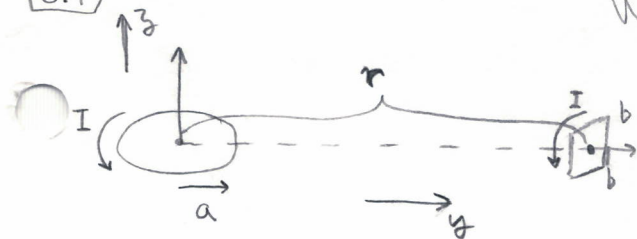


6.1



What is the torque on the square loop due to the circular one.

$$m_1 = \pi a^2 I \hat{z}$$

20/20.

good -

$$\vec{B} = \frac{\mu_0}{4\pi r^3} \{ 3(\vec{m}_1 \cdot \hat{r}) \hat{r} - \vec{m}_1 \}$$

$$= \frac{\mu_0}{4\pi r^3} \{ 3(\vec{0}) \hat{r} - \vec{m}_1 \}$$

$$= -\frac{\mu_0}{4\pi r^3} (\pi a^2 I \hat{z})$$

$$m_2 = -b^2 I \hat{y}$$

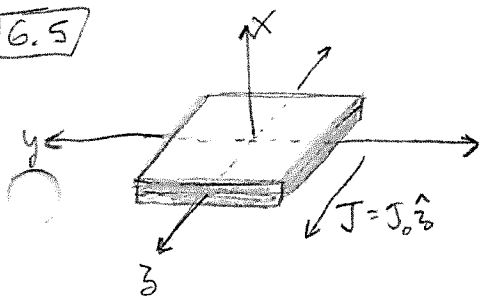
$$\vec{N} = \vec{m}_2 \times \vec{B} = (b^2 I \hat{y}) \times \left(-\frac{\mu_0}{4\pi r^3} \pi a^2 I \hat{z} \right)$$

$$\vec{N} = \frac{-b^2 I \mu_0 a^2 I \hat{x}}{4r^3}$$

$$= -\frac{a^2 b^2 I^2 \mu_0 \hat{x}}{4r^3} = \vec{N}$$

The equilibrium point where $\vec{N} = 0$ is where the loop lies x-y plane and m_2 is in the $\pm \hat{z}$ direction where $\vec{B}$ is $\perp$ to m_2 .

6.5



B must depend only on x as a y dependence is prohibited by the symmetry of the infinite plane. No z dependence is possible by the Biot-Savart law as the cross product of $\hat{z}$ with $\hat{z}$ is zero. The Biot-Savart law also dictates that $\vec{B}$ is in the $\hat{y}$ direction.

$$\int \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} = \int \mu_0 \vec{J} \cdot d\vec{a} = \mu_0 J_0 \int dx dy = \mu_0 J_0 xy = \int B dy = B y$$

$$\Rightarrow \vec{B} = \mu_0 J_0 x \hat{y}$$

$$(a) \vec{F} = \nabla(\vec{m} \cdot \vec{B}) = \nabla(m_0 \hat{x} \cdot \mu_0 J_0 x \hat{y}) = \nabla(0) = \boxed{\vec{0} = \vec{F}}$$

$$(b) \vec{F} = \nabla(\vec{m} \cdot \vec{B}) = \nabla(m_0 \hat{y} \cdot \mu_0 J_0 x \hat{y}) = \nabla(m_0 \mu_0 J_0 x)$$

$$\boxed{\vec{F} = m_0 \mu_0 J_0 \hat{x}}$$

(i) Prove $\nabla(\vec{p} \cdot \vec{E}) = (\vec{p} \cdot \nabla) \vec{E}$

By product rule 4 we may expand $\nabla(\vec{p} \cdot \vec{E})$ to

$$\nabla(\vec{p} \cdot \vec{E}) = \vec{p} \times (\nabla \times \vec{E}) + \vec{E} \times (\nabla \times \vec{p}) + (\vec{p} \cdot \nabla) \vec{E} + (\vec{E} \cdot \nabla) \vec{p}$$

$\nabla \times \vec{E} = 0$ in electrostatics and $\nabla \times \vec{p} = 0$ as $\vec{p}$ is just a constant vector.

$$\text{so } \nabla(\vec{p} \cdot \vec{E}) = \vec{p} \times \vec{0} + \vec{E} \times \vec{0} + (\vec{p} \cdot \nabla) \vec{E} + (\vec{E} \cdot \nabla) \vec{p} = (\vec{p} \cdot \nabla) \vec{E} + (\vec{E} \cdot \nabla) \vec{p}$$

$E \cdot \nabla = E_x \frac{\partial}{\partial x} + E_y \frac{\partial}{\partial y} + E_z \frac{\partial}{\partial z}$ and when this operator acts on $\vec{p}$ a constant vector all the derivatives are zero

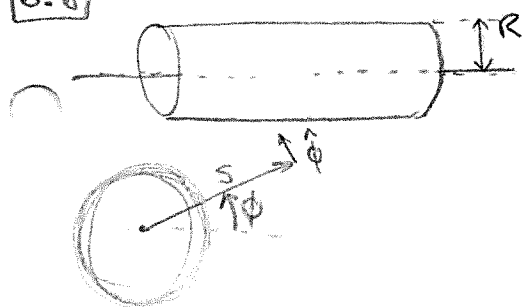
$$\Rightarrow (\vec{E} \cdot \nabla) \vec{p} = 0 \text{ thus } \nabla(\vec{p} \cdot \vec{E}) = (\vec{p} \cdot \nabla) \vec{E} + \vec{0} = \boxed{(\vec{p} \cdot \nabla) \vec{E} = \nabla(\vec{p} \cdot \vec{E})}$$

(ii) Why does $\nabla(\vec{m} \cdot \vec{B}) \neq (\vec{m} \cdot \nabla) \vec{B}$, mathematically this does not hold because $\nabla \times \vec{B} \neq 0$ in general, the other two terms vanish because $\vec{m}$ is also just a constant vector

(iii) Calculate $(\vec{m} \cdot \nabla) \vec{B}$ for (a) and (b)

$$(m_0 \hat{x} \cdot \nabla) \vec{B} = m_0 \frac{\partial}{\partial x} \vec{B} = m_0 \frac{\partial}{\partial x} (\mu_0 J_0 x \hat{y}) = m_0 \mu_0 J_0 \hat{y} \neq \vec{0} \quad \checkmark$$

$$(m_0 \hat{y} \cdot \nabla) \vec{B} = m_0 \frac{\partial}{\partial y} (\vec{B}) = m_0 \frac{\partial}{\partial y} (\mu_0 J_0 x \hat{y}) = \vec{0} \neq m_0 \mu_0 I_0 \hat{x} \quad \checkmark$$

6.8 Find $\vec{B}$ from $\vec{M}$ 

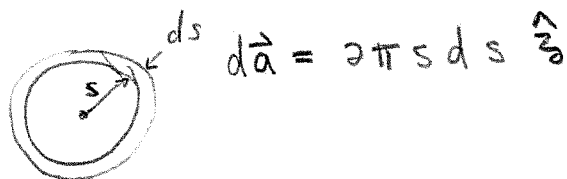
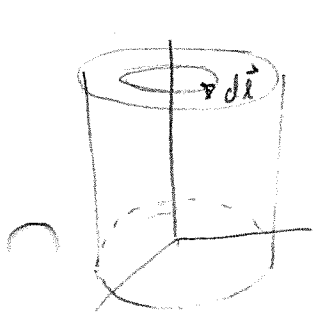
$$\vec{M} = ks^2 \hat{\phi}$$

$$V_\phi \equiv ks^2, V_s \equiv 0, V_z \equiv 0$$

$$\begin{aligned} \vec{J}_b &= \nabla \times \vec{M} \\ &= \left[\frac{1}{s} \frac{\partial V_z}{\partial \phi} - \frac{\partial V_\phi}{\partial s} \right] \hat{s} + \frac{1}{s} \left[\frac{\partial}{\partial s}(s V_\phi) - \frac{\partial V_s}{\partial \phi} \right] \hat{z} \\ &= \frac{1}{s} \frac{\partial}{\partial s}(s ks^2) \hat{z} = \frac{1}{s} k 3s^2 \hat{z} = \boxed{3k s^2 \hat{z} = \vec{J}_b} \end{aligned}$$

$$\begin{aligned} \vec{K}_b &= \vec{M} \times \hat{n} \\ &= ks^2 \hat{\phi} \times \hat{s} \\ &= -ks^2 \hat{z} \big|_{s=R} = \boxed{-kR^2 \hat{z} = \vec{K}_b} \end{aligned}$$

Ampere's law is appropriate if we consider the following loop



$$\begin{aligned} \oint \vec{B} \cdot d\vec{r} &= B(2\pi s) = \mu_0 I_{enc} = \mu_0 \int \vec{J} \cdot d\vec{a} \\ &= \mu_0 \int 3ks^2 \hat{z} \cdot 2\pi s ds \hat{z} \\ &= \mu_0 \int 6\pi k s^2 ds \end{aligned}$$

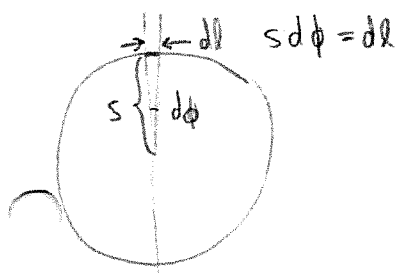
$$B(2\pi s) = 2\mu_0 \pi k s^3$$

$$\boxed{\vec{B}_{in} = \mu_0 k s^2 \hat{\phi}}$$

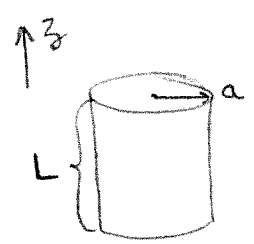
$$\begin{aligned} I_{enc} &= \int_0^R \vec{J} \cdot d\vec{a} + \int_{0, s=R}^{2\pi} -kR^2 s d\phi = 2\pi k s^3 \big|_0^R + -2\pi R^2 R k \\ &= 2\pi k R^3 - 2\pi k R^3 \\ &= 0 \end{aligned}$$

$$\Rightarrow \boxed{\vec{B}_{out} = \vec{0}}$$

✓



6.9



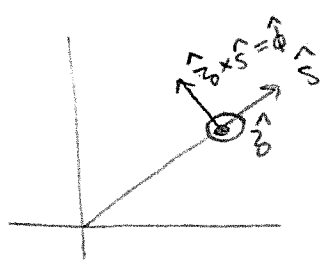
$$\vec{M} = M \hat{z} \quad \text{where } M \in \mathbb{R}$$

$$\vec{J}_B = \nabla \times \vec{M} = 0 \quad \text{as } M \text{ is constant.}$$

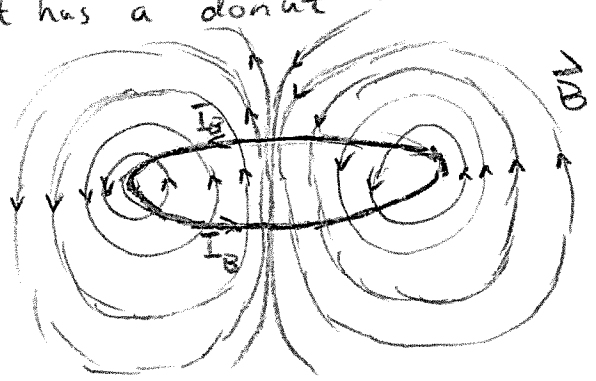
$$\vec{K}_B = \vec{M} \times \hat{n} = \vec{M} \times \hat{s} = M \hat{\phi} = \vec{K}_e$$

Bound Current

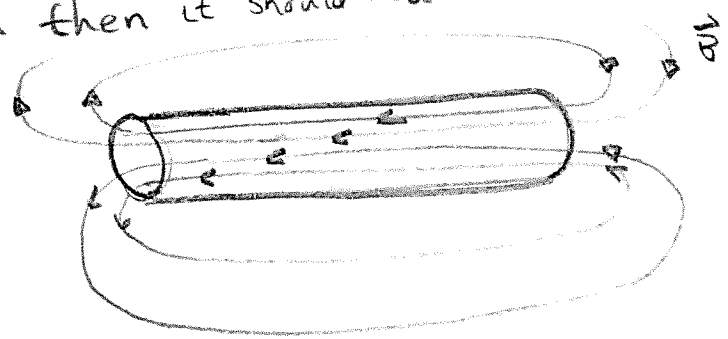
✓



$L \ll a$ then it is just like a wire in the limit
so it has a donut like field

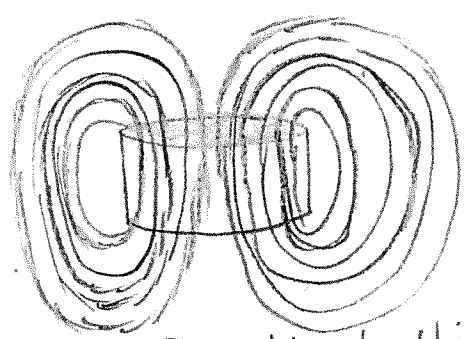


$L \gg a$ then it should resemble a solenoid.



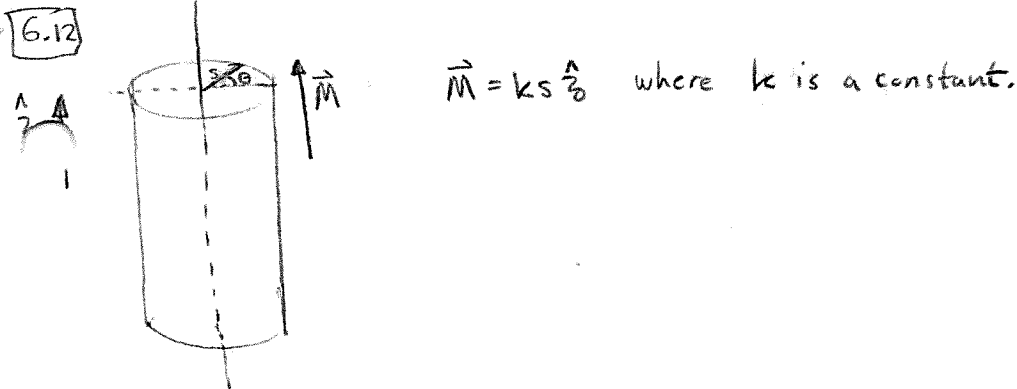
for an ideal solenoid $\vec{B} = 0$ outside I assumed less than perfection

$L \approx a$



a compromise between the 2 extremes of $a \ll L$ and $L \gg a$

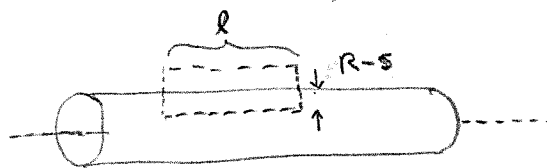
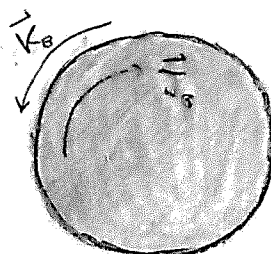
from the problem 4.11 I would note this is the magnetic analogue to the bar electret.



20/20 good

(a) $\vec{K}_s = \vec{M} \times \hat{n} = ks(\hat{z} \times \hat{s}) = ks \hat{\theta} = kR \hat{\theta}$

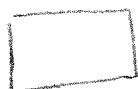
$\vec{J}_s = \nabla \times \vec{M} = \frac{1}{s} \frac{\partial M_z}{\partial \theta} \hat{s} - \frac{\partial M_z}{\partial s} \hat{\theta} = \frac{1}{s} \frac{\partial}{\partial \theta}(ks) \hat{s} - \frac{\partial}{\partial s}(ks) \hat{\theta} = -k \hat{\theta}$



$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} = \mu_0 (-k(R-s)l) + \mu_0 kRl = 0$

$\Rightarrow \vec{B} = \mu_0 sk - \mu_0 kR + \mu_0 kR$

$\Rightarrow \vec{B}_{in} = \mu_0 sk \hat{z}$



Both outside loops $\Rightarrow B$ is constant.
As B comes from a finite current distribution B_{out} must be zero

$\vec{B}_{out} = \vec{0}$

(b) $\oint \vec{H} \cdot d\vec{l} = I_{fenc}$ where $\vec{H} = \frac{1}{\mu_0}(\vec{B} - \vec{M})$

$I_{fenc} = 0 \Rightarrow \oint \vec{H} \cdot d\vec{l} = 0$ over all paths $\Rightarrow \vec{H} = \vec{0}$.

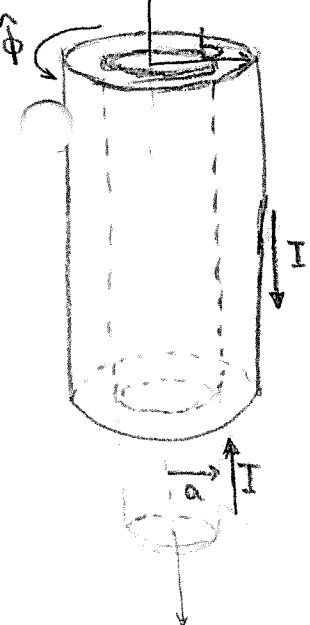
inside $\vec{M} = ks \hat{z}$ and $\vec{H} = \frac{1}{\mu_0}(\vec{B} - ks \hat{z}) = \vec{0} \Rightarrow \vec{B}_{in} = \mu_0 ks \hat{z}$

outside $\vec{M} = 0$ and as $\vec{H} = \frac{1}{\mu_0}(\vec{B} - \vec{0}) = \vec{0} \Rightarrow \vec{B}_{out} = \vec{0}$

good

6-16

Find $\vec{B}$ between the tubes, a material of χ_m fills that space.



$$\oint \vec{H} \cdot d\vec{l} = I_{enc} \Rightarrow H(2\pi s) = I \Rightarrow \vec{H} = \frac{I}{2\pi s} \hat{\phi}$$

$$\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M} = \frac{1}{\mu_0} \vec{B} - \chi_m \vec{H} \Rightarrow \vec{B} = (\vec{H} + \chi_m \vec{H}) \mu_0$$

$$\Rightarrow \vec{B} = \mu_0 (1 + \chi_m) \vec{H} = \mu_0 (1 + \chi_m) \frac{I}{2\pi s} \hat{\phi}$$

$$\Rightarrow \boxed{\vec{B} = \mu_0 (1 + \chi_m) \frac{I}{2\pi s} \hat{\phi} = \frac{\mu I}{2\pi s} \hat{\phi}}$$

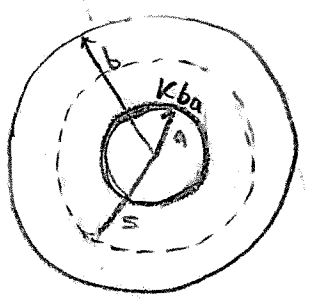
$$\vec{M} = \chi_m \vec{H} = \chi_m \frac{I}{2\pi s} \hat{\phi} = \vec{M}$$

"CHECK"

$$\vec{J}_B = \nabla \times \vec{M} = \nabla \times \chi_m \vec{H} = \frac{\chi_m I}{2\pi} \left(\nabla \times \frac{\hat{\phi}}{s} \right) = \frac{\chi_m I}{2\pi} \left(\frac{1}{s} \frac{\partial}{\partial s} \left(\frac{1}{s} \right) \right) \hat{z} = 0$$

$$\vec{K}_{BA} = \vec{M} \times \hat{n}_A = \chi_m \vec{H} \times \hat{s} = \frac{\chi_m I}{2\pi s} (\hat{\phi} \times \hat{s}) = + \frac{\chi_m I}{2\pi s} \hat{z} \Big|_{s=a} = + \frac{\chi_m I}{2\pi a} \hat{z} = \vec{K}_{BA}$$

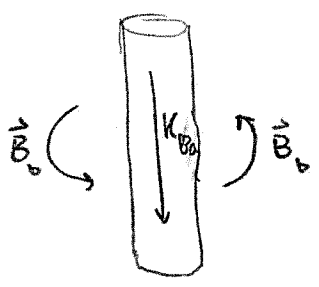
$$\oint \vec{B}_f \cdot d\vec{l} = \mu_0 I_f \Rightarrow \vec{B}_{free} = \frac{\mu_0 I}{2\pi s}$$



$$\oint \vec{B}_e \cdot d\vec{l} = \mu_0 I_{bound} = \mu_0 (2\pi a) \frac{\chi_m I}{2\pi a} \mathcal{R}(\chi)$$

$$\Rightarrow \vec{B}_e(2\pi s) = \mu_0 (\chi_m I)$$

$$\Rightarrow \vec{B}_e = - \frac{\mu_0 \chi_m I}{2\pi s} \hat{\phi} \quad \checkmark$$



$$\vec{B}_{free} + \vec{B}_e = \left\{ \frac{\mu_0 I}{2\pi s} + \frac{\mu_0 \chi_m I}{2\pi s} \right\} \hat{\phi}$$

$$= \frac{\mu_0 I}{2\pi s} \{ 1 + \chi_m \} \hat{\phi}$$

$$= \mu_0 (1 + \chi_m) \frac{I}{2\pi s} \hat{\phi} = \boxed{\frac{\mu I}{2\pi s} \hat{\phi} = \vec{B}_{total}}$$