

COORDINATE CHANGE FOR LINEAR TRANSFORMATIONS ON \mathbb{R}^n

Let $\beta = \{v_1, v_2, \dots, v_n\}$ be basis for \mathbb{R}^n . Recall for $x \in \mathbb{R}^n$

we say $[x]_\beta = (c_1, c_2, \dots, c_n) \iff x = c_1 v_1 + \dots + c_n v_n$

That is, $[x]_\beta = [\beta]^{-1} x$ and $x = [\beta][x]_\beta = [v_1 | v_2 | \dots | v_n] \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$

We also defined $[T] \in \mathbb{R}^{m \times n}$ as the standard matrix of $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ where $T(x) = [T]x \quad \forall x \in \mathbb{R}^n$. We found $[T] = [T(e_1) | T(e_2) | \dots | T(e_n)]$ where $\{e_1, e_2, \dots, e_n\}$ is the standard basis for \mathbb{R}^n .

Defⁿ Given linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ the matrix of T with respect to basis β is denoted $[T]_{\beta, \beta}$ and is defined by $[T]_{\beta, \beta} = [[T(v_1)]_\beta | [T(v_2)]_\beta | \dots | [T(v_n)]_\beta]$ where $\beta = \{v_1, v_2, \dots, v_n\}$

Lemma: for $\beta = \{v_1, v_2, \dots, v_n\}$ a basis for \mathbb{R}^n the coordinates

map $\Phi_\beta: \mathbb{R}^n \rightarrow \mathbb{R}^n$ defined by $\Phi_\beta(x) = [x]_\beta$ has

1.) $\Phi_\beta(x+y) = [x+y]_\beta = [x]_\beta + [y]_\beta$ } in other words, Φ_β is linear transformation

2.) $\Phi_\beta(cx) = [cx]_\beta = c[x]_\beta$

3.) $\Phi_\beta(v_i) = e_i$

4.) $[\Phi_\beta] = [\beta]^{-1}$

Proof: if $x = c_1 v_1 + \dots + c_n v_n$ then $[x]_\beta = (c_1, \dots, c_n)$ by Def? like wise $y = b_1 v_1 + \dots + b_n v_n$ then $[y]_\beta = (b_1, \dots, b_n)$.

Notice,

$$\begin{aligned} cx + y &= c(c_1 v_1 + \dots + c_n v_n) + b_1 v_1 + \dots + b_n v_n \\ &= (cc_1 + b_1)v_1 + \dots + (cc_n + b_n)v_n \end{aligned}$$

Hence $[cx + y]_\beta = (cc_1 + b_1, \dots, cc_n + b_n)$

$$\begin{aligned} &= c(c_1, \dots, c_n) + (b_1, \dots, b_n) \\ &= c[x]_\beta + [y]_\beta \quad (\text{this proves (1.) and (2.)}) \end{aligned}$$

For (3.) Note $v_i = 0v_1 + \dots + 1v_i + \dots + 0v_n \Rightarrow [v_i]_\beta = (0, \dots, 1, \dots, 0) = e_i$.

For (4.) $x = c_1 v_1 + \dots + c_n v_n = [v_1 \dots v_n] \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = [\beta][x]_\beta \Rightarrow [x]_\beta = [\beta]^{-1}x$

Therefore $\Phi_\beta(x) = [x]_\beta = [\beta]^{-1}x \Rightarrow [\Phi_\beta] = [\beta]^{-1}$.

Proposition: $[T]_{\beta\beta} [x]_{\beta} = [T(x)]_{\beta}$

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Proof: $[T(x)]_{\beta} = \mathfrak{F}_{\beta} \left(T \left(\sum_1^n c_i v_i \right) \right) : [x]_{\beta} = (c_1, \dots, c_n)$

$$= \mathfrak{F}_{\beta} \left(\sum_1^n c_i T(v_i) \right) : \text{linearity of } T$$
$$= \sum_1^n c_i \mathfrak{F}_{\beta} (T(v_i)) : \text{linearity of } \mathfrak{F}_{\beta}$$
$$= \sum_1^n c_i [T(v_i)]_{\beta}$$
$$= [T(v_1)]_{\beta} | [T(v_2)]_{\beta} | \dots | [T(v_n)]_{\beta} \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$
$$= [T]_{\beta\beta} [x]_{\beta} //$$

$T_{\mathcal{H}} / [T]_{\beta\beta} = [\beta]^{-1} [T] [\beta]$ where $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $[T]$ is standard matrix
whereas $\beta = \{v_1, \dots, v_n\}$ has $[\beta] = [v_1 | \dots | v_n]$ and $[T]_{\beta\beta} = [[T(v_1)]_{\beta} | \dots | [T(v_n)]_{\beta}]$

Proof: using prop. and lemma, $[T]_{\beta\beta} [x]_{\beta} = [T(x)]_{\beta} = [\beta]^{-1} T(x)$

hence $[T]_{\beta\beta} [\beta]^{-1} x = [\beta]^{-1} [T] x$ for all $x \in \mathbb{R}^n$

thus $[T]_{\beta\beta} [\beta]^{-1} = [\beta]^{-1} [T] \Rightarrow [T]_{\beta\beta} = [\beta]^{-1} [T] [\beta] //$

[E1] Suppose $T(x, y) = \left(\frac{1}{3}(-56x + 46y), \frac{1}{3}(-67x + 56y)\right)$

Let's find $[T]_{\rho, \rho}$ where $\beta = \{v_1, v_2\}$ and $v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 4 \\ 5 \end{bmatrix}$

$$[\beta] = \begin{bmatrix} 1 & 4 \\ 2 & 5 \end{bmatrix} \Rightarrow [\beta]^{-1} = \frac{1}{5-8} \begin{bmatrix} 5 & -4 \\ -2 & 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} -5 & 4 \\ 2 & -1 \end{bmatrix}$$

$$[T]_{\rho, \rho} = [\beta]^{-1} [T] [\beta] = \left(\frac{1}{3} \begin{bmatrix} -5 & 4 \\ 2 & -1 \end{bmatrix} \right) \left(\frac{1}{3} \begin{bmatrix} -56 & 46 \\ -67 & 56 \end{bmatrix} \right) \left(\begin{bmatrix} 1 & 4 \\ 2 & 5 \end{bmatrix} \right)$$

$$= \frac{1}{9} \begin{bmatrix} -5 & 4 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 36 & 6 \\ 45 & 12 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 0 & 18 \\ 27 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 3 & 0 \end{bmatrix}$$

Let $(x, y) = y_1 v_1 + y_2 v_2$

Then $[(x, y)]_{\rho} = (y_1, y_2)$ and

$$[T]_{\rho, \rho} [(x, y)]_{\rho} = [T(x, y)]_{\rho}$$

$$\begin{bmatrix} 0 & 2 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 2y_2 \\ 3y_1 \end{bmatrix}$$

indicates

$$T(x, y) = (2y_2)v_1 + (3y_1)v_2$$

or,

$$T(y_1 v_1 + y_2 v_2) = 2y_2 v_1 + 3y_1 v_2$$

$[T]_{\rho, \rho}$ and $[T]$ are similar matrices; $[T]_{\rho, \rho} = B [T] B^{-1}$.

Remark:

$$\det [T]_{\rho, \rho} = \det [T] = -6$$

$$\text{trace } [T]_{\rho, \rho} = \text{trace } [T] = 0$$

$$[T] = \frac{1}{3} \begin{bmatrix} -56 & 46 \\ -67 & 56 \end{bmatrix}$$

E2

Consider $T(x) = Ax$ where $A = \begin{bmatrix} 1 & 0 & 1 \\ 2 & 2 & 4 \\ 3 & 2 & 5 \end{bmatrix}$. Is T onto or 1-1? (5)

Let's calculate $\ker(T) = \text{Null}(A)$,

$$A \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 2 \\ 0 & 2 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow Ax = 0 \text{ gives } X = (-X_3, -X_3, X_3)$$

so $\text{Null}(A) = \text{span}\{-1, -1, 1\}$.

We find nullity $(T) = 1$ and rank $(T) = 2$.

Thus T is not 1-to-1 and T is not onto.

Let $\beta = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \right\}$ serve as basis for \mathbb{R}^3 . We wish to calculate $[T]_{\beta, \beta}$

Since $[T]_{\beta, \beta} = [Q]^{-1} [T] [Q]$ and $[T] = A$. After some calculation,

$$\text{ref} \begin{bmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 2 & 2 & -1 & 0 & 1 & 0 \\ 3 & 2 & 2 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 4/6 & -2/6 & 2/6 \\ 0 & 1 & 0 & -5/6 & 4/6 & -1/6 \\ 0 & 0 & 1 & -2/6 & -2/6 & 2/6 \end{bmatrix} [Q]^{-1}$$

Hence calculate,

$$[T]_{\beta, \beta} = \frac{1}{6} \begin{bmatrix} 4 & -2 & 2 \\ -5 & 4 & -1 \\ -2 & -2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 2 & 2 & 4 \\ 3 & 2 & 5 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 2 & 2 & -1 \\ 3 & 2 & 1 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 4 & -2 & 2 \\ -5 & 4 & -1 \\ -2 & -2 & 2 \end{bmatrix} \begin{bmatrix} 4 & 2 & 0 \\ 18 & 12 & 0 \\ 22 & 14 & 0 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 8 & 4 & 0 \\ 30 & 24 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$[T]_{\beta, \beta} = \begin{bmatrix} 8/6 & 4/6 & 0 \\ 5 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

E2 continued

For $V_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ and $V_2 = \begin{bmatrix} 0 \\ 2 \\ 2 \end{bmatrix}$ and $V_3 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$

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If $X = aV_1 + bV_2 + cV_3$ then $[X]_{\rho} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$

If $X = y_1V_1 + y_2V_2 + y_3V_3$ then $[X]_{\rho} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$

$$T(X) = T(y_1V_1 + y_2V_2 + y_3V_3)$$

$$= y_1 T(V_1) + y_2 T(V_2) + y_3 T(V_3)$$

$$[T]_{\rho, \rho} = \begin{bmatrix} 8/6 & 4/6 & 0 \\ 5 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$= y_1 \left(\frac{8}{6}V_1 + 5V_2 \right) + y_2 \left(\frac{4}{6}V_1 + 4V_2 \right)$$

to say $[T(V_1)]_{\rho} = \begin{bmatrix} 8/6 \\ 5 \\ 0 \end{bmatrix}$

to say $[T(V_2)]_{\rho} = \begin{bmatrix} 4/6 \\ 4 \\ 0 \end{bmatrix}$

and $[T]_{\rho, \rho} = [[T(V_1)]_{\rho} \mid [T(V_2)]_{\rho} \mid [T(V_3)]_{\rho}]$

means $T(V_1) = \frac{8}{6}V_1 + 5V_2$

means $T(V_2) = \frac{4}{6}V_1 + 4V_2$

Thus,

$$T(X) = \left(\frac{4}{3}y_1 + \frac{2}{3}y_2 \right)V_1 + (5y_1 + 4y_2)V_2$$

Notice $T(X) = T(x_1e_1 + x_2e_2 + x_3e_3) = \begin{bmatrix} 1 & 0 & 1 \\ 2 & 2 & 4 \\ 3 & 2 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = (x_1 + x_3)e_1 + (2x_1 + 2x_2 + 4x_3)e_2 + (3x_1 + 2x_2 + 5x_3)e_3$

$$[T]_{\rho, \rho} [X]_{\rho} = [T(X)]_{\rho} \longrightarrow \begin{bmatrix} 4/3 & 2/3 & 0 \\ 5 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} (4/3)y_1 + (2/3)y_2 \\ 5y_1 + 4y_2 \\ 0 \end{bmatrix}$$