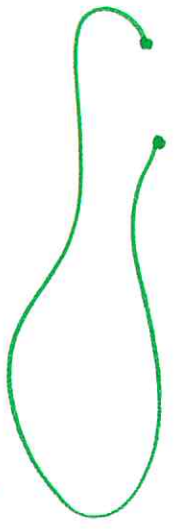
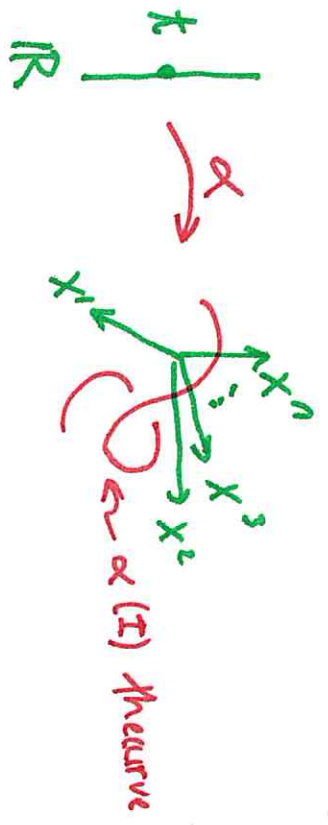


LECTURE 4: CURVES & THE PUSH-FORWARD (SL.4 AND 1.7 of O'NEIL)



smooth, parametrized curve

$$\alpha: I \subseteq \mathbb{R} \rightarrow \mathbb{R}^n$$



Ex] $\alpha: \mathbb{R} \rightarrow [0,1]^2 \subseteq \mathbb{R}^2$



Hans Sagan

Ex] $\alpha(t) = P$
 $\alpha'(t) = 0 \quad \forall t$

Defn/ $\alpha: I \subseteq \mathbb{R} \rightarrow \mathbb{R}^n$ smooth and such that $\boxed{\alpha'(t) \neq 0} \quad \forall t$ is called a regular parametrized curve

Defn/ for a param. ^{smooth} curve α and $t \in \text{dom}(\alpha)$ we define

$$\alpha'(t) = \frac{d\alpha^1}{dt} \frac{\partial}{\partial x^1} \Big|_{\alpha(t)} + \dots + \frac{d\alpha^n}{dt} \frac{\partial}{\partial x^n} \Big|_{\alpha(t)}$$

so, $\alpha'(t) \in T_{\alpha(t)} \mathbb{R}^n$

$$\alpha' = (\alpha^1, \alpha^2, \dots, \alpha^n) \in \mathbb{R}^n$$

Velocity of α is an operator on functions defined near $\alpha(I)$

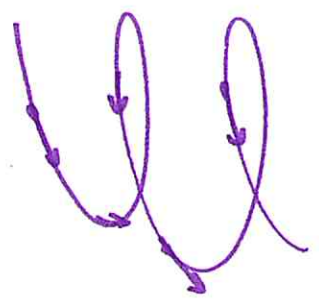
Ex) $\alpha(t) = \frac{1}{\sqrt{2}} (\cos t, \sin t, t)$

① $\alpha'(t) = \frac{1}{\sqrt{2}} \left[-\sin t \frac{\partial}{\partial x} + \cos t \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \right] \Big|_{\alpha(t)} : \underbrace{\|\alpha'(t)\|}_{\text{speed}} = 1$

$\alpha'(t)[\partial] = \frac{1}{\sqrt{2}} (1) = \frac{1}{\sqrt{2}}$

$\alpha'(t)[x^2+y^2] = \frac{-2x \sin t + 2y \cos t}{\sqrt{2}} \Big|_{\substack{x = \cos t/\sqrt{2} \\ y = \sin t/\sqrt{2}}}$

$= \frac{-2 \cos t \sin t + 2 \sin t \cos t}{2} = 0.$



$x^2 + y^2 = 1/2$

$\alpha'(t) [\tan^{-1}(y/x)] = \frac{1}{\sqrt{2}} \left(-\sin t \left[\frac{1}{1+y^2/x^2} \left[\frac{-y}{x^2} \right] + \cos t \left[\frac{1}{1+y^2/x^2} \frac{1}{x} \right] \right) \Big|_{\alpha(t)}$

$\theta \swarrow$

$= \frac{y \sin t + x \cos t}{\sqrt{2} (x^2 + y^2)} \Big|_{\alpha(t)}$

$= \frac{1/2}{1/2} = 1.$

Ex 2) $\alpha(t) = (t, t^2, t^3)$

$\alpha'(t) = \left(\frac{\partial}{\partial x} + 2t \frac{\partial}{\partial y} + 3t^2 \frac{\partial}{\partial z} \right) \Big|_{(t, t^2, t^3)}$

$\alpha'(t) [x^6 + y^3 - 2z^2] = [1]6x^5 + 2t(3y^2) + 3t^2(-4z)$
 $= 6t^5 + 6t^4 - 12t^2 t^3 = 0$
 $x=t, y=t^2, z=t^3$

$F(x,y,z) = x^6 + y^3 - 2z^2 = 0 \leftarrow$ rep. some surface Λ in \mathbb{R}^3
and $\alpha(\mathbb{R}) \subseteq S = F^{-1}\{0\}$

Defⁿ We say $h: J \rightarrow I$ is a reparametrization of param. curve $\alpha: I \rightarrow \mathbb{R}^n$ and $\beta: J \rightarrow \mathbb{R}^n$ when $\beta = \alpha \circ h$ is the reparametrization of α by h .

Ex 5) $\|\alpha'(t)\| = \sqrt{1 + 4t^2 + 9t^4}$

$S(t) = \int_0^t \sqrt{1 + 4u^2 + 9u^4} du$

~~Solve for~~ $t = h(s)$ is the arc length para. of α
Then $\beta = \alpha(h(s))$ is the arc length para. of α

Prop. 14.7] α a param. smooth curve and $\beta = \alpha \circ h$
 a reparam. of α by h then

$$\beta'(s) = \frac{dh}{ds} \alpha'(h(s))$$

$\underbrace{\hspace{100px}}_{\text{operator}}$
 $\underbrace{\hspace{100px}}_{\text{scalar mult.}}$
 $\underbrace{\hspace{100px}}_{\text{operation}}$

Proof $\beta(s) = \alpha(h(s)) \rightarrow \beta^j(s) = \alpha^j(h(s))$
 $\frac{d\beta^j}{ds} = \frac{d\alpha^j}{ds}(h(s)) \frac{dh}{ds} = (\alpha^j)'(h(s)) \frac{dh}{ds}$ for $j=1, 2, \dots, n$

$$\beta'(s) = \sum_{j=1}^n \frac{d\beta^j}{ds} \mathbf{e}_j \Big|_{\beta(s)}$$

\nwarrow \mathbf{e}_j

$$= \sum_{j=1}^n (\alpha^j)'(h(s)) \left(\frac{dh}{ds} \right) \mathbf{e}_j \Big|_{\beta(s)}$$

$$= \frac{dh}{ds} \sum_{j=1}^n (\alpha^j)'(h(s)) \mathbf{e}_j \Big|_{\alpha(h(s))}$$

$\underbrace{\hspace{100px}}_{\alpha'(h(s))}$

$$= \frac{dh}{ds} \alpha'(h(s))$$

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§1.5: THE PUSH-FORWARD IN \mathbb{R}^n

$F: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$F = (F^1, F^2, \dots, F^m)$

$F'_a: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Defn/ $J_F = \left[\frac{\partial F}{\partial x^1} \mid \frac{\partial F}{\partial x^2} \mid \dots \mid \frac{\partial F}{\partial x^n} \right] =$

$\begin{bmatrix} (\nabla F^1)^T \\ (\nabla F^2)^T \\ \vdots \\ (\nabla F^m)^T \end{bmatrix}$

\leftarrow $m \times n$ matrix of function

$F(a+h) \cong F(a) + J_F(a)h$

$\Delta F = F(a+h) - F(a) = J_F(a)h =$

$\begin{bmatrix} (\nabla F^1)_a^T \\ \vdots \\ (\nabla F^m)_a^T \end{bmatrix} \begin{bmatrix} h^1 \\ \vdots \\ h^n \end{bmatrix} = \begin{bmatrix} \nabla F^1(a) \cdot h \\ \vdots \\ \nabla F^m(a) \cdot h \end{bmatrix}$

vectors of directional derivatives

Ex] $F(x,y) = (x^2+y^2, y, \cos(xy)) = \begin{bmatrix} x^2+y^2 \\ y \\ \cos(xy) \end{bmatrix}$

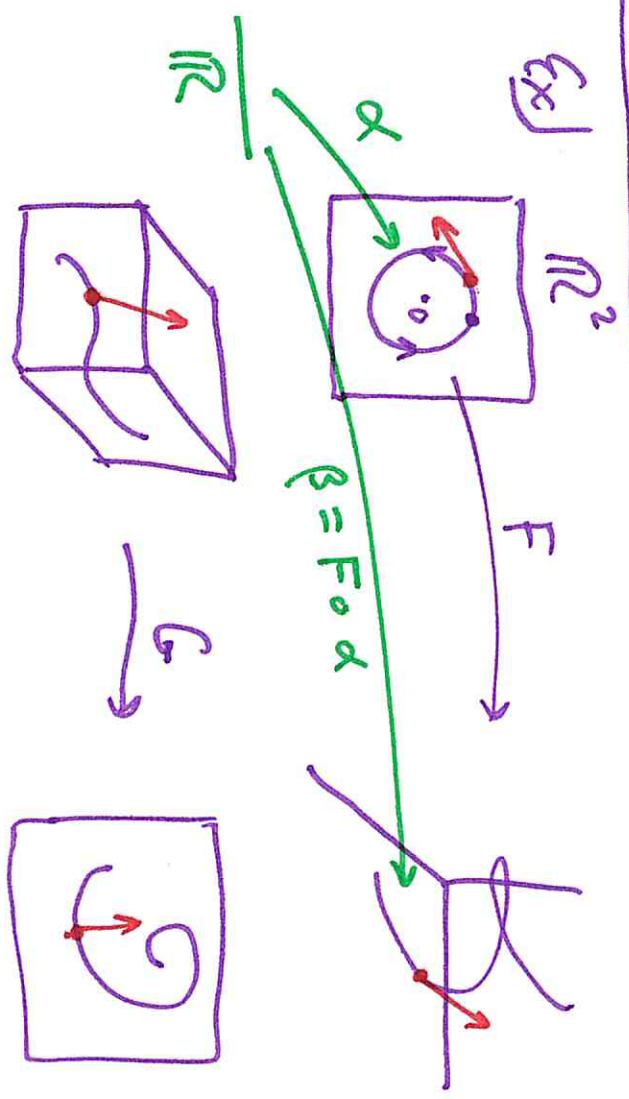
$J_F = \begin{bmatrix} 2x & 2y \\ 0 & 1 \\ -y \sin xy & -x \sin xy \end{bmatrix}$

$\nabla(x^2+y^2)$

$\nabla(y)$

$F: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \hookrightarrow J_F \in \mathbb{R}^{3 \times 2}$

Geometry of $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$



~~Ex] 2)~~
 $F(x, y) = (x, y, \tan^{-1}(y/x))$

Defn/ Let $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be differentiable at p and

suppose $\Sigma \in T_p \mathbb{R}^n$ where $X^j: j=1,2,\dots,n$ for \mathbb{R}^n and $y^i: i=1,2,\dots,m$ then the differential of F at p is denoted $d_p F$ and we define $d_p F: T_p \mathbb{R}^n \rightarrow T_{F(p)} \mathbb{R}^m$

$$d_p F(\Sigma) = \sum_{j=1}^n d_p F^j(\Sigma) \frac{\partial}{\partial y^j} \Big|_{F(p)}$$

$$= \sum_{j=1}^m \sum_{i=1}^n \Sigma[X^i] \frac{\partial F^j}{\partial x^i} \Big|_{F(p)} = \sum_{j=1}^m \sum_{i=1}^n \Sigma[X^i] \frac{\partial F^j}{\partial x^i} \Big|_{(p)} \frac{\partial}{\partial y^j} \Big|_{F(p)}$$

$$\Sigma = \sum_{i=1}^n \Sigma[X^i] \frac{\partial}{\partial x^i} \Big|_p$$

$$F_{*p}(\Sigma) = d_p F(\Sigma)$$

Ex] $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$df \left(\frac{\partial}{\partial x^k} \Big|_{t_0} \right) = \sum_{i=1}^n \frac{\partial f^i(t_0)}{\partial x^i} \frac{\partial}{\partial x^i} \Big|_{f(t_0)}$$

$$f = \alpha$$

Ex] $g: \mathbb{R}^n \rightarrow \mathbb{R}$

$$dg(\Sigma) = \Sigma(g) \frac{\partial}{\partial x^1}$$

$$1 = \frac{\partial}{\partial x^1}$$

scalar function

Ex] $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$F(r, \theta) = (r \cos \theta, r \sin \theta)$$

$$\frac{\partial}{\partial r} = \frac{\partial x}{\partial r} \frac{\partial}{\partial x} + \frac{\partial y}{\partial r} \frac{\partial}{\partial y} = \cos \theta \frac{\partial}{\partial x} + \sin \theta \frac{\partial}{\partial y}$$

$$d_{(r, \theta)} F \left(\frac{\partial}{\partial r} \Big|_{(r, \theta)} \right) = \cos \theta \frac{\partial}{\partial x} \Big|_{F(r, \theta)} + \sin \theta \frac{\partial}{\partial y} \Big|_{F(r, \theta)}$$

Implicit and Inverse Functions Thms

(8)

$$\vec{F}(x, y) = \vec{c}$$

Then can solve for

$$x \in \mathbb{R}^n, y \in \mathbb{R}^n, \vec{c} \in \mathbb{R}^n$$

$$y = G(x), \quad G: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\vec{F} \equiv (x, G(x)) = \vec{c}$$

$$\text{Ex]} \quad F(x, y, z) = \underline{x^2 + y + z^3 = 3}$$

$$\frac{\partial F}{\partial z} = 3z^2 \neq 0$$

$$\frac{\partial F}{\partial y} = 1 \quad J_F = [2x, 1, 3z^2]$$

$$\frac{\partial F}{\partial x} = 2x$$

$$F: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$J_F(a)^{-1}$ exists

$\hookrightarrow \exists U, V$ with $a \in U$

$$F|_U: U \rightarrow V$$

invertible with smooth inverse

$$F(r, \theta) = (r \cos \theta, r \sin \theta)$$

$$J_F = \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix}$$

det $J_F = r \neq 0$ away from $r=0$.