = 0$$

$$\therefore \delta\Delta = \Delta\delta$$

$$(2) d\Delta - \Delta d = d(d\delta + \delta d) - (d\delta + \delta d)d = d^2\delta + d\delta d - d\delta d - \delta d^2 = d\delta d - d\delta d = 0$$

$$\therefore d\Delta = \Delta d$$

(3) First, let $\alpha \in \Sigma^k M$ and $\beta \in \Sigma^{k+1} M$ then

$$\tilde{g}(d\alpha, \beta)\mu_g = \tilde{g}(\alpha, \delta\beta)\mu_g + d(\alpha \wedge \beta)$$

$$\therefore \hat{g}(d\alpha, \beta) = \int_M \tilde{g}(d\alpha, \beta)\mu_g = \int_M \tilde{g}(\alpha, \delta\beta)\mu_g + \int_M d(\alpha \wedge \beta)$$

$$= \int_M \tilde{g}(\alpha, \delta\beta)\mu_g + 0 \text{ (Baby Stokes's Thm)} = \hat{g}(\alpha, \delta\beta)$$

$\hookrightarrow d$ & δ are adjoint.

$$\therefore \text{Let } \alpha, \beta \in \Sigma^k M \text{ then } \hat{g}(\Delta\alpha, \beta) = \hat{g}(d\delta + \delta d)(\alpha), \beta)$$

$$= \hat{g}(d(\delta\alpha), \beta) + \hat{g}(\delta(d\alpha), \beta) = \hat{g}(\delta\alpha, \delta\beta) + \hat{g}(d\alpha, d\beta)$$

$$= \hat{g}(\alpha, d\delta\beta) + \hat{g}(\alpha, \delta d\beta) = \hat{g}(\alpha, (d\delta + \delta d)(\beta))$$

$$= \hat{g}(\alpha, \Delta\beta) \therefore \boxed{\hat{g}(\Delta\alpha, \beta) = \hat{g}(\alpha, \Delta\beta)}$$

$\hookrightarrow \Delta$ is self-adjoint.

$$\text{also we have } \hat{g}(\Delta\alpha, \beta) = \hat{g}(\delta\alpha, \delta\beta) + \hat{g}(d\alpha, d\beta)$$

$\hat{g}$ is positive-definite $\therefore \forall p \in M \exists$ a chart $(U, \varphi = (x^i))$

$$\text{about } p \ni g_{ij} = \delta_{ij} \Rightarrow \tilde{g}(\alpha, \alpha) = \frac{1}{k!} \alpha^{i_1 \dots i_k} \alpha_{i_1 \dots i_k}$$

$$= \frac{1}{k!} g^{i_1 j_1} \dots g^{i_k j_k} \alpha_{j_1 \dots j_k} \alpha_{i_1 \dots i_k} = \frac{1}{k!} \delta^{i_1 j_1} \dots \delta^{i_k j_k} \alpha_{j_1 \dots j_k} \alpha_{i_1 \dots i_k}$$

$$= \sum_{i_1, \dots, i_k} \frac{1}{k!} \alpha_{i_1 \dots i_k} \alpha_{i_1 \dots i_k} = \frac{1}{k!} \sum_{i_1, \dots, i_k} (\alpha_{i_1 \dots i_k})^2 \geq 0$$

(equal only if $\alpha = 0$) $\Rightarrow \tilde{g}$ is pos. def. $\Rightarrow \hat{g}$ is pos. def.

$$\therefore \hat{g}(\Delta\alpha, \alpha) = \hat{g}(\delta\alpha, \delta\alpha) + \hat{g}(d\alpha, d\alpha) \geq 0 \checkmark$$

definitely
need $\tilde{g}$
pos. def.

Exercise 1.6: Let (x^i) be the standard coordinates on $\mathbb{R}^3$
 also let $\mathbb{R}^3$ have the standard Euclidean metric ($g_{ij} = \delta_{ij}$)
 Let $\omega = \omega_i dx^i$ be a 1-form on $\mathbb{R}^3$

$$\delta\omega = \frac{(-1)^{0+1}}{1! |\det I|^{\frac{1}{2}}} \partial_j (|\det I|^{\frac{1}{2}} \delta^{ij} \omega_i) = - \sum_{j=1}^3 \partial_j (\omega_j)$$

$$\therefore d\delta\omega = - \sum_{j=1}^3 d(\partial_j (\omega_j)) = - \sum_{i,j=1}^3 \partial_i \partial_j (\omega_j) dx^i$$

$$d\omega = (\text{Curl}(\vec{\omega}))^1 dx^2 \wedge dx^3 + (\text{Curl}(\vec{\omega}))^2 dx^3 \wedge dx^1 + (\text{Curl}(\vec{\omega}))^3 dx^1 \wedge dx^2$$

where $\vec{\omega} = \sum_{i=1}^3 \omega_i \partial_i$ (using prev. homework problem)

$$= \frac{1}{2!} \epsilon_{ijk} (\text{Curl}(\vec{\omega}))^i dx^j \wedge dx^k$$

$$\Rightarrow (d\omega)_{jk} = \epsilon_{ijk} (\text{Curl}(\vec{\omega}))^i$$

$$(\delta d\omega)^i = \frac{(-1)^{1+1}}{1! |\det I|^{\frac{1}{2}}} \partial_j (|\det I|^{\frac{1}{2}} \delta^{ik} \delta^{jl} (d\omega)_{kl}) = \sum_{j=1}^3 \partial_j ((d\omega)_{ij})$$

$$\Rightarrow \delta d\omega = \sum_{i,j,k=1}^3 \epsilon_{kij} \partial_j ((\text{Curl}(\vec{\omega}))^k) dx^i$$

$$(\Delta\omega)_1 = (d\delta\omega)_1 + (\delta d\omega)_1 = [-\partial_1 \partial_1 \omega_1 - \partial_1 \partial_2 \omega_2 - \partial_1 \partial_3 \omega_3] + [\epsilon_{213} \partial_3 ((\text{Curl}(\vec{\omega}))^2) + \epsilon_{312} \partial_2 ((\text{Curl}(\vec{\omega}))^3)]$$

$$= -\partial_1 \partial_1 \omega_1 - \cancel{\partial_1 \partial_2 \omega_2} - \cancel{\partial_1 \partial_3 \omega_3} - \partial_3 \partial_3 \omega_1 + \cancel{\partial_3 \partial_1 \omega_3} + \cancel{\partial_2 \partial_1 \omega_2} - \partial_2 \partial_2 \omega_1$$

$$(\Delta\omega)_2 = (d\delta\omega)_2 + (\delta d\omega)_2 = [-\partial_2 \partial_1 \omega_1 - \partial_2 \partial_2 \omega_2 - \partial_2 \partial_3 \omega_3] + [\epsilon_{123} \partial_3 ((\text{Curl}(\vec{\omega}))^1) + \epsilon_{321} \partial_1 ((\text{Curl}(\vec{\omega}))^3)]$$

$$= -\cancel{\partial_2 \partial_1 \omega_1} - \partial_2 \partial_2 \omega_2 - \cancel{\partial_2 \partial_3 \omega_3} + \cancel{\partial_3 \partial_2 \omega_3} - \partial_3 \partial_3 \omega_2 - \partial_1 \partial_1 \omega_2 + \cancel{\partial_1 \partial_2 \omega_1}$$

(next page $\rightarrow$)

$$(\Delta\omega)_3 = (d\delta\omega)_3 + (\delta d\omega)_3 = [-\partial_3\partial_1\omega_1 - \partial_3\partial_2\omega_2 - \partial_3\partial_3\omega_3] \\ + [\epsilon_{132}\partial_2((\text{curl}(\vec{\omega}))^1) + \epsilon_{231}\partial_1((\text{curl}(\vec{\omega}))^2)]$$

$$= -\cancel{\partial_3\partial_1\omega_1} - \cancel{\partial_3\partial_2\omega_2} - \partial_3\partial_3\omega_3 - \partial_2\partial_2\omega_3 + \cancel{\partial_2\partial_3\omega_2} + \cancel{\partial_1\partial_3\omega_1} - \partial_1\partial_1\omega_3$$

$$\Rightarrow (\Delta\omega)_i = -\sum_{j=1}^3 \partial_j \partial_j (\omega_i) \quad \therefore \Delta\omega = -\sum_{i,j=1}^3 \frac{\partial^2 \omega_j}{(\partial x^i)^2} dx^i //$$

Extra Credit: $\ast\Delta = \Delta\ast$

note: $\ast\ast = (-1)^{p(n-p)+s+1} \equiv (-1)^k$ (or $\ast\ast(-1)^k = 1$) (sign?)

$$\ast\Delta = \ast(\delta d + d\delta) = \ast\delta d + \ast d\delta = \ast\ast d\ast d + \ast d\ast d\ast$$

$$= (-1)^k d\ast d [(-1)^k \ast\ast] + \delta d\ast = (-1)^{2k+1} d(\ast d\ast)\ast + \delta d\ast$$

$$= d\delta\ast + \delta d\ast = (\delta d + d\delta)\ast = \Delta\ast //$$

Needs a little
more detail
regarding
signs

$$p \xrightarrow{d} p+1 \xrightarrow{\ast} n-p-1$$

$$(-1)^{(n-p')(p) + s + 1}$$

$$(-1)^{p(n-p) + s + 1}$$

||

$$(-1)^{(p(n-p) + s + 1)2}$$

$\ast\ast = \pm 1$
but it depends
on size of form
it's not clear
all your k 's are
the same.

Exercise 1.5 Let M be an n -dimensional manifold,
 g a metric on M and μ_g a volume compatible with g .

Show that

(1) $\delta \Delta = \Delta \delta$

(2) $d \Delta = \Delta d$

(3) if g is positive definite and $\hat{g}$ is the metric on the space $\Omega^p_0 M$ of p -forms with compact support defined by

$$\hat{g}(\alpha, \beta) = \int_M (\alpha \wedge * \beta) = \int_M \tilde{g}(\alpha, \beta) \mu_g$$

then show that $\hat{g}(\Delta \alpha, \alpha) \geq 0$ for all α .

Exercise 1.6 Let ω be a 1-form on $\mathbb{R}^3$ (with the Euclidean metric). Show that

$$\Delta \omega = - \sum_l \frac{\partial^2 \omega_l}{(\partial x^l)^2} dx^l$$

→ Extra Credit $* \Delta = \Delta *$

$$\Delta \omega = - \sum_{i,j} \frac{\partial^2 \omega_j}{(\partial x^i)^2} dx^j$$

$$= - \sum_j \Delta \omega_j dx^j$$

add $\hat{g}(\Delta \alpha, \beta) = \hat{g}(\alpha, \Delta \beta)$

Let V be a vector space equipped with metric g .
 If $L: V \rightarrow V$ is a linear bijection then we call L an isometry
 iff $g(v, w) = g(L(v), L(w)) \quad \forall v, w \in V$

Let $GL(V) = \{L: V \rightarrow V \mid L \text{ is a linear bijection}\}$

Exercise 1.7: Define $L \cdot \alpha \in \wedge^p V^* \quad \forall L \in GL(V), \alpha \in \wedge^p V^*$

by $L \cdot \alpha(v_1, \dots, v_p) = \alpha(L^{-1}(v_1), \dots, L^{-1}(v_p)) \quad \forall v_1, \dots, v_p \in V$
 (note: obviously $L \cdot \alpha \in \wedge^p V^*$ since L linear $\Rightarrow L^{-1}$ linear etc.)

$$\begin{aligned} 1) (L_1 \circ L_2) \cdot \alpha(v_1, \dots, v_p) &= \alpha((L_1 \circ L_2)^{-1}(v_1), \dots, (L_1 \circ L_2)^{-1}(v_p)) = \\ &= \alpha(L_2^{-1} \circ L_1^{-1}(v_1), \dots, L_2^{-1} \circ L_1^{-1}(v_p)) = L_2 \cdot \alpha(L_1^{-1}(v_1), \dots, L_1^{-1}(v_p)) = \\ &= L_1 \cdot (L_2 \cdot \alpha)(v_1, \dots, v_p) \quad \forall v_1, \dots, v_p \in V \text{ hence we have} \\ &\forall L_1, L_2 \in GL(V) \text{ and } \alpha \in \wedge^p V^* \quad (L_1 \circ L_2) \cdot \alpha = L_1 \cdot (L_2 \cdot \alpha) \end{aligned}$$

$$\begin{aligned} 2) \text{ Let } I_V: V \rightarrow V \text{ be the identity } (I_V \in GL(V)) \text{ then} \\ I_V \cdot \alpha(v_1, \dots, v_p) &= \alpha(I_V^{-1}(v_1), \dots, I_V^{-1}(v_p)) = \alpha(v_1, \dots, v_p) \quad \forall v_1, \dots, v_p \in V \\ \Rightarrow I_V \cdot \alpha &= \alpha \quad \forall \alpha \in \wedge^p V^* \quad \therefore \text{ This is an action of } GL(V) \text{ on } \wedge^p V^* \end{aligned}$$

Exercise 1.8: Let $\alpha \in \wedge^1 V^*$ and let L be an isometry

$$\begin{aligned} \alpha(v) &= g(g^\# \alpha, v) \text{ for } v \in V \text{ (by definition)} \\ g(g^\#(L \cdot \alpha), v) &= (L \cdot \alpha)(v) = \alpha(L^{-1}(v)) = g(g^\# \alpha, L^{-1}(v)) \\ &= g(L(g^\# \alpha), L(L^{-1}(v))) = g(L(g^\# \alpha), v) \quad \forall v \in V \\ \Rightarrow g^\#(L \cdot \alpha) &= L(g^\# \alpha) \text{ since } g \text{ is non-deg.} \end{aligned}$$

Suppose $L \in GL(V)$ and $L(g^\# \alpha) = g^\#(L \cdot \alpha) \quad \forall \alpha \in \wedge^1 V^*$ then

$$\begin{aligned} g(g^\#(L \cdot \alpha), L(v)) &= L \cdot \alpha(L(v)) = \alpha(L^{-1}(L(v))) = \alpha(v) \\ &= g(g^\# \alpha, v) \text{ but } g^\#(L \cdot \alpha) = L(g^\# \alpha) \Rightarrow \end{aligned}$$

$$g(L(g^\# \alpha), L(v)) = g(g^\#(L \cdot \alpha), L(v)) = g(g^\# \alpha, v) \quad \forall v \in V$$

but $g^\#$ is an isomorphism $\Rightarrow \forall w \in V \exists \alpha \in V^* \ni g^\# \alpha = w$

$$\Rightarrow g(L(w), L(v)) = g(L(g^\# \alpha), L(v)) = g(g^\# \alpha, v) = g(w, v)$$

$\Rightarrow L$ is an isometry (thus isometry is a necessary assumption)

Nice

Continue in this manner:

$$= \frac{1}{p!} g^{i_1 j_1} g^{i_2 j_2} \alpha_{i_1 i_2 k_3 \dots k_p} \beta_{j_1 j_2 l_3 \dots l_p} g^{i_3 j_3} \dots g^{i_p j_p} (L^{-1})_{j_3}^{k_3} \dots (L^{-1})_{j_p}^{k_p} \\ \dots (L^{-1})_{i_3}^{l_3} \dots (L^{-1})_{i_p}^{l_p}$$

$$= \frac{1}{p!} g^{i_1 j_1} \dots g^{i_p j_p} \alpha_{i_1 \dots i_p} \beta_{j_1 \dots j_p} = \frac{1}{p!} \alpha^{i_1 \dots i_p} \beta_{j_1 \dots j_p}$$

$$= \tilde{g}(\alpha, \beta) \quad \therefore \quad \tilde{g}(\alpha, \beta) = \tilde{g}(L \cdot \alpha, L \cdot \beta)$$

$$\forall \alpha, \beta \in \wedge^p V^*$$

Exercise 1.9: Let $L: V \rightarrow V$ be an isometry and fix a basis (e_i) of V . Then we have $\forall \alpha \in \Lambda^p V^*$

$$\begin{aligned} (L \cdot \alpha)_{i_1, \dots, i_p} &= (L \cdot \alpha)(e_{i_1}, \dots, e_{i_p}) = \alpha(L^{-1}(e_{i_1}), \dots, L^{-1}(e_{i_p})) \\ &= \alpha((L^{-1})_{i_1}^{j_1} e_{j_1}, \dots, (L^{-1})_{i_p}^{j_p} e_{j_p}) = (L^{-1})_{i_1}^{j_1} \dots (L^{-1})_{i_p}^{j_p} \alpha(e_{j_1}, \dots, e_{j_p}) \\ &= (L^{-1})_{i_1}^{j_1} \dots (L^{-1})_{i_p}^{j_p} \alpha_{j_1, \dots, j_p} \end{aligned}$$

Consider $\alpha, \beta \in \Lambda^1 V^*$ note: $g^\# \alpha = g^{ij} \alpha_j e_i$ where $\alpha = \alpha_i e^i$ (of course (e^i) is the dual of (e_i)) then we have
 $\tilde{g}(\alpha, \beta) = \frac{1}{1!} \alpha^i \beta_i = g^{ij} \alpha_j \beta_i$ but $g(g^\# \alpha, g^\# \beta) =$
 $g(g^{ij} \alpha_j e_i, g^{kl} \beta_k e_l) = g^{ij} g^{kl} \alpha_j \beta_k g(e_j, e_l) = g^{ij} g^{kl} g_{jl} \alpha_j \beta_k$
 $= g^{ij} \delta_j^k \alpha_j \beta_k = g^{ij} \alpha_j \beta_i = \tilde{g}(\alpha, \beta)$

Thus $\tilde{g}(\alpha, \beta) = g(g^\# \alpha, g^\# \beta) \quad \forall \alpha, \beta \in \Lambda^1 V^*$ now use Ex 1.8
 $\tilde{g}(\alpha, \beta) = g(g^\# \alpha, g^\# \beta) = g(L(g^\# \alpha), L(g^\# \beta))$ (isometry)
 $= g(g^\#(L \cdot \alpha), g^\#(L \cdot \beta)) = \tilde{g}(L \cdot \alpha, L \cdot \beta)$

$$\Rightarrow g^{ij} \alpha_j \beta_i = \tilde{g}(\alpha, \beta) = \tilde{g}(L \cdot \alpha, L \cdot \beta) = \frac{1}{1!} (L \cdot \alpha)^i (L \cdot \beta)_i$$

$$= g^{ij} (L \cdot \alpha)_j (L \cdot \beta)_i = g^{ij} (L^{-1})_j^{k_1} \alpha_{k_1} (L^{-1})_i^{l_1} \beta_{l_1}$$

$$\therefore g^{ij} \alpha_j \beta_i = g^{ij} (L^{-1})_j^{k_1} (L^{-1})_i^{l_1} \alpha_{k_1} \beta_{l_1}$$

$$\text{Let } \alpha, \beta \in \Lambda^p V^* \quad \tilde{g}(L \cdot \alpha, L \cdot \beta) = \frac{1}{p!} (L \cdot \alpha)^{i_1, \dots, i_p} (L \cdot \beta)_{i_1, \dots, i_p}$$

$$= \frac{1}{p!} g^{i_1 j_1} \dots g^{i_p j_p} (L \cdot \alpha)_{j_1, \dots, j_p} (L \cdot \beta)_{i_1, \dots, i_p} =$$

$$= \frac{1}{p!} g^{i_1 j_1} \dots g^{i_p j_p} (L^{-1})_{j_1}^{k_1} \dots (L^{-1})_{j_p}^{k_p} \alpha_{k_1, \dots, k_p} (L^{-1})_{i_1}^{l_1} \dots (L^{-1})_{i_p}^{l_p} \beta_{l_1, \dots, l_p}$$

$$= \frac{1}{p!} g^{i_1 j_1} (L^{-1})_{j_1}^{k_1} (L^{-1})_{i_1}^{l_1} \alpha_{k_1, \dots, k_p} \beta_{l_1, \dots, l_p} \cdot g^{i_2 j_2} \dots g^{i_p j_p} (L^{-1})_{j_2}^{k_2} \dots (L^{-1})_{j_p}^{k_p} (L^{-1})_{i_2}^{l_2} \dots (L^{-1})_{i_p}^{l_p}$$

$$= \frac{1}{p!} g^{i_1 j_1} \alpha_{\underline{i_1 k_2 \dots k_p} \underline{j_1 l_2 \dots l_p}} \beta_{\underline{j_1 l_2 \dots l_p}} \cdot g^{i_2 j_2} \dots g^{i_p j_p} (L^{-1})_{j_2}^{k_2} \dots (L^{-1})_{j_p}^{k_p} (L^{-1})_{i_2}^{l_2} \dots (L^{-1})_{i_p}^{l_p}$$

~~It would be a little clearer to first show~~
 $g^{ij} (L^{-1})_j^{k_1} (L^{-1})_i^{l_1} = g^{kl}$

Exercise 1.10 Let G be a Lie group. $\forall \alpha \in T_e^*G$ let ℓ_α be a 1-form on G defined by:

$$(\ell_\alpha)_g \equiv (L_g^{-1})^*(\alpha) = (L_{g^{-1}})^*(\alpha)$$

$\forall g \in G$. Note: $(\ell_\alpha)_g(v) = \alpha(d_g L_{g^{-1}}(v)) \quad \forall g \in G, v \in T_g G$

① Let $h \in G, \alpha \in T_e^*G$. Then for $g \in G, v \in T_g G$ we have

$$\begin{aligned} (L_h^*(\ell_\alpha))_g(v) &= (\ell_\alpha)_{L_h(g)}((d_g L_h)(v)) = (\ell_\alpha)_{hg}((d_g L_h)(v)) \\ &= \alpha(d_{hg} L_{(hg)^{-1}}[(d_g L_h)(v)]) = \alpha(d_g (L_{(hg)^{-1}} \circ L_h)(v)) \\ &= \alpha(d_g L_{(hg)^{-1}h}(v)) \text{ but } (hg)^{-1}h = g^{-1}h^{-1}h = g^{-1} \text{ hence} \\ &= \alpha(d_g L_{g^{-1}}(v)) = (\ell_\alpha)_g(v) \quad \therefore L_h^*(\ell_\alpha) = \ell_\alpha \end{aligned}$$

② $\beta \in \Omega^1 G$ is a left-invariant form iff $L_h^* \beta = \beta \quad \forall h \in G$.
Let $\Omega_{\text{inv}}^1 G = \{\beta \in \Omega^1 G \mid \beta \text{ left-invariant}\}$

$\S \beta \in \Omega_{\text{inv}}^1 G$ then $\beta_e \in T_e^*G$ let $g \in G, v \in T_g G$ then

$$\begin{aligned} (\ell_{\beta_e})_g(v) &= \beta_e(d_g L_{g^{-1}}(v)) = \beta_{gg^{-1}}(d_g L_{g^{-1}}(v)) = (L_{g^{-1}}^* \beta)_g(v) \\ &= \beta_g(v) \text{ because } \beta \text{ is left-inv. } \therefore \ell_{\beta_e} = \beta \end{aligned}$$

Define $\varphi: T_e^*G \rightarrow \Omega_{\text{inv}}^1 G$ by $\varphi(\alpha) = \ell_\alpha$ (① $\Rightarrow \ell_\alpha \in \Omega_{\text{inv}}^1 G$)
we have just shown that $\varphi(\beta_e) = \ell_{\beta_e} = \beta$ where $\beta_e \in T_e^*G$
 $\therefore \varphi$ is onto.

$\S k \in \mathbb{R}, \alpha, \beta \in T_e^*G$ then $\forall g \in G, v \in T_g G$

$$\begin{aligned} \varphi(k\alpha + \beta)_g(v) &= (\ell_{k\alpha + \beta})_g(v) = (k\alpha + \beta)(d_g L_{g^{-1}}(v)) = \\ &= k \cdot \alpha(d_g L_{g^{-1}}(v)) + \beta(d_g L_{g^{-1}}(v)) = k(\ell_\alpha)_g(v) + (\ell_\beta)_g(v) \end{aligned}$$

Let V be a vector space and g a metric on V . An isometry of V is an invertible linear mapping $L: V \rightarrow V$ such that

$$g(L(v), L(w)) = g(v, w)$$

for all $v, w \in V$.

Let $\mathcal{GL}(V)$ denote the group of all invertible linear mappings from V to V .

Exercise 1.7 Define an action of $\mathcal{GL}(V)$ on $\wedge^p V^*$ by

$$(L \cdot \alpha)(v_1, v_2, \dots, v_p) = \alpha(L^{-1}(v_1), L^{-1}(v_2), \dots, L^{-1}(v_p))$$

for $\alpha \in \wedge^p V^*$, $L \in \mathcal{GL}(V)$, $v_1, v_2, \dots, v_p \in V$.

Show that this is indeed an action:

$$(L_1 \circ L_2) \cdot \alpha = L_1 \cdot (L_2 \cdot \alpha)$$

$$I_V \cdot \alpha = \alpha,$$

$$\overset{\text{identity}}{I_V: V \rightarrow V}$$

Exercise 1.8 If $\alpha \in \wedge^1 V^*$ show that

$$L((g^\# \alpha)) = g^\#(L \cdot \alpha)$$

for each $L \in \mathcal{GL}(V)$

Exercise 1.9 If $L: V \rightarrow V$ is an isometry and

$\alpha, \beta \in \wedge^p V^*$ show that $\tilde{g}(L \cdot \alpha, L \cdot \beta) = \tilde{g}(\alpha, \beta)$.

Hint: First show that if $\tilde{g}$ is the metric on $\wedge^p V^*$ then $\tilde{g}(L \cdot \alpha, L \cdot \beta) = \tilde{g}(\alpha, \beta)$. Write the result in terms of an orthonormal basis of V and write out a proof of the case when $\alpha, \beta \in \wedge^1 V^*$ using components.

Continue 2...

$$\therefore \varphi(k\alpha + \beta) = k\ell_\alpha + \ell_\beta = k\varphi(\alpha) + \varphi(\beta) \Rightarrow \varphi \text{ is linear.}$$

Let $\alpha \in \text{Ker}(\varphi) \Rightarrow \varphi(\alpha) = \ell_\alpha = 0 \therefore \forall v \in T_e G$ we have

$$0 = (\ell_\alpha)_e(v) = \alpha(d_e L_e(v)) = \alpha(v) \text{ because } L_e \text{ is the identity map on } G \text{ hence } d_e L_e \text{ is the identity map on } T_e G$$

$$\therefore \alpha(v) = 0 \quad \forall v \in T_e G \Rightarrow \alpha = 0 \therefore \text{Ker}(\varphi) = \{0\} \therefore \varphi \text{ is 1-1}$$

$\therefore \varphi$ is a linear isomorphism from $T_e^* G$ to $\Omega_{\text{inv}}^1 G$,

③ Let $\beta \in \Omega_{\text{inv}}^1 G$ and $X \in \mathfrak{X}_{\text{inv}} G$ then $\forall g \in G$

$$\text{We know from 2 that } \beta = \ell_{\beta_e} \therefore \beta_g(X_g) = (\ell_{\beta_e})_g(X_g)$$

$$= \beta_e(d_g L_{g^{-1}}(X_g)) = \beta_e(X_{gg^{-1}}) \text{ (because } X \text{ is left-invar.)}$$

$$= \beta_e(X_e) \therefore \beta_g(X_g) = \beta_e(X_e) \text{ hence } g \mapsto \beta_g(X_g) \text{ is a constant map.}$$

④ Let $\{e_i\}$ be a basis for $T_e G$ and let $\{e^i\}$ be the corresponding dual basis for $T_e^* G$, let $\beta^i = \ell_{e^i}$ and $X_i = \ell_{e_i}$
First note that $\beta^i \in \Omega_{\text{inv}}^1 G$ and $X_i \in \mathfrak{X}_{\text{inv}} G$

$$\begin{aligned} \text{(a) } \beta_g^i(X_j(g)) &= (\ell_{e^i})_g(\ell_{e_j}(g)) = e^i(d_g L_{g^{-1}}(d_e L_g(e_j))) \\ &= e^i(d_e(L_{g^{-1}} \circ L_g)(e_j)) = e^i(d_e L_{g^{-1}g}(e_j)) = e^i(d_e L_e(e_j)) \quad \swarrow \text{identity} \\ &= e^i(e_j) = \delta_j^i \quad \forall g \in G \therefore \beta_g^i(X_j(g)) = \delta_j^i \quad \forall g \in G \end{aligned}$$

Continue 4...

(b) Choose $f_{jk}^i \in \mathbb{R} \ni [X_i, X_j] = f_{ij}^k X_k$ ← it's clear that there always exist such numbers

$$\begin{aligned} d\beta^i(X_j, X_k) &= X_j(\beta^i(X_k)) - X_k(\beta^i(X_j)) - \beta^i([X_j, X_k]) \\ &= X_j(\delta_k^i) - X_k(\delta_j^i) - \beta^i(f_{jk}^l X_l) \quad (\text{vector field on const. is 0}) \\ &= -f_{jk}^l \beta^i(X_l) = -f_{jk}^l \delta_l^i = -f_{jk}^i \end{aligned}$$

$$\begin{aligned} -\frac{1}{2} f_{ab}^i \beta^a \wedge \beta^b(X_j, X_k) &= -\frac{1}{2} f_{ab}^i (\beta^a(X_j) \beta^b(X_k) - \beta^b(X_j) \beta^a(X_k)) \\ &= -\frac{1}{2} f_{ab}^i \delta_j^a \delta_k^b + \frac{1}{2} f_{ab}^i \delta_k^a \delta_j^b = -\frac{1}{2} f_{jk}^i + \frac{1}{2} f_{kj}^i \quad \text{but} \end{aligned}$$

$$-[X_j, X_k] = [X_k, X_j] \Rightarrow -f_{jk}^i = f_{kj}^i \quad \therefore = -\frac{1}{2} f_{jk}^i - \frac{1}{2} f_{jk}^i$$

$$\text{hence } -\frac{1}{2} f_{ab}^i \beta^a \wedge \beta^b(X_j, X_k) = -f_{jk}^i$$

$$\therefore d\beta^i = -\frac{1}{2} f_{jk}^i \beta^j \wedge \beta^k$$

⑤ Define Θ a 1-form on G with values in the Lie algebra $\mathfrak{X}_{\text{inv}}(G)$ by $\Theta_g(v) = \beta_g^i(v) X_i \quad \forall g \in G, v \in T_g G$

(a) Let $\{f_i\}$ be a basis for $T_e G$ and let $\{f^i\}$ be its corresponding dual basis (basis for $T_e^* G$) also define $\bar{\beta}^i = l_{f^i}^*$ and $\bar{X}_j = l_{f_j}$ (note: again $\bar{\beta}^i \in \Omega_{\text{inv}}^1 G$ and $\bar{X}_j \in \mathfrak{X}_{\text{inv}}(G)$)

Now we can write the f_i 's as a linear comb. of e_i 's
 $f_i = B_i^l e_l$ then we know that $(C^k)_j^i e^i = f^k$ since they are dual bases we have:

$$\delta_j^i = f^i(f_j) = C_l^i e^l(B_j^k e_k) = C_l^i B_j^k e^l(e_k) = C_l^i B_j^k \delta_k^l = C_l^i B_j^l$$

Continue 5...

for $g, h \in G$ and $v \in T_g G$ we have:

$$\bar{\beta}_g^i(v) \bar{\Sigma}_i(h) = (l_{f_i}^i)_g(v) l_{f_i}^i(h) = f^i(d_g L_{g^{-1}}(v)) d_e L_h(f_i)$$

$$= C_\ell^i e^\ell(d_g L_{g^{-1}}(v)) d_e L_h(B_i^k e_k) = C_\ell^i (l_{e^\ell}^i)_g(v) B_i^k d_e L_h(e_k)$$

$$= C_\ell^i B_i^k (l_{e^\ell}^i)_g(v) l_{e_k}(h) = \delta_\ell^k \beta_g^\ell(v) \Sigma_k(h) = \beta_g^\ell(v) \Sigma_\ell(h)$$

$\therefore \bar{\beta}_g^i(v) \bar{\Sigma}_i = \beta_g^i(v) \Sigma_i \therefore \Theta$ is independent of basis choices.

(b) Let $\Sigma \in \mathcal{X}_{\text{inv}}(G) \Rightarrow \Sigma = l_\alpha$ for some $\alpha \in T_e G$ hence $\alpha = k^i e_i$ where $k^i \in \mathbb{R}$. $\therefore \Sigma = l_{k^i e_i} = k^i l_{e_i} = k^i \Sigma_i$

$$\Theta_g(\Sigma_g) = \beta_g^i(k^i \Sigma_i(g)) \Sigma_i = k^i \beta_g^i(\Sigma_i(g)) \Sigma_i = k^i \delta_j^i \Sigma_i =$$

$$k^i \Sigma_i = \Sigma \therefore \Theta(\Sigma) = \Sigma \leftarrow \text{Note: This means } \Theta_g(\Sigma_g) = \Sigma \text{ a const.}$$

(c) Let $\Upsilon \in \mathcal{X}(G)$ then $\Upsilon = \lambda^i \Sigma_i$ but λ^i are non-constant functions unless $\Upsilon \in \mathcal{X}_{\text{inv}} G$

So we can't say $\Theta(\lambda^i \Sigma_i) = \lambda^i \Theta(\Sigma_i)$. $\leftarrow$ Actually $\ll$ missed you here, $\ll$ will discuss it in class

Exercise 1.10

4/11/22

me ~ March 12

Let G be an arbitrary but fixed Lie group. For each $\alpha \in T_e^*G$ let $l\alpha$ be the 1-form on G defined by

$$(l\alpha)_g \equiv (L_g^{-1})^*(\alpha) = L_{g^{-1}}^*(\alpha), \quad g \in G.$$

Note that $(l\alpha)_g(v) = \alpha(dL_g^{-1}(v))$ for $g \in G, v \in T_g G$.

① Show that for $h \in G$ and $\alpha \in T_e^*G$, $L_h^*(l\alpha) = l\alpha$

② We say that β is a left-invariant 1-form on G iff $\beta \in \Omega^1 G$ and $L_h^* \beta = \beta$ for all $h \in G$. Denote the set of all left-invariant 1-forms on G by $\Omega_{\text{inv}}^1(G)$. Show that for every left-invariant 1-form β there exists $\alpha \in T_e^*G$ such that $\beta = l\alpha$. Show that the mapping from T_e^*G onto $\Omega_{\text{inv}}^1 G$ defined by $\alpha \rightarrow l\alpha$ is a vector space isomorphism.

③ Assume that $\beta \in \Omega_{\text{inv}}^1(G)$ and $X \in \mathfrak{X}_{\text{inv}}(G)$. Show that $\beta_g(X_g) = \beta_e(X_e)$ for all $g \in G$. Thus the mapping from G into $\mathbb{R}$ defined by $g \rightarrow \beta_g(X_g)$ is constant.

④ Let $\{e_i\}$ be a basis of $T_e G$ and $\{e^i\}$ the corresponding basis of T_e^*G dual to $\{e_i\}$. Let $\beta^i = l e^i$ and $X_i = l e_i$.

(a) Show that $\beta_g^i(X_j(g)) = \delta_{jk}^i \quad \forall g \in G$

(b) Choose $f_{jk}^i \in \mathbb{R}$ such that $[X_j, X_k] = f_{jk}^i X_i$. Show that $d\beta^i = -\frac{1}{2} f_{jk}^i (\beta^j \wedge \beta^k)$.

Hint: Evaluate $d\beta^i$ and $-\frac{1}{2} f_{jk}^i (\beta^j \wedge \beta^k)$ at an arbitrary pair of basis vector fields (X_p, X_q) . You will need (a) and the identity $d\beta(X, Y) = X(\beta(Y)) - Y(\beta(X)) - \beta([X, Y])$.

⑤ Using the same notation as in 4., define a 1-form Θ on G with values in the Lie algebra $\mathfrak{X}_{\text{inv}}(G)$ by

$$\Theta_g(v) = \beta_g^i(v) X_i.$$

(a) Show that if $\{f_i\}$ is another basis of $T_e G$ with dual basis $\{f^i\}$ and if $\bar{\beta}^i = l f^i$, $\bar{X}_i = l f_i$ then

$$\bar{\beta}_g^i(v) \bar{X}_i = \beta_g^j(v) X_j \quad \forall g \in G, v \in T_g G.$$

It follows that Θ is independent of the choice of basis.

(b) Show that $\Theta(X) = X$ for every $X \in \mathcal{X}_{\text{inv}}(G)$.

(c) Explain what is wrong with the following argument.

Let $Y \in \mathcal{X}(G)$ and write $Y = \lambda^i \frac{\partial}{\partial x^i} = \lambda^i X_i$ which holds since $Y_g \in T_g G$ and $\{X_i(g)\}$ is a basis of $T_g G$ for each $g \in G$. Now

$$\Theta(Y) = \Theta(\lambda^i X_i) = \lambda^i \Theta(X_i) = \lambda^i X_i = Y.$$

So $\Theta(Y) = Y$ for every vector field Y . This result is false. What's the problem?

depend on g

$\rightarrow$ not $\lambda^i \in \mathbb{R}$
but $\lambda^i \in \mathbb{F}(M)$ //

$$\Theta_g(v) = \beta_g^i(v) X_i(g)$$

$$\Theta_g(\lambda^i(g) X_i(g))$$

$$= \beta_g^i(\lambda^i(g) X_i(g)) X_i(g)$$

Exercise 2.1: Let U, F be manifolds, and let $\varphi: U \rightarrow F$ be a smooth mapping. Let $\Delta: U \rightarrow U \times F$ be defined by $\Delta(u) = (u, \varphi(u)) \forall u \in U$.

(a) $\S$ $x: U_x \rightarrow \mathbb{R}^m, y: U_y \rightarrow \mathbb{R}^n$ are charts on U , and $z: U_z \rightarrow \mathbb{R}^d$ is a chart on F then y is a chart $\exists x^{-1}(x) \in U_y$
 If $t \in x(U_x) \in \mathbb{R}^m$ then
 $(y \times z) \circ \Delta \circ x^{-1}(t) = y \times z(x^{-1}(t), \varphi \circ x^{-1}(t)) = (y \circ x^{-1}) \times (z \circ \varphi \circ x^{-1})(t)$
 but $y \circ x^{-1}$ is smooth (both are charts on U) and $z \circ \varphi \circ x^{-1}$ is smooth (composition of smooth maps)
 $\Rightarrow (y \times z) \circ \Delta \circ x^{-1} = (y \circ x^{-1}) \times (z \circ \varphi \circ x^{-1})$ is smooth
 hence Δ is a smooth map.

$\pi \circ \Delta(u) = \pi(u, \varphi(u)) = u \Rightarrow \Delta$ is a smooth section of the trivial bundle $\pi: U \times F \rightarrow U$.

(b) Let $u_0 \in U, x: U_0 \rightarrow \mathbb{R}^m$ be a chart of $U \ni u_0 \in U_0$ and $y: V_0 \rightarrow \mathbb{R}^d$ a chart of $F \ni \varphi(u_0) \in V_0$.
 define $z: U_0 \times V_0 \rightarrow \mathbb{R}^m \times \mathbb{R}^d$ by $z(u, f) = (x(u), y(f) - y(\varphi(u)))$
 $\forall (u, f) \in U_0 \times V_0$
 then $\text{id} \circ z \circ (x \times y)^{-1}(s, t) = z(x^{-1}(s), y^{-1}(t)) = (x \circ x^{-1}(s), y \circ y^{-1}(t) - y \circ \varphi \circ x^{-1}(s)) = (s, t - y \circ \varphi \circ x^{-1}(s))$
 now $y \circ \varphi \circ x^{-1}$ is smooth and subtraction is smooth
 $\Rightarrow (s, t) \xrightarrow{\Theta} t - y \circ \varphi \circ x^{-1}(s)$ is smooth $\therefore \text{id} \circ z \circ (x \times y)^{-1} = \text{id} \times \Theta$ is smooth $\Rightarrow z$ is smooth.

$$\begin{aligned} z^{-1}(s, t) &= (x^{-1}(s), y^{-1}(t + y \circ \varphi \circ x^{-1}(s))) \\ z \circ z^{-1}(s, t) &= (x \circ x^{-1}(s), y(y^{-1}(t + y \circ \varphi \circ x^{-1}(s))) - y \circ \varphi \circ x^{-1}(s)) \\ &= (s, t + y \circ \varphi \circ x^{-1}(s) - y \circ \varphi \circ x^{-1}(s)) = (s, t) \end{aligned}$$

$$\begin{aligned}\bar{z}^{-1} \circ z(u, f) &= (\bar{x}^{-1} \circ x(u), \bar{y}^{-1}(y(f) - y \circ \varphi(u) + y \circ \varphi \circ \bar{x}^{-1} \circ x(u))) \\ &= (u, \bar{y}^{-1}(y(f) - y \circ \varphi(u) + y \circ \varphi(u))) = (u, \bar{y}^{-1} \circ y(f)) = (u, f)\end{aligned}$$

$\Rightarrow \bar{z}^{-1}$ is in fact the inverse of z ,

$$\text{and } (x \times y) \circ \bar{z}^{-1} \circ \text{id}(s, t) = (x \times y) \circ \bar{z}^{-1}(s, t) =$$

$$(x \times y)(\bar{x}^{-1}(s), \bar{y}^{-1}(t + y \circ \varphi \circ \bar{x}^{-1}(s))) = (x \circ \bar{x}^{-1}(s), y \circ \bar{y}^{-1}(t + y \circ \varphi \circ \bar{x}^{-1}(s)))$$

$$= (s, t + y \circ \varphi \circ \bar{x}^{-1}(s)) \text{ again, } (s, t) \xrightarrow{\Theta'} t + y \circ \varphi \circ \bar{x}^{-1}(s)$$

is smooth since $y \circ \varphi \circ \bar{x}^{-1}$ is smooth (composition of smooth maps)

and addition is smooth. $\therefore (x \times y) \circ \bar{z}^{-1} \circ \text{id} = \text{id} \times \Theta'$ is smooth

hence $\bar{z}^{-1}$ is smooth.

$$\begin{aligned}u \in U_0 \text{ then } z \circ \Delta(u) &= z(u, \varphi(u)) = (x(u), y \circ \varphi(u) - y \circ \varphi(u)) \\ &= (x(u), 0) \equiv x(u) \Rightarrow z \circ \Delta = x\end{aligned}$$

Now let $\bar{x}: \bar{U}_0 \rightarrow \mathbb{R}^m$, $\bar{y}: \bar{V}_0 \rightarrow \mathbb{R}^d$ be charts on U and F resp.

$\exists u_0 \in \bar{U}_0$, $\varphi(u_0) \in \bar{V}_0$ and $\bar{z}: \bar{U}_0 \times \bar{V}_0 \rightarrow \mathbb{R}^m \times \mathbb{R}^d$ is defined

by $\bar{z}(u, f) = (\bar{x}(u), \bar{y}(f) - \bar{y} \circ \varphi(u))$ then

$$\bar{z} \circ \bar{z}^{-1}(s, t) = \bar{z}(\bar{x}^{-1}(s), \bar{y}^{-1}(t + y \circ \varphi \circ \bar{x}^{-1}(s))) =$$

$$(\bar{x} \circ \bar{x}^{-1}(s), \bar{y} \circ \bar{y}^{-1}(t + y \circ \varphi \circ \bar{x}^{-1}(s)) - \bar{y} \circ \varphi \circ \bar{x}^{-1}(s))$$

$$= (\bar{x} \circ \bar{x}^{-1}) \times (\bar{y} \circ \bar{y}^{-1} \circ \Theta' - \bar{y} \circ \varphi \circ \bar{x}^{-1})(s, t), \text{ which is smooth}$$

Since it is compositions of smooth maps etc.

$\Rightarrow z$ and $\bar{z}$ are compatible charts

note:

It is obvious that $d_p z$ is full rank $\forall p \in U_0 \times V_0$

$$\text{since } z(u, f) = x(u) \times (y(f) - y \circ \varphi(u))$$

$\uparrow$ rank m $\uparrow$ rank d $\uparrow$ depends only on u

(in the right basis)

Jacobian looks like $\begin{bmatrix} I_m & * \\ 0 & I_d \end{bmatrix}$ $\therefore$ by the inverse function

thm $\exists$ nbhd V_p of $p \ni z(V_p)$ open thus $z(U_0 \times V_0) = \bigcup_{p \in U_0 \times V_0} z(V_p)$ is open

Exercise 2.2: Let $\pi: E \rightarrow M$ be a fiber bundle with fiber F . Let $\Delta: U \rightarrow E$ be a local section of π , $U \subseteq E$ open

$\forall x \in \Delta(U)$ then $\exists u \in U \ni \Delta(u) = x \Rightarrow \pi(x) = \pi \circ \Delta(u) = u \in U$
 $\therefore \Delta(U) \subseteq \pi^{-1}(U)$ but π is smooth hence $\pi^{-1}(U)$ open $\therefore$ an open submanifold of E .

Choose coordinates on $\pi^{-1}(U)$, say $\psi: V_0 \rightarrow \mathbb{R}^{m+d}$ (let $\dim(M) = m$ and $\dim(F) = d$) $\exists$ we also have a local trivializing map $\psi_{u_0}: V_0 \rightarrow U_0 \times F$ and finally we also want $V_0 \cap \Delta(U) \neq \emptyset$.

Note: $\Delta|_{U_0}$ is a homeomorphism

maybe $V_0 \subseteq \pi^{-1}(U_0)$ $\psi_{u_0}: \pi^{-1}(U_0) \rightarrow U_0 \times F$ $\Delta(U_0)$ open? Does it need to be?

Thus we have for $u \in \Delta^{-1}(\Delta(U) \cap V_0) = W_0 (\subseteq M)$
 $\pi \circ \Delta = \text{id}_U$, $\pi|_{V_0} = \pi_{u_0} \circ (\psi_{u_0}|_W) \Rightarrow \pi|_{V_0} \circ \Delta|_{W_0} = \text{id}_{W_0}$

$$\therefore \text{id}_{W_0} = \pi_{u_0} \circ \psi_{u_0} \circ \Delta|_{W_0} \Rightarrow d_p(\text{id}_{W_0}) = d_p(\pi_{u_0} \circ \psi_{u_0} \circ \Delta)$$

$$= (d_{\psi_{u_0} \circ \Delta(p)} \pi_{u_0}) \circ (d_{\Delta(p)} \psi_{u_0}) \circ (d_p \Delta)$$

$$\text{rank}(d_p \text{id}_{W_0}) = \dim(M) = m = \text{rank}((d_{\psi_{u_0} \circ \Delta(p)} \pi_{u_0}) \circ (d_{\Delta(p)} \psi_{u_0}) \circ (d_p \Delta))$$

$$\leq \min \{ \text{rank}(d_{\psi_{u_0} \circ \Delta(p)} \pi_{u_0}), \text{rank}(d_{\Delta(p)} \psi_{u_0}), \text{rank}(d_p \Delta) \}$$

$$= \min \{ m, m+d, \text{rank}(d_p \Delta) \}$$
 since ψ_{u_0} is a diff.

and π_{u_0} is a proj. onto U_0 , but $\Delta: U \rightarrow E$, $U \subseteq M$

$$\Rightarrow \text{rank}(d_p \Delta) \leq \dim(M) = m$$

$$\text{hence } \min \{ m, m+d, \text{rank}(d_p \Delta) \} = \text{rank}(d_p \Delta) \leq m$$

$$\Rightarrow m \leq \text{rank}(d_p \Delta) \leq m \Rightarrow \text{rank}(d_p \Delta) = m$$

$\therefore \forall p \in U$ we have $\text{rank}(d_p \Delta) = \dim(U) (= \dim(M))$
 $\Rightarrow d_p \Delta$ is 1-1

Small gap

needs a little work here

it doesn't make sense to say j is smooth unless $\Delta(U)$ is a manifold structure. What manifold structure are you putting on $\Delta(U)$?

finally the inclusion map $j: \Delta(U) \hookrightarrow E$ is smooth since $j = \Delta \circ \pi$ ($j(x) = j(\Delta(u)) = \Delta \circ \pi \circ \Delta(u) = \Delta(u) = x$ ✓) which is the composition of smooth maps.

$\Rightarrow \Delta(U)$ is a submanifold of E . (* need relative top.)
✓ see below

$\nexists p \in U \Rightarrow \Delta(p) \in U$ and $\pi \circ \Delta(p) = p \Rightarrow \Delta(p) \in \pi^{-1}\{p\}$
 $\therefore \{\Delta(p)\} \subseteq \Delta(U) \cap \pi^{-1}\{p\}$

$\nexists x, y \in \Delta(U) \cap \pi^{-1}\{p\} \Rightarrow \exists u, v \in U \ni \Delta(u) = x, \Delta(v) = y$
 $\Rightarrow u = \pi \circ \Delta(u) = \pi(x) = p = \pi(y) = \pi \circ \Delta(v) = v$
 $\Rightarrow x = \Delta(u) = \Delta(v) = y$

$\therefore \Delta(U) \cap \pi^{-1}\{p\} = \{\Delta(p)\}$

(*) $\Gamma \quad \emptyset \subseteq U$ open then $\pi_U^{-1}(\emptyset) = \emptyset \times F$ open $\Rightarrow \psi_U^{-1}(\emptyset \times F)$ open

$\nexists x \in \psi_U^{-1}(\emptyset \times F) \Rightarrow \pi_U \circ \psi_U(x) \in \emptyset \Rightarrow \pi(x) \in \emptyset$
hence $\Delta \circ \pi(x) = x$ i.e. $x \in \Delta(\emptyset)$

$\Rightarrow \Delta(\emptyset) \cap \psi_U^{-1}(\emptyset \times F) = \Delta(\emptyset) \therefore$ open in relative top.

Note you could define the manifold structure on $\Delta(U)$ as $\Delta(U) \rightarrow \Delta(U)$ to force to be a diffeom.

Exercise 2.3: Let M be a manifold, $\dim(M) = m$

Let $x^i: \mathbb{R}^m \rightarrow \mathbb{R}$ be $x^i(p_1, \dots, p_m) = p_i$ (global coords on $\mathbb{R}^m$)

Let $y: V \rightarrow \mathbb{R}^m$ be a chart on M then if $(p, \alpha) \in \Lambda_p^k M$
we can write $\alpha = \alpha_{i_1 \dots i_k} dy^{i_1} \wedge \dots \wedge dy^{i_k}$

thus our chart on $\Lambda^k M$ is $\Lambda^k y: \Lambda^k V \rightarrow \mathbb{R}^m \times \mathbb{R}^{\binom{m}{k}}$
defined by $\Lambda^k y(p, \alpha) = (y(p), \dots, y^m(p), \alpha_{i_1 \dots i_k})$

note: $\Lambda^k y(\Lambda^k V) = V \times \mathbb{R}^{\binom{m}{k}}$ open
and $\Lambda^k y^{-1}(t_1, \dots, t_m, \alpha_{i_1 \dots i_k}) = (y^{-1}(t_1, \dots, t_m), \alpha_{i_1 \dots i_k} dy^{i_1} \wedge \dots \wedge dy^{i_k})$
thus $\Lambda^k y$ is invertible.

Let $z: W \rightarrow \mathbb{R}^m$ is another chart on M giving rise to
another chart $\Lambda^k z: \Lambda^k W \rightarrow \mathbb{R}^m \times \mathbb{R}^{\binom{m}{k}}$ on $\Lambda^k M$

then
 $\Lambda^k y \circ \Lambda^k z^{-1}(t_1, \dots, t_m, \alpha_{i_1 \dots i_k}) = \Lambda^k y(z^{-1}(t_1, \dots, t_m), \alpha_{i_1 \dots i_k} dz^{i_1} \wedge \dots \wedge dz^{i_k})$

$$= \Lambda^k y(p, \alpha_{i_1 \dots i_k} \frac{\partial z^{i_1}}{\partial y^{j_1}} \dots \frac{\partial z^{i_k}}{\partial y^{j_k}} dy^{j_1} \wedge \dots \wedge dy^{j_k})$$

$$= \Lambda^k y(p, \beta_{j_1 \dots j_k} dy^{j_1} \wedge \dots \wedge dy^{j_k}) = (y(p), \beta_{j_1 \dots j_k})$$

$= (y \circ z^{-1}(t_1, \dots, t_m), \beta_{j_1 \dots j_k})$ now $y \circ z^{-1}$ is smooth (both are charts of M) and $\beta_{j_1 \dots j_k}$ depend smoothly because they are sums and products of smooth objects.

$\Rightarrow \Lambda^k y$ & $\Lambda^k z$ are compatible charts

$\Rightarrow \Lambda^k M$ is a manifold.

• Let $\pi: \Lambda^k M \rightarrow M$ be defined by $\pi(p, \alpha) = p$

let $y: V \rightarrow \mathbb{R}^m$ be a chart on M then

$$y \circ \pi \circ \Lambda^k y^{-1}(t_1, \dots, t_m, \alpha_{i_1, \dots, i_k}) = y \circ \pi(y^{-1}(t_1, \dots, t_m)) = p,$$

$$\alpha_{i_1, \dots, i_k} d_p y^{i_1} \wedge \dots \wedge d_p y^{i_k} = y \circ y^{-1}(t_1, \dots, t_m) = (t_1, \dots, t_m)$$

$\Rightarrow y \circ \pi \circ \Lambda^k y^{-1} = \text{id}$ which is smooth $\Rightarrow \pi$ is smooth $\checkmark$

• Define $\psi_V: \Lambda^k V \rightarrow V \times \Lambda^k \mathbb{R}^m$ by $\psi_V(p, \alpha) =$

$$(p, \alpha_{i_1, \dots, i_k} d_{y(p)} x^{i_1} \wedge \dots \wedge d_{y(p)} x^{i_k}) \quad (\alpha = \alpha_{i_1, \dots, i_k} d_p y^{i_1} \wedge \dots \wedge d_p y^{i_k})$$

and recall x^i 's are global coords on $\mathbb{R}^m$

Obviously $\alpha_{i_1, \dots, i_k} d_{y(p)} x^{i_1} \wedge \dots \wedge d_{y(p)} x^{i_k} \in \Lambda^k \mathbb{R}^m$ and ψ_V is onto $V \times \Lambda^k \mathbb{R}^m$.

$$(y \times \Lambda^k x) \circ \psi_V \circ \Lambda^k y^{-1}(t_1, \dots, t_m, \alpha_{i_1, \dots, i_k}) = (y \times \Lambda^k x) \circ \psi_V(p =$$

$$y^{-1}(t_1, \dots, t_m), \alpha_{i_1, \dots, i_k} d_p y^{i_1} \wedge \dots \wedge d_p y^{i_k}) =$$

$$(y \times \Lambda^k x)(p, \alpha_{i_1, \dots, i_k} d_{y(p)} x^{i_1} \wedge \dots \wedge d_{y(p)} x^{i_k}) = (y(p), \alpha_{i_1, \dots, i_k})$$

$$= (y \circ y^{-1}(t_1, \dots, t_m), \alpha_{i_1, \dots, i_k}) = (t_1, \dots, t_m, \alpha_{i_1, \dots, i_k})$$

$\therefore (y \times \Lambda^k x) \circ \psi_V \circ \Lambda^k y^{-1} = \text{id}$ which is smooth $\Rightarrow \psi_V$ is smooth

Obviously, $\psi_V^{-1}(p, \alpha_{i_1, \dots, i_k} d_{y(p)} x^{i_1} \wedge \dots \wedge d_{y(p)} x^{i_k}) = (p, \alpha)$
where $\alpha_{i_1, \dots, i_k} d_p y^{i_1} \wedge \dots \wedge d_p y^{i_k}$

and $\Lambda^k y \circ \psi_V^{-1} \circ (y \times \Lambda^k x)^{-1} = [(y \times \Lambda^k x) \circ \psi_V \circ \Lambda^k y^{-1}]^{-1} = \text{id}^{-1} = \text{id}$
hence smooth $\Rightarrow \psi_V^{-1}$ is smooth $\Rightarrow \psi_V$ is a diffeomorphism

finally we need that commutes.

$$\begin{array}{ccc} \Lambda^k M & \xrightarrow{\psi_V} & V \times \Lambda^k \mathbb{R}^m \\ \pi \searrow & & \swarrow \pi_V \\ & M & \end{array}$$

$$\pi_V \circ \psi_V(p, \alpha) = \pi_V(p, \alpha_{i_1, \dots, i_k} d_{y(p)} x^{i_1} \wedge \dots \wedge d_{y(p)} x^{i_k}) = p$$

where $\alpha = \alpha_{i_1, \dots, i_k} d_{y(p)} y^{i_1} \wedge \dots \wedge d_{y(p)} y^{i_k}$

but $\pi(p, \alpha) = p$ hence $\pi = \pi_V \circ \psi_V$ $\therefore$ the diagram commutes.

Exercise 2.1 Let U, F be manifolds and $\varphi: U \rightarrow F$ a smooth mapping. Let $\lambda: U \rightarrow U \times F$ be defined by $\lambda(u) = (u, \varphi(u))$, $u \in U$.

(a) Show that λ is a smooth section of the trivial bundle $U \times F \xrightarrow{\pi} U$.

(b) Let $u_0 \in U$. Choose charts $x: U_0 \rightarrow \mathbb{R}^m$, $y: V_0 \rightarrow \mathbb{R}^d$ of U and F respectively such that $u_0 \in U_0$, $\varphi(u_0) \in V_0$. Show that the mapping

$z: U_0 \times V_0 \rightarrow \mathbb{R}^m \times \mathbb{R}^d$ defined by

$$z(u, f) = (x(u), y(f) - y(\varphi(u))) \quad (u, f) \in U_0 \times V_0$$

is smooth and has a smooth inverse. Also show that $z(\lambda(u)) = x(u)$ for each $u \in U_0$. Finally show that if $\bar{z}(u, f) = (\bar{x}(u), \bar{y}(f) - \bar{y}(\varphi(u)))$ is similarly defined for charts $\bar{x}, \bar{y}$ then $z, \bar{z}$ are compatible charts.

This exercise shows that $\lambda(U)$ is a submanifold of $U \times F$ in the strongest sense. Note: you can show $z(U_0 \times V_0)$ is open using the inverse function theorem.

Exercise 2.2. Let $E \xrightarrow{\pi} M$ be a fiber bundle with fiber F and assume that $\lambda: U \rightarrow E$ is a local section of π defined on an open set $U \subseteq M$. Show that $\lambda(U)$ is a submanifold of the open submanifold $\pi^{-1}(U)$ of E . Also show that $\lambda(U)$ intersects each fiber $\pi^{-1}(p)$, $p \in U$, in precisely one point.

Exercise 2.3 Show that $\wedge^R M \rightarrow M$ is a fiber bundle with fiber $\wedge^R \mathbb{R}^m$ where $m = \dim M$.

Exercise 2.4: Let $G \in \mathcal{L}(n) \ni G^2 = I$. Define $f: \mathfrak{gl}(n) \rightarrow \mathfrak{gl}(n)$
by $f(A) = A^t G A - G$ and $G = G^t$

(a) Let $A \in \mathfrak{gl}(n)$, $B \in T_A \mathfrak{gl}(n)$ then $\exists$ a curve $\lambda \mapsto A_\lambda \ni$
 $A_0 = A$ and $\left. \frac{d}{d\lambda} [A_\lambda] \right|_{\lambda=0} = B$

$$\therefore d_A f(B) = d_{A_0} f \left[\left. \frac{d}{d\lambda} [A_\lambda] \right|_{\lambda=0} \right] = \left. \frac{d}{d\lambda} [f(A_\lambda)] \right|_{\lambda=0}$$

(by the chain rule)

$$= \left. \frac{d}{d\lambda} [A_\lambda^t G A_\lambda - G] \right|_{\lambda=0} = \left. \frac{d}{d\lambda} [A_\lambda^t G A_\lambda] \right|_{\lambda=0} - \left. \frac{d}{d\lambda} [G] \right|_{\lambda=0}$$

$$= \left. \frac{d}{d\lambda} [A_\lambda^t] \right|_{\lambda=0} G A_\lambda \Big|_{\lambda=0} + A_\lambda^t \Big|_{\lambda=0} \left. \frac{d}{d\lambda} [G] \right|_{\lambda=0} A_\lambda \Big|_{\lambda=0} + A_\lambda^t G \left. \frac{d}{d\lambda} [A_\lambda] \right|_{\lambda=0}$$

$$= B^t G A + A^t G B = A^t G B + [A^t G B]^t \checkmark$$

(b) Let $L: \mathfrak{gl}(n) \rightarrow \mathfrak{gl}(n)$ be defined by $L(X) = A^t G X$
then

$$L(\alpha X + Y) = A^t G (\alpha X + Y) = \alpha A^t G X + A^t G Y \\ = \alpha L(X) + L(Y) \text{ hence linear.}$$

Let $A \in \mathcal{L}(n)$ then $A^t \in \mathcal{L}(n)$. Consider, $L^{-1}(X) = G A^{t^{-1}} X$
then

$$L L^{-1}(X) = A^t G G A^{t^{-1}} X = A^t \overset{I}{\cancel{G}} A^{t^{-1}} X = A^t A^{t^{-1}} X = X \\ \text{and } L^{-1} L(X) = G A^{t^{-1}} A^t X = G \overset{I}{\cancel{A^t A}} X = G X = \overset{I}{\cancel{G}} X = X$$

$\therefore L$ is an isomorphism (has an inverse)

$$L^{-1} \{ B \mid B = -B^t \} = \{ G A^{t^{-1}} B \mid B = -B^t \} = \{ B \mid A^t G B = -(A^t G B)^t \}$$

(because if we have $G A^{t^{-1}} B = C \ni B = -B^t \Leftrightarrow C \ni$
 $B = A^t G C \ \& \ B = -B^t \Leftrightarrow C \ni A^t G C = -(A^t G C)^t$)

$$\text{but } d_A f(B) = A^t G B + [A^t G B]^t = 0 \Leftrightarrow A^t G B = -[A^t G B]^t$$

$$\therefore \text{Ker}(d_A f) = L^{-1} \{ B \mid B = -B^t \}$$

$$\therefore \forall A \in \mathfrak{gl}(n) \quad \text{Ker}(d_A f) = L^{-1}\{B \mid B = -B^t\}$$

now L an isomorphism $\Rightarrow L^{-1}$ an isomorphism $\Rightarrow$

$$\dim(\text{Ker}(d_A f)) = \dim\{B \mid B = -B^t\} = \frac{n(n-1)}{2} \quad (\text{no dependence on } A)$$

(because $E_{ij} - E_{ji}$ for $i < j$ is a basis for $\{B \mid B = -B^t\}$)

(c) Let $A \in \mathfrak{gl}(n)$ then $f(A)^t = [A^t G A - G]^t = [A^t G A]^t - G^t \xrightarrow{+G}$
 $= A^t G^t A - G = f(A)$ hence $f(A)$ is symmetric

$$\therefore f: \mathfrak{gl}(n) \rightarrow \{A \in \mathfrak{gl}(n) \mid A = A^t\}$$

Consider $A \in \mathfrak{gl}(n) \ni f(A) = A^t G A - G = 0 \Rightarrow A^t G A = G \Rightarrow$
 $\det(A^t G A) = \det(A) \det(G) \det(A) = \det(G) \neq 0$
 $\Rightarrow \det(A) \neq 0 \Rightarrow A \in \mathfrak{GL}(n)$

$$\therefore \forall A \in \{A \in \mathfrak{gl}(n) \mid f(A) = 0\} \text{ we have } A \in \mathfrak{GL}(n) \text{ hence}$$

$$\text{rank}(d_A f) = \dim(T_A \mathfrak{gl}(n)) - \dim(\text{Ker}(d_A f)) =$$

$$\dim(\mathfrak{gl}(n)) - \dim(\text{Ker}(d_A f)) = n^2 - \frac{n(n-1)}{2}$$

$$\therefore \text{rank}(d_A f) = \frac{2n^2 - n^2 + n}{2} = \frac{n(n+1)}{2} = \dim(\text{range}(f))$$

since $\dim\{A \in \mathfrak{gl}(n) \mid A^t = A\} = \frac{n(n+1)}{2} \therefore d_A f$ has maximal rank $\forall A \in \mathfrak{gl}(n) \ni f(A) = 0$

$$\therefore \{A \in \mathfrak{gl}(n) \mid f(A) = 0\} \text{ is a submanifold of } \mathfrak{gl}(n),$$

(d) $O(p, k) = \{A \in \mathfrak{gl}(n) \mid A^t G A = G\} = \{A \in \mathfrak{gl}(n) \mid f(A) = 0\}$

which is a submanifold if $G = G^t$ and $G^2 = I$ ✓

$$\therefore O(p, k) \text{ is a submanifold of } \mathfrak{gl}(n) (= \mathfrak{gl}(p+k))$$

see back $\hookrightarrow$

Yes, $GL(p+k)$ is an open submanifold of $gl(p+k)$
 $\Rightarrow O(p,k) \subseteq GL(p+k)$ is a submanifold of $GL(p+k)$
and $O(p,k)$ is a subgroup of $GL(p+k)$

$\therefore O(p,k)$ is a Lie subgroup of $GL(p+k)$

Exercise 2.4. Let $G \in \text{Gl}(n)$ such that $G^2 = I$, $G^t = G$. Define $f: \mathfrak{gl}(n) \rightarrow \mathfrak{gl}(n)$ by $f(A) = A^T G A - G$.

(a) Let $A \in \mathfrak{gl}(n)$ and show that $d_A f(B) = (A^T G B) + (A^T G B)^T$ for all $B \in T_A(\mathfrak{gl}(n))$. Hint: For each $B \in T_A \mathfrak{gl}(n)$

choose a curve $\lambda \rightarrow A_\lambda$ in $\mathfrak{gl}(n)$ such that

$A_0 = A$, $\frac{d}{d\lambda}(A_\lambda)|_{\lambda=0} = B$ then observe that

$$d_A f(B) = \frac{d}{d\lambda}(f(A_\lambda))|_{\lambda=0}.$$

(b) Let $L: \mathfrak{gl}(n) \rightarrow \mathfrak{gl}(n)$ be defined by $L(X) = A^T G X$. Show that L is a vector space isomorphism and that $L^{-1}(\{B \mid B \text{ is skew-symmetric}\}) = \text{Ker}(d_A f)$ for each $A \in \mathfrak{gl}(n)$. Find $\dim(\text{Ker}(d_A f))$ and show that it is independent of A .

(c) If $G^t = G$, show that f maps $\mathfrak{gl}(n)$ into the set of symmetric matrices. Show that the set of all $A \in \mathfrak{gl}(n)$ such that $f(A) = 0$ is a submanifold of $\mathfrak{gl}(n)$. Hint: Recall that if T is a linear transformation on a vector space V then

$$\dim V = \dim(\text{rk } T) + \dim(\text{Ker } T).$$

(d) Show that $O(p, k)$ is a submanifold of $\mathfrak{gl}(p+k)$ (it is enough to say that $O(p, k)$ is a Lie subgroup of $\text{Gl}(p+k)$).

Exercise 2.5: Let $SU(2) = \{A \in GL(2, \mathbb{C}) \mid \bar{A}^t A = I, \det(A) = 1\}$

(a) $A = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$ where $\alpha, \beta, \gamma, \delta \in \mathbb{C}$

$\nexists A \in SU(2) \Rightarrow \det(A) = \alpha\delta - \beta\gamma = 1$ &
 $\begin{pmatrix} \bar{\alpha} & \bar{\gamma} \\ \bar{\beta} & \bar{\delta} \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \begin{pmatrix} \alpha\bar{\alpha} + \gamma\bar{\gamma} & \alpha\bar{\beta} + \gamma\bar{\delta} \\ \alpha\bar{\beta} + \gamma\bar{\delta} & \beta\bar{\beta} + \delta\bar{\delta} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

$\nexists \beta \neq 0 \Rightarrow \frac{\alpha\delta - 1}{\beta} = \gamma \Rightarrow \alpha\bar{\beta} + \left(\frac{\alpha\delta - 1}{\beta}\right)\bar{\delta} = 0$

$\Rightarrow \alpha\bar{\beta} + \alpha\bar{\delta} - \bar{\delta} = \alpha(\bar{\beta} + \bar{\delta}) - \bar{\delta} = 0 \Rightarrow \underline{\alpha = \bar{\delta}}$

$\Rightarrow \alpha\bar{\beta} + \gamma\bar{\delta} = \alpha\bar{\beta} + \gamma\alpha = \alpha(\bar{\beta} + \gamma) = 0 \quad \nexists \alpha \neq 0 \Rightarrow \underline{\bar{\beta} = -\gamma}$

$\nexists \alpha = 0 \Rightarrow -\beta\gamma = 1$ and $\gamma\bar{\gamma} = 1 \Rightarrow \gamma \neq 0$ and $\beta = -\frac{1}{\gamma} = -\bar{\gamma}$

hence for $\beta \neq 0$ we have $\alpha = \bar{\delta}$ & $\beta = -\bar{\gamma}$

$\nexists \beta = 0 \Rightarrow \delta\bar{\delta} = 1$ and $\alpha\delta = 1 \Rightarrow \delta \neq 0$ and $\underline{\alpha = \frac{1}{\delta} = \bar{\delta}}$

$\Rightarrow \alpha\bar{\beta} + \gamma\bar{\delta} = \alpha\bar{\beta} + \gamma\alpha = \alpha(\bar{\beta} + \gamma) = 0$ but $\alpha = \bar{\delta} \neq 0 \Rightarrow$

$\underline{\bar{\beta} = -\gamma}$ hence for $\beta = 0$ we have $\alpha = \bar{\delta}$ & $\beta = -\bar{\gamma}$

$\therefore A = \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix}$ & $\alpha\delta - \beta\gamma = \alpha\bar{\alpha} + \beta\bar{\beta} = 1 \checkmark$

$\nexists A = \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix}$ & $\alpha\bar{\alpha} + \beta\bar{\beta} = 1 \Rightarrow \det(A) = \alpha\bar{\alpha} + \beta\bar{\beta} = 1 \checkmark$

$$\bar{A}^t A = \begin{pmatrix} \bar{\alpha} & -\beta \\ \bar{\beta} & \alpha \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} = \begin{pmatrix} \alpha\bar{\alpha} + \beta\bar{\beta} & \bar{\alpha}\beta - \bar{\alpha}\beta \\ \alpha\bar{\beta} - \alpha\bar{\beta} & \alpha\bar{\alpha} + \beta\bar{\beta} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I$$

$$\Rightarrow A \in SU(2) \quad \therefore \quad SU(2) = \left\{ \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \mid \alpha, \beta \in \mathbb{C} \text{ \& } |\alpha|^2 + |\beta|^2 = 1 \right\}$$

(b) $SU(2)$ is a Lie-subgroup of $GL(2, \mathbb{C})$ and $\mathfrak{su}(2)$ (the Lie algebra of $SU(2)$) is a Lie-subalgebra of $\mathfrak{gl}(2, \mathbb{C})$ (the Lie algebra of $GL(2, \mathbb{C})$)

$\nexists B \in \mathfrak{su}(2) \Rightarrow \exists$ a curve $A_k \in SU(2) \ni A_0 = I$ &

$$\frac{d}{dk}[A_k] \Big|_{k=0} = B \quad \therefore \quad 0 = \frac{d}{dk}[I] \Big|_{k=0} = \frac{d}{dk}[\bar{A}^t A] \Big|_{k=0}$$

$$= \frac{d}{dk}[\bar{A}] \Big|_{k=0}^t A_0 + \bar{A}_0^t \frac{d}{dk}[A_k] \Big|_{k=0} = \bar{B}^t I + \bar{I}^t B = \bar{B}^t + B$$

$$\therefore \bar{B}^t + B = 0 \quad \checkmark$$

$$\exp(B) \in SU(2) \Rightarrow \det \exp(B) = e^{\text{tr} B} = 1 \Rightarrow \underline{\text{tr} B = 0} \quad \checkmark$$

$\nexists B \in \mathfrak{gl}(2, \mathbb{C}) \ni \bar{B}^t + B = 0$ & $\text{tr} B = 0$ then we have $\exp(\lambda B) \in GL(2, \mathbb{C})$ defined for some nbhd about zero.

$$\overline{\exp(\lambda B)}^t \exp(\lambda B) = \exp(\lambda \bar{B}^t) \exp(\lambda B) = \exp(\lambda \bar{B}^t) \exp(\lambda B)$$

$$\boxed{\bar{B}^t = -B} \quad \rightarrow \quad \boxed{-\lambda B \text{ \& } \lambda B \text{ commute}}$$

$$= \exp(-\lambda B) \exp(\lambda B) \stackrel{\downarrow}{=} \exp(-\lambda B + \lambda B) = \exp(0) = I$$

$$\text{also } \det \exp(\lambda B) = e^{\text{tr} \lambda B} = e^{\lambda \text{tr} B} = e^0 = 1 \Rightarrow \exp(\lambda B) \in SU(2)$$

$$\Rightarrow B \in \mathfrak{su}(2)$$

$$\therefore \mathfrak{su}(2) = \{ B \in \mathfrak{gl}(2, \mathbb{C}) \mid \bar{B}^t + B = 0 \text{ \& } \text{tr} B = 0 \}$$

$$B = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \ni \alpha, \beta, \gamma, \delta \in \mathbb{C} \quad \text{tr } B = 0 \Rightarrow \underline{\alpha = -\delta}$$

$$\text{and } \bar{B}^t + B = \begin{pmatrix} \bar{\alpha} & \bar{\gamma} \\ \bar{\beta} & \bar{\delta} \end{pmatrix} + \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \begin{pmatrix} \alpha + \bar{\alpha} & \bar{\gamma} + \beta \\ \bar{\beta} + \gamma & \bar{\delta} + \delta \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$\Rightarrow \alpha + \bar{\alpha} = 0$ i.e. α is pure imaginary & $\beta = -\bar{\gamma}$

Let $\alpha = x_3 i$, $\beta = -x_2 + x_1 i$ where $(x_1, x_2, x_3) \in \mathbb{R}^3$ then

$$B = \begin{pmatrix} x_3 i & -x_2 + x_1 i \\ x_2 + x_1 i & -x_3 i \end{pmatrix} \quad \text{Conversely, if we have such a } B$$

$$\text{tr } B = x_3 i - x_3 i = 0 \quad \& \quad \bar{B}^t + B = \begin{pmatrix} -x_3 i & x_2 - x_1 i \\ -x_2 - x_1 i & x_3 i \end{pmatrix} + \begin{pmatrix} x_3 i & -x_2 + x_1 i \\ x_2 + x_1 i & -x_3 i \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \Rightarrow B \in \text{su}(2)$$

$$\therefore \text{su}(2) = \left\{ \begin{pmatrix} x_3 i & -x_2 + x_1 i \\ x_2 + x_1 i & -x_3 i \end{pmatrix} \mid (x_1, x_2, x_3) \in \mathbb{R}^3 \right\}$$

$$\text{define: } \varphi: \mathbb{R}^3 \rightarrow \text{su}(2) \text{ by } \varphi(x_1, x_2, x_3) = \begin{pmatrix} x_3 i & -x_2 + x_1 i \\ x_2 + x_1 i & -x_3 i \end{pmatrix} = \hat{x}$$

$$\begin{aligned} \varphi(cx_1 + y_1, cx_2 + y_2, cx_3 + y_3) &= \begin{pmatrix} (cx_3 + y_3)i & -(cx_2 + y_2) + (cx_1 + y_1)i \\ (cx_2 + y_2) + (cx_1 + y_1)i & -(cx_3 + y_3)i \end{pmatrix} \\ &= c \begin{pmatrix} x_3 i & -x_2 + x_1 i \\ x_2 + x_1 i & -x_3 i \end{pmatrix} + \begin{pmatrix} y_3 i & -y_2 + y_1 i \\ y_2 + y_1 i & -y_3 i \end{pmatrix} = c\varphi(x_1, x_2, x_3) + \varphi(y_1, y_2, y_3) \end{aligned}$$

$$\S \varphi(x_1, x_2, x_3) = \begin{pmatrix} x_3 i & -x_2 + x_1 i \\ x_2 + x_1 i & -x_3 i \end{pmatrix} = 0 \Rightarrow x_3 = 0 \quad \&$$

$$\begin{aligned} -x_2 + x_1 i &= 0 \Rightarrow 2x_1 i = 0 \Rightarrow x_1 = 0 \quad \therefore (x_1, x_2, x_3) = 0 \\ x_2 + x_1 i &= 0 \Rightarrow -2x_2 i = 0 \Rightarrow x_2 = 0 \end{aligned}$$

φ obviously onto. $\Rightarrow$ isomorphism

$$\begin{aligned}
 (c) \quad -\frac{1}{2} \operatorname{tr}(\hat{x}\hat{y}) &= -\frac{1}{2} \operatorname{tr} \begin{pmatrix} x_3 i & -x_2 + x_1 i \\ x_2 + x_1 i & -x_3 i \end{pmatrix} \begin{pmatrix} y_3 i & -y_2 + y_1 i \\ y_2 + y_1 i & -y_3 i \end{pmatrix} \\
 &= -\frac{1}{2} \operatorname{tr} \begin{bmatrix} -x_3 y_3 - x_2 y_2 - x_1 y_1 - x_2 y_1 i + x_1 y_2 i & * \\ * & -y_3 x_3 - y_2 x_2 - y_1 x_1 - y_2 x_1 i + y_1 x_2 i - x_3 y_3 \end{bmatrix} \\
 &= -\frac{1}{2} (-2x_3 y_3 - 2x_2 y_2 - 2x_1 y_1) = x_1 y_1 + x_2 y_2 + x_3 y_3 = \langle x, y \rangle
 \end{aligned}$$

$$\begin{aligned}
 \text{and } \|x\|^2 &= x_1^2 + x_2^2 + x_3^2 \quad \det(\hat{x}) = x_3^2 - (-x_2^2 - x_1^2 + x_2 x_1 i - x_2 x_1 i) \\
 &= x_1^2 + x_2^2 + x_3^2 \quad \therefore \det(\hat{x}) = \|x\|^2 \quad \& \quad \langle x, y \rangle = -\frac{1}{2} \operatorname{tr}(\hat{x}\hat{y})
 \end{aligned}$$

Define $\langle \hat{x}, \hat{y} \rangle_0 = -\frac{1}{2} \operatorname{tr}(\hat{x}\hat{y})$ for $\hat{x}, \hat{y} \in \mathfrak{su}(2)$

$\langle, \rangle_0$ is an inner-product because $\langle, \rangle$ is and we have $\langle \hat{x}, \hat{y} \rangle_0 = \langle x, y \rangle$ where $x \mapsto \hat{x}$ is an isomorphism.

$$\Rightarrow x \mapsto \hat{x} \text{ is an isometry } \& \quad \|\hat{x}\|_0^2 = \|x\|^2 = \det(\hat{x})$$

(d) Let $\tilde{\varphi}: \mathfrak{su}(2) \rightarrow \operatorname{End}(\mathfrak{su}(2))$ be defined by

$$\tilde{\varphi}(A)(X) = AXA^{-1} \text{ for } X \in \mathfrak{su}(2)$$

$$(*) \quad \overline{AXA^{-1}}^t + AXA^{-1} = (\bar{A}^t)^{-1} \bar{X}^t \bar{A}^t + AXA^{-1} \text{ but } A \in \mathfrak{su}(2) \Rightarrow$$

$$\bar{A}^t A = I \text{ hence } \bar{A}^t = \bar{A}^{-1} \& \quad (\bar{A}^t)^{-1} = A \quad \therefore (*) = A \bar{X}^t \bar{A}^{-1} + AXA^{-1}$$

$$= A(\bar{X}^t + X)A^{-1} = 0 \quad \& \quad \operatorname{tr}(A(\bar{X}^t + X)A^{-1}) = \operatorname{tr}((\bar{X}^t + X)A^{-1}A) = \operatorname{tr}(\bar{X}^t + X) = \operatorname{tr}(X) = 0$$

$\Rightarrow \tilde{\varphi}(A)(X) \in \mathfrak{su}(2)$ we can see that $\tilde{\varphi}(A)$ is

obviously linear $\Rightarrow \tilde{\varphi}(A) \in \operatorname{End}(\mathfrak{su}(2)) \checkmark$

$$\begin{aligned}
 \langle \tilde{\varphi}(A)(X), \tilde{\varphi}(A)(Y) \rangle_0 &= -\frac{1}{2} \text{tr}(A X \overline{A}^{\uparrow} A Y \overline{A}^{\uparrow}) = -\frac{1}{2} \text{tr}(A(X Y \overline{A}^{\uparrow})) \\
 &= -\frac{1}{2} \text{tr}((X Y \overline{A}^{\uparrow}) A)^{\uparrow} = -\frac{1}{2} \text{tr}(X Y) = \langle X, Y \rangle_0 \quad \checkmark
 \end{aligned}$$

(e) Let $\psi: \mathbb{R}^3 \rightarrow \text{su}(2)$ be defined by $\psi(x) = \hat{x}$

recall ψ is an isometry,

Define $\varphi: \text{SU}(2) \rightarrow \text{GL}(3, \mathbb{R})$ by $\varphi(A) = \psi^{-1} \circ \tilde{\varphi}(A) \circ \psi$
 $\hookrightarrow$ which means $\varphi(A)(x) = \psi(\varphi(A)(x)) = \tilde{\varphi}(A)(\psi(x)) = \tilde{\varphi}(A)(\hat{x})$
 (note: all is well defined because ψ is a bijection)

Now, ψ (and thus ψ^{-1}) is linear, so is $\tilde{\varphi}(A) \Rightarrow \varphi(A)$ is linear (composition of linear maps is linear) $\Rightarrow \varphi(A) \in \text{GL}(3, \mathbb{R})$

$\forall A \in \text{SU}(2) \Rightarrow \det(A) = 1 \Rightarrow \det(A^{-1}) = 1$ also $\overline{A}^t A = I$ $\therefore$
 $(A^{-1})^t (A^{-1}) = (\overline{A}^t)^t A^{-1} = (\overline{A} \overline{A}^t)^{-1} = [(\overline{A}^t A)^t]^{-1} = [(I)^t]^{-1} = I \Rightarrow A^{-1} \in \text{SU}(2)$

$\tilde{\varphi}(A^{-1}) \tilde{\varphi}(A)(X) = A^{-1} (A X A^{-1}) A = X \Rightarrow \tilde{\varphi}(A^{-1}) \tilde{\varphi}(A) = I$ likewise

$\tilde{\varphi}(A) \tilde{\varphi}(A^{-1}) = I$ $\therefore \tilde{\varphi}(A)^{-1} = \tilde{\varphi}(A^{-1})$ hence $\tilde{\varphi}(A)$ is injective

ψ, ψ^{-1} are injective $\Rightarrow \varphi(A) = \psi^{-1} \circ \tilde{\varphi}(A) \circ \psi$ is injective

(composition of injective maps is injective) $\Rightarrow \varphi(A) \in \text{GL}(3, \mathbb{R})$

Hence φ is well defined. $\checkmark$

(f) ψ is an isometry $\Rightarrow \psi^{-1}$ is an isometry.

$$\langle \varphi(A)(x), \varphi(A)(y) \rangle = \langle \psi^{-1} \circ \tilde{\varphi}(A) \circ \psi(x), \psi^{-1} \circ \tilde{\varphi}(A) \circ \psi(y) \rangle$$

$$= \langle \tilde{\varphi}(A)(\psi(x)), \tilde{\varphi}(A)(\psi(y)) \rangle_0 \quad (\text{b/c } \psi^{-1} \text{ is an isometry})$$

$$= \langle \psi(x), \psi(y) \rangle_0 \quad (\text{by Part (d)})$$

$$= \langle x, y \rangle \quad (\text{b/c } \psi \text{ is an isometry}) \quad \forall A \in \text{SU}(2), x, y \in \mathbb{R}^3$$

$$\therefore \varphi(A) \in \text{O}(3) \quad \forall A \in \text{SU}(2)$$

Let $\{e_i\}$ be the standard basis for $\mathbb{R}^3$ then $\varphi(A)(e_i) = \varphi(A)_i^j e_j$

for some $\varphi(A)_i^j \in \mathbb{R}$. $\tilde{\varphi}(A)(\hat{e}_i) = \tilde{\varphi}(A)(\psi(e_i)) = \psi(\varphi(A)(e_i))$

$$= \psi(\varphi(A)_i^j e_j) = \varphi(A)_i^j \psi(e_j) = \varphi(A)_i^j \hat{e}_j$$

$$\Rightarrow A \mapsto \det(\varphi(A)_i^j) \text{ is continuous.}$$

Exercise 2.6: $\varphi: \text{SU}(2) \rightarrow \text{SO}(3)$ is onto & $\text{Ker}(\varphi) = \{\pm I\}$

recall $\psi: \mathbb{R}^3 \rightarrow \text{su}(2)$ is an isometry. & $\varphi(A) = \psi^{-1} \circ \tilde{\varphi}(A) \circ \psi$
 $\therefore \varphi(AB) = \psi^{-1} \circ \tilde{\varphi}(AB) \circ \psi = \psi^{-1} \circ \tilde{\varphi}(A) \tilde{\varphi}(B) \circ \psi = \psi^{-1} \circ \tilde{\varphi}(A) \circ \psi \circ \psi^{-1} \circ \tilde{\varphi}(B) \circ \psi = \varphi(A) \varphi(B)$ (φ is group homomorphism - this is why we can speak of its kernel)

note: $\tilde{\varphi}(AB)(\mathbf{x}) = AB \mathbf{x} (AB)^{-1} = A(B \mathbf{x} B^{-1}) A^{-1} = \tilde{\varphi}(A) \tilde{\varphi}(B)(\mathbf{x})$

$$R_x^\theta = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & \sin \theta \\ 0 & -\sin \theta & \cos \theta \end{pmatrix}, R_y^\theta = \begin{pmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{pmatrix} \in \text{SO}(3)$$

Nice

$$R_x^\theta R_y^\phi (0,0,1) = R_x^\theta (\sin \phi, 0, \cos \phi) = (\sin \phi, \sin \theta \cos \phi, \cos \theta \cos \phi)$$

$\Rightarrow$ by choosing appropriate angles we can rotate to anywhere on the sphere (S^2)

define an action of $\text{SU}(2)$ on $S^2 (= \{x \in \mathbb{R}^3 \mid \|x\| = 1\})$
 by $A \cdot x = \varphi(A)(x)$

note: $(AB) \cdot x = \varphi(AB)(x) = \varphi(A) \varphi(B)(x) = \varphi(A)(B \cdot x) = A \cdot (B \cdot x)$

and $I \cdot x = \varphi(I)(x) = I(x) = x \therefore$ this is an action $\checkmark$

(a) Let $x \in S^2$ then $\exists R_x^\theta, R_y^\phi \in \text{SO}(3) \ni R_x^\theta R_y^\phi (0,0,1) = x$
 φ is onto & $R_x^\theta R_y^\phi \in \text{SO}(3) \Rightarrow \exists A \in \text{SU}(2) \ni \varphi(A) = R_x^\theta R_y^\phi$

$\Rightarrow A \cdot (0,0,1) = \varphi(A)(0,0,1) = R_x^\theta R_y^\phi (0,0,1) = x$
 $\therefore \text{SU}(2) \cdot (0,0,1) = S^2$ hence the action is transitive.

(b) Let $\{e_i\}$ be the standard basis for $\mathbb{R}^3$

$$e_3 = (0,0,1) \longmapsto \hat{e}_3 = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

stabilizer of e_3

$$\S A \in \text{SU}(2)_{e_3} \iff A \cdot e_3 = e_3 \iff \Psi(A)(e_3) = e_3$$

$$\iff \Psi^{-1} \circ \tilde{\Psi}(A) \circ \Psi(e_3) = e_3 \iff \tilde{\Psi}(A) \circ \Psi(e_3) = \Psi(e_3)$$

rewrite:

$$\tilde{\Psi}(A)(\hat{e}_3) = \hat{e}_3 \iff A\hat{e}_3A^{-1} = \hat{e}_3 \checkmark$$

$$\S A\hat{e}_3A^{-1} = \hat{e}_3. \text{ Let } A = \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \quad (|\alpha|^2 + |\beta|^2 = 1)$$

$$\begin{aligned} \therefore A^{-1} &= \begin{pmatrix} \bar{\alpha} & -\beta \\ \bar{\beta} & \alpha \end{pmatrix} \text{ hence } A\hat{e}_3A^{-1} = \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \begin{pmatrix} \bar{\alpha} & -\beta \\ \bar{\beta} & \alpha \end{pmatrix} \\ &= \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \begin{pmatrix} \bar{\alpha}i & -\beta i \\ -\bar{\beta}i & -\alpha i \end{pmatrix} = \begin{pmatrix} (|\alpha|^2 - |\beta|^2)i & -2\alpha\beta i \\ -2\bar{\alpha}\bar{\beta}i & -(|\alpha|^2 - |\beta|^2)i \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \end{aligned}$$

$$\Rightarrow -2\alpha\beta i = 0 \text{ hence either } \alpha = 0 \text{ or } \beta = 0$$

$$\S \alpha = 0 \text{ then } -|\beta|^2 i = i \Rightarrow |\beta|^2 = -1 \rightarrow \leftarrow \therefore \beta = 0$$

$$\text{hence } A = \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \text{ and } |\alpha|^2 + |\beta|^2 \stackrel{0}{=} |\alpha|^2 = 1 \checkmark$$

$$\S A = \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \& |\alpha|^2 = 1 \Rightarrow A^{-1} = \begin{pmatrix} \bar{\alpha} & 0 \\ 0 & \alpha \end{pmatrix} \text{ and}$$

$$\begin{aligned} A\hat{e}_3A^{-1} &= \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} \begin{pmatrix} \bar{\alpha} & 0 \\ 0 & \alpha \end{pmatrix} = \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \begin{pmatrix} \bar{\alpha}i & 0 \\ 0 & -\alpha i \end{pmatrix} = \\ &= \begin{pmatrix} |\alpha|^2 i & 0 \\ 0 & -|\alpha|^2 i \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = \hat{e}_3 \end{aligned}$$

$$\therefore \text{SU}(2)_{e_3} = \left\{ \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \mid \alpha \in \mathbb{C} \& |\alpha|^2 = 1 \right\}$$

(c) $SU(2)_{e_3} = \left\{ \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \mid |\alpha|=1 \right\}$ is obviously a closed subgroup of $SU(2)$

$\therefore$ We get a P.F.B. $SU(2) \rightarrow \cancel{SU(2)}_{SU(2)_{e_3}}$ with fiber $SU(2)_{e_3}$

but $\cancel{SU(2)}_{SU(2)_{e_3}} \cong SU(2) \cdot \overset{\text{transitive}}{\downarrow} e_3 = \overset{\downarrow}{S^2}$ (orbit/stabilizer thm)

and $\Theta: SU(2)_{e_3} \rightarrow U(1)$ defined by $\Theta \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} = \alpha$

is an isomorphism (obviously smooth)

$\square \bullet \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \in SU(2)_{e_3} \Rightarrow |\alpha|=1 \Rightarrow \alpha \in U(1) \checkmark$

$$\bullet \nexists \Theta \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} = 0 \Rightarrow \alpha = 0 \Rightarrow \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\bullet \nexists \alpha \in U(1) \Rightarrow |\alpha|=1 \Rightarrow \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \in SU(2)_{e_3} \text{ \& } \Theta \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} = \alpha$$

$$\square \bullet \overset{\text{onto}}{\Theta} \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \begin{pmatrix} \beta & 0 \\ 0 & \bar{\beta} \end{pmatrix} = \Theta \begin{pmatrix} \alpha\beta & 0 \\ 0 & \overline{\alpha\beta} \end{pmatrix} = \alpha\beta = \Theta \begin{pmatrix} \alpha & 0 \\ 0 & \bar{\alpha} \end{pmatrix} \Theta \begin{pmatrix} \beta & 0 \\ 0 & \bar{\beta} \end{pmatrix}$$

$$\therefore SU(2)_{e_3} \cong U(1)$$

Hence we have a P.F.B. $\begin{matrix} SU(2) \\ \downarrow \pi \\ S^2 \end{matrix}$ with fiber $U(1)$

$$\cong \pi_1(S^2 \times U(1))$$

$$(d) \nexists SU(2) = S^2 \times U(1) \Rightarrow \pi_1(SU(2)) = \pi_1(S^2) \times \pi_1(U(1))$$

$$\text{but } U(1) \cong S^1 \therefore \pi_1(U(1)) = \mathbb{Z} \text{ \& } \pi_1(S^2) = \{0\}$$

$$\text{but } SU(2) \cong S^3 \therefore \pi_1(SU(2)) = \pi_1(S^3) = \{0\} \neq \mathbb{Z} \times \{0\}$$

$\Rightarrow SU(2)$ is not a trivial bundle. //

Exercise 2.5 Let $SU(2)$ denote the set of all matrices $A \in GL(2, \mathbb{C})$ such that $\bar{A}^t A = I$, $\det A = 1$

(a) Show that $A \in SU(2)$ iff $A = \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix}$ for $\alpha, \beta \in \mathbb{C}$, $|\alpha|^2 + |\beta|^2 = 1$.

(b) The Lie algebra $\mathfrak{su}(2)$ of $SU(2)$ is a sub-Lie algebra of the Lie algebra $\mathfrak{gl}(2, \mathbb{C})$ of $GL(2, \mathbb{C})$. Show that $B \in \mathfrak{su}(2)$ iff $\bar{B}^t + B = 0$ and $\text{Tr } B = 0$, then show that this is true iff $B = \hat{x}$ for some $x \in \mathbb{R}^3$. Here $\hat{x}$ is defined by

$$\hat{x} = \begin{pmatrix} ix_3 & -x_2 + ix_1 \\ x_2 + ix_1 & -ix_3 \end{pmatrix}$$

Show that the mapping from $\mathbb{R}^3$ to $\mathfrak{su}(2)$ defined by $x \rightarrow \hat{x}$ is a vector space isomorphism.

Standard dot product

(c) For $x, y \in \mathbb{R}^3$ show that $\langle x, y \rangle = -\frac{1}{2} \text{Tr}(\hat{x}\hat{y})$ and that $\|x\|^2 = \det(\hat{x})$. It follows that we have an inner product $\langle, \rangle_0$ defined on $\mathfrak{su}(2)$ by $\langle \hat{x}, \hat{y} \rangle_0 \equiv -\frac{1}{2} \text{Tr}(\hat{x}\hat{y})$ relative to which $x \rightarrow \hat{x}$ is an isometry and $\|\hat{x}\|_0^2 = \det \hat{x}$.

(d) Let $\varphi: SU(2) \rightarrow \text{End}(\mathfrak{su}(2))$ be defined by $\varphi(A)(X) = A X A^{-1}$ for $X \in \mathfrak{su}(2)$. Explain why $A X A^{-1} \in \mathfrak{su}(2)$ for $X \in \mathfrak{su}(2)$ and show that

$$\langle \tilde{\varphi}(A)(\underline{X}), \tilde{\varphi}(A)(\underline{Y}) \rangle_0 = \langle \underline{X}, \underline{Y} \rangle_0$$

for all $\underline{X}, \underline{Y} \in \mathfrak{su}(2)$.

(e) Define $\varphi: \mathrm{SU}(2) \rightarrow \mathrm{GL}(3, \mathbb{R})$ by

$$\widehat{\varphi(A)(\underline{x})} = \tilde{\varphi}(A)(\hat{\underline{x}})$$

for all $\underline{x} \in \mathbb{R}^3$. Show that this is well-defined by showing that $\varphi(A): \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is invertible. This should follow from the fact that $\tilde{\varphi}(A)$ is invertible which in turn should be a consequence of the identity at the top of the page.

(f) Show that $\varphi(A) \in \mathrm{O}(3) \quad \forall A \in \mathrm{SU}(2)$ by showing that $\langle \varphi(A)(\underline{x}), \varphi(A)(\underline{y}) \rangle = \langle \underline{x}, \underline{y} \rangle$ for all $\underline{x}, \underline{y} \in \mathbb{R}^3$. If $\{\underline{e}_i\}$ is the standard basis of $\mathbb{R}^3$ write $\varphi(A)(\underline{e}_i) = \varphi(A)_i^j \underline{e}_j$ so that $A \rightarrow (\varphi(A)_i^j)$ is a map from $\mathrm{SU}(2)$ into 3×3 matrices. Show that the matrix of $\tilde{\varphi}(A)$ relative to $\{\hat{\underline{e}}_i\}$ satisfies $\tilde{\varphi}(A)(\hat{\underline{e}}_i) = \varphi(A)_i^j \hat{\underline{e}}_j$. Thus $A \rightarrow \det(\varphi(A)_i^j)$ is continuous. Use this to show that $\varphi(\mathrm{SU}(2)) \subseteq \mathrm{SO}(3)$.

Exercise 2.6 It may be shown that

$\varphi: SU(2) \rightarrow SO(3)$ of Exercise 2.5 is "onto" and that $\text{Ker } \varphi = \{\pm I\}$. Define an action of $SU(2)$ on the 2-sphere

$$S^2 = \{x \in \mathbb{R}^3 \mid \|x\| = 1\}$$

by $(A, x) \mapsto \varphi(A)x$, $A \in SU(2)$, $x \in S^2$.

(a) Show that the action $SU(2) \times S^2 \rightarrow S^2$ is transitive.

(b) If $\{e_i\}$ is the standard basis of $\mathbb{R}^3$ show that $A \in SU(2)$ is in the isotropy subgroup of $e_3 \in \mathbb{R}^3$ iff $A \hat{e}_3 A^{-1} = \hat{e}_3$ which is true iff

$$A = \begin{pmatrix} \alpha & 0 \\ 0 & +\bar{\alpha} \end{pmatrix} \quad \alpha \in \mathbb{C}, |\alpha| = 1.$$

see notes (c) Show that $SU(2) \rightarrow S^2$ is a principal fiber bundle with fiber a Lie subgroup of $SU(2)$ which is isomorphic to $U(1) = \{z \in \mathbb{C} \mid |z| = 1\}$

(d) It is known that the fundamental group of a product of two spaces is the product of the fundamental groups:

$$\pi_1(P \times Q) = \pi_1(P) \times \pi_1(Q)$$

Use this fact to show that the principal fiber bundle $SU(2) \rightarrow S^2$ is not trivial

$$\begin{array}{c} \uparrow \\ \text{Simply connected} \\ \pi_1(S^1) = \mathbb{Z} \end{array}$$

Let $P \xrightarrow{\pi} M$ be a principal fiber bundle with structure group G . Let F be a manifold. $\nexists G$ acts on the left of F .

Define $\sigma: (P \times F) \times G \rightarrow P \times F$ by $\sigma(u, z, g) = (u \cdot g, \bar{g}^1 \cdot z)$
 σ is smooth because the actions & inversion in G are smooth. ✓

Exercise 2.7:

$$(1) \sigma(u, z, g_1 g_2) = (u \cdot (g_1 g_2), (g_1 g_2)^1 \cdot z) = (u \cdot g_1 \cdot g_2, \bar{g}_2^1 (\bar{g}_1^1 \cdot z))$$

$$= \sigma((u \cdot g_1), (\bar{g}_1^1 \cdot z), g_2) = \sigma(\sigma(u, z, g_1), g_2) \quad \checkmark$$

$$\sigma(u, z, e) = (u \cdot e, \bar{e}^1 \cdot z) = (u, z) \quad \checkmark$$

$\Rightarrow \sigma$ is a right action

(2) Let $\tau: P \times F \rightarrow M$ be defined by $\tau(u, z) = \pi(u)$

$$\tau((u, z) \cdot g) = \tau(u \cdot g, \bar{g}^1 \cdot z) = \pi(u \cdot g) = \pi(u)$$

(the group action moves us up & down the fiber)

$$\Rightarrow \tau((u, z) \cdot g) = \pi(u) = \tau(u, z) \quad \forall (u, z) \in P \times F, g \in G \quad \checkmark$$

Let $(u, z)_G = \{(u, z)g \mid g \in G\}$ (the G -orbit of (u, z))

$\tilde{\tau}: P \times F / G \rightarrow M$ defined by $\tilde{\tau}((u, z)_G) \equiv \tau(u, z) = \pi(u)$
 is well defined.

$$\nexists (v, y) \in (u, z)_G \Rightarrow \exists g \in G \ni (v, y) = (u, z) \cdot g$$

$$\therefore \tilde{\tau}((u, z)_G) = \tau((u, z) \cdot g) = \tau(u, z) = \pi(u) \quad \checkmark$$

(3) Let $x \in M$ and $u_0 \in \pi^{-1}\{x\}$

$$\nexists (u, z)_G \in \tilde{\tau}^{-1}(x) \Rightarrow \tilde{\tau}((u, z)_G) = \pi(u) = x \therefore u \in \pi^{-1}(x)$$

hence $\exists g \in G \ni u_0 \cdot g = u$ (action is transitive on fibers)

$$(u_0, g \cdot z) \cdot g = (u_0 \cdot g, \bar{g}^1 g \cdot z) = (u, z) \Rightarrow$$

$$(u, z)_G = (u_0, g \cdot z)_G \in \{(u_0, z)_G \mid z \in F\}$$

$$\forall z \in F \text{ then } \tilde{\pi}((u_0, z)_G) = \pi(u_0) = x \Rightarrow (u_0, z)_G \in \tilde{\pi}^{-1}\{x\}$$

$$\therefore \tilde{\pi}^{-1}\{x\} = \{(u_0, z)_G \mid z \in F\} \quad (\subseteq P \times \cancel{F}_G)$$

$$\Rightarrow \omega: F \rightarrow \tilde{\pi}^{-1}(x) \text{ def. by } \omega(z) = (u_0, z)_G \text{ is onto}$$

$$\forall \omega(z_1) = \omega(z_2) \Rightarrow (u_0, z_1)_G = (u_0, z_2)_G$$

$$\therefore (u_0, z_1) = (u_0, z_2) \cdot g \text{ for some } g \in G$$

$$\Rightarrow (u_0, z_1) = (u_0 \cdot g, g^{-1} \cdot z_2) \Rightarrow u_0 = u_0 \cdot g \Rightarrow g = e$$

(because the action is free)

$$\therefore z_1 = e^{-1} \cdot z_2 = z_2 \Rightarrow \omega \text{ is 1-1} \quad \therefore z \mapsto (u_0, z)_G \text{ is a bijection} \checkmark$$

(4) Let $\Delta: U \rightarrow P$ be a local section of π also define $\Phi_U: U \times F \rightarrow \tilde{\pi}^{-1}(U)$ by $\Phi_U(x, z) = (\Delta(x), z)_G$

$$\text{We know } \tilde{\pi}^{-1}(U) = \bigcup_{x \in U} \tilde{\pi}^{-1}\{x\} = \bigcup_{x \in U} \{(u_x, z)_G \mid z \in F\}$$

$$= \{(u_x, z)_G \mid x \in U, z \in F\} \text{ where } u_x \text{ is a fixed element of } \pi^{-1}\{x\} \text{ we can choose } \Delta(x) = u_x.$$

$$\Rightarrow w \in \tilde{\pi}^{-1}(U) \text{ then } w = (\Delta(x), z)_G \text{ for some } x \in U, z \in F$$

$$\Rightarrow \Phi_U(x, z) = (\Delta(x), z)_G = w \text{ hence } \Phi_U \text{ is onto.}$$

$\Phi \Phi_u(x, z) = \Phi_u(x_1, z_1) \Rightarrow (\Delta(x), z)_G = (\Delta(x_1), z_1)_G$
 hence $x = \pi(\Delta(x)) = \tau((\Delta(x), z)_G) = \tau((\Delta(x_1), z_1)_G) = \pi(\Delta(x_1)) = x_1$
 but $z \mapsto (u_0, z)_G$ is a bijection hence $(\Delta(x), z)_G = (\Delta(x), z_1)_G$
 $\Rightarrow z = z_1 \therefore (x, z) = (x_1, z_1) \Rightarrow \Phi_u$ is a bijection $\checkmark$

$\mathcal{F}M \xrightarrow{\pi} M$ be the frame bundle
 and denote an action of $GL(n)$ on $(\mathbb{R}^n)^*$, $g \cdot \alpha$
 where $(g \cdot \alpha)(x) = \alpha(g^{-1}x) \forall x \in \mathbb{R}^n$

define

$\rho: \mathcal{F}M \times (\mathbb{R}^n)^* \rightarrow T^*M$ by $\rho((p, \{e_i\}), \alpha) = \alpha_i e^i$
 (where $\alpha \in (\mathbb{R}^n)^* \Rightarrow \alpha = \alpha_i n^i$, $\{n_i\}$ & $\{n^i\}$ is the standard basis and its dual) e^i is a basis for $(T_p M)^* \Rightarrow \alpha_i e^i \in (T_p M)^*$

Now let $g \in GL(n)$ then $(g^{-1} \cdot \alpha)(n_i) = \alpha(g n_i) = \alpha(g_j^i n_j)$
 $= g_j^i \alpha(n_j) = g_j^i \alpha_j$

$\therefore ((p, \{e_i\}), \alpha) \cdot g = ((p, \{e_i\}) \cdot g, g^{-1} \cdot \alpha) = ((p, \{e_j g_j^i\}), g_j^i \alpha_j n^j)$
 hence $\rho((p, \{e_i\}), \alpha) \cdot g = g_j^i \alpha_j g_l^j e^l = g_j^i g_l^j \alpha_j e^l = \delta_l^i \alpha_j e^l = \alpha_i e^i$
 $= \rho((p, \{e_i\}), \alpha) \checkmark$ hence constant on orbits

So we can induce a mapping $\tilde{\rho}: \mathcal{F}M \times_{GL(n)} (\mathbb{R}^n)^* \rightarrow T^*M$

Now construct an inverse by, $\zeta(x, \gamma) = ((x, \{e_i\}), \gamma(e_i) n^i)_{GL(n)}$
 where $\{e_i\}$ is any basis of $T_x M$. Let $\{f_i\}$ be any other basis.

then $f_i = g_j^i e_j$ for some $g = (g_j^i) \in GL(n)$

$((x, \{f_i\}), \gamma(f_i) n^i) = ((x, \{g_j^i e_j\}), g_j^i \gamma(e_j) n^i) = ((x, \{e_j\}) \cdot g, g^{-1} \cdot (\gamma(e_j) n^j))$
 $= ((x, \{f_i\}), \gamma(e_i) n^i) \cdot g \Rightarrow$ They are in the same orbit

$\Rightarrow \zeta$ is well defined. $\checkmark$

$\zeta \cdot \tilde{\rho}((p, \{e_i\}), \alpha) \cdot GL(n) = \zeta(p, \alpha_i e^i) = ((p, \{e_i\}), \alpha_i e^i (e_j^i) n^j)$
 $= ((p, \{e_i\}), \alpha_j n^j) = ((p, \{e_i\}), \alpha)$

$\tilde{\rho} \cdot \zeta(p, \gamma) = \tilde{\rho}((p, \{e_i\}), \gamma(e_j) n^j) \cdot GL(n) = (p, \gamma(e_j) e^j)$
 $= (p, \gamma) \therefore \tilde{\rho}^{-1} = \zeta \checkmark$

ρ is smooth & since it is constant on orbits it induces a smooth map $\bar{\rho}$.

Take a chart on T^*M say $(T^*U, T^*\chi)$
 where $(p, \alpha) \in T^*U$ then $T^*\chi(x, \alpha) = (x(p), (\alpha_i(p)))$
 where $\alpha = \alpha_i(p) d_p x^i$

And a chart on $\mathbb{F}M$ say $(\mathbb{F}U, \mathbb{F}\chi)$
 where $(p, \{e_i\}) \in \mathbb{F}U$ then $\mathbb{F}\chi(p, \{e_i\}) = (x(p), (A_j^i))$
 where $e_i = A_j^i \frac{\partial}{\partial x_j}|_p$. let $\tilde{\chi} = \widehat{\mathbb{F}\chi} \times \underset{=P}{\mathbb{Y}}$ $\mathbb{Y}(\alpha_i, r^i) = (\alpha_i)$

$$\tilde{\chi} \circ \zeta \circ T^*\chi^{-1}((c_i), (\alpha_i)) = \tilde{\chi} \circ \zeta(\tilde{\chi}^{-1}(c_i), \alpha_i d_p x^i)$$

$$= \tilde{\chi}((\tilde{\chi}^{-1}(c_i), \{\frac{\partial}{\partial x_j}|_p\}), \alpha_i r^i) \cdot \text{Id}(n)$$

$$= (\chi \circ \tilde{\chi}^{-1}(c_i), I) \times (\alpha_i) = ((c_i), I, (\alpha_i)) \text{ which is smooth}$$

$\Rightarrow \zeta$ is smooth

Thus we have a bundle isomorphism:

$$\begin{array}{ccc} T^*M & \xrightarrow{\zeta} & (\mathbb{F}M \times (\mathbb{R}^n)^*) / \text{Id}(n) \\ & \searrow & \swarrow \\ & M & \end{array}$$

Exercise 2.8: $\mathcal{FM} \xrightarrow{\pi} M$ the frame bundle and denote an action of $\mathcal{GL}(n)$ on $T^*_1\mathbb{R}^n$ by $g \cdot \lambda$ where
 $(g \cdot \lambda)(x, \alpha) = \lambda(\tilde{g}^{-1}x, \tilde{g}^{-1}\alpha) \quad \forall x \in \mathbb{R}^n, \alpha \in (\mathbb{R}^n)^*, \lambda \in T^*_1\mathbb{R}^n, g \in \mathcal{GL}(n)$
 define

$\rho: \mathcal{FM} \times T^*_1\mathbb{R}^n \rightarrow T^*_1M$ by $\rho((p, \{e_i\}), \lambda) = (p, \lambda^i_j e^j \otimes e_i)$
 (where $\lambda \in T^*_1\mathbb{R}^n \Rightarrow \lambda^i_j n^j \otimes n_i$, $\{n_i\}$ & $\{n^i\}$ is the standard basis and its dual) e_i is a basis for $T_p M$, e^i is a basis for $(T_p M)^* \Rightarrow e^i \otimes e_j$ is a basis for $(T^*_1M)_p \Rightarrow (p, \lambda^i_j e^j \otimes e_i) \in T^*_1M$ ✓

Now let $g \in \mathcal{GL}(n)$ then as before $(g^{-1} \cdot \alpha)(n_j) = g^{-1}_j \alpha_i$ and
 $g^{-1} \cdot x(n^i) = \tilde{g}^i_j x^j \Rightarrow (g \cdot \lambda)(n_i, n^i) = \lambda(\tilde{g}^l_i n_l, g^k_j n^k) =$
 $\tilde{g}^l_i g^k_j \lambda(n_l, n^k) = \tilde{g}^l_i g^k_j \lambda^k_l$

$$\Rightarrow ((p, \{e_i\}), \lambda) \cdot g = ((p, \{e_i\}) \cdot g, g^{-1} \cdot \lambda) \\ = ((p, \{e_j g^j_i\}), g^l_i \tilde{g}^k_j \lambda^k_l n^j \otimes n_i)$$

$$\therefore \rho((p, \{e_i\}), \lambda) \cdot g = \rho((p, \{e_j g^j_i\}), g^l_i \tilde{g}^k_j \lambda^k_l n^j \otimes n_i) \\ = g^l_i \tilde{g}^k_j \lambda^k_l (e^a \tilde{g}^i_a) \otimes (e_b g^j_b) = \tilde{g}^i_a g^l_i \tilde{g}^k_j g^j_b \lambda^k_l e^a \otimes e_b \\ = \delta^l_a \delta^k_b \lambda^k_l e^a \otimes e_b = \lambda^b_a e^a \otimes e_b = \lambda^b_a e^a \otimes e_b = \rho((p, \{e_i\}), \lambda)$$

$\therefore \rho$ is constant on the orbits.

hence we get an induced map $\tilde{\rho}: \mathcal{FM} \times T^*_1\mathbb{R}^n / \mathcal{GL}(n) \rightarrow T^*_1M$

As before we now construct the inverse: $\zeta: T^*_1M \rightarrow \mathcal{FM} \times T^*_1\mathbb{R}^n / \mathcal{GL}(n)$

$\zeta(x, \lambda) = ((x, \{e_i\}), \lambda(e_i, e^j) n^j \otimes n_i)_{\mathcal{GL}(n)}$ where $\{e_i\}$ is any basis for $T_x M$ and $\{e^i\}$ is its dual. Let $\{f_i\}$ be any other basis for $T_x M$ (with dual $\{f^i\}$) Then $f_i = g^j_i e_j$ & $f^i = \tilde{g}^i_j e^j$ for some

$$g = (g^j_i) \in \mathcal{GL}(n), ((x, \{f_i\}), \lambda(f_i, f^j) n^j \otimes n_i) = \\ ((x, \{g^k_j e_k\}), \lambda(g^a_i e_a, \tilde{g}^j_b e^b) n^j \otimes n_i) = ((x, \{e_k\}) \cdot g, g^a_i \tilde{g}^j_b \lambda(e_a, e^b) n^j \otimes n_i) \\ = ((x, \{e_k\}) \cdot g, g^{-1} \cdot (\lambda(e_a, e^b) n^a \otimes n_b)) = ((x, \{e_k\}), \lambda(e_a, e^b) n^a \otimes n_b) \cdot g \\ \Rightarrow \text{they are in the same orbit} \therefore \text{choice of basis doesn't matter} \\ \Rightarrow \zeta \text{ is well defined} \checkmark$$

$$(\lambda = \lambda^i_j n^j \otimes n_i)$$

$$\zeta \circ \tilde{\rho}((p, \{e_i\}), \lambda)_{\mathcal{GL}(n)} = \zeta(p, \lambda^i_j e^j \otimes e_i) = (p, \{e_i\}), \text{ back } \hookrightarrow$$

$$\begin{aligned} \lambda_j^i e^j \otimes e_i (e_a, e^b) \eta^a \otimes \eta_b)_{\text{geom}} &= (p, \{e_i\}), \lambda_j^i \delta_a^j \delta_i^b \eta^a \otimes \eta_b)_{\text{geom}} \\ &= (p, \{e_i\}), \lambda_a^b \eta^a \otimes \eta_b)_{\text{geom}} = (p, \{e_i\}), \lambda)_{\text{geom}} \checkmark \end{aligned}$$

$$\begin{aligned} \tilde{\mathcal{C}} \circ \mathcal{F}(p, \lambda) &= \tilde{\mathcal{C}}((p, \{e_i\}), \lambda(e_i, e^j) \eta^i \otimes \eta_j)_{\text{geom}} \\ &= (p, \lambda(e_i, e^j) e^i \otimes e_j) = (p, \lambda) \checkmark \end{aligned}$$

$\therefore \tilde{\mathcal{C}} = \mathcal{F}^{-1}$ hence $\mathcal{F}$ is 1-1/onto

$\mathcal{F}^{-1} = \tilde{\mathcal{C}}$ is smooth as in Exercise 2.7 $\checkmark$

Take a chart on T_1^*M say (T_1^*U, T_1^*x)
 where $(p, \lambda) \in T_1^*U$ then $T_1^*x(p, \lambda) = (x(p), (\lambda_i^j))$
 where $\lambda = \lambda_i^j d_p x^i \otimes \frac{\partial}{\partial x^j}|_p$

And take a chart on $\overline{\mathcal{F}}M$ say $(\overline{\mathcal{F}}U, \overline{\mathcal{F}}x)$
 where $(p, \{e_i\}) \in \overline{\mathcal{F}}U$ then $\overline{\mathcal{F}}x(p, \{e_i\}) = (x(p), (A_i^j))$
 where $e_i = A_i^j \frac{\partial}{\partial x^j}|_p$ let $\tilde{x} = \overline{\mathcal{F}}x \times y$ $y(\lambda_i^j \eta^i \otimes \eta_j) = (\lambda_i^j)$

$$\begin{aligned} \tilde{x} \circ \mathcal{F} \circ (T_1^*x)^{-1}(c_i), (\lambda_i^j)) &= \tilde{x} \circ \mathcal{F}(\tilde{x}^{-1}(c_i)^p, \lambda_i^j d_p x^i \otimes \frac{\partial}{\partial x^j}|_p) \\ &= \tilde{x}((\tilde{x}^{-1}(c_i), \{\frac{\partial}{\partial x^j}|_p\}), \lambda_i^j \eta^i \otimes \eta_j)_{\text{geom}} \end{aligned}$$

$$= (x \circ \tilde{x}^{-1}(c_i), I) \times (\lambda_i^j) = (c_i, I, \lambda_i^j) \Rightarrow \mathcal{F} \text{ is smooth}$$

Thus we have a bundle isomorphism:

$$T_1^*M \xrightarrow{\mathcal{F}} (\overline{\mathcal{F}}M \times T_1^*(\mathbb{R}^n))_{\text{geom}}$$



Due: 4/26

1

Assume that $P \xrightarrow{\pi} M$ is a PFB with structure group G and that G acts on the left of some manifold F . Define a mapping σ from $(P \times F) \times G \rightarrow P \times F$ by $((u, \xi), g) \rightarrow (ug, \bar{g}^{-1}\xi)$. The mapping is clearly smooth.

Exercise 2.7

(1) Show that σ is a right action of G on $P \times F$.

(2) Let $\tau : P \times F \rightarrow M$ be defined by $\tau(u, \xi) = \pi(u)$.

Show that $\tau((u, \xi)g) = \tau(u, \xi) \quad \forall (u, \xi) \in P \times F, g \in G$ and that one obtains a well-defined function

$\tilde{\tau} : P \times F / G \rightarrow M$ defined by $\tilde{\tau}((u, \xi)_G) = \tau(u, \xi) = \pi(u)$.

where $(u, \xi)_G = \{ (u, \xi)g \mid g \in G \}$ is the G orbit of (u, ξ) in $P \times F$.

(3) Let $x \in M$ and $u_0 \in \pi^{-1}(x)$. Write $w_0 = (u_0, \xi_0)_G$ for some arbitrary $\xi_0 \in F$. Show that

$$\tilde{\tau}^{-1}(x) = \{ (u_0, \xi)_G \mid \xi \in F \}$$

and that $\xi \mapsto (u_0, \xi)_G$ is a bijection from F onto $\tilde{\tau}^{-1}(x)$.

(4) Let $\lambda : U \rightarrow P$ be a local section of π

and show that $\Phi_U : U \times F \rightarrow \tilde{\tau}^{-1}(U)$

defined by $\Phi_U(x, \xi) = (\lambda(x), \xi)_G$ is a bijection.

Let $P = FM \xrightarrow{\pi} M$ denote the frame bundle.
 $GL(n)$ acts on $(\mathbb{R}^n)^*$ via $(g, \alpha) \rightarrow g \cdot \alpha$
 where $(g \cdot \alpha)(x) = \alpha(g^{-1}x) \quad \forall x \in \mathbb{R}^n$.

Consider the bundle $(FM \times (\mathbb{R}^n)^*) / GL(n)$.

We show that it is really T^*M . To
 show this first define a mapping p from
 $FM \times (\mathbb{R}^n)^* \rightarrow T^*M$ as follows:

$$p((p, e_i), \alpha) = \alpha_i e^i.$$

Notice that $\alpha \in (\mathbb{R}^n)^*$ implies $\alpha = \alpha_i r^i$
 where $\{r_i\}$ is the standard basis of $\mathbb{R}^n$
 and $\{r^i\}$ is the dual basis. So the α_i
 are components of α relative to $\{r^i\} \subseteq (\mathbb{R}^n)^*$.

But $\{e_i\}$ is a basis of $T_p M$ and so
 $\{e^i\}$ is the dual basis in $T_p^* M$. Thus
 $\alpha_i e^i \neq \alpha$ as it is in $T_p^* M$. We
 show p is constant on orbits of the action
 of G on $FM \times (\mathbb{R}^n)^*$. This action is

$$\text{defined by } (p, e_i), \alpha \cdot g = (p, e_i) \cdot g, g^{-1} \cdot \alpha$$

$$\text{But } (p, e_i) \cdot g = (p, \{e_j g^j_i\}) \text{ and}$$

$$(g^{-1} \alpha) = g^j_i \alpha_j r^i \text{ since}$$

$$(\bar{g}^i \alpha)_i = (\bar{g}^i \alpha)(r_i) = \alpha(g r_i) = \alpha(g_i^j r_j) = g_i^j \alpha(r_j) = g_i^j \alpha_j$$

But if $f_i = e_j g_i^j$ then the dual basis is $f^k = \bar{g}^k_l e^l$

Thus

$$\begin{aligned} ((p, e_i), \alpha) \cdot g &= ((p, e_i) \cdot g, \bar{g}^i \cdot \alpha) \\ &= ((p, e_j g_i^j), g_i^j \alpha_j r^i) \end{aligned}$$

← ρ replaces r^i with dual to $e_j g_i^j$

$$\begin{aligned} \rho((p, e_i), \alpha) \cdot g &= \rho((p, e_j g_i^j), g_i^j \alpha_j r^i) \\ &= (g_i^j \alpha_j) (\bar{g}^i_r e^r) = \delta^i_r \alpha_j e^r \\ &= \alpha_j e^j = \rho((p, e_i), \alpha) \end{aligned}$$

So ρ is constant on $((p, e_i), \alpha) \cdot \mathcal{GL}(n)$. Thus ρ induces a mapping $\tilde{\rho}: [TM \times (\mathbb{R}^n)^*] / \mathcal{GL}(n) \rightarrow T^*M$

We construct an inverse to $\tilde{\rho}$. Let $\zeta: T^*M \rightarrow [TM \times (\mathbb{R}^n)^*] / \mathcal{GL}(n)$ be defined by $\zeta(x, \gamma) = ((x, \{e_i\}), \gamma(e_i) r^i)$

where $\{e_i\}$ is any basis of $T_x M$. We must show that ζ is well-defined by showing that it is independent of the choice $\{e_i\}$. Let $\{f_i\}$ be any other basis of $T_x M$ and write $f_i = g_i^j e_j$. Clearly $(g_i^j) \in \mathcal{GL}(n)$.

Notice that

$$\begin{aligned} ((x, \{f_i\}), \gamma(f_i) r^i) &= ((x, \{g_i^j e_j\}), g_i^j \gamma(e_j) r^i) \\ &= ((x, \{e_i\}) \cdot g, \bar{g}^i \cdot (\gamma(e_i) r^i)) \end{aligned}$$

(see calculation at top of page 1)

$$= ((x, \{e_i\}), \gamma(e_i)r^i) \cdot g$$

Thus $((x, \{e_i\}), \gamma(e_i)r^i)$ and $((x, \{e_i\}), \gamma(e_i)r^i)$ are on the same $G(n)$ orbit of $TM \times (\mathbb{R}^n)^*$ and $((x, f_i), \gamma(f_i)r_i)_{G(n)} = ((x, e_i), \gamma(e_i)r^i)_{G(n)}$ and so ζ is well-defined. It is easy to check that ζ is the inverse of $\hat{p}$. It is trivial to show that ρ is smooth and since it is constant on orbits it induces a smooth map $\hat{p}$. Smoothness of the inverse requires more effort which we leave to the reader. Thus we have a bundle isomorphism

$$T^*M \xrightarrow{\zeta} (TM \times (\mathbb{R}^n)^*) / G(n)$$

$\swarrow \quad \searrow$
 M

Exercise 2.8 Consider the action of $G(n)$ on $T_1^* \mathbb{R}^n$ defined by $(g \cdot \lambda)(x, \alpha) = \lambda(\tilde{g}^{-1} \cdot x, \tilde{g}^{-1} \cdot \alpha)$. Show that one has a bundle isomorphism $\zeta: T_1^* M \rightarrow (TM \times T_1^* \mathbb{R}^n) / G(n)$

Bill Cook

4/28/2

Ma 756

Exercises 2.7 & 2.8

2.7 extra credit

2.8 ✓ $\frac{18}{19}$

Problem 1: Let $\omega: T(\mathcal{F}(TM)) \rightarrow \mathfrak{gl}(n)$ be a connection on the P.F.B. $\mathcal{F}(TM) \xrightarrow{\pi} M$ where $\dim M = n$.

Let $(U, \chi = (\chi^\mu))$ and $(\bar{U}, \bar{\chi} = (\bar{\chi}^\nu))$ be overlapping charts on M . Also let $\Delta: U \rightarrow \mathcal{F}(TM)$ and $\bar{\Delta}: \bar{U} \rightarrow \mathcal{F}(TM)$ be local sections of π , defined by $\Delta(p) = (p, \{\frac{\partial \chi^\mu}{\partial x^\mu}|_p\})$, $\bar{\Delta}(p) = (p, \{\frac{\partial \bar{\chi}^\nu}{\partial \bar{x}^\nu}|_p\})$

Finally, let $\Gamma_\mu = \Delta^* \omega(\frac{\partial \chi^\mu}{\partial x^\mu})$ and $\bar{\Gamma}_\nu = \bar{\Delta}^* \omega(\frac{\partial \bar{\chi}^\nu}{\partial \bar{x}^\nu})$.

by the Thm on page 264 $\exists!$ mapping $g: U \cap \bar{U} \rightarrow G$ $\exists$

$$\bar{\Delta}(p) = \Delta(p)g(p) \text{ and } (\bar{\Delta}^* \omega)_p = \text{Ad}(g(p)^{-1})(\Delta^* \omega)_p + d_{g(p)} l_{g(p)}^{-1} \circ d_p g$$

$$\begin{aligned} \bar{\Delta}(p) &= (p, \{\frac{\partial \bar{\chi}^\nu}{\partial \bar{x}^\nu}|_p\}) = (p, \{\frac{\partial \chi^\mu}{\partial \bar{x}^\nu} \frac{\partial \bar{x}^\nu}{\partial x^\mu}|_p\}) = (p, \{\frac{\partial \chi^\mu}{\partial x^\mu}|_p\}) \circ (\frac{\partial \bar{x}^\nu}{\partial x^\mu}|_p) \\ &= \Delta(p) \circ g(p) \text{ but } g \text{ is unique hence } g(p) = (\frac{\partial \bar{x}^\nu}{\partial x^\mu}|_p) \end{aligned}$$

Now let $\gamma(t) \in M$ be a curve $\exists \gamma(0) = p$ & $\gamma'(0) = \frac{\partial \bar{\chi}^\nu}{\partial \bar{x}^\nu}|_p (= \partial_\nu(p))$

$$\begin{aligned} \therefore d_{g(p)} l_{g(p)}^{-1} \circ d_p g(\partial_\nu(p)) &= d_{g(p)} l_{g(p)}^{-1} \circ d_p g(\frac{d}{dt}[\gamma(t)]|_{t=0}) \quad \text{use chain rule} \\ &= \frac{d}{dt} [l_{g(p)}^{-1}(g(\gamma(t)))]|_{t=0} = \frac{d}{dt} [g(p)^{-1}g(\gamma(t))]|_{t=0} \\ &= \frac{d}{dt} [g(p)^{-1}]|_{t=0} g(\gamma(0)) + g(p)^{-1} \frac{d}{dt} [g(\gamma(t))]|_{t=0} = g(p)^{-1} d_{\gamma(0)} g(\gamma'(0)) \\ &= g(p)^{-1} d_p g(\partial_\nu(p)) = g(p)^{-1} (\partial_\nu g)(p) \quad \checkmark \end{aligned}$$

$$\begin{aligned} \therefore \bar{\Gamma}_\nu(p) &= (\bar{\Delta}^* \omega)_p(\partial_\nu) = \text{Ad}(g(p)^{-1})(\Delta^* \omega)_p(\partial_\nu) + d_{g(p)} l_{g(p)}^{-1} \circ d_p g(\partial_\nu) \\ &= \text{Ad}(g(p)^{-1}) \Gamma_\nu(p) + g(p)^{-1} (\partial_\nu g)(p) \end{aligned}$$

$$\therefore \bar{\Gamma}_\nu(p) = g(p)^{-1} \Gamma_\nu(p) g(p) + g(p)^{-1} (\partial_\nu g)(p) \quad \checkmark$$

back

$$\overline{\Gamma}_{\mu\delta}^e(p) = [g(p)^{-1} \Gamma_{\mu}(p) g(p) + g(p)^{-1} (\partial_{\mu} g)(p)]_{\delta}^e$$

but $g(p)_{\delta}^e = \frac{\partial x^e}{\partial \bar{x}^{\delta}}|_p$ and $\frac{\partial x^e}{\partial \bar{x}^{\delta}} \frac{\partial \bar{x}^{\delta}}{\partial x^{\mu}}|_p = \delta_{\mu}^e \Rightarrow g(p)^{-1}_{\delta}^e = \frac{\partial \bar{x}^e}{\partial x^{\delta}}|_p$

$$\therefore \overline{\Gamma}_{\mu\delta}^e(p) = \frac{\partial \bar{x}^e}{\partial x^k}|_p \Gamma_{\mu\lambda}^k(p) \frac{\partial x^{\lambda}}{\partial \bar{x}^{\delta}}|_p + \frac{\partial \bar{x}^e}{\partial x^k}|_p \partial_{\mu} \left(\frac{\partial x^k}{\partial \bar{x}^{\delta}}|_p \right)$$

$$\Rightarrow \underline{\overline{\Gamma}_{\mu\delta}^e = \Gamma_{\mu\lambda}^k \frac{\partial \bar{x}^e}{\partial x^k} \frac{\partial x^{\lambda}}{\partial \bar{x}^{\delta}} + \frac{\partial^2 x^k}{\partial x^{\mu} \partial \bar{x}^{\delta}}|_p \frac{\partial \bar{x}^e}{\partial x^k}|_p} \quad \checkmark$$

Problem 2: Make appropriate identifications

$$W^\mu(p) = (\Delta(p), \chi^\mu) G \cong d\chi^\mu$$

$$\text{where } \Delta(p) = (p, \{\partial_\mu \chi^\mu|_p\}) \text{ also, } \alpha(p) = (\Delta(p), \hat{\alpha}(\Delta(p))) G \\ = \hat{\alpha}_\mu(\Delta(p)) (\Delta(p), \chi^\mu) G = \hat{\alpha}_\mu(\Delta(p)) W^\mu(p) \cong \hat{\alpha}_\mu(\Delta(p)) d\chi^\mu$$

$$\text{So, } \alpha \cong \hat{\alpha}_\mu(\Delta(p)) d\chi^\mu = \alpha_\mu(p) d\chi^\mu$$

Using the equation from class we get,

$$(\nabla_{\partial_\mu} \alpha)(p) = (d\alpha_v(\partial_\mu(p)) + [\Delta^* \omega)(\partial_\mu(p)) \cdot \alpha(p)]_v) W^\nu(p)$$

$$= ((\partial_\mu \alpha_v)(p) + [\Gamma_\mu(p) \cdot \alpha(p)]_v) W^\nu(p)$$

$$\cong ((\partial_\mu \alpha_v)(p) + [\Gamma_\mu(p) \cdot \alpha(p)]_v) d\chi^\nu$$

$$(\Gamma_\mu \cdot \alpha)(p) = \Gamma_\mu(p) \cdot \alpha(p) = \Gamma_\mu(p) \cdot (\Delta(p), \hat{\alpha}(\Delta(p))) G$$

$$= -\Gamma_{\mu\lambda}^\nu(p) \alpha_\nu(p) W^\lambda(p) \cong -\Gamma_{\mu\lambda}^\nu(p) \alpha_\nu(p) d\chi^\lambda$$

$$\Rightarrow \boxed{\nabla_{\partial_\mu} \alpha \cong [\partial_\mu \alpha_\lambda - \Gamma_{\mu\lambda}^\nu \alpha_\nu] d\chi^\lambda}$$

handout: 4/24/2

Final Homework

Let $P \xrightarrow{\pi} M$ be a principal fiber bundle with structure group G . Assume there is given a left action $G \times V \xrightarrow{\sigma} V$ on a finite dimensional vector space V and assume that for each $g \in G$ the mapping $v \mapsto \sigma(g, v) = g \cdot v$, $v \in V$, is linear. Define a mapping $\hat{\sigma}: \mathfrak{g} \times V \rightarrow V$ by

$$\hat{\sigma}(\xi, v) = \left. \frac{d}{dt} [\sigma(\exp(t\xi), v)] \right|_{t=0}$$

for $(\xi, v) \in \mathfrak{g} \times V$. Observe that for each $\xi \in \mathfrak{g}$ the mapping $v \mapsto \hat{\sigma}(\xi, v) \equiv \xi \cdot v$, $v \in V$, is also linear.

Let $\text{Hom}_G(P, V)$ denote the linear space of all equivariant mappings from P to V and let $\Gamma_M(P \times_G V)$ denote the set of all sections of $P \times_G V \xrightarrow{\tau} M$.

Theorem There is a vector space isomorphism Ξ from $\text{Hom}_G(P, V)$ onto $\Gamma_M(P \times_G V)$ defined by

$$\Xi(\hat{\varphi}) = \varphi.$$

The mappings $\hat{\varphi}$ and φ are related by the identities: $\varphi(x) = (u_x, \hat{\varphi}(u_x))_G$ where the latter denotes the G orbit of $(u_x, \hat{\varphi}(u_x)) \in P \times V$ for $u_x \in \pi^{-1}(x)$ and $\hat{\varphi}(u) = \hat{\sigma}^{-1}(\varphi(\pi(u)))$ for $u \in P$ and where $\hat{\sigma}$ is the mapping from

↓ V into $\tau^{-1}(\pi(u)) \subseteq P \times_G V$ defined by
 $\hat{u}(\xi) = (u, \xi)G.$

Definition Given a PFB $\pi: P \rightarrow M$ and a principal connection $\omega: TP \rightarrow \mathfrak{g}$ defined on P define the horizontal lift of a vector field X on M to be the vector field $\tilde{X}$ on P such that

$$d\pi(\tilde{X}_u) = X_{\pi(u)} \quad \omega_u(\tilde{X}_u) = 0$$

for all $u \in P$. It may be shown that $\tilde{X}$ exists and is unique given a vector field X on M .

Proposition Let $P \xrightarrow{\pi} M$ be a PFB and ω a principal connection on P . Let X be a vector field defined on an open subset $U \subseteq M$ which is a chart domain and on which a local section $s: U \rightarrow P$ is defined. Then, for each $p \in U$

$$\boxed{\tilde{X}(s(p)) = d_s(X(p)) - \delta_{(s^*\omega)(X_p)}(s(p))}$$

In particular if (x^μ) is a chart of M defined on U then for $A_\mu(p) = (s^*\omega)(\partial_\mu)$,

$$\boxed{\tilde{\partial}_\mu(s(p)) = (\partial_\mu s)(p) - \delta_{A_\mu(p)}(s(p))}$$

Proof Clearly $d_s(X_p) \in T_{A(p)}(S(U)) \subseteq T_{A(p)}P$ and

$$d_{\pi_{A(p)}}(d_s(X_p)) = d_{\pi \circ s}(X_p) = \bar{X}_p = d_{\pi_{A(p)}}(\tilde{X}_{A(p)})$$

$$\text{Thus } d_{\pi_{A(p)}}(\tilde{X}_{A(p)} - d_s(X_p)) = 0 \text{ and } \tilde{X}_{A(p)} - d_s(X_p)$$

is vertical. Since $\delta_{A(p)}: \rightarrow V T_p P$ is an isomorphism there exists $\xi \in \mathfrak{g}$ such

$$\text{that } \tilde{X}_{A(p)} - d_s(X_p) = \delta_{\xi}(A(p)) \text{ and}$$

$$\tilde{X}_{A(p)} = d_s(X_p) + \delta_{\xi}(A(p))$$

$$\text{But } 0 = \omega(\tilde{X}_{A(p)}) = \omega(d_s(X_p)) + \omega(\delta_{\xi}(A(p)))$$

$$\text{and } \xi = -\omega(d_s(X_p)) = -(s^*\omega)(X_p).$$

$$\text{Thus } \tilde{X}_{A(p)} = d_s(X_p) - \delta_{(s^*\omega)(X_p)}(A(p)). \text{ When } X = \partial_\mu,$$

$$\tilde{\partial}_\mu(s(p)) = d_s(\partial_\mu) - \delta_{(s^*\omega)(\partial_\mu)}(A(p)) = (\partial_\mu s)(p) - \delta_{A_\mu(p)}(s(p))$$

Proposition Given $P \xrightarrow{\pi} M$ a PFB, ω a principal connection on P , $G \times V \rightarrow V$ a left action on the finite dimensional vector space V and a vector field X on M it follows that $\tilde{X} \hat{\varphi} \in \text{Hom}_G(P, V)$ for every $\hat{\varphi} \in \text{Hom}_G(P, V)$.

$$\begin{aligned} \text{Proof } \tilde{X}(\hat{\varphi})(u\alpha) &= d_{u\alpha} \hat{\varphi}(\tilde{X}(u\alpha)) = d_{u\alpha} \hat{\varphi}(d_{u\alpha}(\tilde{X}(u))) \\ &= d_u(\hat{\varphi} \circ \alpha)(\tilde{X}(u)) = d_u(\alpha^* \hat{\varphi})(X(u)) \end{aligned}$$

$$= \bar{a}^{-1} d_u \hat{\varphi}(\tilde{X}(u)) = \bar{a}^{-1} \tilde{X}(\hat{\varphi})(u),$$

for each $a \in G$, $u \in P$. Here we have used the identity $d_{ra}(\tilde{X}(u)) = \tilde{X}(ua)$. This follows from the fact that $\tilde{X}(ua) \in T_{ua}P$ is the unique horizontal vector such that $d_{\pi}(\tilde{X}(ua)) = \tilde{X}_{\pi(ua)}$, whereas one also has that $d_{ra}(\tilde{X}(u)) \in d_{ra}(H(u)) = H(ua)$ is horizontal and $d_{\pi}(\tilde{X}(u)) = d_{\pi \circ r_a}(\tilde{X}(u)) = d_{\pi}(\tilde{X}(ua)) = \tilde{X}_{\pi(ua)} = \tilde{X}_{\pi(ua)}$. Uniqueness implies $\tilde{X}(ua) = d_{ra}(\tilde{X}(u))$ as we require.

Definition Let $\pi: P \rightarrow M$ be a PFB with structure group G , $\omega: TP \rightarrow \mathfrak{g}$ a principal connection and $\hat{\varphi} \in \text{Hom}_G(P, V)$ where V is a finite dimensional vector space on which there is a left (linear) action $G \times V \rightarrow V$. The covariant derivative of $\hat{\varphi}$ is the mapping $D\hat{\varphi}: TP \rightarrow \mathfrak{g}$ defined by $(D\hat{\varphi})_u(Y) = d\hat{\varphi}(\text{th } Y)_u$ for $u \in P$, $Y \in T_u P$.

↑ Theorem Given $P \xrightarrow{\pi} M$, $\omega: TP \rightarrow \mathfrak{g}$, $G \times V \rightarrow V$
as above it follows that

$$\boxed{D\hat{\varphi} = d\hat{\varphi} + \omega \cdot \hat{\varphi}},$$

i.e., if $u \in P$ and $Y \in T_u P$,

$$(D\hat{\varphi})_u(Y) = d_u \hat{\varphi}(Y) + \omega_u(Y) \cdot \hat{\varphi}(u).$$

Proof Let $Y \in T_u P$ and observe that $(vY)_u \in VT_u P$
and so $(vY)_u = \delta_{A(u)}^{(u)}$ for some $A(u) \in \mathfrak{g}$.

$$\begin{aligned} \text{But } \omega(Y_u) &= \omega(hY_u) + \omega(vY_u) \\ &= 0 + \omega(\delta_{A(u)}^{(u)}) = A(u) \end{aligned}$$

$$\text{Thus } (vY)_u = \delta_{\omega(Y_u)}^{(u)} = \frac{d}{dt} [u \cdot \exp(t \omega(Y_u))] \Big|_{t=0}$$

$$\begin{aligned} \text{and } d_u \hat{\varphi}(vY)_u &= d_u \hat{\varphi} \frac{d}{dt} [u \exp(t \omega(Y_u))] \Big|_{t=0} \\ &= \frac{d}{dt} [\hat{\varphi}(u \exp(t \omega(Y_u)))] \Big|_{t=0} \\ &= \frac{d}{dt} [\exp(-t \omega(Y_u)) \hat{\varphi}(Y_u)] \Big|_{t=0} \\ &= -\omega(Y_u) \cdot \hat{\varphi}(Y_u) \end{aligned}$$

It follows that

$$\begin{aligned} (D\hat{\varphi})_u(Y_u) &= (d\hat{\varphi})_u(hY_u) \\ &= (d\hat{\varphi})_u(Y_u - (vY)_u) \\ &= (d\hat{\varphi})_u(Y_u) - d_u \hat{\varphi}(vY)_u \end{aligned}$$

$$\begin{aligned}
 &= (d\hat{\varphi})_u(Y_u) - (-\omega(Y_u) \cdot \hat{\varphi}(Y_u)) \\
 &= (d\hat{\varphi})_u(Y_u) + \omega(Y_u) \cdot \hat{\varphi}(Y_u).
 \end{aligned}$$

Definition If $\varphi \in \Gamma_M(P \times_G V)$ and X is a vector field on M then $\nabla_X \varphi$, the covariant derivative of φ in the direction X , is that element of $\text{Hom}_G(PV)$ such that

$$\nabla_X \varphi = \tilde{\Xi}(\tilde{X} \hat{\varphi})$$

where $\varphi = \tilde{\Xi}(\hat{\varphi})$. Thus

$$(\nabla_X \varphi)(x) = (u_x, \tilde{X}(\hat{\varphi})(u_x)G$$

for $u_x \in \pi^{-1}(x)$, $x \in M$.

Theorem Assume that $\varphi \in \Gamma_M(P \times_G V)$ and that $\Delta: U \rightarrow P \times_G V$ is a local section of $P \times_G V \xrightarrow{\tau} M$. Let $\{e_b\}$ be a basis of $\mathfrak{g}$ and $\{v_a\}$ a basis of V , thus $\bar{W}_a(x) = (\Delta(x), v_a)G$ is a basis of $\tau^{-1}(x)$ for each $x \in U$, if $\varphi(x) = \varphi^a(x) \bar{W}_a(x) \forall x \in U$ and $\hat{\varphi}(u) = \hat{\varphi}^a(u) v_a$ for all $u \in P$, then $\varphi^a(x) = \hat{\varphi}^a(\Delta(x))$ for all $x \in U$. Moreover if $(\nabla_X \varphi)(x) = (\nabla_X \varphi)^a(x) \bar{W}_a(x)$ then

$$(\nabla_X \varphi)^a(x) = d\varphi^a(X_x) + h^a_{bc} A^b(x) \varphi^c(x)$$

↓ for all $x \in U$. Here $\{h_{bc}^a\}$ are the numbers defined by the action of $\mathcal{G}$ on V , i.e.

$$e_b \cdot v_c = h_{bc}^a v_a.$$

~~Proof~~ Since $\varphi(x) = (\lambda(x), \hat{\varphi}(\lambda(x)))G = (\lambda(x), \hat{\varphi}^a(x) v_a)G = \hat{\varphi}^a(x) (\lambda(x), v_a)G = \hat{\varphi}^a(x) W_a(x)$ we see that $\varphi^a(x) = \hat{\varphi}^a(\lambda(x))$.

$$\begin{aligned} \text{Now } (\nabla_X \varphi)(x) &= (\lambda(x), \tilde{X}(\hat{\varphi})(\lambda(x)))G \\ &= (\lambda(x), d\hat{\varphi}(\tilde{X}(\lambda(x))))G \\ &= (\lambda(x), d\hat{\varphi}^a(\tilde{X}(\lambda(x)) v_a)G \\ &= d\hat{\varphi}^a(\tilde{X}(\lambda(x))) W_a(x) \end{aligned}$$

and also since $\tilde{X}(\lambda(x)) = d_x \lambda(X_x) - \delta_{(\lambda^* \omega)(X_x)}(\lambda(x))$

$$\begin{aligned} d\hat{\varphi}(\tilde{X}(\lambda(x))) &= d\hat{\varphi}(d_x \lambda(X_x)) - d\hat{\varphi}(\delta_{(\lambda^* \omega)(X_x)}(\lambda(x))) \quad \text{Use (*)} \\ &= d\hat{\varphi}(d_x \lambda(X_x)) + (\lambda^* \omega)(X_x) \cdot \hat{\varphi}(\lambda(x)) \\ &= d\hat{\varphi}^c(d_x \lambda(X_x)) + (\lambda^* \omega)^b(X_x) \hat{\varphi}^a(\lambda(x)) (e_b \cdot v_a) \\ &= [d\hat{\varphi}^c(d_x \lambda(X_x)) + h_{ba}^c (\lambda^* \omega)^b(X_x) \hat{\varphi}^a(\lambda(x))] v_c \\ &= [d_x(\hat{\varphi}^c \circ \lambda)(X_x) + h_{ba}^c A^b(X_x) (\hat{\varphi}^a \circ \lambda)(x)] v_c \\ &= [d_x \varphi^c(X_x) + h_{ba}^c A^b(X_x) \varphi^a(x)] v_c. \end{aligned}$$

$$\text{So } (\nabla_X \varphi)(x) = d\hat{\varphi}^a(\tilde{X}(\lambda(x))) W_a(x) = [d_x \varphi^c(X_x) + h_{ba}^c A^b(X_x) \varphi^a(x)] v_c$$

Remark Notice that in the proof of the last Theorem we have shown that

$$(\nabla_X \varphi)(x) = (\lambda(x), d\hat{\varphi}(\tilde{X}(\lambda(x))) \in G$$

and that

$$d\hat{\varphi}(\tilde{X}(\lambda(x))) = d\hat{\varphi}(d_x \lambda(X_x)) + (\lambda^* \omega)(X_x) \cdot \hat{\varphi}(\lambda(x)).$$

Moreover, $\varphi = \hat{\varphi} \circ \lambda$ so that

$$\begin{aligned} (\nabla_X \varphi)(x) &= (\lambda(x), d_x \varphi(X_x) + (\lambda^* \omega)(X_x) \cdot \varphi(x)) \in G \\ &= d_x \varphi^a(X_x) + [(\lambda^* \omega)(X_x) \cdot \varphi(x)]^a (\lambda(x), v_a) \in G \\ &= \left[(d_x \varphi^a)(X_x) + [(\lambda^* \omega)(X_x) \cdot \varphi(x)]^a \right] \bar{W}_a(x) \end{aligned}$$

It follows that the components of $\nabla_X \varphi$ relative to the local basis of sections $\{\bar{W}_a\}$ are

$$d_x \varphi^a(X_x) + [(\lambda^* \omega)(X_x) \cdot \varphi(x)]^a.$$

(1)
Problem 1 Consider the PFB $\mathcal{F}(TM) \rightarrow M$ and
 let $\omega : T(\mathcal{F}(TM)) \rightarrow \mathfrak{gl}(n)$ be a principal connection
 ($n = \dim M$). Choose a chart (x^μ) on M and
 define a local section Δ of π by $\Delta(p) = (p, \frac{\partial}{\partial x^\mu}|_p)$
 Let $\Gamma_\mu = (\Delta^* \omega)(\partial_\mu)$. Use the Theorem on
 page 264 to prove that if $\bar{\Delta}(p) = (p, \frac{\partial}{\partial \bar{x}^\nu}|_p)$
 is another section defined by a chart $(\bar{x}^\nu)$
 then $\bar{\Gamma}_\nu = (\bar{\Delta}^* \omega)(\partial_\nu)$ is related to Γ_μ by

$$\bar{\Gamma}_\nu(x) = g(x)^{-1} \Gamma_\mu(x) g(x) + \bar{g}^{-1}(x) (\partial_\nu g)(x)$$

where $g(x)$ is the matrix $(\frac{\partial x^\mu}{\partial \bar{x}^\nu}(x)) \in \mathfrak{gl}(n)$.
 Use this fact to show that

$$\bar{\Gamma}_{\mu\delta}^{\rho} = \Gamma_{\mu\lambda}^{\kappa} \left(\frac{\partial \bar{x}^\rho}{\partial x^\kappa} \right) \left(\frac{\partial x^\lambda}{\partial \bar{x}^\delta} \right) + \left(\frac{\partial^2 x^\kappa}{\partial \bar{x}^\delta \partial \bar{x}^\mu} \right) \frac{\partial \bar{x}^\rho}{\partial x^\kappa}$$

Problem 2 Recall that T^*M is bundle
isomorphic to $\mathcal{F}(TM) \times_G (\mathbb{R}^n)^*$ where

$G = \mathfrak{gl}(n)$ and the action of G on $(\mathbb{R}^n)^*$
 is given by $(A \cdot \pi^i)(\pi_k) = \pi^i(A^{-1} \cdot \pi_k) = \pi^i(A_k^{-1l} \pi_l)$
 $= A_k^{li} \pi_l = (A^{-1})_p^i \pi^p$ so that

$$\boxed{A \cdot \pi^i = A_p^{-1i} \pi^p}$$

Here $\{r_i\}$ is the standard basis of $\mathbb{R}^n$ and $\{r^i\}$ is the basis of $(\mathbb{R}^n)^*$ dual to $\{r_i\}$. This isomorphism sends

$$W^\mu(x) = (s(x), r^\mu)G$$

to dx^μ if the section s is defined by $s(p) = (p, \frac{\partial}{\partial x^\mu}|_p)$. Since a section α of $\mathcal{F}(TM) \times_G (\mathbb{R}^n)^* \rightarrow M$ may be written as

$$\alpha(p) = (s(p), \hat{\alpha}(s(p)))G = \hat{\alpha}_\mu(s(p))(s(p), r^\mu)G$$

and $W^\mu(p) = (s(p), r^\mu)G$ is identified with dx^μ we see that α is identified with the 1-form $\hat{\alpha}_\mu(s(p))dx^\mu = \alpha_\mu(p)dx^\mu$.

② Problem 2 Use the Remark above to show that $\nabla_\mu \alpha$ may be identified with

$$[\partial_\mu \alpha_\nu + (\Gamma_\mu \cdot \alpha)_\nu] dx^\nu$$

and that

$$\begin{aligned} (\Gamma_\mu \cdot \alpha)(x) &= \Gamma_\mu(x) \cdot \alpha(x) = \Gamma_\mu(x)(s(x), \hat{\alpha}(s(x)))G \\ &= -\Gamma_{\mu\lambda}^\nu(x) \alpha_\nu(x) W^\lambda(x) \\ &\approx -\Gamma_{\mu\lambda}^\nu(x) \alpha_\nu(x) dx^\lambda \end{aligned}$$

$$\text{So } \nabla_\mu \alpha = [\partial_\mu \alpha_\lambda - \Gamma_{\mu\lambda}^\nu \alpha_\nu] dx^\lambda.$$