

LECTURE 13: DIFFERENTIAL FORMS, MAPS, \int ON M

①

$\dim(T_p M) = 2$, BASIS $\{\Sigma_u, \Sigma_v\}$

0-forms: $f: M \rightarrow \mathbb{R}$

1-forms: $\alpha \in \Lambda^1(M) \hookrightarrow \alpha(p) \in (T_p M)^*$ for each $p \in M$

2-forms: $\beta \in \Lambda^2(M) \hookrightarrow \beta(p): T_p M \times T_p M \rightarrow \mathbb{R}$

k -form: $\Lambda^k(M) = \{0\}$
for $k \geq 3$

$\beta(p)$ — bilinear
— skew-symmetric

$$\beta(p)(v, w) = -\beta(p)(w, v)$$

1-form α smooth: $\alpha(V)$ is smooth fct for all $V \in \Gamma(M)$

2-form β smooth: $\beta(V, W)$ is smooth fct.

for all $V, W \in \Gamma(M)$.

$V(p) \in T_p M$

0-form f smooth $\Leftrightarrow f \circ \Sigma: D \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}$ is smooth $\forall \Sigma$ on M .

Lemma 4.2: For $\{v, w\} \subset T$ in $T_p M$, a 2-form η ,

$$\eta(av + bw, cv + dw) = \underbrace{(ad - bc)}_{\text{det}} \eta(v, w)$$

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$$

Proof η a 2-form,

$$\eta(av + bw, cv + dw) = a\eta(v, cv + dw) + b\eta(w, cv + dw)$$

$$= ac\cancel{\eta(v, v)} + ad\eta(v, w) + bc\eta(w, v) + bd\cancel{\eta(w, w)}$$

$$= \underbrace{(ad - bc)}_{\text{det}} \eta(v, w) //$$

Exterior Algebra over M : $\Sigma^2(M) = \Lambda^2 M \oplus \Lambda^1 M \oplus \Lambda^0 M$ \leftarrow Λ -product
exterior derivative

$$\text{Det}^2 \phi, \psi \text{ 1-forms} \Rightarrow (\phi \wedge \psi)(v, w) = \phi(v)\psi(w) - \phi(w)\psi(v)$$

P_{props}

$$(\phi_1 + \phi_2) \wedge \psi = \phi_1 \wedge \psi + \phi_2 \wedge \psi$$
$$\phi \wedge \psi = -\psi \wedge \phi$$

$$\alpha \wedge \beta = (-1)^{pq} \beta \wedge \alpha \quad p, q = 0, 1, 2$$

Exterior Derivative $d: \Lambda^r M \rightarrow \Lambda^{r+1} M$

P=0 $(df)(v) = v[f]$

P=1 $d\phi(v, w) = v[\phi(w)] - w[\phi(v)] = - (w[d\phi] - v[d\phi]) = -d\phi(w, v).$

Thm/ If $f: M \rightarrow \mathbb{R}$ then $d(df) = 0$

Proof: Let $\psi = df$, $d(df) = d\psi$. Let $v, w \in \Gamma(M)$

$$\begin{aligned} (d\psi)(v, w) &= v[\psi(w)] - w[\psi(v)] \\ &= v[df(w)] - w[df(v)] \\ &= v[w[f]] - w[v[f]] \end{aligned}$$

Use lemma 4.2 use Σ_u, Σ_v

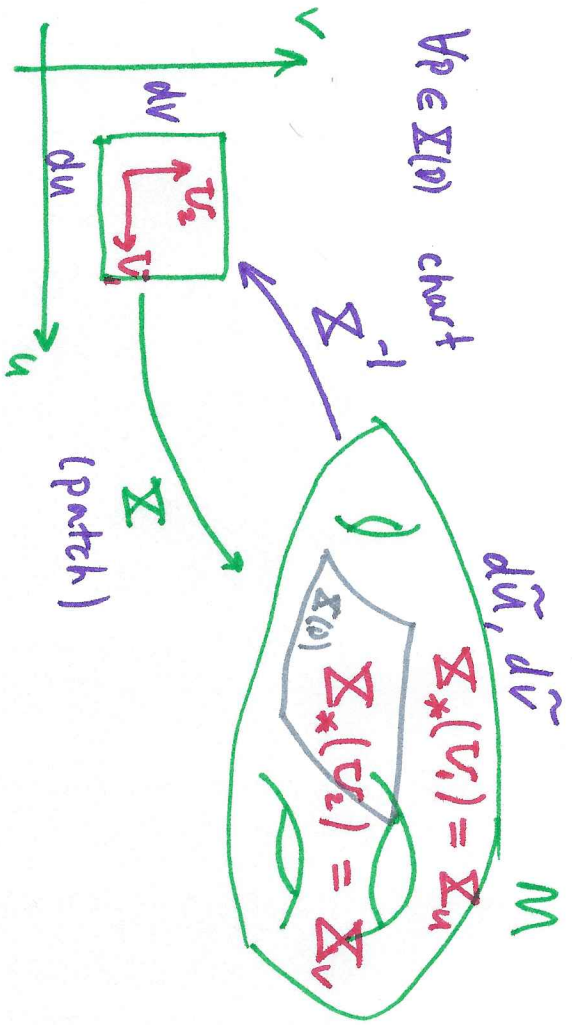
$$\begin{aligned} d\psi(\Sigma_u, \Sigma_v) &= \Sigma_u(\Sigma_v(f)) - \Sigma_v(\Sigma_u(f)) \\ &= \frac{\partial}{\partial u} \frac{\partial}{\partial v} [f \circ \Sigma] - \frac{\partial}{\partial v} \frac{\partial}{\partial u} [f \circ \Sigma] \\ &= 0. \Rightarrow d\psi = d(df) = 0. \end{aligned}$$

Recall $\alpha = \sum_I \alpha_I dx^I \rightarrow d\alpha = \sum_I d\alpha_I \wedge dx^I$

Discuss (HARTS)

$\Sigma^{-1}(p) = (\tilde{u}(p), \tilde{v}(p)) \forall p \in \Sigma(0)$ chart

$\frac{\tilde{u}(\Sigma(u,v))}{\tilde{v}(\Sigma(u,v))} = u$
 $\frac{\tilde{v}(\Sigma(u,v))}{\tilde{u}(\Sigma(u,v))} = v$



$\Sigma^{-1}(\Sigma(u,v)) = (u,v)$

$(\tilde{u}(\Sigma(u,v)), \tilde{v}(\Sigma(u,v))) = (\underline{u}, \underline{v})$

using # 4 of p. 156

$d\tilde{u}(\Sigma_u) = \frac{\partial}{\partial u} [\tilde{u}(\Sigma(u,v))] = \frac{\partial \tilde{u}}{\partial u} = 1$ $d\tilde{u}(\Sigma_v) = \frac{\partial \tilde{u}}{\partial v} = 0$
 $d\tilde{v}(\Sigma_v) = \frac{\partial \tilde{v}}{\partial v} = 1$ $d\tilde{v}(\Sigma_u) = \frac{\partial \tilde{v}}{\partial u} = 0$

Why $\Sigma_*(V_1) = \Sigma_u$ and $\Sigma_*(V_2) = \Sigma_v$:

$\Sigma: D \subseteq \mathbb{R}^2 \rightarrow M \subseteq \mathbb{R}^3$ frame in $\mathbb{R}^3: \bar{V}_1, \bar{V}_2, \bar{V}_3$
 $V_1 = \frac{\partial}{\partial u}$ $V_2 = \frac{\partial}{\partial v}$

$$\begin{aligned} \Sigma_*(V_1) &= dx(V_1)\bar{V}_1 + dy(V_1)\bar{V}_2 + dz(V_1)\bar{V}_3 & \Sigma &= (x, y, z) \\ &= V_1[x]\bar{V}_1 + V_1[y]\bar{V}_2 + V_1[z]\bar{V}_3 \\ &= \frac{\partial x}{\partial u}\bar{V}_1 + \frac{\partial y}{\partial u}\bar{V}_2 + \frac{\partial z}{\partial u}\bar{V}_3 \\ &= \Sigma_u & \text{Likewise } \Sigma_*(V_2) &= \Sigma_v \end{aligned}$$

Also, $\Sigma_u[f] = \frac{\partial}{\partial u}(f \circ \Sigma)$ $\Sigma_*(\frac{\partial}{\partial u}) = \Sigma_u$
 $\Sigma_*(\frac{\partial}{\partial v}) = \Sigma_v$

$$\Sigma_u[f] = \frac{\partial x}{\partial u} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial u} \frac{\partial f}{\partial y} + \frac{\partial z}{\partial u} \frac{\partial f}{\partial z} = \frac{\partial}{\partial u} [(f \circ \Sigma)] //$$

~~Example~~

$$M = \mathbb{R}^2$$

$$U = \tilde{u}, \quad V = \tilde{v}$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\phi = f, du + f_2 dv$$

$$\eta = \textcircled{g} du \wedge dv$$

$$g = \eta(v_1, v_2)$$

$$\Sigma(u, v) = (u, v)$$

⑤

$$\phi(\Sigma_u) = f_1, \quad \phi(\Sigma_v) = f_2$$

$$\phi(v_1) = f_1, \quad \phi(v_2) = f_2$$

$$df = \frac{\partial f}{\partial u} du + \frac{\partial f}{\partial v} dv$$

$$d\phi = df_1 \wedge du + df_2 \wedge dv = \left(\frac{\partial f_1}{\partial u} - \frac{\partial f_2}{\partial v} \right) du \wedge dv$$

$$\phi = f_1 du + f_2 dv$$

Example $\Sigma(u, v) = (1, 2, 3)u + (-3, 0, 1)v$
 is a plane through origin.

$$\Sigma_u = v_1 + 2v_2 + 3v_3$$

$$\Sigma_v = -3v_1 + v_3$$

$\Sigma(u, v) = (x, y, z)$ find $\Sigma^{-1}(x, y, z)$ just solve for u & v

$$x = u - 3v$$

$$y = 2u$$

$$z = 3u + v$$

$$\rightarrow u = y/2 = \tilde{u}$$

$$\rightarrow v = z - 3u = z - \frac{3}{2}y = \tilde{v}$$

$$\Sigma^{-1}(x, y, z) = (y/2, z - \frac{3}{2}y)$$

$$\underline{d\tilde{u}} = \frac{1}{2}dy \quad \& \quad \underline{d\tilde{v}} = dz - \frac{3}{2}dy$$

$$d\tilde{u}(\Sigma_u) = \frac{1}{2}dy (\underbrace{v_1 + 2v_2 + 3v_3}_{\tilde{v}_0}) = 1 = d\tilde{v}(\Sigma_v)$$

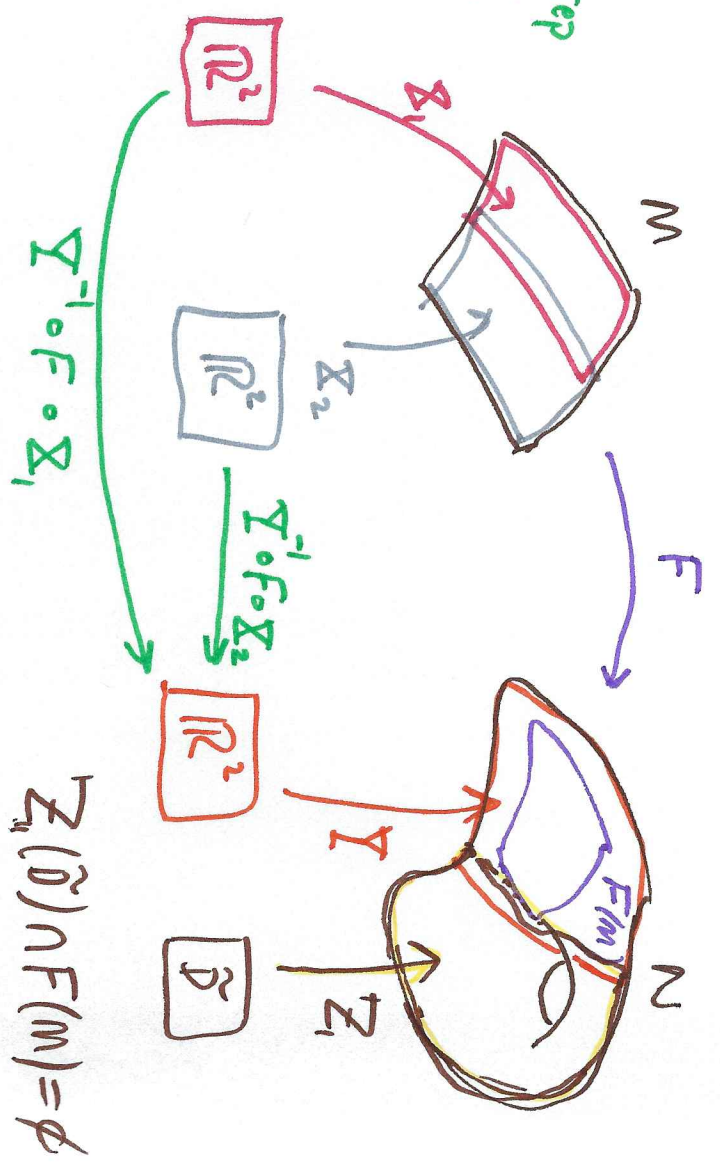
$$\text{Likewise } d\tilde{u}(\Sigma_v) = d\tilde{v}(\Sigma_u) = 0$$

Defⁿ / a form ϕ is closed if $d\phi = 0 \Rightarrow \phi = d\psi$
 a form ϕ is exact if $\phi = d\psi \Rightarrow d\phi = d^2\psi = 0$.

MAPS BETWEEN SURFACES IN \mathbb{R}^3 (84.5)

(7)

Defⁿ / $F: M \rightarrow N$ is smooth iff every local coord. rep. of F is smooth. Where local coord. rep is a composite of the patch Σ on M and patch Σ on N



11/1/2019

Ex ①) $\Sigma = \{N, S\} \longrightarrow$ cylinder

$$\Sigma(u, v) = (\cos v \cos u, \cos v \sin u, \sin v)$$

$$F(\Sigma(u, v)) = (\cos u, \sin u, \sin v)$$

$$\Sigma(u, v) = (\cos u, \sin u, v)$$

$$\Sigma^{-1}(P^1, P^2, P^3) = (\tan^{-1}(P^2/P^1), P^3)$$

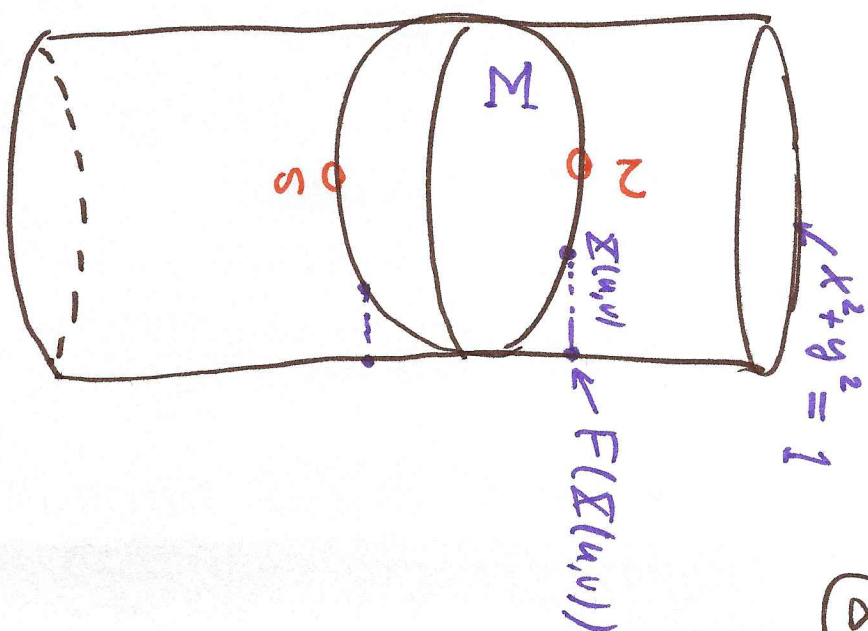
$$\Sigma^{-1}(F(\Sigma(u, v))) = (u, \sin v)$$

$$\left[\tan^{-1}\left(\frac{\sin v}{\cos v}\right) = \tan^{-1}(\tan v) = v. \right]$$

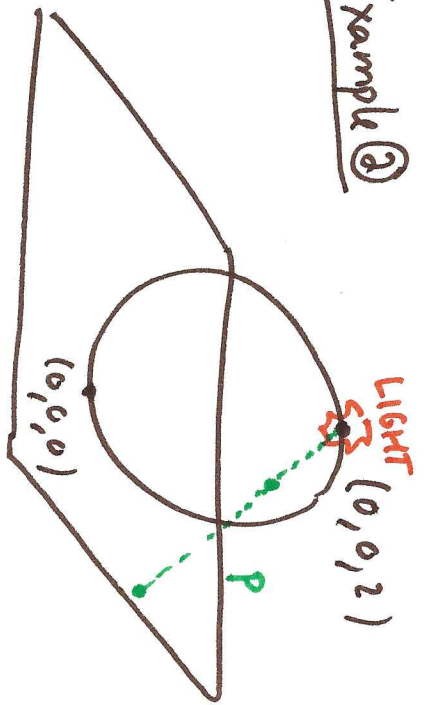
$$(u, v) \xrightarrow{h} (u, \sin v)$$

$$J_h = \begin{bmatrix} 1 & 0 \\ 0 & \cos v \end{bmatrix}$$

$$\det(J_h) = \cos v$$



Example 2



$$P(p^1, p^2, p^3) = \left(\frac{2p^1}{2-p^3}, \frac{2p^2}{2-p^3} \right)$$

$$P: M \rightarrow N$$

Sphere
Module
N

plane

$$P(\Sigma(u,v)) = \left(\frac{2 \cos v \cos u}{1 - \sin v}, \frac{2 \cos v \sin u}{1 - \sin v} \right)$$

$$h(u,v) = \frac{2 \cos v}{1 - \sin v} (\cos u, \sin u) = f(v) (\cos u, \sin u)$$

$$J_h = \begin{bmatrix} \frac{\partial h}{\partial u} & \frac{\partial h}{\partial v} \end{bmatrix} = \begin{bmatrix} -f(v) \sin u & f'(v) \cos u \\ f(v) \cos u & f'(v) \sin u \end{bmatrix}$$

$$\det(J_h) = -f(v) f'(v) [\sin^2 u + \cos^2 u]$$

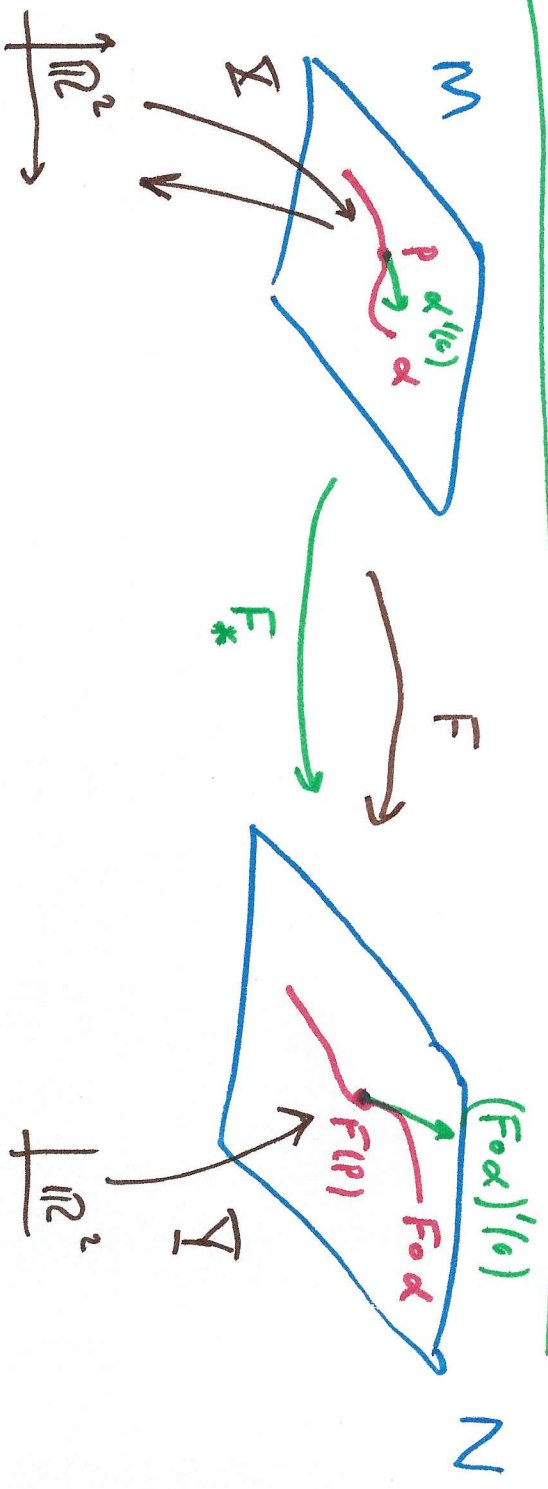
$$= -\frac{2 \cos v}{1 - \sin v} \left[\frac{-2 \sin v (1 - \sin v) - 2 \cos v (-\cos v)}{(1 - \sin v)^2} \right]$$

$$= \frac{-2 \cos v [2 - 2 \sin v]}{(1 - \sin v)^3} = \frac{-4 \cos v}{(1 - \sin v)^2} \neq 0$$

9

Defⁿ $F: M \rightarrow N$ $\text{Ker}(F_*) = (F_*)^{-1}(0)$

$$F_* (\alpha'(t_0)) = (F \circ \alpha)'(t_0)$$



Prop. $F_* (\Sigma_u) = \Sigma_v$ & $F_* (\Sigma_v) = \Sigma_w$

Defⁿ $F: M \rightarrow N$ is regular if $(F_*)_p$ is injective for each $p \in M$

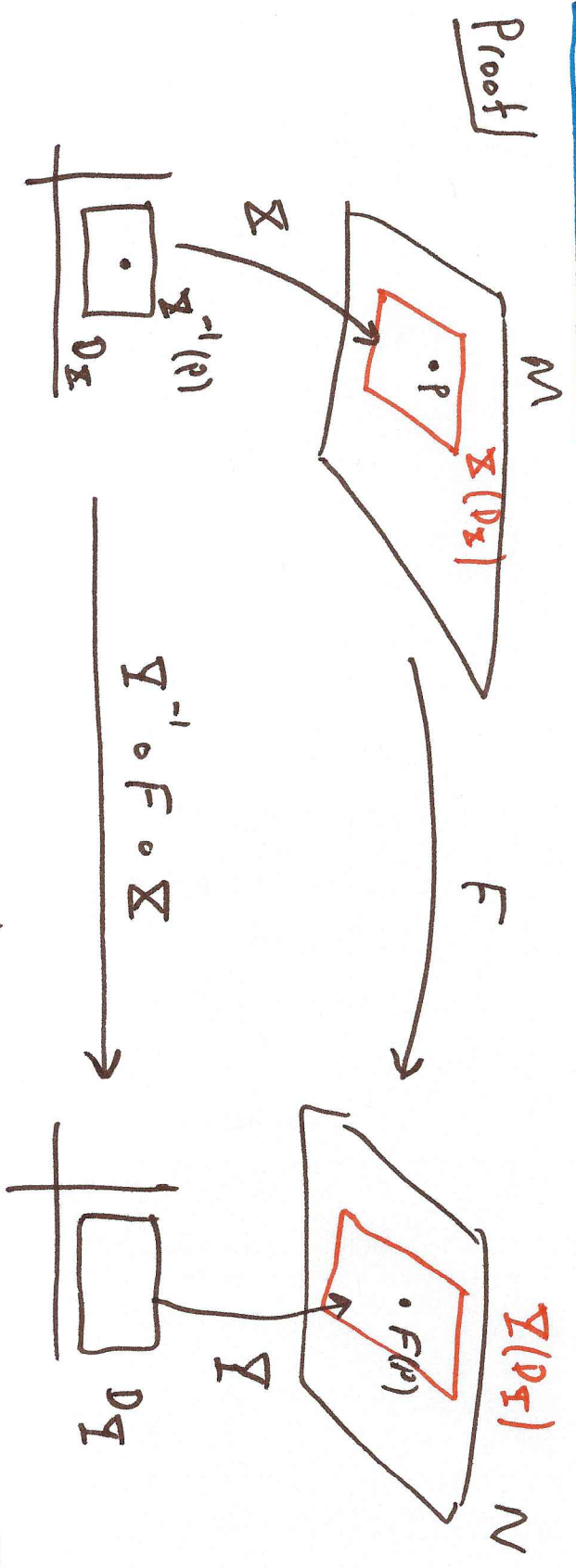
$(F_*)_p$ is linear from $T_p M \rightarrow T_{F(p)} N$

$$\text{Ker}(F_*)_p = \{0\}$$

Defⁿ A smooth map $F: M \rightarrow N$ with smooth inverse $F^{-1}: N \rightarrow M$ is called a DIFFEOMORPHISM.

(11)

Th^m/Let $F: M \rightarrow N$ be smooth map of surfaces and $\exists p \in M$ such that $(F_*)_p: T_p M \rightarrow T_{F(p)} N$ is injective then \exists nbhd U of p in M and V of $F(p)$ in N such that $F|_U: U \rightarrow V$



Claim: injectivity of $(F_*)_p \Rightarrow h = \Sigma^{-1} \circ F \circ \Sigma$ has invertible J_h at $\Sigma^{-1}(p)$.

//

Corollary: a bijection $F: M \rightarrow N$ which is smooth and regular has smooth F^{-1} . That is, a regular bijection of M to N is a diffeomorphism.

Ex ①: $F(u, v) = (\tan u, \tan v)$ | $F^{-1}(u, v) = (\tan^{-1}(u), \tan^{-1}(v))$
 $F: (-\pi/2, \pi/2)^2 \rightarrow \mathbb{R}^2$ | $J_F = \begin{bmatrix} \sec^2 u & 0 \\ 0 & \sec^2 v \end{bmatrix}$ invertible on dom F .

Ex ②: $\Sigma - N \approx \mathbb{R}^2$
 O'Neill argues $P_x(\Sigma_u) = \Sigma_u$ } \perp hence P_x injective.
 $P_x(\Sigma_v) = \Sigma_v$

Ex ③: A cylinder C over a closed is diffeomorphic to $\mathbb{R} - \{0\}$
 $x^2 + y^2 = 1$ $F(x, y, z) = e^z(x, y)$

$\Sigma(u, v) = (\cos u, \sin u, v)$ $F(\Sigma(u, v)) = e^v(\cos u, \sin u)$

$F(x, y, z) = (u, v)$
 $u = e^z x \rightarrow x = u e^{-z}$
 $v = e^z y \rightarrow y = v e^{-z}$
 $x^2 + y^2 = 1$
 $u^2 + v^2 = e^{2z}$
 $e^z = \sqrt{u^2 + v^2}$

$z = \ln(u^2 + v^2)$
 $x = u / \sqrt{u^2 + v^2}$
 $y = v / \sqrt{u^2 + v^2}$
 $F^{-1}(u, v)$

Not wrong, but ignore for what follows

THE PULL-BACK

Defⁿ Let $F: M \rightarrow N$ be smooth map (F need not be invertible etc.) of surfaces M & N then define:

(0.) $F^*g = g \circ F$ for each $g: N \rightarrow \mathbb{R}$

(1.) for $\phi \in \Lambda^1(N)$ we define $F^*\phi \in \Lambda^1(M)$ by $(F^*\phi)(v) = \phi(F_*v)$

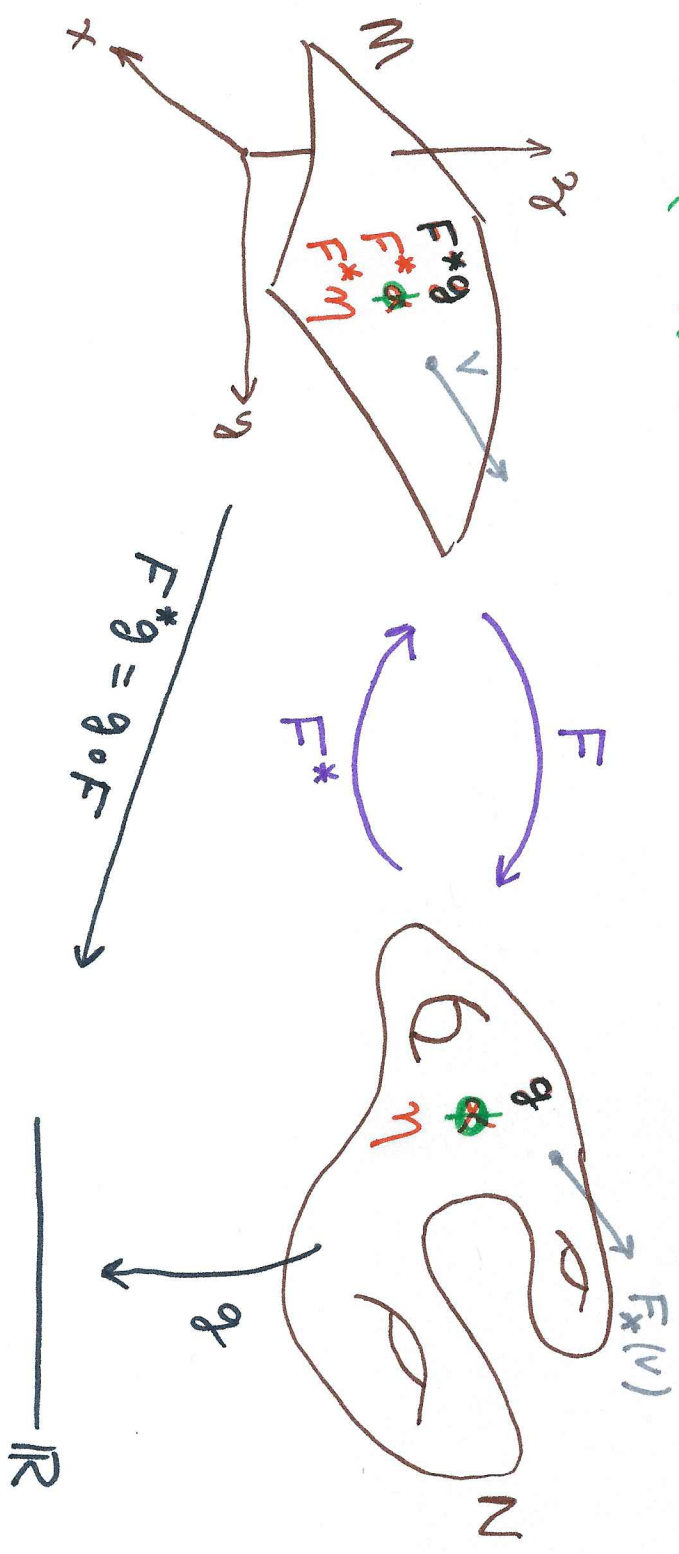
for each tangent v to M

(2.) for $\eta \in \Lambda^2(N)$ define $F^*\eta \in \Lambda^2(M)$ by

$$(F^*\eta)(v, w) = \eta(F_*v, F_*w) \text{ for all tangents } v, w \text{ to } M$$

$$(F^*\phi)_p(v) = \phi_{F(p)}((F_*)_p(v))$$

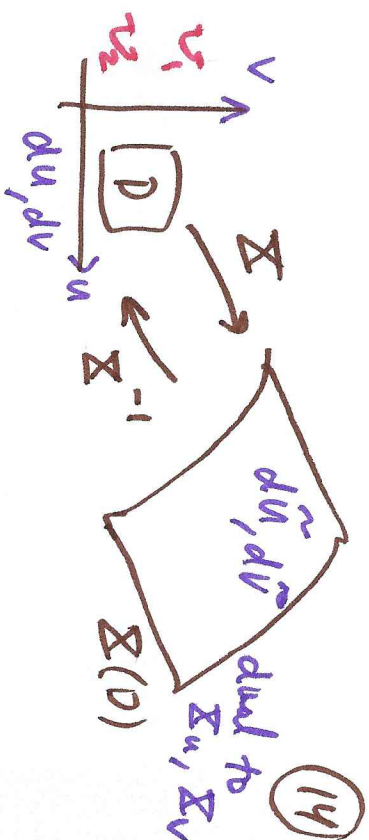
\swarrow
 $v \in T_p M$



Example: $(\Sigma^{-1})^*(du) = d\tilde{u}$

$$\begin{aligned} \left((\Sigma^{-1})^*(du) \right) (\Sigma_u) &= du \left(\underline{(\Sigma^{-1})^*} (\Sigma_u) \right) \\ &= du \left(\underline{V_1} \right) \\ &= \frac{\partial u}{\partial v} \\ &= 1. \end{aligned}$$

Likewise, $\left((\Sigma^{-1})^*(du) \right) (\Sigma_v) = \frac{\partial u}{\partial v} = 0$



$$\Sigma_* (V_1) = \Sigma_u \rightarrow V_1 = (\Sigma^{-1})^*(\Sigma_u)$$

$$\Sigma^{-1} \circ \Sigma = Id$$

$$\underline{(\Sigma^{-1})^* \circ \Sigma_* = Id}$$

$$\therefore \underline{(\Sigma^{-1})^*(du) = d\tilde{u}} \quad \underline{dg \circ dF = d(g \circ F)}$$

$$F_* = dF$$

Properties:

- (1) $F^*(\alpha + \beta) = F^*\alpha + F^*\beta$
- (2) $F^*(\alpha \wedge \beta) = (F^*\alpha) \wedge (F^*\beta)$
- (3) $F^*(d\alpha) = d(F^*\alpha)$

Proof: Let g be 0-form

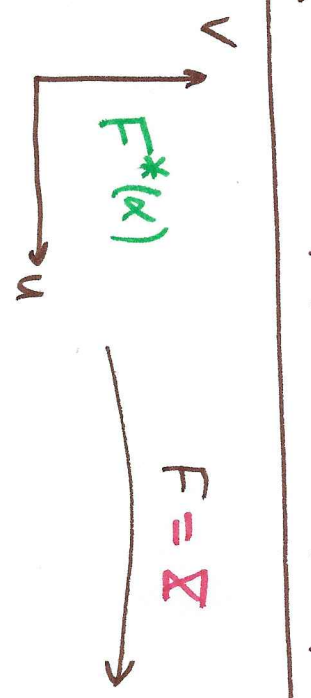
$$(F^*(dg)) (\Sigma_u) = dg (F_*(\Sigma_u))$$

$$= d(g \circ F) (\Sigma_u)$$

$$= d(F^*g) (\Sigma_u)$$

$$\therefore \underline{F^*(dg) = d(F^*g)}$$

Example: $F(u, v) = (u+v, u, u-v) = (x, y, z)$



$$(F^* \alpha)(v_i) = \alpha(\Sigma_* v_i) = \alpha(\Sigma_u)$$

$$(F^* \alpha)(v_2) = \alpha(\Sigma_v)$$

$$F^* \alpha = \alpha(\Sigma_u) du + \alpha(\Sigma_v) dv = u dv \rightarrow d(F^* \alpha) = d(u dv) = du \wedge dv$$

$$\alpha(\Sigma_u) = (\tilde{u} d\tilde{v}) (\Sigma_u) = \tilde{u} d\tilde{v} (\Sigma_u) = 0$$

$$\alpha(\Sigma_v) = (\tilde{u} d\tilde{v}) (\Sigma_v) = \tilde{u} \rightarrow u$$

$$F^* (\alpha) = F^* (d\tilde{u} \wedge d\tilde{v}) = (F^* d\tilde{u}) \wedge (F^* d\tilde{v}) = \underline{du \wedge dv}$$

$$\alpha = \tilde{u} d\tilde{v} = \frac{y}{2} (dx - dz) \rightarrow d\alpha = \frac{1}{2} dy \wedge dx - \frac{1}{2} dy \wedge dz$$

$$F^* \alpha = \frac{u}{2} (du + dv - (du - dv)) = u dv$$

$$F^* d\alpha = \frac{1}{2} du \wedge (du + dv) - \frac{1}{2} du \wedge (du - dv) = du \wedge dv = d(u dv) \cdot x$$

subst. u, v for x, y, z

$$F^{-1}(x, y, z) = (y, \frac{1}{2}(x-z))$$

$$v = \frac{1}{2}(x-z)$$

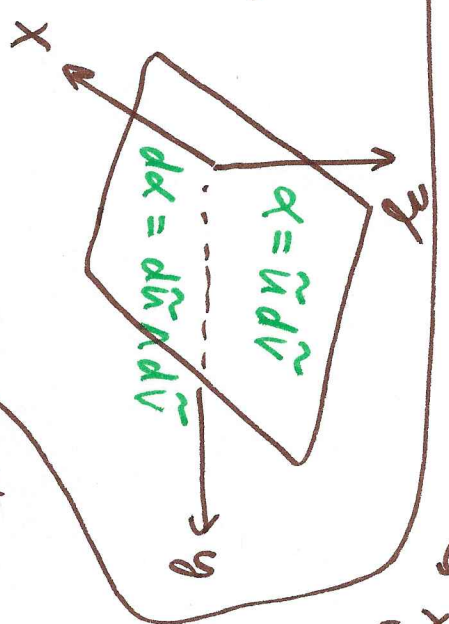
$$x-z = 2v$$

$$y = u$$

$$z = u - v$$

$$y = u$$

$$x = u + v$$

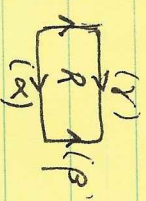


Integration of Forms

- ① 1-forms on curve segments
 2-forms on two-segments

① $\int_{\alpha} \phi = \int_{[a,b]} \alpha^* \phi = \int_a^b \phi(\alpha'(t)) dt$

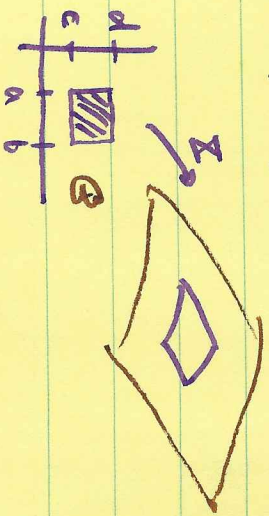
$\mathbb{R}^n / (0,1) \quad \alpha: [a,b] \rightarrow M$ a curve segment from
 $p = \alpha(a)$ to $q = \alpha(b)$ then $\int_{\alpha} df = f(q) - f(p)$

② 2-segment is image of (D) 

$$\iint_{\Sigma} \eta = \iint_{D} \alpha^* \eta = \int_a^b \int_c^d \eta(\Sigma_u, \Sigma_v) du dv$$

$$\partial \Sigma = \alpha + \beta - \gamma - \delta$$

$$\iint_{\Sigma} d\phi = \int_{\partial \Sigma} \phi$$



oriented integrals, switch signs when a reversal of direction of α .