

LECTURE 14: TOPOLOGICAL PROP. OF SURFACES & MANIFOLDS:

Defⁿ A surface M is connected if for each $p, q \in M$ there exist a map $\alpha: [a, b] \rightarrow M$ s.t. $\alpha(a) = p$ & $\alpha(b) = q$
(curve-segment) (path-connected)

Defⁿ M is compact if every open cover of M admits a finite subcover

$\left\{ \begin{array}{l} [a, b] \\ [a, b] \times [c, d] \end{array} \right\}$ examples of compact sets.

Lemma 7.2: A surface M is compact iff it can be covered by the images of finitely many 2-segments

Btw, Massey's Algebraic Topology: [any compact surface is the image of a single 2-segment]

Lemma (7.3) A continuous fct on a compact $\mathcal{Q} \subseteq M$ attains a maximum value at some point $p \in \mathcal{Q}$.

Ex] $C : x^2 + y^2 = 1$

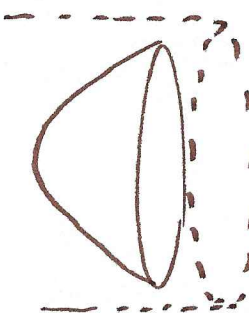
$f(x, y, z) = z \leftarrow$ continuous & unbounded on C

$\therefore C$ is NOT compact

Ex] OPEN DISK : $D : x^2 + y^2 < 1$

$f(x, y) = \frac{1}{1 - x^2 - y^2}$ unbounded on D

$\therefore D$ NOT compact.



compact: smoothly closed up with no fuzzy edges & finite in size.

Defⁿ A surface M is orientable if \exists a diff. 2-form μ on M which is everywhere non zero.

Ex] $\mathbb{R}^2_{uv} : \mu = du \wedge dv$

Ex] $\Sigma(D) : \mu = d\tilde{u} \wedge d\tilde{v}$

Prop. 7.5/ A surface $M \subset \mathbb{R}^3$ is orientable $\iff \exists \mathcal{T}$ a unit-normal vector field on M .
Moreover, if M is connected then $\pm \mathcal{T}$ are the only two normals.

Proof \implies $\exists p \in \Lambda^2 M$ and $\mu(p) \neq 0 \forall p \in M$. Define, for v, w a basis of $T_p M$

$$\mathcal{T}(p) = \frac{v \times w}{\mu(p)(v, w)} = \frac{v' \times w'}{\mu(p)(v', w')} \in (T_p M)^\perp$$

Observe $\in (v, w) = v \times w. \in (\underbrace{av+bw}, \underbrace{cv+dw}) = \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mu(p)(v, w)$

Likewise, $\mu(p)(av+bw, cv+dw) = \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mu(p)(v, w)$.

Let $\mathcal{U}(p) = \frac{\mathcal{T}(p)}{\|\mathcal{T}(p)\|}$ is a unit-normal. Consider

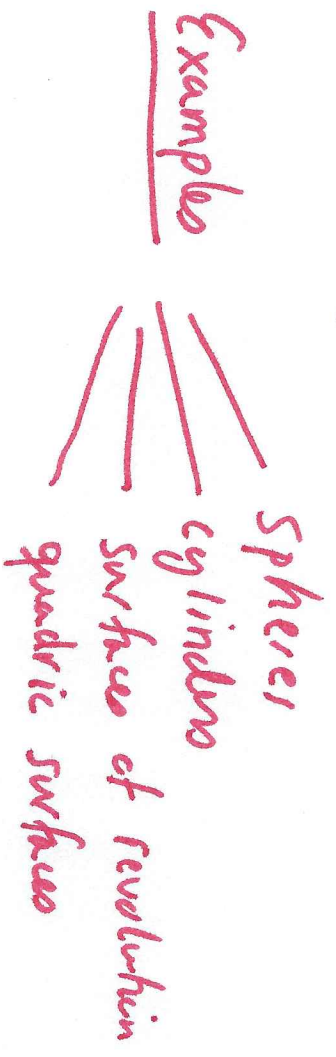
fnct $f(p) = \mathcal{V}(p) \cdot \mathcal{U}(p)$ where $\mathcal{V}(p)$ is any other unit-normal

$\implies f(p) = \pm 1 \xrightarrow{\text{connected}} f(p) = 1$ or $f(p) = -1$ for all $p \in M$
 $\therefore \mathcal{V} = \mathcal{U}$ or $\mathcal{V} = -\mathcal{U}$

Proof: $\exists \perp$ \exists a unit-normal U on M . Let $v, w \in T_p M$ (4)

$$\nu(p)(v, w) = U(p) \cdot (v \times w)$$

Since $\exists \{v, w\}$ LI at each p , $v \times w \neq 0$ and so $U(p) \neq 0$ and by \perp Theorems $U(p)$ is colinear to $v \times w \Rightarrow \nu(p) \neq 0$.



Non-EXAMPLE: Mobius BAND

Th^m A compact surface in \mathbb{R}^3 is orientable

Th^m A simply-connected is orientable

Defⁿ A closed curve α is homotopic to a constant

provided $\exists \alpha$ -segment $\Sigma: [a, b] \times [0, 1] \rightarrow M$ (homotopy)

s.t. α is the base curve $\alpha(u) = \Sigma(u, 0)$

and the other three edge curves are constant at $p = \alpha(a) = \alpha(b)$

Defⁿ M is simply connected provided it is connected and every loop in M is homotopic to a constant

$\beta(v) = \Sigma(b, v)$

$\gamma(u) = \Sigma(u, 1)$

$\delta(v) = \Sigma(a, v)$



$\partial \Sigma(R) = \alpha + \beta - \gamma - \delta$

$\alpha_v(u) = \Sigma(u, v)$
 $v=0 \rightarrow \alpha_0(u) = \Sigma(u, 0) = \alpha(u)$
 $v=1 \rightarrow \alpha_1(u) = \Sigma(u, 1) = \gamma(u) = p$

Lemma (7.8): ϕ is a closed 1-form on surface M and if a loop α in M is homotopic to a constant then $\int_{\alpha} \phi = 0$

Proof: $d\phi = 0$
 $0 = \iint_{\Sigma} d\phi = \int_{\partial \Sigma} \phi = \int_{\alpha} \phi = \int_{\alpha} \phi = \int_{\alpha} \phi$
 $\therefore \int_{\alpha} \phi = 0 \quad \parallel$

Application : punctured plane P

(6)

$$\mathcal{V} = \frac{x dy - y dx}{x^2 + y^2} \quad \alpha \text{ loop around origin}$$

$\int_{\alpha} \mathcal{V} = 2\pi \quad \therefore \alpha$ is NOT Homotopic to constant
 $\therefore P$ NOT simply connected.

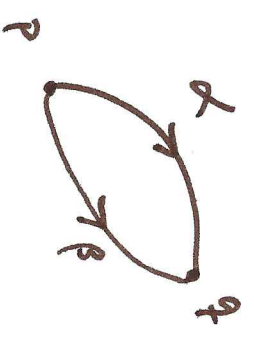
Lemma (7.9) (Poincaré) On simply connected surface every closed form is exact.

$$\phi \text{ s.t. } d\phi = 0 \Rightarrow \exists \psi \text{ s.t. } d\psi = \phi$$

Proof : M simply connected surface

α, β are two curve-segments

both from p to q . Let ϕ have $d\phi = 0$



$\alpha - \beta = \text{loop}$

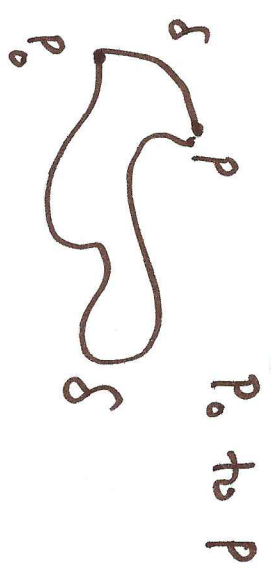
$$0 = \int_{\text{loop}} \phi = \int_{\alpha - \beta} \phi = \int_{\alpha} \phi + \int_{\beta} \phi = \int_{\alpha} \phi - \int_{\beta} \phi = 0$$

ψ a potential

PATH-INDPENDENCE!

Proof continued: pick $P_0 \in M$ then let γ be curve-seg. from P_0 to P (7)

$$f(P) = \int_{\gamma} \phi$$



We wish $\phi = df \implies \phi(v) = df(v)$

Consider $\alpha: [a, b] \rightarrow M$ with $\alpha'(a) = v$

The path β is formed by $\underbrace{\gamma}_{\text{starts at } P_0}$ then $\alpha|_{[a, t]}$ ends at $\alpha(t)$.

$$f(\alpha(t)) = \int_{\beta} \phi = \int_{\gamma} \phi + \int_{\alpha|_{[a, t]}} \phi = f(P) + \int_a^t \phi(\alpha'(u)) du$$

~~$$\alpha'(t) [f] = (f \circ \alpha)'(t) = \frac{d}{dt} \left[\int_a^t \phi(\alpha'(u)) du \right] = \phi(\alpha'(t))$$~~

$$\alpha'(0) [f] = \phi(\alpha'(0))$$

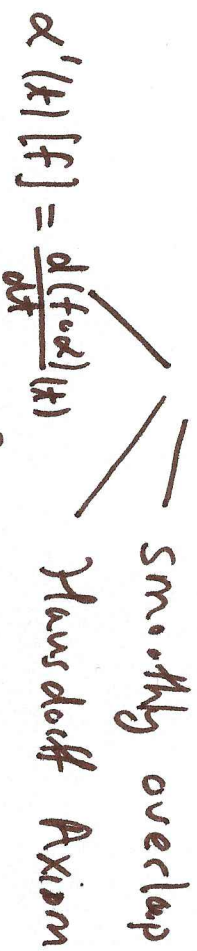
$$v [f] = \phi(v)$$

$\underbrace{df(v)} = \phi(v) \therefore df = \phi$ hence ϕ is exact. \parallel

Manifolds

§4.8: O'Neill describes an axiomatic geometric surface.

M an abstract set — cover of it by patches



§4.1-4.7: CALCULUS FOR $M \subseteq \mathbb{R}^3$ where topology given by subspace topology of Euclidean \mathbb{R}^3 topology.

Defⁿ A n -dim'l manifold is a set M with a collection \mathcal{P} of patches (one-to-one frct. $\Sigma: D \rightarrow M, D \subseteq \mathbb{R}^n$)
satisfying — (1) the patches cover M
(2) the patches smoothly overlap ($\gamma^{-1}\Sigma, \Sigma^{-1}\gamma$)
(3) the Hausdorff property
 $p \neq q \in M$ then \exists disjoint patches
 $\Sigma \in \mathcal{I}$ with $p \in \Sigma(D), q \in \gamma(E)$

SURFACE IS JUST $n=2$ dim'l manifold.