

LECTURE 9: ISOMETRY & EUCLIDEAN GEOMETRY

①

(\mathbb{R}^n, d) where $d(p, q) = \sqrt{(q-p) \cdot (q-p)} = \|q-p\|$

Defn $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an isometry $d(F(p), F(q)) = d(p, q) \forall p, q \in \mathbb{R}^n$

Prop F & G isometries then $F \circ G$ an isometry

Proof: $d((F \circ G)(p), (F \circ G)(q)) = d(F(G(p)), F(G(q)))$
 $= d(G(p), G(q))$ if F is isom.
 $= d(p, q)$ //

Remark: The set of isometries is closed under composition.

Ex ① translation

$T(p) = p+a \quad \forall p \in \mathbb{R}^n$ and for some $a \in \mathbb{R}^n$ $T(p) = p$ is an isometry.

$$d(T(p), T(q)) = \|(p+a) - (q+a)\| = \|q-p\| = d(p, q)$$

orthogonal

Ex ② orthogonal transformation

$L(p) = Rp \quad \forall p \in \mathbb{R}^n$ and $R^T R = I \quad [L] = R$

$$R = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Continuing,

$$\begin{aligned}
 d(RP, RQ)^2 &= (RQ - RP) \cdot (RQ - RP) \\
 &= R(Q - P) \cdot R(Q - P) \\
 &= (R(Q - P))^T R(Q - P) \\
 &= (Q - P)^T \cancel{R^T R} (Q - P) = (Q - P)^T I (Q - P) = d(P, Q)^2
 \end{aligned}$$

$$\therefore d(RP, RQ) = d(P, Q)$$

Remark: $R \in O(n) \iff R^T R = I$

$$\begin{aligned}
 \det(R^T R) &= \det(R^T) \det(R) \\
 &= (\det(R))^2 = \det I = 1 \\
 \therefore \det(R) &= \pm 1
 \end{aligned}$$

\swarrow $R \in SO(n)$ $\det(R) = 1$
 \searrow $R \in -SO(n)$ $\det(R) = -1$

~~L~~ $L = L_R$ is an isometry.

Th^m / an isometry for which $F(0) = 0$ is an orthogonal transformation

Proof] Assume $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an isometry and $F(0) = 0$.

Notice $d(F(P), F(0)) = d(P, 0) = \|0 - P\| = \|P\|$

$$d(F(P), 0) = \|F(P)\| \quad \therefore \|F(P)\| = \|P\|$$

Observe $P \neq 0 \implies F(P) \neq 0$.

Let $p, q \in \mathbb{R}^n$,

(3)

$$\begin{aligned} d(F(p), F(q))^2 &= \|F(q) - F(p)\|^2 \\ &= (F(q) - F(p)) \cdot (F(q) - F(p)) \quad \curvearrowright \|v\|^2 = v \cdot v \\ &= \underbrace{F(q) \cdot F(q)} - 2 \underbrace{F(p) \cdot F(q)} + \underbrace{F(p) \cdot F(p)} \\ &\quad \underbrace{\|F(q)\|^2 = \|q\|^2} \quad \underbrace{\|F(p)\|^2 = \|p\|^2} \\ &\downarrow \\ d(p, q)^2 &= q \cdot q - 2p \cdot q + p \cdot p = \|q\|^2 - 2p \cdot q + \|p\|^2 \end{aligned}$$

Hence $F(p) \cdot F(q) = p \cdot q \quad \forall p, q \in \mathbb{R}^n$.

Standard basis e_1, e_2, \dots, e_n ($e_i \cdot e_j = \delta_{ij}$) then $F(e_i) \cdot F(e_j) = e_i \cdot e_j = \delta_{ij}$.
Thus, $\{F(e_i)\}$ is an orthonormal basis for \mathbb{R}^n .

Let $x, y, z \in \mathbb{R}^n$ and $c \in \mathbb{R}$

$$\begin{aligned} \underline{F(cx+y)} \cdot F(z) &= (cx+y) \cdot z \\ &= cx \cdot z + y \cdot z \\ &= cF(x) \cdot F(z) + F(y) \cdot F(z) \\ &= \underline{[cF(x) + F(y)] \cdot F(z)} \end{aligned}$$

Take $F(z) = F(e_i)$ for $i=1, \dots, n \therefore F(cx+y) = cF(x) + F(y)$.

Thus F is linear transformation. $\Rightarrow F(x) = Rx$ and $F(x) \cdot F(y) = x \cdot y$
forces us to find $R^T R = I \therefore F$ is isometry. \parallel

Th^m/ Every isometry $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ can be written uniquely (4)
 as $F = T \circ R$ where T is a translation & R is an orthog. trans.
 That is, $\exists! a \in \mathbb{R}^n$ and $M \in O(n)$ such that $F(x) = Mx + a$
 for all $x \in \mathbb{R}^n$

Proof: \Leftarrow $T \circ R$ is the comp. of isometries & hence is an isometry.

\Rightarrow Let F be an isometry. Let $G(x) = F(x) - F(0)$
 and observe G is an isometry & $G(0) = F(0) - F(0) = 0$.

Thus $G(x) = Mx$ for some $M \in O(n)$. consequently

$$F(x) - F(0) = G(x) = Mx \Rightarrow F(x) = Mx + F(0)$$

identifying $T(x) = x + F(0)$ gives together with $L_M(x) = Mx$

$$F = T \circ L_M. \text{ Check it: } F(x) = T(L_M(x)) = T(Mx) = Mx + F(0).$$

Uniqueness? Suppose $F(x) = M_1x + a_1$ & $F(x) = M_2x + a_2$

Notice $F(0) = a_1 = a_2 \therefore a_1 = a_2$. But,

$$F(e_j) = F(e_j) \Rightarrow M_1 e_j + a_1 = M_2 e_j + a_2$$

$$\text{col}_j(M_1) = \text{col}_j(M_2) \text{ for } j=1, \dots, n$$

$$\therefore M_1 = M_2 \quad //$$

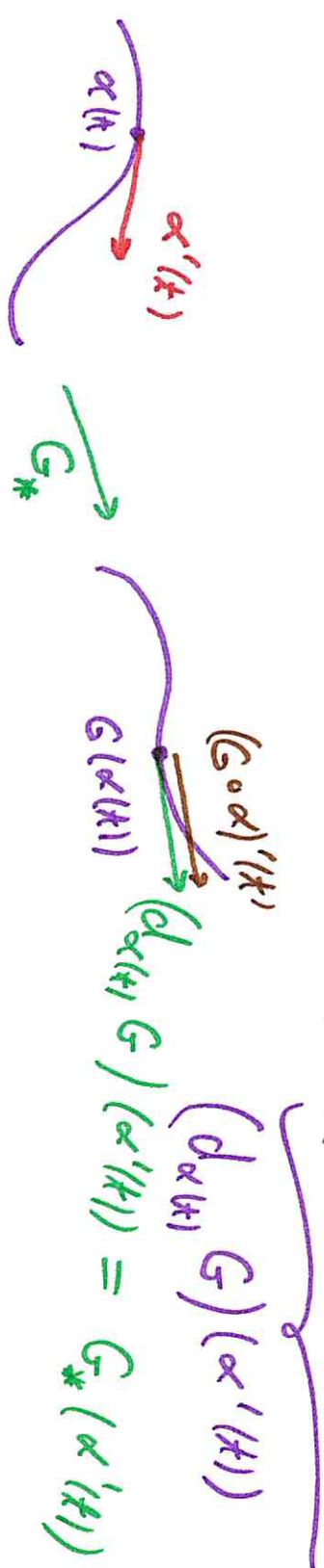
§ 3.2: How ISOMETRIES ACT ON VECTORS

$$\alpha: I \rightarrow \mathbb{R}^n$$

$$\alpha'(t) = \sum_{i=1}^n \frac{d\alpha^i}{dt} \frac{\partial}{\partial x^i} \Big|_{\alpha(t)} \quad \hookrightarrow \quad \alpha^{(k)}(t) = \sum_{i=1}^n \frac{d^k \alpha^i}{dt^k} \frac{\partial}{\partial x^i} \Big|_{\alpha(t)}$$

Given an isometry $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ form $F \circ \alpha = \beta$
 we can calculate $\beta', \beta'', \dots, \beta^{(k)}$. Consider G a map $\mathbb{R}^n \rightarrow \mathbb{R}^n$

$$(G \circ \alpha)'(t) = \sum_{i=1}^n \frac{d(G \circ \alpha)^i}{dt} \frac{\partial}{\partial x^i} \Big|_{G(\alpha(t))} = \sum_{i,j=1}^n \frac{\partial G^j}{\partial x^i}(\alpha(t)) \frac{d\alpha^i}{dt} \frac{\partial}{\partial x^j} \Big|_{\alpha(t)}$$



$$Th^m / F_*(\alpha'(t)) = (F \circ \alpha)'(t)$$

3.2.1 $(F \text{ smooth } \mathbb{R}^n \rightarrow \mathbb{R}^n)$

(This is not true for $\alpha'', \dots, \alpha^{(k)}$ unless we give further data about F)

$$F_*(\mathbf{x}) = F_*\left(\sum_i \mathbf{x}^i \frac{\partial}{\partial x^i}\right) = \sum_{i,j} \frac{\partial F^j}{\partial x^i} \mathbf{x}^i \frac{\partial}{\partial x^j}$$

$$F_*(\mathbf{x}) = J_F \mathbf{x} \quad \underbrace{(J_F)^j_i}_{(J_F)^j_i} \mathbf{x}^i = (J_F \mathbf{x})^j$$

Suppose F is an isometry:

$$F^i(x) = \sum_{j=1}^n R^i_j x^j + a^i \quad (\text{for some } R^T R = I, R \in O(n))$$

$$\frac{\partial F^i}{\partial x^k} = \sum_{j=1}^n R^i_j \frac{\partial x^j}{\partial x^k} \stackrel{\delta_{jk}}{=} R^i_k \quad \therefore J_F = R$$

$$F_*(\mathbf{x}) = R \mathbf{x}$$

$$F_*(p, v) = (F(p), Rv)$$

3.2.2

\mathbb{R}^n / If $F(x) = Rx + a$ is an isometry for some $R \in O(n)$

and $\alpha: I \rightarrow \mathbb{R}^n$ is a smooth parametrized curve then for $h \in \mathcal{N}$

$$F_*(\alpha^1) = (F \circ \alpha)', \quad F_*(\alpha^2) = (F \circ \alpha)'', \dots, \quad F_*(\alpha^{(h)}) = (F \circ \alpha)^{(h)}$$

Moreover, $\|F_*(\alpha^{(i)}(h))\| = \|\alpha^{(i)}(h)\| \quad \& \quad F_*(\alpha^{(i)}(h)) \cdot F_*(\alpha^{(j)}(h)) = \alpha^{(i)}(h) \cdot \alpha^{(j)}(h)$.

Proof: Let $v = \alpha^{(n)}(t)$. Recall, $F_*(v) = Rv$
 $F_*(\alpha^{(n)}(t)) = R\alpha^{(n)}(t)$. Also calculate

$$(F \circ \alpha)(t) = R\alpha(t) + a \Rightarrow (F \circ \alpha)^{(n)}(t) = R\alpha^{(n)}(t) = F_*(\alpha^{(n)}(t)).$$

But, $F_*(v) \cdot F_*(w) = (Rv)^T R w = v^T R^T R w = v^T w = v \cdot w$
apply this identity to the i^{th} and j^{th} derivatives along α .

Comment: $n=3$ $T, N, B \leftarrow T = \alpha'$

$$F_x(\alpha') \cdot F_x(\alpha'') = \alpha' \cdot \alpha''$$

$$N = \frac{1}{\kappa} T'$$

$$B = T \times N$$

$\beta = F \circ \alpha$ has same relations between β', β'' etc as α', α''

Newton's Mechanics: $\vec{F}_{net} = m\vec{a}$