

LECTURE 12 : SURFACES IN \mathbb{R}^3 (§4.1 - 4.3 of O'Neill)

(1)

Defⁿ / $\Sigma: D \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^3$

Σ 1-1 (injective)

Σ smooth

proper

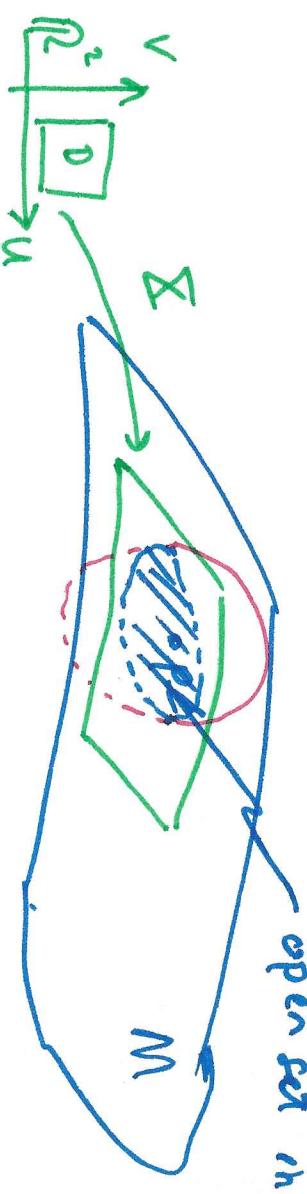
coordinate patch

$\Sigma^{-1}: \Sigma(D) \rightarrow D$ is continuous

Σ regular $J_{\Sigma(p)}^{(1)}$ has rank 2
at each $p \in D$

Consider $M \subseteq \mathbb{R}^3$ we say $U \subseteq M$ is an open set
if \exists an open set $\tilde{U} \subseteq \mathbb{R}^3$ such that $U = \tilde{U} \cap M$.
It suffices to use $\tilde{U} = B_\epsilon(p) = \{x \in \mathbb{R}^3 \mid d(x, p) < \epsilon\}$

open set in M



Defⁿ / M is surface if $M \subseteq \mathbb{R}^3$ and for each $p \in M$

\exists an open set $U \subseteq M$, containing p , and a proper patch $\Sigma: D \rightarrow \Sigma(D)$, for which $U \subseteq \Sigma(D)$. We say M is simple surface if $M = \Sigma(D)$.

EXAMPLES OF SURFACES

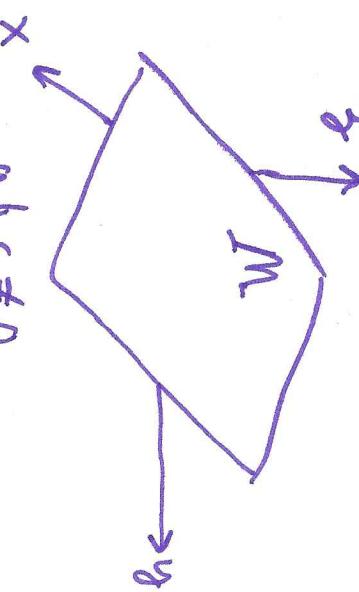
(2)

E1 $ax + by + cz = d$

$$\Sigma(x, y) = \left(x, y, \frac{d - ax - by}{c} \right)$$

$$\Sigma(u, v) = \left(u, v, \frac{1}{c}(d - au - bv) \right)$$

$$\Sigma^{-1}(p^1, p^2, p^3) = (p^1, p^2)$$



$$a, b, c \neq 0$$

$$\Sigma(u, v) = \left(u, \frac{1}{b}(d - au - cv), v \right)$$

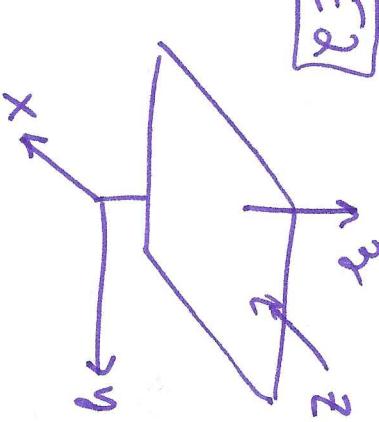
$$\Sigma(u, v) = \left(\frac{1}{a}(d - bu - cv), u, v \right)$$

E2 $x^2 + y^2 + z^2 = 3$

$$\Sigma(u, v) = (u, v, 3)$$

$$J_x = \begin{bmatrix} \frac{\partial \Sigma}{\partial u} & \frac{\partial \Sigma}{\partial v} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

assume open



✓

E3 $\text{Graph } \text{Graph } \{f\} = \{(x, y, f(x, y)) \mid (x, y) \in \text{dom}(f)\}$

is simple surface with Monge patch $\Sigma(u, v) = (u, v, f(u, v))$.

$$J_x = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ f_u & f_v \end{bmatrix} \text{ rank 2 everywhere.}$$

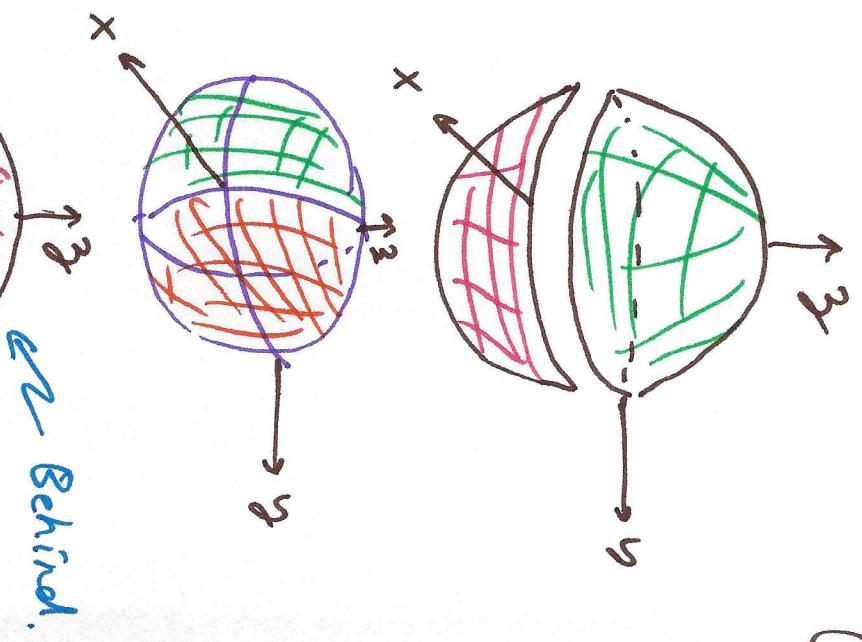
E4

$$\sum : x^2 + y^2 + z^2 = 1$$

$$X(u,v) = (u, v, \pm \sqrt{1-u^2-v^2})$$

$$\nabla(u,v) = (v, \pm \sqrt{1-u^2-v^2}, u)$$

$$Z_1(u,v) = (\pm \sqrt{1-u^2-v^2}, u, v)$$



(3)

(4)

Thⁿ / Let g be $g: \text{dom}(g) \subseteq \mathbb{R}^3 \rightarrow \mathbb{R}$ and $c \in \mathbb{R}$ then $\{g^{-1}\{c\} = \{(x, y, z) \mid g(x, y, z) = c\} = M \neq \emptyset\}$ is a surface if $d_p g \neq 0 \forall p \in M$

Proof: $\$ M \neq \emptyset$ and $p \in M$ and $d_p g = \frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy + \frac{\partial g}{\partial z} dz \neq 0$
 wlog, $\$ \frac{\partial g}{\partial z} \neq 0$ at p . Then the implicit function theorem tells us $\exists h$ for which $g(x, y, h(x, y)) = c$ for all (x, y) near enough to (p^1, p^2) . Thus $\Sigma(u, v) = (u, v, h(u, v))$. Then p was arbitrary $\Rightarrow \exists$ a proper patch at each $p \in M$.
 (e.g. $\Sigma(u, v) = (u, hv, v, v)$ good for p with $\frac{\partial g}{\partial y}(p) \neq 0$)

E4

$$g(x, y, z) = x^2 + y^2 + z^2 = 1$$

$$dg = 2x dx + 2y dy + 2z dz \neq 0$$

SURFACES OF REVOLUTION

(5)

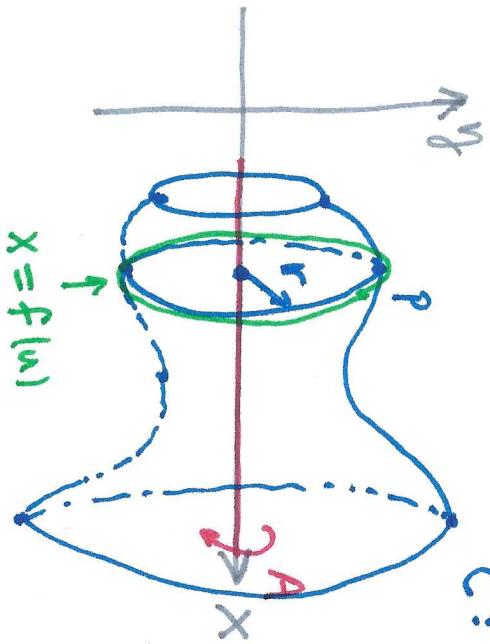
E6

$$c: (f(u), g(u), 0)$$

$$r = g(u)$$

$$\gamma(v) = (f(u), g(u)\cos(v), g(u)\sin(v))$$

$$0 \leq v \leq 2\pi$$



$$\Sigma(u, v) = (f(u), g(u)\cos(v), g(u)\sin(v))$$

E6

$$c: (\cos(u), \sin(u), 0) \quad 0 \leq u \leq \pi$$

$$\Sigma(u, v) = (\cos(u), \sin(u)\cos(v), \sin(u)\sin(v))$$

$$0 \leq u < \pi$$

$$0 \leq v < 2\pi$$

$$\text{Shows } c = \begin{cases} 0 \leq u \leq \pi \\ 0 \leq v \leq 2\pi \end{cases}$$

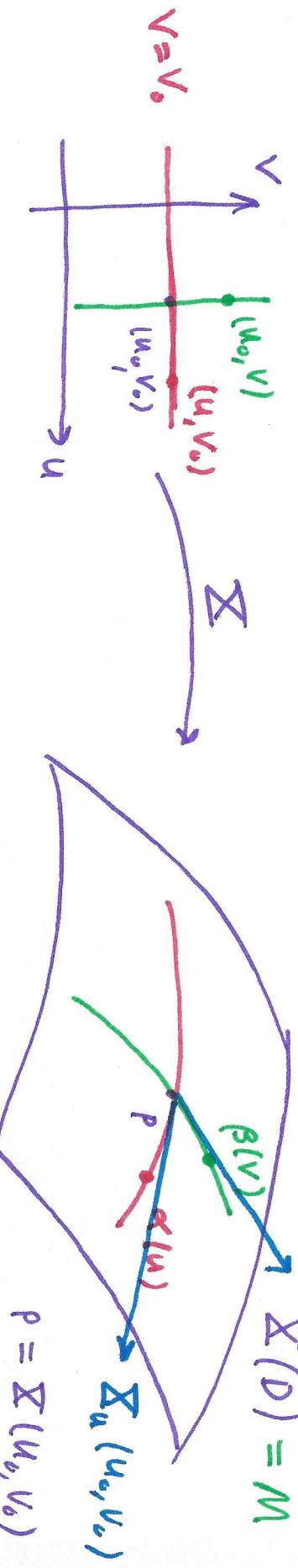
gives
a "parametrization"

CALCULUS ON M:

$$\Sigma(u, v) = (x(u, v), y(u, v), z(u, v))$$

$$\Sigma_v(u, v)$$

$$\Sigma(D) = M$$



$$p = \Sigma(u_0, v_0)$$

$$\alpha(u) = \Sigma(u, v_0)$$

$$\beta(v) = \Sigma(u_0, v)$$

understood as vector in $T_p \mathbb{R}^3$

$$\begin{aligned}\Sigma_u(u_0, v_0) &= \alpha'(u_0) = \frac{d}{dt} [\Sigma(t, v_0)] \Big|_{t=u_0} \\ \Sigma_v(u_0, v_0) &= \beta'(v_0) = \frac{d}{dt} [\Sigma(u_0, t)] \Big|_{t=v_0}\end{aligned}$$

understood as vector in $T_p \mathbb{R}^3$

$$\begin{aligned}\Sigma_u(u_0, v_0) &= \frac{d}{dt} [x(t, v_0)] \Big|_{t=u_0} + \frac{d}{dt} [y(t, v_0)] \Big|_{t=u_0} \tau_1(p) + \frac{d}{dt} [z(t, v_0)] \Big|_{t=u_0} \tau_2(p) \\ \Sigma_v(u_0, v_0) &= \frac{\partial x}{\partial u} \frac{du}{dt} + \frac{\partial y}{\partial u} \frac{dv}{dt} = \frac{\partial x}{\partial u}(u_0, v_0)\end{aligned}$$

$$\tau_1(p) = \frac{\partial}{\partial x_i}|_p$$

$$\begin{aligned}\frac{d}{dt} [x(t, v_0)] &= \frac{\partial x}{\partial u} \frac{du}{dt} + \frac{\partial x}{\partial v} \frac{dv}{dt} = \frac{\partial x}{\partial u}(u_0, v_0) \\ t=u, u=t \\ v=v_0\end{aligned}$$

$$\Sigma_u = \frac{\partial X}{\partial u} U_1 + \frac{\partial Y}{\partial u} U_2 + \frac{\partial Z}{\partial u} U_3$$

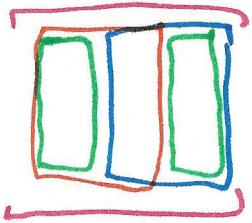
$$\Sigma_v = \frac{\partial X}{\partial v} U_2 + \frac{\partial Y}{\partial v} U_1 + \frac{\partial Z}{\partial v} U_3$$

(Det'ly A regular mapping $\Sigma: D \rightarrow \mathbb{R}^3$ with $\Sigma(D) \subseteq M$
is a parametrization of the region $\Sigma(D)$ in M .

REGULAR: $\text{rank } (\Sigma_x) = 2 \Leftrightarrow \Sigma_x =$

$$\begin{bmatrix} \frac{\partial X}{\partial u} & \frac{\partial X}{\partial v} \\ \frac{\partial Y}{\partial u} & \frac{\partial Y}{\partial v} \\ \frac{\partial Z}{\partial u} & \frac{\partial Z}{\partial v} \end{bmatrix} = \begin{bmatrix} \Sigma_u & \Sigma_v \end{bmatrix}$$

$$3 \times 2 \quad \underbrace{\Sigma_u \times \Sigma_v \neq 0}_{\text{LT given}} \Rightarrow \Sigma_u \text{ & } \Sigma_v \text{ rank 2.}$$



$\hookrightarrow \Sigma \text{ regular}$

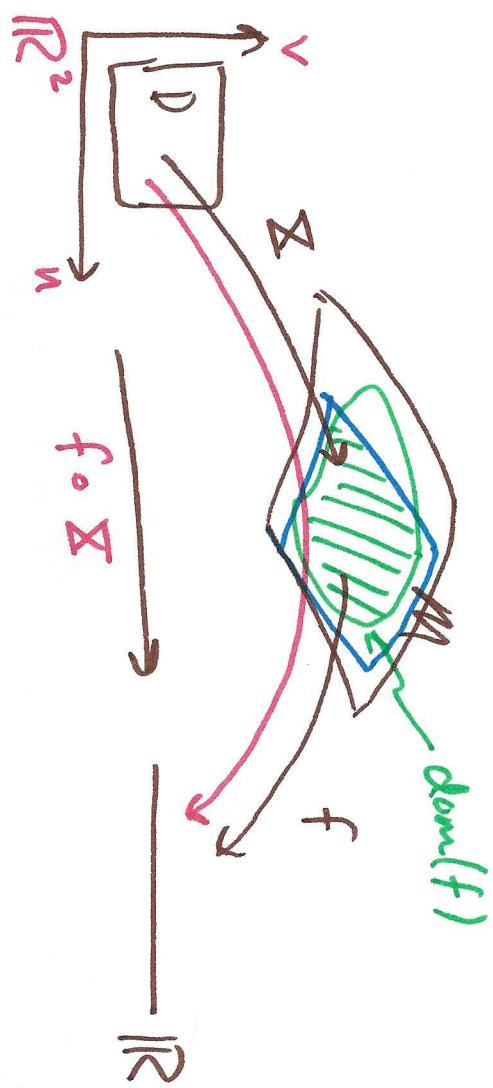
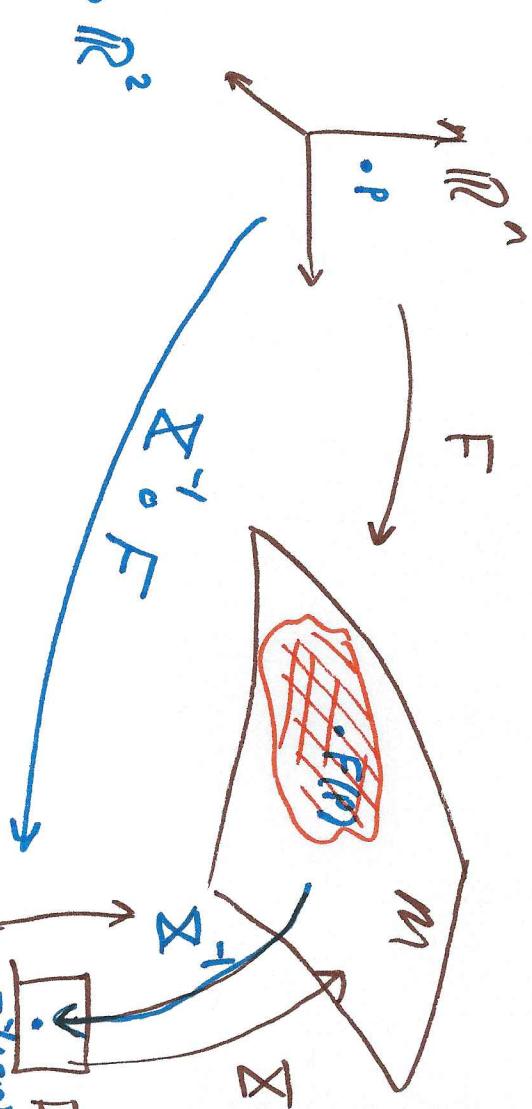
DERIVATIVES ON M

(8)

$f : M \rightarrow \mathbb{R}$
is diff. on M
provided the
local coord. rep
 $f \circ \Sigma$ are diff
in the usual sense
for each patch on M.

$F : \mathbb{R}^n \rightarrow M$
is diff. provided
 $\Sigma^{-1} \circ F$ is diff.
find. from appropriate
open sets in $\mathbb{R}^n \rightarrow \mathbb{R}^2$

$\alpha : \mathbb{R} \rightarrow M$
smooth curve if
 $\Sigma^{-1} \circ \alpha$ is smooth.
Btw Σ^{-1} is
called a CHART

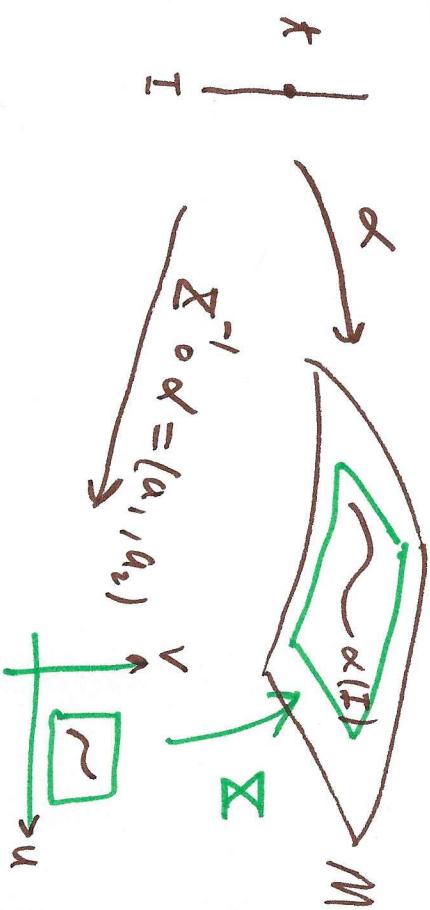


(9)

Lemma (3.1) If $\alpha: I \rightarrow M$ and $\alpha(I) \subset \Sigma(D)$
 Then $\exists!$ diff. fcts a_1, a_2 on I s.t. $\alpha(t) = \Sigma(a_1(t), a_2(t))$

$$\alpha = \Sigma(a_1, a_2)$$

Proof If $\alpha: I \rightarrow M$ smooth



$$\text{If } \Sigma^{-1} \circ \alpha = (a_1, a_2) \\ \Sigma(\Sigma^{-1} \circ \alpha) = \Sigma(a_1, a_2)$$

$$\alpha = \Sigma(a_1, a_2) \iff$$

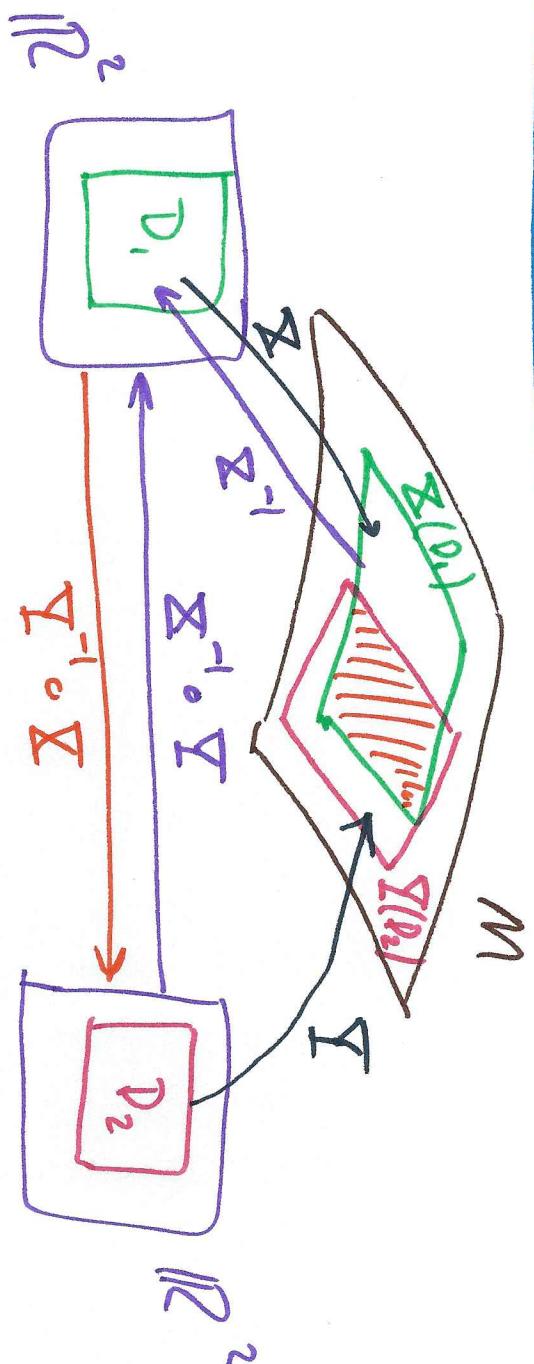
$\Sigma^{-1} \circ F: \mathbb{R}^n \rightarrow \mathbb{R}^3$, If $F: \mathbb{R}^n \rightarrow \mathbb{R}^3$ is a diff. map
 where image $F(\mathbb{R}^n) \subseteq M$ then F is diff. (w.r.t. M)

Proof Sketch:

The diagram shows a patch Σ_i on a manifold M , which is mapped by a function F to a patch $\Sigma_i(D_i)$ in \mathbb{R}^3 . The patch $\Sigma_i(D_i)$ is represented as a parallelogram in \mathbb{R}^3 . A green bracket groups D_i with the text "w.r.t. Σ_i ".

(10)

Cor (3.3) If $\Sigma, \bar{\Sigma}$ are overlapping patches on M (meaning $\Sigma(D_1) \cap \Sigma(D_2) \neq \emptyset$) then $\Sigma^{-1} \circ \bar{\Sigma} \notin \bar{\Sigma}^{-1} \circ \Sigma$ are smooth maps on \mathbb{R}^2 .



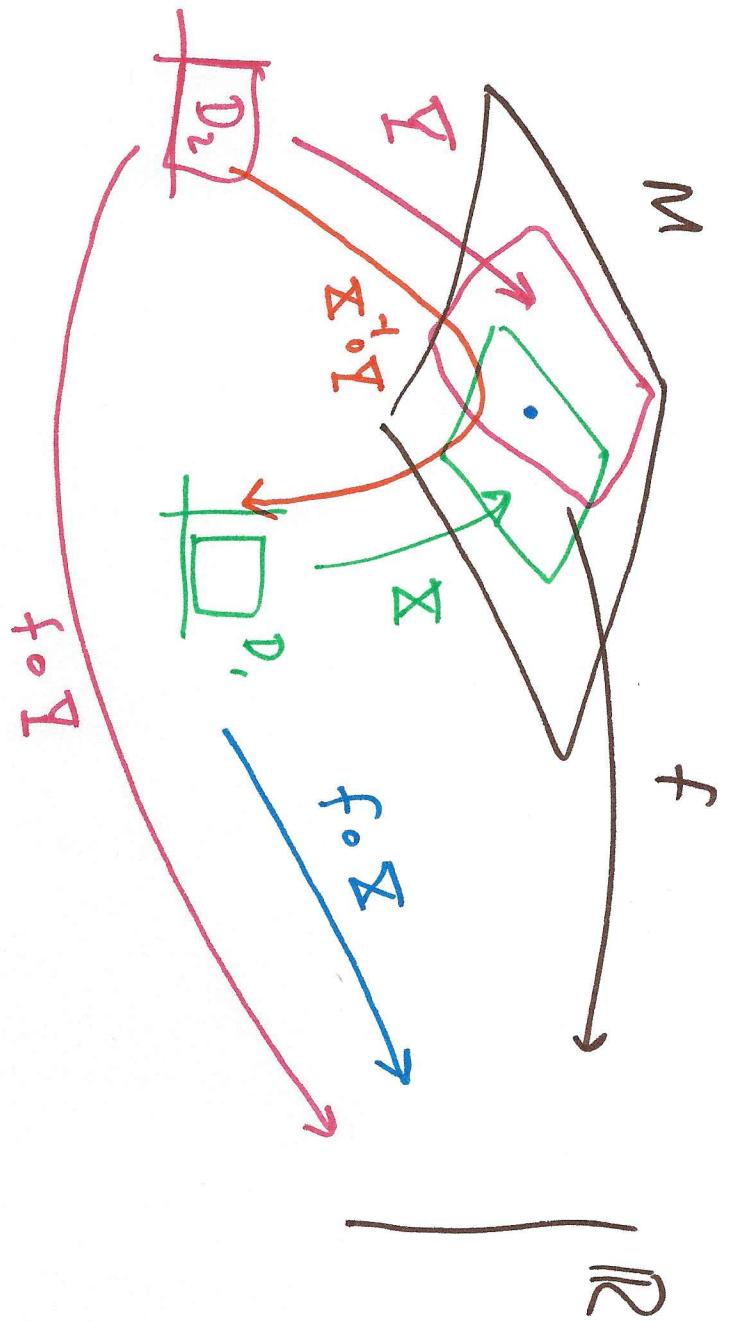
Cor (3.4) $\nabla(u, v) = \Sigma(\bar{u}(u, v), \bar{v}(u, v))$ for diff. facts
 $\bar{u} \notin \bar{\Sigma}$ from $\mathbb{R}^2 \rightarrow \mathbb{R}$. (for all $(u, v) \in \text{dom}(\Sigma^{-1} \circ \bar{\Sigma})$)

[Prop] $f(\Sigma)$ smooth iff $f(\bar{\Sigma})$ smooth for all overlapping patches Σ

Proof \hookrightarrow

unit. Σ

$$f \circ \nabla = (\underbrace{f \circ \nabla}_{\text{smooth}}) \circ (\underbrace{\nabla^{-1} \circ \nabla}_{\text{smooth}}) = \nabla \circ f$$



(11)

Def' $(P, V) \in T_p M$ iff $\exists \alpha : I \rightarrow M$ and $\alpha'(t_0) = (P, V)$
 for $P = \alpha(t_0)$. That is $T_p M \subset T_p \mathbb{R}^3$ formed by
 all possible tangents to curves on M

Lemma (3.6) $T_p M = \text{span} \{ \Sigma_u, \Sigma_v \}$
 where $\Sigma_u(u, v), \Sigma_v(u, v)$
 and $\Sigma(u_0, v_0) = P$

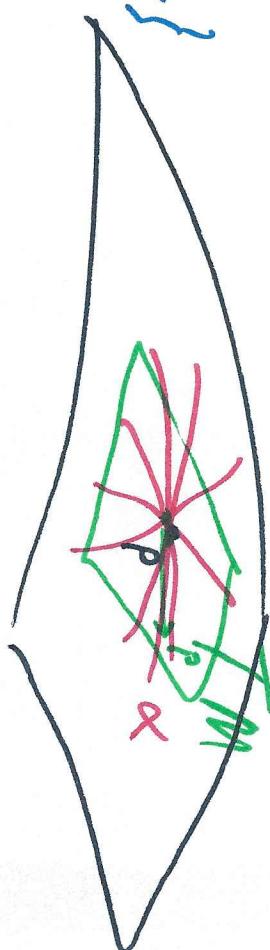
Proof : $\alpha = \Sigma(a_1, a_2)$ α some curve on M , $\alpha(0) = p$.

$$\alpha'(0) = \dot{\alpha}(t) = (\dot{x}(a_1(t), a_2(t)), \dot{y}(a_1(t), a_2(t)), \dot{z}(a_1(t), a_2(t)))$$

$$\alpha'(t) = \sum_{i=1}^3 \frac{dx^i(a_1(t), a_2(t))}{dt} \nu_i(\alpha(t))$$

$$= \sum_{i=1}^3 \left(\frac{\partial x^i}{\partial u} \frac{da_1}{dt} + \frac{\partial x^i}{\partial v} \frac{da_2}{dt} \right) \nu_i(\alpha(t))$$

$$= \frac{da_1}{dt} \underbrace{\sum_{i=1}^3 \frac{\partial x^i}{\partial u} \nu_i(\alpha(t))}_{\Sigma_u(\alpha(t))} + \frac{da_2}{dt} \underbrace{\sum_{i=1}^3 \frac{\partial x^i}{\partial v} \nu_i(\alpha(t))}_{\Sigma_v(\alpha(t))} \Rightarrow \alpha'(0) \in \text{span of } \Sigma_u, \Sigma_v$$



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Part continued:

(13)

Cartesian coordinate

$$\alpha(t) = \sum (u_0 + tc_1, v_0 + tc_2)$$

$$\alpha'(t) = c_1 \sum_u (u_i, v_i) + c_2 \sum_v (u_i, v_i)$$

Given anything in $\text{Span} \{ \sum_u (u_i, v_i), \sum_v (u_i, v_i) \}$ we have

$$(\alpha(0), \alpha'(0)) = (p, \alpha'(0)) \in T_p M \rightarrow \text{Span} \{ \sum_u (u_i, v_i), \sum_v (u_i, v_i) \} \subseteq T_p M.$$

$$\therefore T_p M = \langle \sum_u (u_i, v_i), \sum_v (u_i, v_i) \rangle$$

Defn Euclidean vector field on M

is an assignment $p \mapsto \sum (p) \in T_p \mathbb{R}^3$ for each $p \in M$.

Normal vector field $\sum(p) \in (T_p M)^\perp$ at each $p \in M$

Comment: $M: g = c$ then $\nabla g = \frac{\partial}{\partial x} v_1 + \frac{\partial}{\partial y} v_2 + \frac{\partial}{\partial z} v_3$
give Normal vector field to M .

$$\begin{aligned} E] \quad g &= x^2 + y^2 + z^2 = 1 & v(p) &= -p_1 v_1 + p_2 v_2 + \\ Dg &= 2x v_1 + 2y v_2 + 2z v_3 \end{aligned}$$