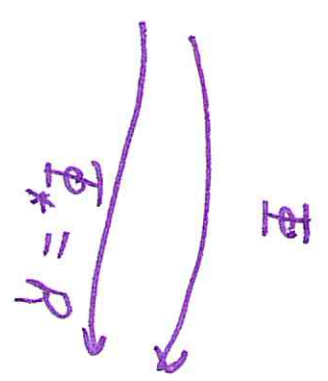


LECTURE 11: ON FRAMES AND CONGRUENCE IN  $\mathbb{R}^n$

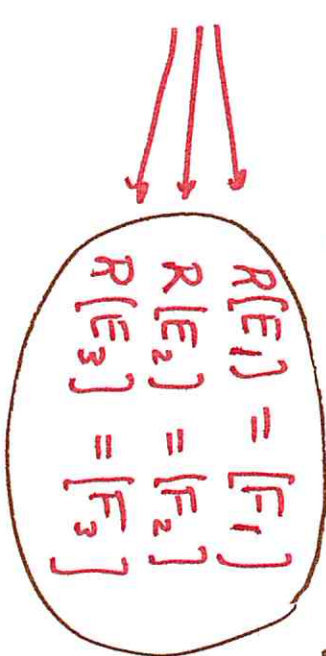
$P \cdot$

$E_1, E_2, E_3$   
at  $P$



$\Phi(P) = P \quad \Phi(E_i) = F_i$

Recall  $E_i = A_{i1} v_1 + A_{i2} v_2 + A_{i3} v_3$   
 $[E_i] = [A_{i1}, A_{i2}, A_{i3}]^T$



$F_1, F_2, F_3$   
have aff. frame  $B$

$R \text{ row}_1(A)^T = \text{row}_1(B)^T$   
 $R \text{ row}_2(A)^T = \text{row}_2(B)^T$   
 $R \text{ row}_3(A)^T = \text{row}_3(B)^T$   
 $R [\text{col}_1(A^T) | \text{col}_2(A^T) | \text{col}_3(A^T)] = B^T$

$RA^T = B^T \quad A^T A = I$   
 $R = B^T A$

Th<sup>y</sup>/ Let  $E_1, E_2, E_3 \in T_p \mathbb{R}^3$  with attitude  $A$   
 and  $F_1, F_2, F_3 \in T_q \mathbb{R}^3$  with attitude  $B$   
 then  $\exists \mathbb{E}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  for which  $\mathbb{E}(p) = q$   
 and  $\mathbb{E}_*(E_j) = F_j$  for  $j=1, 2, 3$ .

Proof: Let  $R = B^T A$  and define  $\mathbb{E}(x) = Rx + q - Rp$

Note  $\mathbb{E}(p) = Rp + q - Rp = q$ . Also,  $[\mathbb{E}_*(E_j)] = R[E_j] = [F_j]$ .

- See details on pg. 68 (§3.3 of my notes)
- also Example 3.3.2 is nice

(Th<sup>y</sup>/(3.3.3))  $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  and  $V, W \in \mathcal{X}(\mathbb{R}^3)$

$$F_*(V) \cdot F_*(W) = V \cdot W$$

$$F_*(V) \times F_*(W) = \text{det}(F_*) F_*(V \times W)$$

Proof  $F_*(V) \cdot F_*(W) = (RV) \cdot (RW)$

$$= (RV)^T RW$$

$$= V^T \cancel{R^T R} W$$

$$= V^T W = V \cdot W. \quad \curvearrowright$$

Proof continued

(3)

$$F_*(V) \times F_*(W) = (RV) \times (RW)$$

$R^T R = I$  and  $F_*(v_j), F_*(v_2), F_*(v_3)$  forms a frame for  $\mathbb{R}^3$   
ignore  
note  $F_*(v_j) = R v_j$

$$(F_*(V) \times F_*(W)) \cdot v_j = (RV \times RW) \cdot v_j$$

$$= \det [RV \mid RW \mid v_j] \quad R^T R = I$$

$$= \det [RV \mid RW \mid R R^T v_j]$$

$$= \det R [V \mid W \mid R^T v_j]$$

$$= \det R \det [V \mid W \mid R^T v_j]$$

$$= (\det F_*)(V \times W) \cdot (R^T v_j) \quad (Mx) \cdot y = x \cdot (M^T y)$$

$$= (\det F_*) \underline{R(V \times W)} \cdot v_j$$

$$= \det F_*(V \times W) \cdot v_j \quad \text{for } j=1,2,3.$$

$$\text{Thus } F_*(V) \times F_*(W) = (\det F_*) F_*(V \times W). //$$



Thm 3.3.4 FRENET APPARATUS OF ISOMETRIC IMAGE

(4)

Let  $\alpha$  be a nonlinear, arc length parametrized curve with Frenet frame  $T, N, B$  and curvature  $\kappa$ , torsion  $\tau$ . Suppose  $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is an isometry and define  $\bar{\alpha} = F \circ \alpha$ . If  $\bar{T}, \bar{N}, \bar{B}, \bar{\kappa}, \bar{\tau}$  form the Frenet frame and curvature & torsion of  $\bar{\alpha}$  then

$$\bar{T} = F_* (T), \quad \bar{N} = F_* (N), \quad \bar{B} = \det(F_*) F_* (B), \quad \bar{\kappa} = \kappa, \quad \bar{\tau} = \tau \det(F_*)$$

Proof  $T(s) = \alpha'(s)$  &  $\bar{T}(s) = \bar{\alpha}'(s) = (F \circ \alpha)'(s) = F_* (\alpha'(s)) = F_* (T(s))$

Hence  $F_* (T) = \bar{T}$ . Next consider the Frenet normals

$$\kappa = \|\alpha''\| \quad \text{and} \quad \bar{\kappa} = \|\bar{\alpha}''\| = \|(F \circ \alpha)''\| = \|F_* (\alpha'')\| = \|\alpha''\| = \kappa.$$

$$N = \frac{1}{\kappa} \alpha'' \quad \text{and} \quad \bar{N} = \frac{1}{\bar{\kappa}} \bar{\alpha}'' = \frac{1}{\kappa} (F \circ \alpha)'' = \frac{1}{\kappa} F_* (\alpha'') = F_* \left( \frac{\alpha''}{\kappa} \right) = F_* (N)$$

Thus  $\bar{N} = F_* (N)$ . Next consider  $B = T \times N$  &  $\bar{B} = \bar{T} \times \bar{N}$

$$\begin{aligned} \bar{B} &= \bar{T} \times \bar{N} = F_* (T) \times F_* (N) \\ &= \det(F_*) F_* (T \times N) \\ &= \det(F_*) F_* (B). \end{aligned}$$

Finally  $T = -B' \cdot N$  and  $\bar{T} = -\bar{B}' \cdot \bar{N}$

$$-T = B' \cdot N = F_* (B') \cdot F_* (N) = (F_* (B))' \cdot F_* (N) = \det(F_*) (\bar{B}' \cdot \bar{N}) = \det(F_*) \bar{T}(-1)$$

$$\boxed{\text{Ex}} \quad \alpha(s) = (R \cos \gamma s, R \sin \gamma s, m \gamma s) \quad \gamma = \frac{1}{\sqrt{R^2 + m^2}} \quad (5)$$

$$F(x, y, z) = (y, x, z) \quad \theta = \gamma s$$

$$\bar{\alpha}(s) = (F \circ \alpha)(s) = (R \sin \theta, R \cos \theta, m \theta) \quad \frac{d\theta}{ds} = \gamma.$$

$$\underline{\bar{T}} = \bar{\alpha}'(s) = R \gamma \cos \theta \underline{U}_1 - R \gamma \sin \theta \underline{U}_2 + m \gamma \underline{U}_3$$

$$\|\underline{\bar{T}}\| = R^2 \gamma^2 + m^2 \gamma^2 = \frac{R^2 + m^2}{R^2 + m^2} = 1.$$

$$\bar{\alpha}''(s) = -R \gamma^2 \sin \theta \underline{U}_1 - R \gamma^2 \cos \theta \underline{U}_2$$

$$\|\bar{\alpha}''(s)\| = R \gamma^2 = \frac{R}{R^2 + m^2} = \underline{\bar{K}} \quad \left\{ \underline{\bar{N}} = \frac{-\sin \theta \underline{U}_1 - \cos \theta \underline{U}_2}{\sqrt{2}} \right.$$

$$\text{like wise, } \rightarrow \underline{\bar{B}} = \frac{1}{\sqrt{R^2 + m^2}} [m \cos \theta \underline{U}_1 - m \sin \theta \underline{U}_2 - R \underline{U}_3]$$

$$\underline{\bar{B}}' = -m \gamma^2 \sin \theta \underline{U}_1 - m \gamma^2 \cos \theta \underline{U}_2$$

$$\underline{\bar{T}} = -\underline{\bar{B}}' \cdot \underline{\bar{N}} = -m \gamma^2 = \frac{-m}{R^2 + m^2} = -\underline{\bar{T}}_\alpha$$

$$\det(\underline{\bar{T}}_*) = \det \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = -1.$$

## Def<sup>n</sup>/ congruence of parametrized curves

(6)

We say  $\alpha: I \rightarrow \mathbb{R}^3$  and  $\beta: I \rightarrow \mathbb{R}^3$  ~~are congruent~~ are congruent if there exists an isometry  $F$  for which  $\beta = F \circ \alpha$ .

Example  $\beta(t) = (c_1 R \cos t + c_2 R \sin t + c_3 mt - 1 + 3\sqrt{6},$

$$c_3 R \cos t + c_3 R \sin t - 2c_3 mt - 2,$$

$$c_2 R \cos t + c_1 R \sin t + c_3 mt - 3 - 3\sqrt{6})$$

where  $c_1 = 1/\sqrt{6} + 1/2$  and  $c_2 = 1/\sqrt{6} - 1/2$  and  $c_3 = 1/\sqrt{6}$   
This is the standard helix with radius  $R$  and slope  $m$ .  
isometric image of

Helix:  $\alpha(t) = (R \cos t, R \sin t, mt)$

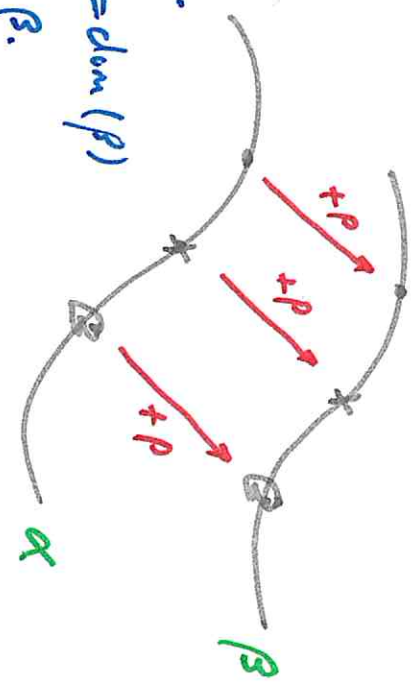


Def<sup>n</sup> parallel curves. We say  $\alpha \& \beta : I \rightarrow \mathbb{R}^3$  are  $\parallel$  if  $\exists P \in \mathbb{R}^3$  for which  $\beta(t) = \alpha(t) + P \quad \forall t \in I$

Prop 3.3.9

Parameterized curves  $\alpha$  &  $\beta$  are  $\parallel$  iff  $\alpha'(t) = \beta'(t)$  for all  $t \in I$ .

Moreover, if  $\alpha \parallel \beta$  and  $\exists t_0 \in \text{dom}(\alpha) = \text{dom}(\beta)$  for which  $\alpha(t_0) = \beta(t_0)$  then  $\alpha = \beta$ .



Proof |  $\beta(t) = \alpha(t) + P$  (assume  $\alpha \parallel \beta$ ) ( $I = \text{dom } \alpha = \text{dom } \beta$ )

Then  $\beta'(t) = \alpha'(t)$  for all  $t \in I$ .

Conversely, if  $\alpha'(t) = \beta'(t)$  for all  $t \in I$

$$\sum_{j=1}^3 \frac{d\alpha^j}{dt} v_j = \sum_{j=1}^3 \frac{d\beta^j}{dt} v_j \implies \frac{d\alpha^j}{dt} = \frac{d\beta^j}{dt}$$

for  $j=1, 2, 3$

$$\text{Hence } \alpha^j(t) = \beta^j(t) + P^j \implies \alpha(t) = \beta(t) + P.$$

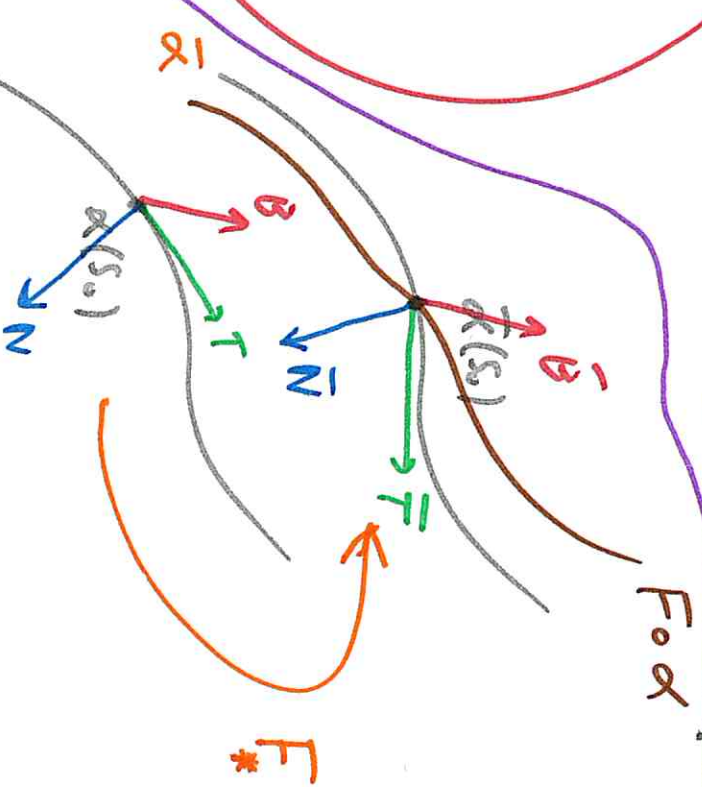
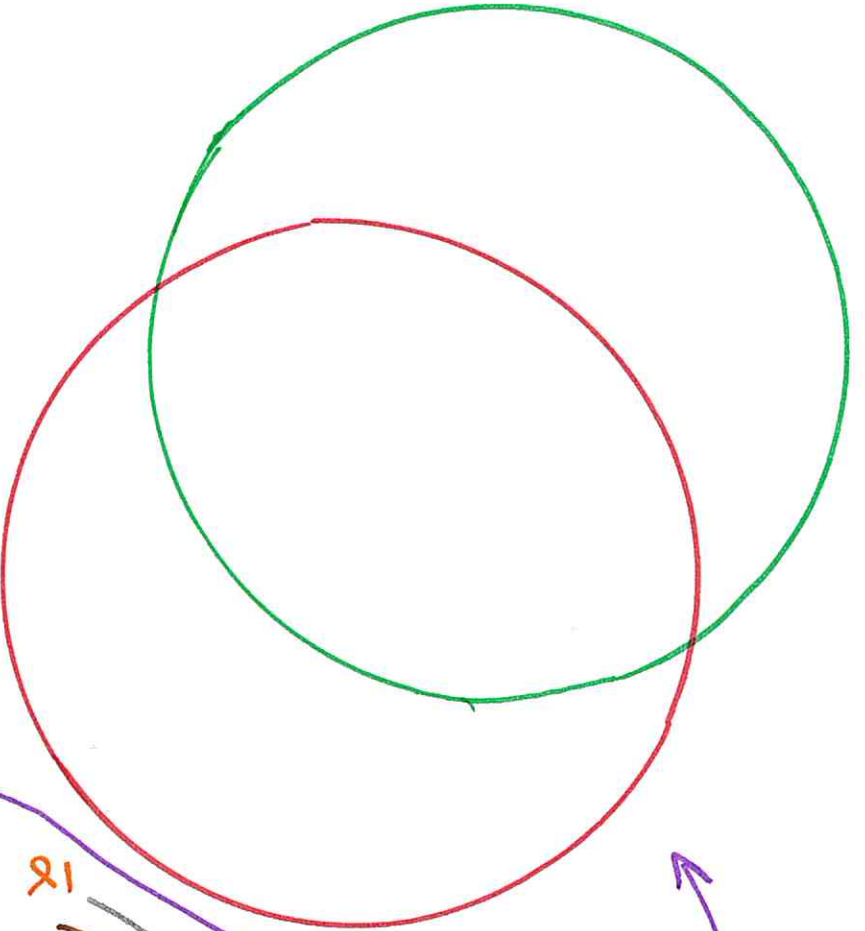
$$\text{If } \alpha(t_0) = \beta(t_0) \implies \alpha(t_0) = \beta(t_0) + P = \beta(t_0) \implies P = 0$$

$$\implies \alpha(t) = \beta(t) \quad \forall t \in I$$

Ex 1

8

These parallel circles intersect.



(proved  $\mathcal{T}h^u$  3.3.11

from pg. 72-73

& discussed Prop. 3.3.12 on 73 and  $\mathcal{T}h^u$  3.3.13 briefly)