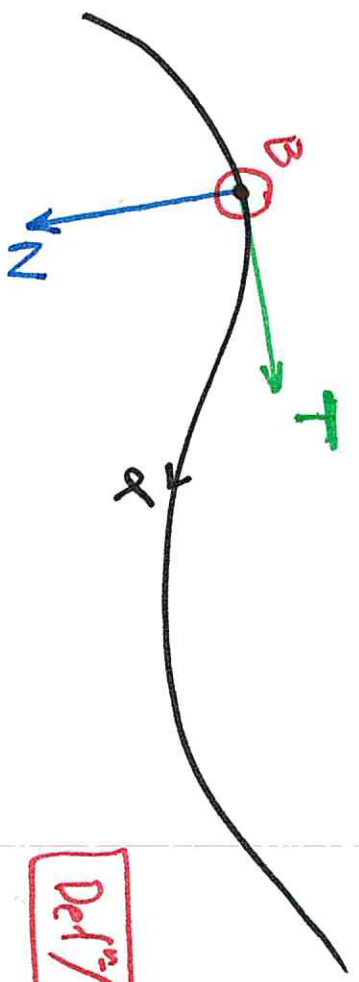


# LECTURE 6: FRENET SERRET FOR CURVES IN $\mathbb{R}^3$

(1)



$$\alpha: I \rightarrow \mathbb{R}^3$$

regular  $\alpha'(s) \neq 0 \forall s \in I$   
 arc length  $\|\alpha'(s)\| = 1 = \frac{ds}{ds}$ .

$$\text{Defn} \quad B = T \times N \quad \text{Binormal.}$$

$$\text{Defn} \quad T = \alpha'$$

$$T \cdot T = \alpha' \cdot \alpha' = \|\alpha'\|^2 = 1.$$

$$\hookrightarrow T' \cdot T + T \cdot T' = 0$$

$\Rightarrow 2T \cdot T' = 0$  can use  $T'$  to obtain a  $\perp$  direction to  $T$

$$\text{Defn} \quad N = \frac{T'}{\|T'\|}$$

$$\hookrightarrow B = \|T'\|$$

$$T' = \frac{dT}{ds}$$

$$\underline{T}' = \|T'\| N = \underline{B} N$$

Frenet Serret Eq<sup>n</sup>.

Thy/ Given  $T, N, B$  for  $\alpha$ -arclength param. (non linear  $\mathbb{R} \neq 0$ )  
 there exists another fund.  $T$  for which:

$$\frac{dT}{ds} = T' = \kappa N, \quad N' = -\kappa T + \tau B, \quad B' = -\tau N$$

(a)

Proof  $T = \frac{\alpha'}{\|\alpha'\|} = \alpha'$  and  $T \cdot T = \alpha' \cdot \alpha' = 1 \implies T' \cdot T + T \cdot T' = 0$

$\therefore T \cdot \left( \frac{T'}{\|T'\|} \right) = 0$  provided  $\mathbb{R} = \|T'\| \neq 0 \quad \therefore \underline{T \cdot N = 0}$ .

And as  $B = T \times N$  it follows that  $\{T, N, B\}$ .

Consider  $B' = (\cancel{B' \cdot T})T + \underline{(B' \cdot N)N} + \underline{(B' \cdot B)B}$

Since  $B \cdot B = 1 \implies 2B' \cdot B = 0 \quad \therefore B' \cdot B = 0$

$B = T \times N \implies \begin{cases} B \cdot T = 0 & B' \cdot T + B \cdot T' = 0 \\ B \cdot N = 0 & B' \cdot T = -B \cdot T' = -\mathbb{R} \cdot (BN) = -\mathbb{R} \cdot B \cdot N = 0. \end{cases}$

Let  $T = -B' \cdot N$  then  $B' = -\tau N$

$N' = \cancel{(N' \cdot T)T} + \cancel{(N' \cdot N)N} + \underline{(N' \cdot B)B} = -\mathbb{R}T + \tau B$

$N' \cdot T = -N \cdot T' = -N \cdot (BN) = -\mathbb{R}$

$N \cdot T = 0 \implies N' \cdot T + N \cdot T' = 0$

$N' \cdot B = -N \cdot B' \quad (N \cdot B = 0)$   
 $= -N \cdot (-\tau N)$   
 $= \tau \cdot \parallel$

Def<sup>n</sup>  $T = -\frac{dB}{ds} \cdot N$  for  $\alpha: I \rightarrow \mathbb{R}^3$

Torsion

unit-speed, nonlinear, regular curves.

Example:  $\alpha(s) = (R \cos ks, R \sin ks, mks)$  :  $k = \frac{1}{\sqrt{R^2 + m^2}}$

$$\alpha'(s) = \underbrace{-Rk \sin ks \mathbf{U}_1 + Rk \cos ks \mathbf{U}_2 + mk \mathbf{U}_3}_{\mathbf{T}(s)} \rightarrow \|\alpha'\| = \sqrt{k^2(R^2 + m^2)} = 1.$$

$$\mathbf{T}' = -Rk^2 \cos ks \mathbf{U}_1 - Rk^2 \sin ks \mathbf{U}_2$$

$$\hookrightarrow \|\mathbf{T}'\| = Rk^2 =$$

$$\boxed{\frac{R}{R^2 + m^2}} = \kappa$$

curvature of circular helix

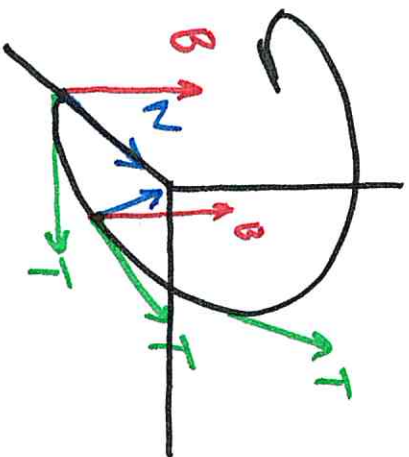
$$\boxed{N = -\cos ks \mathbf{U}_1 - \sin ks \mathbf{U}_2}$$

$$B = \mathbf{T} \times N = \underline{mk \sin ks \mathbf{U}_1 - mk \cos ks \mathbf{U}_2 + kR \mathbf{U}_3}$$

$$B' = mk^2 \cos ks \mathbf{U}_1 + mk^2 \sin ks \mathbf{U}_2 \rightarrow B' \cdot N = -mk^2 = T$$

$$\therefore \boxed{T = \frac{m}{R^2 + m^2}}$$

torsion.



$$m=0$$

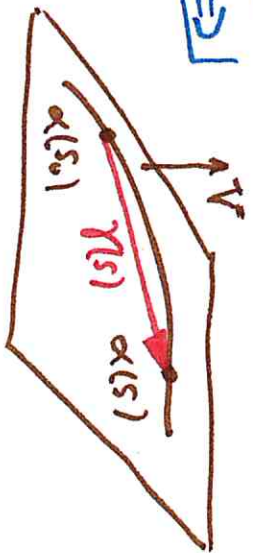
$$\alpha(s) = (R \cos ks, R \sin ks)$$

$$\mathbf{T} = 0$$

$$\kappa = \frac{R}{R^2} = \frac{1}{R}.$$

Th<sup>4</sup> / Let  $\alpha$  be unit speed, non-linear, then  $\alpha$  is planar curve  $\Leftrightarrow T = 0$

(4)



$$\gamma(s) \cdot T = 0$$

$$\gamma(s) = \alpha(s) - \alpha(s_0)$$

$$\hookrightarrow \alpha'(s) \cdot T = 0$$

$$\gamma' = \alpha'$$

$$T \cdot T = 0$$

But diff. again,  $T' \cdot T = 0 \Rightarrow$   ~~$N \cdot T = 0$~~   $N \cdot T = 0$

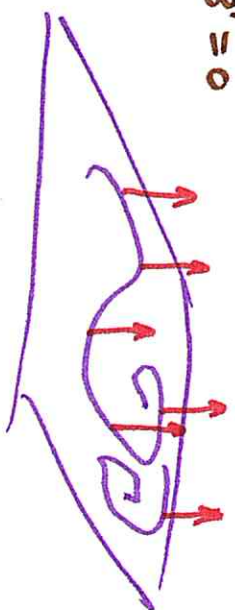
But,  $N \neq 0 \therefore N \cdot T = 0 \Rightarrow T$  colinear with  $B \Rightarrow B = kT$

Then  $B' = k'T + kT' = \frac{k'}{n} nT = \frac{k'}{n} B$  But  $B' \cdot B = 0 \Rightarrow \frac{k'}{n} = 0$

$$B' \cdot B = \frac{k'}{n} B \cdot B = \frac{k'}{n} (1) = 0 \hookrightarrow k' = 0$$

$$\therefore k = \text{const.} \Rightarrow T = 0$$

$$\hookrightarrow B' = 0$$



$$\Leftrightarrow \int T = 0 \Rightarrow B' = 0 \Rightarrow B = B_0.$$

or  $B(s) = B(s_0) \quad \forall s \in \text{dom}(\alpha).$

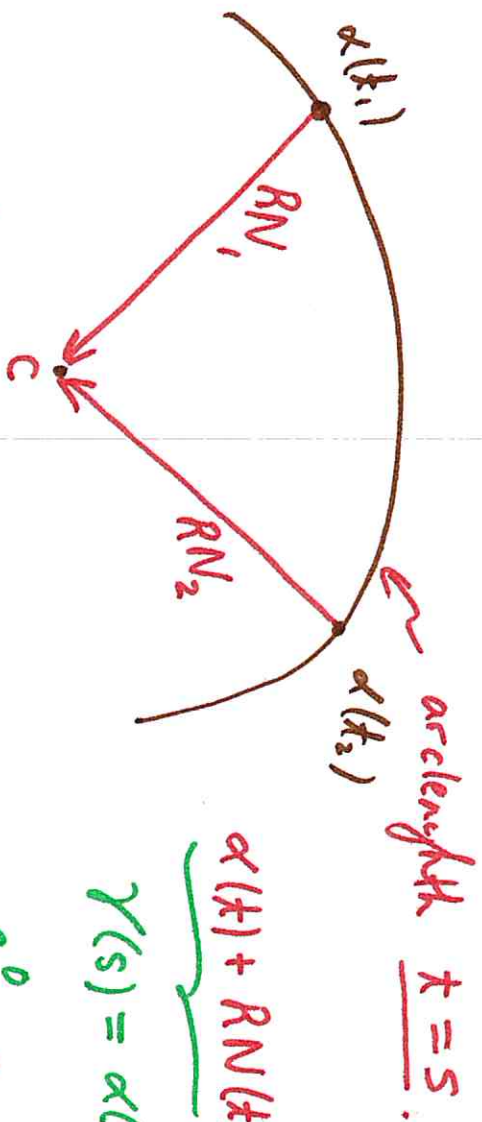
$$f(s) = [\alpha(s) - \alpha(s_0)] \cdot B(s_0)$$

$$f'(s) = \alpha'(s) \cdot B(s_0) = T(s) \cdot B(s_0) = 0 \quad \forall s.$$

$$\text{But } f(s_0) = [\alpha(s_0) - \alpha(s_0)] \cdot B(s_0) = 0 \therefore f(s) = 0 \quad \forall s \in I$$

$$[\alpha(s) - \alpha(s_0)] \cdot B(s_0) = 0 \quad \forall s \Rightarrow \underline{[\alpha(s) - \alpha(s_0)] \cdot B(s) = 0.}$$

Proof  $\mathbb{R} = \mathbb{R}_0$  with  $T=0 \Rightarrow$  curve is part of circle)



$$\alpha(t) + RN(t) = C$$

$$\gamma(s) = \alpha(s) + RN(s)$$

$$\gamma'(s) = \alpha'(s) + RN'(s) = T(s) + R(-\mathbb{E}T(s) + \mathbb{F}B(s))$$

$$\gamma'(s) = T(s) - R\mathbb{E}T(s) = 0 \quad \text{provided we}$$

$$\text{set } R = \frac{1}{\mathbb{E}_0}$$

$$\mathbb{E}(s) = \mathbb{E}_0 \quad \forall s.$$

Hence,  $\gamma'(s) = 0 \quad \forall s$

$$\gamma(s_0) = \gamma(s) \quad \text{let } C = \gamma(s_0)$$

$$\alpha(t) = C - RN(t) \Rightarrow \alpha(s) = C - RN(s)$$

$$\|\alpha(s) - C\| = R \quad \forall s.$$

$\hookrightarrow$   $\alpha$  on a circle, centered at  $C$  with radius  $R = \frac{1}{\mathbb{E}_0}$ .

NON UNIT SPEED CASE:

Let  $\alpha: I \rightarrow \mathbb{R}^3$  a smooth, regular curve with  $\alpha'(t) \neq 0$  and for which the arclength reparametrization  $\bar{\alpha}: J \rightarrow \mathbb{R}^3$  is given by  $S: I \rightarrow J$ . So  $\alpha(t) = \bar{\alpha}(S(t)) \forall t \in I$  we define  $T, N, B, \tau, \zeta$  in terms of  $\bar{T}, \bar{N}, \bar{B}, \bar{\tau}, \bar{\zeta}$  of  $\bar{\alpha}$  as follows:

$$\begin{aligned} T(t) &= \bar{T}(S(t)) & \tau(t) &= \bar{\tau}(S(t)) \\ N(t) &= \bar{N}(S(t)) & \zeta(t) &= \bar{\zeta}(S(t)) \\ B(t) &= \bar{B}(S(t)) \end{aligned}$$

$$\begin{aligned} \alpha'(t) &= \frac{d}{dt}(\bar{\alpha}(S(t))) \\ &= \frac{d\bar{\alpha}(S(t))}{dS} \frac{dS}{dt} & \alpha' &= \bar{T} \\ &= \bar{T}(S(t)) \frac{dS}{dt} \\ &= v \bar{T}(t) \text{ where } v = \frac{dS}{dt} = \|\alpha'(t)\| \end{aligned}$$

$$\frac{dT}{dt} = \frac{d}{dt}(\bar{T}(S(t))) = \frac{d\bar{T}(S(t))}{dS} \frac{dS}{dt} = v \underbrace{\bar{T}'(S(t))}_{(\bar{\tau} \bar{N})(S(t))} = v \underbrace{\bar{\tau}(S(t)) \bar{N}(S(t))}_{\tau(t) N(t)}$$

Like wise  $\begin{cases} T' = v \tau N \\ N' = -v \tau T + v \zeta B \\ B' = -v \zeta N \end{cases}$

$$\underline{\tau = \frac{1}{v}(T' \cdot N)} \quad \& \quad \underline{\zeta = -\frac{1}{v} B' \cdot N}$$

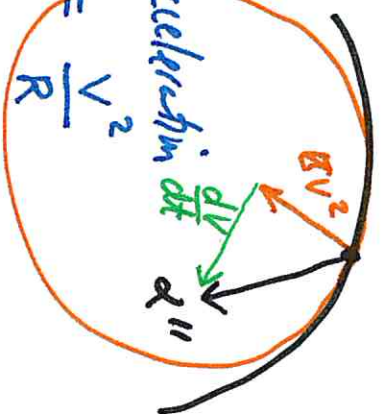
# Acceleration

$$\alpha'(t) = v T$$

$$\alpha''(t) = \frac{dv}{dt} T + v \frac{dT}{dt}$$

$$= \underbrace{\frac{dv}{dt} T}_{\text{tangential}} + \underbrace{Rv^2 N}_{\text{normal acceleration}}$$

$$a_c = \frac{v^2}{R}$$



$$\text{Prop: } B = \frac{\alpha' \times \alpha''}{\|\alpha' \times \alpha''\|}$$

(TR 2.4.11)

$$\alpha'' = v' T + v T', \quad \alpha' = v T \quad \hookrightarrow \quad \alpha' \parallel T$$

$$\alpha' \times \alpha'' = (v T) \times (v' T + v T') = v^2 T \times T' = v^3 \underbrace{B}_{\text{TR 2.4.11}}$$

$$B = \frac{\alpha' \times \alpha''}{\|\alpha' \times \alpha''\|}$$

$$\|\alpha' \times \alpha''\| = v^3 B$$

$$B = \frac{\|\alpha' \times \alpha''\|}{v^3}$$