

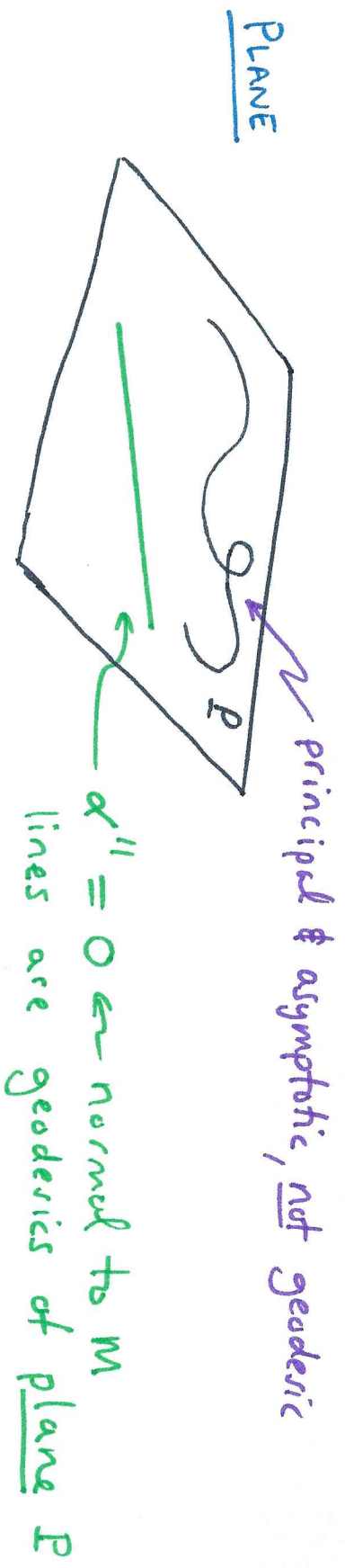
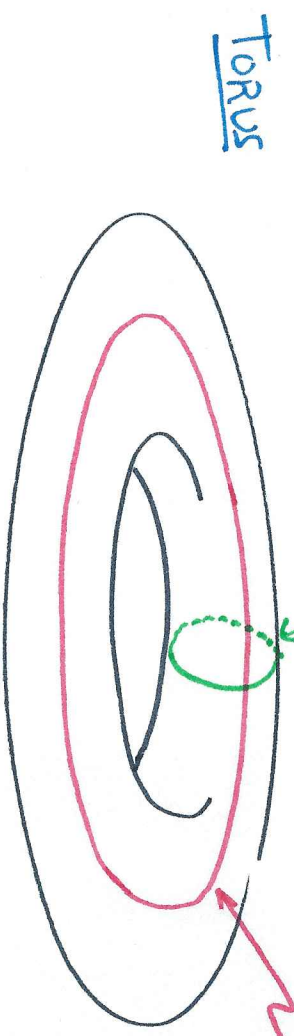
LECTURE 17: SPECIAL CURVES (§5.6) & SURFACES OF REVOLUTION (§8.2)

1.) PRINCIPAL CURVE: α regular in M with α' always pointing in a principal direction

2.) ASYMPTOTIC CURVE: α regular curve in M with α' always pointing in an asymptotic direction (normal curvature zero)

3.) GEODESIC CURVE: α with α'' always normal to M .
again assume α regular.

These are not mutually exclusive. There is much to say, 1st or two



Lemma (6.2): Let α be regular curve and U the unit normal of M restricted to α in M

(1.) α principal $\iff U'$ and α' are colinear at each point

(2.) α principal \implies principal curvature in α' -direction is $\frac{\alpha'' \cdot U}{\alpha' \cdot \alpha'}$

(1) Proof: β α principal then $S(\alpha') = k\alpha'$ along α

But, $S'(\alpha') = -\nabla_{\alpha'} U = -\underbrace{U'}_{\text{derivative of } U}$ hence U' and α' are colinear.

Conversely, if $U' = -k\alpha' \implies S(\alpha') = k\alpha' \implies \alpha$ principal.

(2) Proof: β α principal curve $\implies S(\alpha') = k\alpha'$

However, $\alpha' \cdot S(\alpha') = \alpha'' \cdot U$ by Lemma 2.1 of (SS.2 pg. 209)

Hence $k\alpha' \cdot \alpha' = \alpha'' \cdot U \therefore k = \frac{\alpha'' \cdot U}{\alpha' \cdot \alpha'}$

Lemma 6.3: Let α be curve formed by intersection of surface M and plane P . If the angle between M and P is constant along α then α is principal curve of M

Proof: Let U be normal to M $\theta_1 \neq \theta_2$

Let V be normal to P (V constant vector field)

Both $U \neq V$ are assumed to be of unit-length; $\|U\| = \|V\| = 1$. If θ_0 is

the fixed angle between $U \neq V$ along $\alpha = M \cap P$

then $U \cdot V = \cos \theta_0$ along α ; $\frac{d}{dt}(U \cdot V) = \frac{d}{dt}(\cos \theta_0) = 0$.

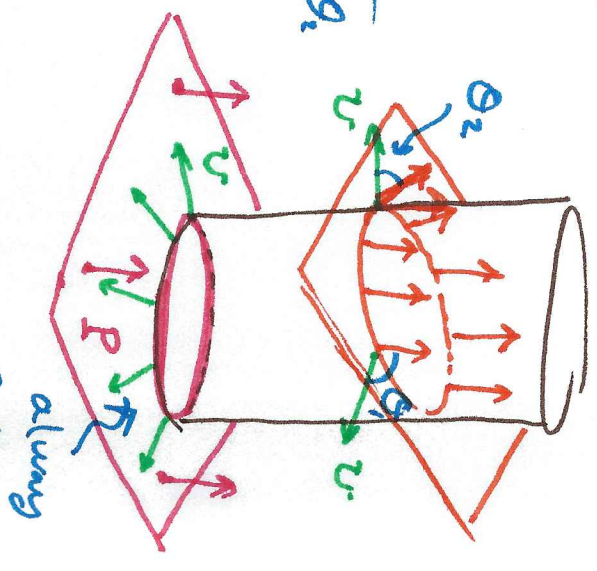
Product Rule,

$$U'_\alpha \cdot V + U \cdot V'_\alpha = 0 \iff U'_\alpha \cdot U = 0 \iff \underline{U'_\alpha \cdot U = 0}$$

~~Then $U'_\alpha \cdot V = 0$ (no need to reprove lemma 6.2 again)~~

Like wise $\alpha' \cdot V = 0$ and $\alpha' \cdot U = 0$ as α lies in both M and P its tangent is \perp to normals of both.

If $U \neq V$ are LI then it follows α' colinear to U' hence by lemma 6.2 α' is principal \curvearrowright



Remark ① if U, V are LI then $U \times V \neq 0$ and $\text{if } U' \perp U, V \Rightarrow U'$ colinear to $U \times V$ $\beta \rightarrow U'$ colinear to $\alpha' \perp U, V \Rightarrow \alpha'$ colinear to $U \times V$ $\beta \rightarrow U'$ colinear to α'

② On the other hand if $U = \pm V$ then U is also constant since V is plane-normal $\Rightarrow S(\alpha') = 0$

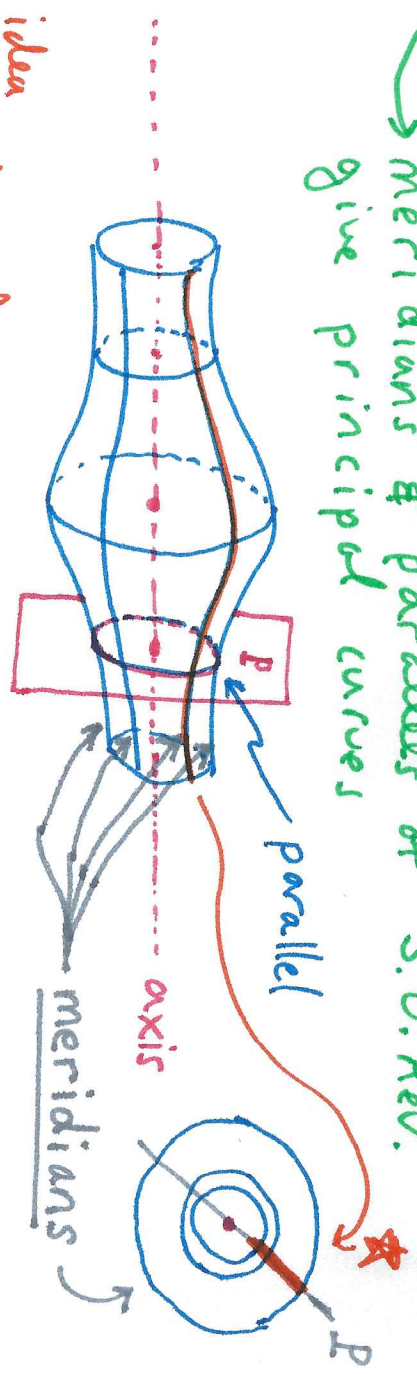
Hence α' is principal with $k(\alpha') = 0$ (α unit-speed)

Remark: to apply Lemma 6.3 we need a special type of plane P with respect to M , it must make constant angle θ_0 between the normals of M & P .

meridians & parallels of S.O.Rev. give principal curves

I'm not attempting the P to obtain meridian

well, I give some idea from the other perspective



or $h(\frac{\alpha'}{\|\alpha'\|}) = 0$ if allow non-unit speed... sorry for this boring comment :)

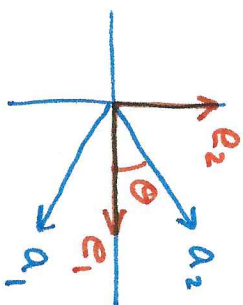
ASYMPTOTIC CURVES

(5)

Lemma (6.4): Let $p \in M \subset \mathbb{R}^3$ and $K(p) = \det S_p$ the Gaussian curvature,

(1.) If $K(p) > 0$ then \nexists asymptotic directions at p

(2.) If $K(p) < 0$ then \exists exactly two asymptotic directions at p (a_1, a_2) which are bisected by the principal ~~axis~~ directions at angle θ as shown



with $\tan^2 \theta = \frac{-k_1(p)}{k_2(p)}$

(3.) IF $K(p) = 0$ then all directions are asymptotic if p is planar pt. Otherwise \exists exactly one asymptotic direction which is also principal

Proof: Asymptotic α has $h(\alpha') = 0$ along unit-speed α . Recall $K = k_1 k_2$ and Euler's formula $h(u) = h_1(p) \cos^2 \theta + k_2(p) \sin^2 \theta$ where $h_1 = h(e_1)$ $k_2 = h(e_2)$

(1.) $K(p) > 0 \Rightarrow k_1, k_2 > 0$ or $k_1, k_2 < 0 \Rightarrow h(u) \neq 0 \forall \theta$.

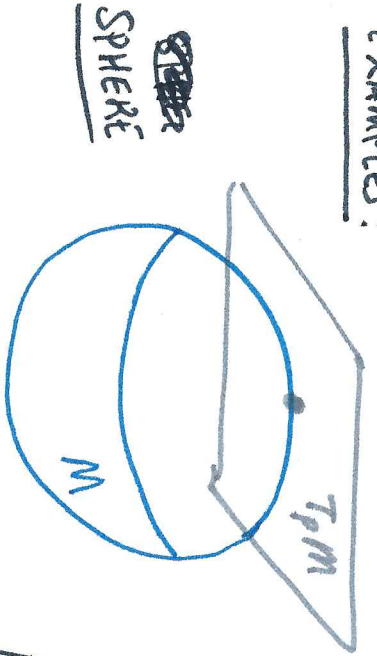
(2.) $K(p) < 0 \Rightarrow 0 = h_1 \cos^2 \theta + k_2 \sin^2 \theta \Rightarrow \tan^2 \theta = \frac{-k_1}{k_2} \therefore \theta = \pm \tan^{-1} \sqrt{\frac{-k_1}{k_2}}$.

The domain of \tan^{-1} places θ as shown a_1, a_2 above & below $\theta = 0$

(3.) p planar $\Rightarrow h_1 = h_2 = 0 \therefore h(u) = 0 \forall u$. e_1 -direction.

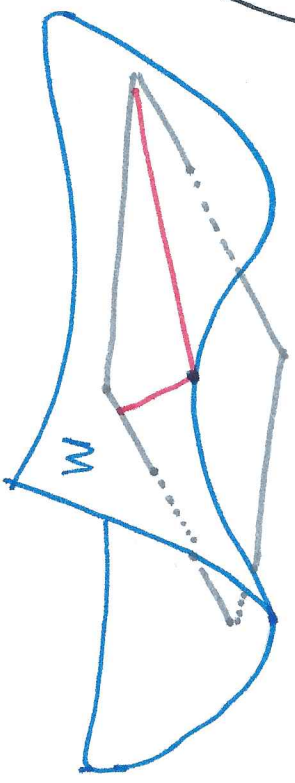
otherwise, say $k_2(p) = 0 \Rightarrow h(u) = h_1(p) \cos^2 \theta = 0$ only for $\theta = \frac{\pi}{2}$ e_2 -direction.

EXAMPLES:



SPHERE

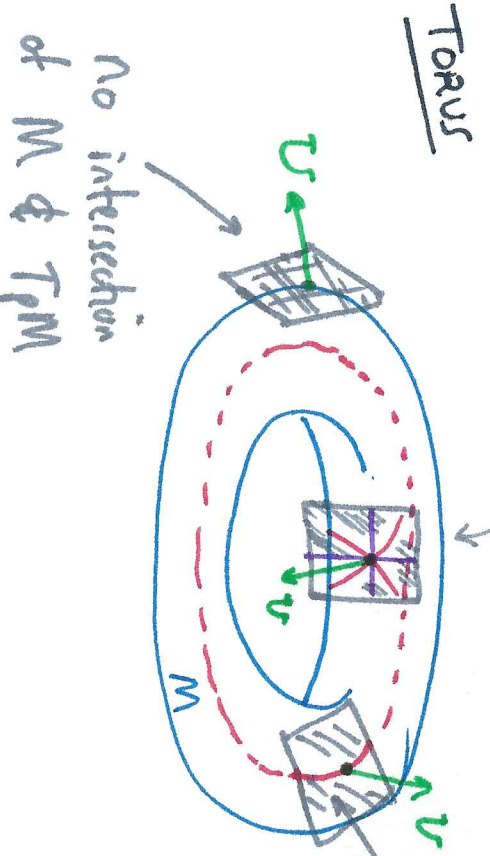
(no intersection,
no asymptotic
directions.)



SADDLE
SURFACE

$z = xy$ intersects
 $z = 0$ $T_{(0,0,0)} M$
along x & y axes
which are the asymptotic
directions at $P = (0,0,0)$

two asymptotic
direction where $K < 0$
birected princ. direction.



TORUS

No intersection
of M & $T_p M$

Gives
one asymptotic direction
at $K = 0$ non-planar point
 M & $T_p M$ intersect along
the top curve.

Def: A regular curve α in $M \subset \mathbb{R}^3$ is an asymptotic curve if α' is always pointing in an asymptotic direction (that is, $h(\alpha') = 0$)

Recall, $S(\alpha') \cdot \alpha' = \alpha'' \cdot \nu$ (we learned this in §5.2)

However, $h(\alpha') = S(\alpha') \cdot \alpha'$ by def of normal curvature

Thus α asymptotic $\Rightarrow h(\alpha') = 0 \Rightarrow S(\alpha') \cdot \alpha' = \alpha'' \cdot \nu = 0$.

Remark: α asymptotic \Rightarrow acceleration α'' is tangent to M ($\alpha'' \cdot \nu = 0$)

Also, as $S(\alpha') = -\frac{\nu'}{|\alpha'|}$ we have the criterion $\nu' \cdot \alpha' = 0$

Proposition: M is minimal iff there exist two orthogonal asymptotic directions at each point on M

See Helicoid Example from LECTURE 16
 $L = 0$ and $N = 0$ show coord. curves have acceler. tangent to M .

Proof: If M minimal then $h_1 + h_2 = 0 \Rightarrow h_1 = -h_2$ thus

$h(\nu) = h_1(\cos^2\theta - \sin^2\theta) \Rightarrow 0 = \pm \pi/4$ gives $a_1, a_2 = u$ with $\frac{\pi}{2} <$
 Conversely, if there exist a_1, a_2 with $a_1 \cdot a_2 = 0$
 and $h(a_1) = h(a_2) = 0$. Let a_1 be at θ_1 and a_2 at θ_2
 between thus $a_1 \cdot a_2 = 0$

$$0 = h_1 \cos \theta_1 + h_2 \sin \theta_1$$

$$0 = h_1 \cos \theta_2 + h_2 \sin \theta_2$$

$$\Rightarrow -h_1 \sin \theta_1 + h_2 \cos \theta_1 = -h_1 \sin \theta_2 + h_2 \cos \theta_2$$

$$\Rightarrow h_1 = -h_2$$

$$\therefore H = 0$$

$\theta_2 = \theta_1 + \frac{\pi}{2}$

Def 10/ A RULED surface is swept out by a line moving in \mathbb{R}^3

⑧

Lemma 6.6: A RULED surface M has Gaussian curvature $K \leq 0$. Furthermore, $K = 0$ iff the unit-normal \mathcal{V} is parallel along each ruling of M

→ Helicoid
→ Saddle surface
I'd be pretty to have the line sweeping animated.

Proof: since ruled surfaces contain lines $\alpha(t) = P + t\mathbf{q}$ and $\alpha'' = 0 \Rightarrow \alpha$ asymptotic $\Rightarrow K \leq 0$ by Lemma 6.4 (see ⑤)

Suppose $\alpha(t) = P + t\mathbf{q}$ is line (ruling) in M and $\mathcal{V} \parallel$ along α

Then $S(\alpha') = -\mathcal{V}' = 0 \Rightarrow h(\alpha') = 0$ and α principal $\therefore K = 0$.

Likewise, if $K = 0$ then by Lemma 6.4 case (3) ~~the~~ asymptotic curves are principal

~~the~~ \mathcal{V} is parallel to ruling α . (see pg. 245 for uncluttered statement, sorry.)

Silly application: Spheres and torus are not ruled. (they have $K > 0$ somewhere or everywhere)

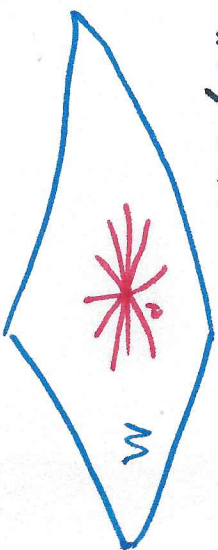
GEODESICS OF M

Def³/ A curve α in $M \subset \mathbb{R}^3$ is geodesic of M provided its acceleration α'' is always normal to M

Comments

① • "inhabitants" of M "feel" no acceleration along geodesic α as α'' is off-world.

② • later we'll learn geodesics, like lines in plane, give length minimizing paths on M . Also there are many geodesics through a point on M , one for each choice of initial velocity.



③ • $\alpha'' \perp T_p M \rightarrow \alpha'' \cdot \alpha' = 0$

$$\rightarrow \frac{d}{dt}(\alpha' \cdot \alpha') = 2\alpha'' \cdot \alpha' = 0$$

$\therefore \|\alpha'\|$ is constant.

geodesics have constant speed.

④ • constant curves are trivially geodesic, usually omit to reduce clutter.

⑤ • lines have $\alpha'' = 0$ hence line in M will be geodesic

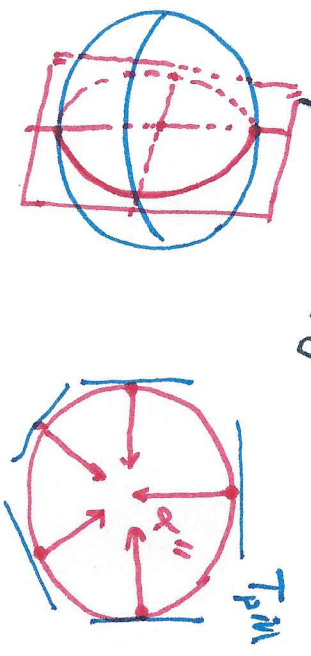
EXAMPLES OF GEODESICS

• Planes: if α is geodesic to plane with normal $U \Rightarrow \alpha' \cdot U = 0$

$\Rightarrow \alpha'' \cdot U = 0$ also know
 $\Rightarrow \alpha'' = 0$ \leftarrow α'' colinear with U
 $\Rightarrow \alpha$ a line

• SPHERES: the geodesics are great circles.

A great circle is formed by intersection of plane through origin and the sphere. (given constant speed parametrization)



• CYLINDERS: for $x^2 + y^2 = R^2$ the geodesics have form

$\alpha(t) = (R \cos(at+b), R \sin(at+b), ct+d)$ (derived \curvearrowright)

$\alpha''(t) = -a^2 R \langle \cos(at+b), \sin(at+b), 0 \rangle = -a^2 R \underbrace{U(\alpha(t))}_{\text{unit-normal to cylinders}}$

$a=0$ ROLLING $\alpha(t) = (R \cos b, R \sin b, ct+d)$
 $a, c \neq 0$ gives helix —
 $c=0$ circle $\alpha(t) = (R \cos(at+b), R \sin(at+b), d)$
 unit-normal to cylinders

Derivation of Cylinder Geodesic

$$\alpha(t) = (R \cos \theta, R \sin \theta, H) \leftarrow \theta, H \text{ functions of } t$$

$$\alpha''(t) = (R \cos \theta'', (R \sin \theta''), H'')$$

$$U = \cos \theta' v_1 + \sin \theta' v_2 \Rightarrow H'' = 0 \therefore H = ct + d.$$

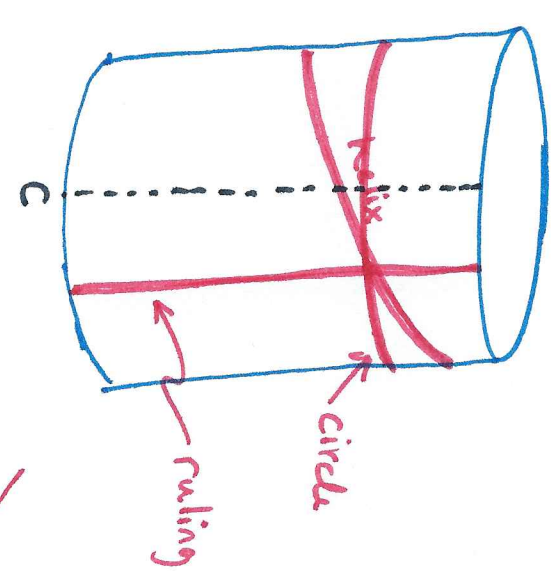
Also, $\alpha'(t) = \langle -R \sin \theta \theta', R \cos \theta \theta', H' \rangle$

$$\|\alpha'(t)\|^2 = R^2 (\sin^2 \theta + \cos^2 \theta) (\theta')^2 + c^2 = \text{constant}$$

$$R^2 (\theta')^2 = \text{constant}$$

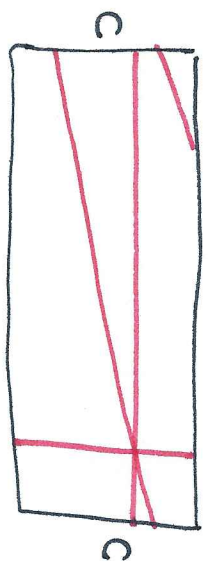
$$\theta' = \text{constant}$$

$$\theta = at + b \therefore \alpha(t) = (R \cos(at+b), R \sin(at+b), ct+d)$$



Not quite
I'll try again in video.

Remark: if we cut the cylinder along C then lay it flat then the ruling, circle and helix are just lines



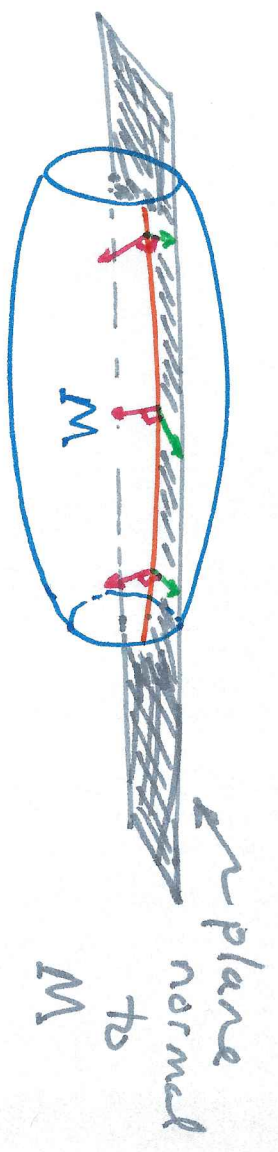
Proposition: If a unit-speed curve α in M lies in a plane P everywhere orthogonal to M along α then α is geodesic to M

Proof: $\alpha' \cdot \alpha' = 1$ and ~~$\alpha' \cdot \alpha'' = 0$~~

Thus $\alpha' \cdot \alpha'' = 0$ and both α', α'' lie in P

and so α' is tangent to $M \Rightarrow \alpha''$ is orthogonal to $M \Rightarrow \alpha$ geodesic. //

Application: meridians are geodesics to surface of revolution.



§5.7: SURFACES OF REVOLUTION:

(13)

Study patch $\Sigma(u, v) = (g(u), h(u)\cos v, h(u)\sin v)$ for $h(u) > 0$

$$\Sigma_u = \langle g', h' \cos v, h' \sin v \rangle$$

$$\Sigma_v = \langle 0, -h \sin v, h \cos v \rangle$$

Likewise calculate,

$$\Sigma_u \times \Sigma_v = \langle hh', -h g' \cos v, -h g' \sin v \rangle$$

$$\|\Sigma_u \times \Sigma_v\| = h \sqrt{(g')^2 + (h')^2} \quad (\text{using } \sqrt{EG - F^2})$$

$$U = \frac{1}{\sqrt{(g')^2 + (h')^2}} \langle h', -g' \cos v, -g' \sin v \rangle \quad (\text{the } h' \text{ is cancelled})$$

$$\Sigma_{uu} = \langle g'', h'' \cos v, h'' \sin v \rangle$$

$$\Sigma_{uv} = \langle 0, -h' \sin v, h' \cos v \rangle$$

$$\Sigma_{vv} = \langle 0, -h \cos v, -h \sin v \rangle$$

$$L = \frac{\Sigma_{uu} \cdot U}{\sqrt{(g')^2 + (h')^2}} = \frac{-g' h'' + g'' h'}{\sqrt{(g')^2 + (h')^2}}$$

$$M = 0$$

$$N = \frac{\Sigma_{vv} \cdot U}{\sqrt{(g')^2 + (h')^2}} = \frac{g' h}{\sqrt{(g')^2 + (h')^2}}$$

Thus Σ is PRINCIPAL PATCH so we have: (see LECTURE 16)

$$S(\Sigma_u) = \frac{1}{E} \Sigma_u \quad \text{and} \quad S(\Sigma_v) = \frac{N}{G} \Sigma_v$$

But, $u \mapsto \Sigma(u, v_0)$ and $v \mapsto \Sigma(u_0, v)$ are meridians & circles of M and we can identify $k_p = \frac{1}{E}$ & $k_\pi = \frac{N}{G}$ \curvearrowright

We found,

$$K_{\rho} = \frac{L}{E} = \frac{-g' h'' + g'' h'}{(g')^2 + (h')^2}^{3/2}$$

Principal curvature along Σ_u

$$K_{\pi} = \frac{N}{G} = \frac{g' h''}{h((g')^2 + (h')^2)^{3/2}}$$

Principal curvature along Σ_v

Then as $K = K_{\rho} K_{\pi}$,

$$K = \frac{-g' | \begin{matrix} g' & h' \\ g'' & h'' \end{matrix} |}{h((g')^2 + (h')^2)^2}$$

← determinant.

← function of u alone, K

If we specialize to case $g(u) = u$ then,

constant as v -varies over parallels.

$$K = \frac{-h''}{h(1+(h')^2)^2}$$

Example: Torus: for $0 < r < R$

$$g(u) = r \sin u$$

$$h(u) = R + r \cos u$$

$$E = \dot{g}^2 + \dot{h}^2 = r^2$$

$$F = 0$$

$$G = (R + r \cos u)^2$$

$$L = \frac{(r \cos u)(-r \cos u) - (r \sin u)(-r \sin u)}{r} = r$$

$$M = 0$$

$$N = \frac{(r \cos u)(R + r \cos u)}{r} = R \cos u + r \cos^2 u$$

Then,

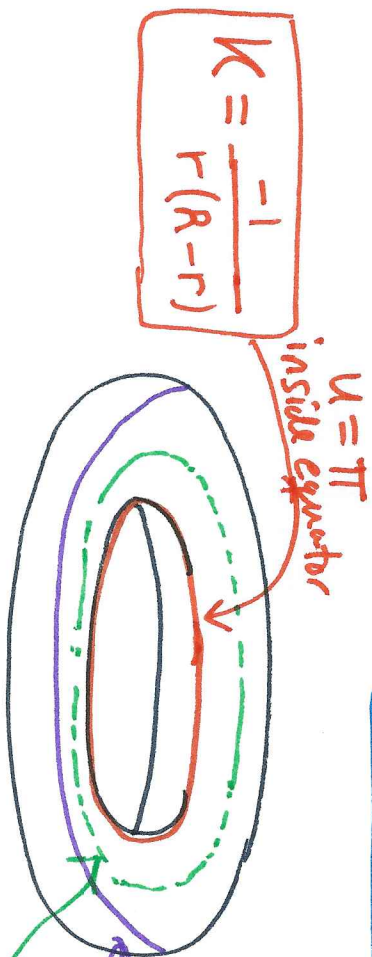
$$K_u = \frac{L}{E} = \frac{1}{r}$$

$$\text{and } K_v = \frac{N}{G} = \frac{R \cos u + r \cos^2 u}{(R + r \cos u)^2} = \frac{\cos u}{R + r \cos u}$$

\therefore

$$K = \frac{\cos u}{r(R + r \cos u)}$$

$$\Delta(u,v) = (r \sin u, (R + r \cos u) \cos v, (R + r \cos u) \sin v)$$



$U=0$ outside equator: $K = \frac{1}{r(R+r)}$
 top circle, $u = \frac{\pi}{2}$, $K = 0$
 bottom circle $u = -\frac{\pi}{2}$ also)

Example: catenoid

$$y = c \cosh(x/c)$$

$$\rightarrow H = 0$$

$$\rightarrow K =$$

$$= \frac{-1}{c^2 \cosh^4(x/c)}$$

Th^m / If a surface of revolution M is a minimal surface, then M is contained either in a plane or a catenoid.

Proof: pg. 255, O'Neill.