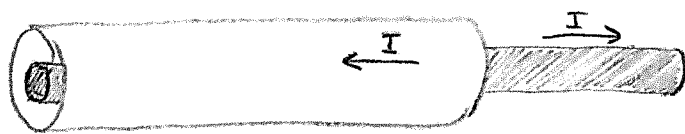


8.1

Calculate $\vec{E}$ transported by cables assuming the conductors are held at a constant potential and carry I in opposite directions along cable

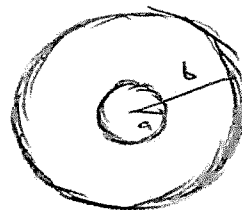


18/2a good

$$\vec{B}_{in} = \left(\frac{\mu_0 I}{2\pi s} \hat{\phi} \right), \quad \vec{B}_{out} = \vec{0} \quad \text{now as } B \neq B(t) \text{ we have } \frac{\partial \vec{B}}{\partial t} = 0$$

and so $\nabla \times \vec{E} = 0$ thus we may use the electrostatic results. That is $\vec{E}_{in} = \left(\frac{\lambda}{2\pi\epsilon_0 s} \right) \hat{s}$ where $\lambda = \frac{q}{l}$

$$\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B}) = \frac{1}{\mu_0} \left(\frac{\mu_0 I}{2\pi s} \right) \left(\frac{\lambda}{2\pi\epsilon_0 s} \right) \hat{s} \times \hat{\phi}$$



$$\begin{aligned} P &= \frac{1}{\mu_0} \oint (\vec{E} \times \vec{B}) \cdot d\vec{a} = \frac{I}{4\pi^2\epsilon_0} \oint \left(\frac{\lambda}{s^2} \hat{s} \cdot (2\pi s ds \hat{s}) \right) \\ &= \frac{I\lambda}{2\pi\epsilon_0} \int_a^b \frac{ds}{s} \\ &= \frac{I\lambda}{2\pi\epsilon_0} \ln\left(\frac{b}{a}\right) \end{aligned}$$

$$V = \int_a^b \vec{E} \cdot d\vec{s} = \int_a^b \frac{\lambda}{2\pi\epsilon_0 s} ds = \frac{\lambda}{2\pi\epsilon_0} \ln\left(\frac{b}{a}\right) \Rightarrow \lambda = \frac{V(2\pi\epsilon_0)}{\ln(b/a)}$$

$$P = \left(\frac{I \ln(b/a)}{2\pi\epsilon_0} \right) \left(\frac{V(2\pi\epsilon_0)}{\ln(b/a)} \right) = \boxed{IV = P} !$$

This is a general result for any element with current I that drops a voltage V the power is dissipated at the rate $P = \frac{dW}{dt} = \frac{dW}{dq} \frac{dq}{dt} = VI$.

$\therefore$ Ex. 7.58 no detail is needed. We have an element (the ribbon) which has the constant current I flow through it dropping the voltage V on it thus $\boxed{P = IV}$ regardless of the details!
(7.58)

8.2



Q PILING UP at gap.

$$I = \frac{dq}{dt} \Rightarrow Q = It. \quad \text{Also } \vec{E} = \frac{\sigma}{\epsilon_0} \hat{z} = \frac{It}{\pi a^2 \epsilon_0} \hat{z} = \vec{E}$$

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left(\frac{It}{\pi a^2 \epsilon_0} \right) \hat{z} = \frac{\mu_0 I}{\pi a^2} \hat{z}$$

$$\oint \vec{B} \cdot d\vec{l} = \oint \frac{\mu_0 I \hat{z}}{\pi a^2} (s d\phi ds \hat{z}) = \frac{\mu_0 I}{\pi a^2} (\partial\pi) \int s ds = \frac{\mu_0 I}{a^2} s^2 = \mu_0 I \frac{s^2}{a^2} = B_\phi (\partial\pi s)$$

$$\vec{B} = \frac{\mu_0 I s}{2\pi a^2} \hat{\phi}$$

$$(b) \quad u_{em} = \frac{1}{2} \left(\epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right) = \frac{1}{2} \left(\epsilon_0 \frac{I^2 t^2}{\pi^2 a^4 \epsilon_0^2} + \frac{1}{\mu_0} \frac{\mu_0^2 I^2 s^2}{4\pi^2 a^4} \right) = \frac{I^2}{2\pi^2 a^4} \left(\frac{t^2}{\epsilon_0} + \frac{\mu_0 s^2}{4} \right) = u_{em}$$

$$\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B}) = \frac{1}{\mu_0} \left(\frac{It}{\pi a^2 \epsilon_0} \right) \left(\frac{\mu_0 I s}{2\pi a^2} \right) \hat{z} \times \hat{\phi} = \frac{-I^2 s t}{2\pi^2 a^4 \epsilon_0} \hat{s} = \vec{S}$$

Show the above relations satisfy Eq. 8.14

$$\text{Pf// } \frac{d}{dt} (u_{em} + u_{mech}) = -\nabla \cdot \vec{S} \quad \text{Energy flow Equation}$$

 $u_{mech} = 0$ no mass in motion in gap.

$$\frac{d}{dt} (u_{em}) = \frac{d}{dt} \left(\frac{I^2}{2\pi^2 a^4} \left(\frac{t^2}{\epsilon_0} + \frac{\mu_0 s^2}{4} \right) \right) = \frac{\partial t I^2}{2\pi^2 a^4 \epsilon_0} = \frac{t I^2}{\pi^2 a^4 \epsilon_0} = \dot{u}_{em}$$

$$-\nabla \cdot \vec{S} = -\frac{1}{s} \frac{\partial}{\partial s} \left(s \left[\frac{-I^2 s t}{2\pi^2 a^4 \epsilon_0} \right] \right) = \frac{1}{s} \frac{I^2 t}{2\pi^2 a^4 \epsilon_0} (\partial s) = \frac{t I^2}{\pi^2 a^4 \epsilon_0}$$

$$\therefore \frac{d}{dt} (u_{em} + u_{mech}) = -\nabla \cdot \vec{S} = \frac{t I^2}{\pi^2 a^4 \epsilon_0} !$$

(c)

ENERGY IN GAP

$$\text{Note } \oint \vec{S} \cdot d\vec{a} = \frac{I^2 t}{2\pi^2 a^4 \epsilon_0} \int s (s d\phi dz) = \frac{I^2 t a^2 \omega}{\pi a^4 \epsilon_0} = \frac{I^2 t \omega b^2}{\pi a^2 \epsilon_0 a^2}$$

$$- / \frac{du_{em}}{dt} = \frac{d}{dt} \int u_{em} d\tau = \frac{d}{dt} \int \frac{I^2}{2\pi^2 a^4} \left(\frac{t^2}{\epsilon_0} + \frac{\mu_0 s^2}{4} \right) ds dz s d\phi = \frac{d}{dt} \frac{\omega I^2}{2\pi^2 a^4} \partial\pi \int \left(\frac{t^2}{\epsilon_0} + \frac{\mu_0 s^2}{4} \right) s ds$$

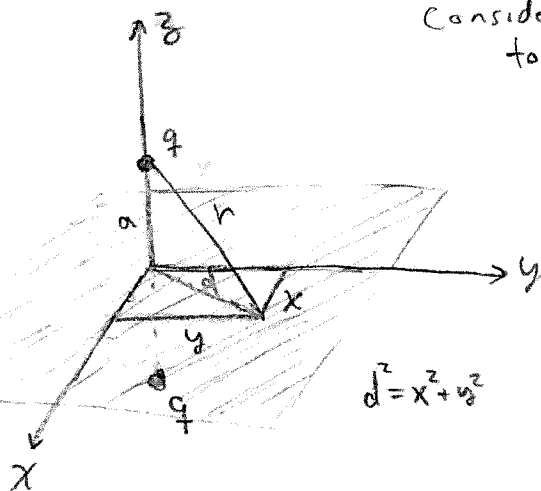
$$= \frac{d}{dt} \left(\frac{\omega I^2}{\pi a^4} \left(\frac{t^2 a^2}{2\epsilon_0} + \frac{\mu_0 a^4}{16} \right) \right) = \frac{\omega I^2 t}{\pi a^2 \epsilon_0}$$

$$\frac{du_{em}}{dt} = \int \vec{S} \cdot d\vec{a} = \frac{\omega I^2 t}{\pi a^2 \epsilon_0} \quad \left\{ \begin{array}{l} \text{Energy flow} \\ \text{Energy in gap} \end{array} \right. = \frac{\omega I^2 t^2 b^2}{2\pi a^4 \epsilon_0} + \frac{\mu_0 I^2 \omega b^4 t}{16\pi a^4} \quad E_{in \text{ gap}}$$

8-4

Consider charges on z axis for my convenience, to make picture easier.

20/20



$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2}$$

$$\left. \begin{aligned} \vec{E}_{+q} &= \frac{q}{4\pi\epsilon_0 r^2} \left(\frac{x}{d} \hat{x} + \frac{y}{d} \hat{y} - \frac{a}{r} \hat{z} \right) \\ \vec{E}_{-q} &= \frac{q}{4\pi\epsilon_0 r^2} \left(\frac{x}{d} \hat{x} + \frac{y}{d} \hat{y} + \frac{a}{r} \hat{z} \right) \end{aligned} \right\} \text{eval. at } x-y \text{ plane.}$$

$$\vec{E}_{\text{total}} = \frac{q}{4\pi\epsilon_0 r^2} \left(\frac{2x}{d} \hat{x} + \frac{2y}{d} \hat{y} \right)$$

$$E_x = \frac{q}{4\pi\epsilon_0 r^2 d} \frac{2x}{d} = \frac{q}{2\pi\epsilon_0} \frac{x}{r^2 d}$$

$$\text{let } \beta \equiv \frac{q}{2\pi\epsilon_0}$$

$$E_y = \frac{q}{4\pi\epsilon_0 r^2 d} \frac{2y}{d} = \frac{q}{2\pi\epsilon_0} \frac{y}{r^2 d}$$

$$E_z = 0$$

$$\vec{F}_j = \oint \sum_i T_{ji} da_i, \quad d\vec{a} = da_z \hat{z} = dx dy \hat{z}, \quad da_x = da_y = 0.$$

$$\Rightarrow F_j = T_{zj} da_z, \quad F_x = T_{zx} da_z, \quad F_y = T_{zy} da_z, \quad F_z = T_{zz} da_z$$

$$T_{zx} = \epsilon_0 E_z E_x = 0, \quad T_{zy} = \epsilon_0 E_z E_y = 0$$

$$\begin{aligned} T_{zz} &= \frac{1}{2} \epsilon_0 (-E_x^2 - E_y^2) = -\frac{1}{2} \epsilon_0 \left(\beta^2 \left(\frac{x^2}{r^4 d^2} + \frac{y^2}{r^4 d^2} \right) \right) = -\frac{1}{2} \epsilon_0 \beta^2 \left(\frac{x^2 + y^2}{r^4 (x^2 + y^2)} \right) \\ &= -\frac{1}{2} \epsilon_0 \beta^2 \frac{1}{r^4} = -\frac{1}{2} \epsilon_0 \left(\frac{q^2}{4\pi^2 \epsilon_0^2} \right) \frac{1}{r^4} \end{aligned}$$

$$\begin{aligned} \vec{F}_z &= \int_{x-y \text{ plane}} T_{zz} da_z = \delta \int \frac{dx dy}{r^4} = \delta \int \frac{dx dy}{(x^2 + y^2 + a^2)^2} = \delta \left(\int \frac{dx}{(x^2 + b^2)^2} \right) dy, \quad y^2 + a^2 = b^2 \\ &= \delta \int \left(\frac{x}{2b^2(b^2 + x^2)} + \frac{1}{2b^3} \tan^{-1} \left(\frac{x}{b} \right) \right) dy \\ &= \delta \int \lim_{x \rightarrow \infty} \left[\frac{x}{2(y^2 + a^2)(y^2 + a^2 + x^2)} + \frac{1}{2(y^2 + a^2)^{3/2}} \tan^{-1} \left(\frac{x}{y^2 + a^2} \right) \right] dy \\ &= \delta \int \frac{\pi}{2(y^2 + a^2)^{3/2}} dy = \frac{\delta \pi}{2} \left(\lim_{y \rightarrow \infty} \frac{y}{a^2 (y^2 + a^2)^{3/2}} \right) = \frac{\delta \pi}{a^2} \end{aligned}$$

$$\vec{F}_z = \frac{-q^2}{8\pi^2 \epsilon_0} \frac{\pi}{2a^2} = \frac{-q^2}{4\pi\epsilon_0} \frac{1}{(2a)^2} \hat{z} \Rightarrow \vec{F} = \frac{+q^2}{4\pi\epsilon_0} \frac{1}{(2a)^2} \frac{\hat{z}}{2}$$

this is force on bottom charge! I took $da_z > 0$

8.4

(b) $q_{\text{bottom}} = -q$ where $q = q_{\text{top}}$ hence $E_z = \frac{\partial q a}{4\pi\epsilon_0 r^3}$

$$T_{zz} = \frac{1}{2} \epsilon_0 (E_z^2) \quad \text{no } E_x \text{ and } E_y \text{ as } E_x, E_y \text{ of } q \text{ cancels } E_x, E_y \text{ of } -q !$$

$$F_z = \int T_{zz} da_z$$

$$= \underbrace{\frac{1}{2} \epsilon_0 \left(\frac{\partial q a}{4\pi\epsilon_0} \right)^2}_{\phi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{dx dy}{(x^2 + y^2 + a^2)^{3/2}}$$

$$= \phi \int_{-\infty}^{\infty} \left\{ \frac{3\pi}{8(y^2 + a^2)^{5/2}} \right\} dy$$

← (This is why I bought the TI-89)

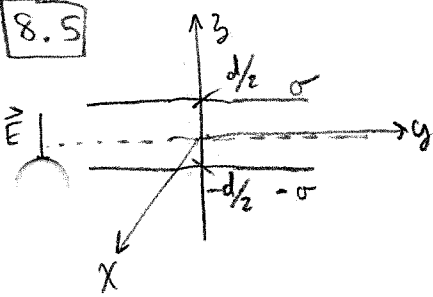
$$= \phi \frac{\pi}{2a^4}$$

$$= \frac{1}{2} \epsilon_0 \frac{\partial^2 q^2 a^2}{4^2 \pi^2 \epsilon_0^2} \frac{\pi}{2a^4}$$

$$= \frac{4}{64} \frac{q^2}{\epsilon_0 a^2}$$

$$\checkmark \quad \vec{F} = -\frac{1}{4\pi\epsilon_0} \frac{q^2}{(2a)^2} \hat{z}$$

8.5



$$E_x = E_y = 0 \quad B_x = B_y = B_z = 0$$

$$E_z = -\frac{\sigma}{\epsilon_0}$$

$$T_{xx} = \frac{1}{2} \epsilon_0 (-E_z^2) = -\frac{1}{2} \frac{\sigma^2}{\epsilon_0}$$

$$T_{yy} = \frac{1}{2} \epsilon_0 (-E_z^2) = -\frac{1}{2} \frac{\sigma^2}{\epsilon_0}$$

$$T_{zz} = \frac{1}{2} \epsilon_0 (E_z^2) = \frac{1}{2} \frac{\sigma^2}{\epsilon_0}$$

$$T_{xy} = T_{yx} = 0$$

$$T_{yz} = T_{zy} = 0$$

$$T_{zx} = T_{xz} = 0$$

$$\checkmark \quad \underline{\underline{T}} = \begin{pmatrix} -\frac{1}{2} \frac{\sigma^2}{\epsilon_0} & 0 & 0 \\ 0 & -\frac{1}{2} \frac{\sigma^2}{\epsilon_0} & 0 \\ 0 & 0 & \frac{1}{2} \frac{\sigma^2}{\epsilon_0} \end{pmatrix}$$

(b) Use eq. 8.22 to find F/A on top plate.

$$\vec{F} = \oint \vec{T} \cdot d\vec{a} = \epsilon_0 \mu_0 \frac{d}{dt} \int \vec{S} d\vec{a} = \oint \vec{T} \cdot d\vec{a}$$

$$F_i = \int T_{ix} da_x + \int T_{iy} da_y + \int T_{iz} da_z$$

$$F_x = \int T_{zx} dx dy = 0$$

$$F_y = \int T_{zy} dx dy = 0$$

$$F_z = \int T_{zz} dx dy = \int \frac{1}{2} \frac{\sigma^2}{\epsilon_0} dx dy = \frac{\sigma^2}{2\epsilon_0} (xy) = \frac{\sigma^2}{2\epsilon_0} (\text{AREA}).$$

$$\checkmark \quad \Rightarrow \frac{\vec{F}}{\text{unit Area}} = \vec{\text{Pressure}} = \frac{\sigma^2}{2\epsilon_0} \hat{z} = -\frac{\sigma^2}{2\epsilon_0} \hat{n} \quad \text{just like eq. 2.51!}$$

8.5

(c) What is momentum per unit area time crossing x-y plane between plates.

$-T_{ij}$ = the momentum in the i^{th} direction crossing a surface oriented in the j^{th} direction, per unit area time!

the x-y plane $\Rightarrow j = z$.

$$T_{iz} = T_{xz}, T_{yz}, T_{zz} = 0, 0, T_{zz}$$

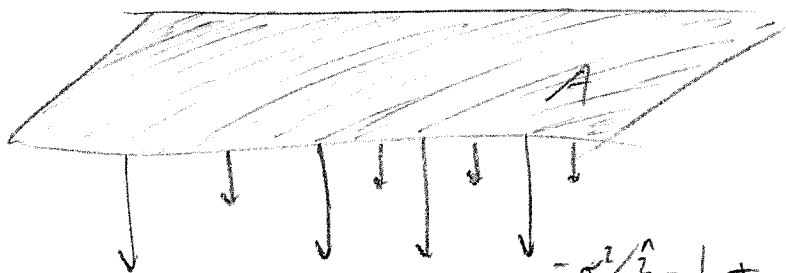
$$\checkmark \quad \hat{z} (-T_{zz}) = \boxed{-\frac{1}{2} \frac{\sigma^2}{\epsilon_0} \hat{z}} = \text{momentum per unit area, time}$$

(d) find the recoil force per unit area on top plate.

$$\frac{\Delta P}{\Delta t \Delta A} = -\frac{1}{2} \frac{\sigma^2}{\epsilon_0} \quad \text{between plates}$$

then a t plate field collides with plate which was at rest, if momentum is conserved as field is absorbed then plates recoil with $\frac{1}{2} \frac{\sigma^2}{\epsilon_0} = \text{RECOIL FORCE / AREA}$

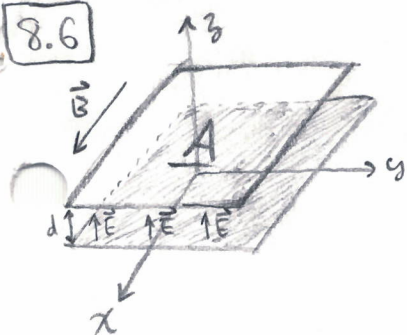
that is the plate pushes upward as the field pulls down with $\frac{-\sigma^2}{2\epsilon_0}$



$$-\frac{\sigma^2}{2\epsilon_0} \hat{z} = (-T_{zz}) \hat{z} = \frac{dP}{dt} \left(\frac{1}{A} \right)$$

$$\checkmark \quad \boxed{\vec{f}_{\text{recoil}} = \frac{-\sigma^2}{2\epsilon_0} \hat{z}}$$

8.6



$$\vec{E} = E \hat{z}$$

$$\vec{B} = B \hat{x}$$

17/20

$$(a) \vec{P}_{em} = \epsilon_0 [\vec{E} \times \vec{B}] = \epsilon_0 EB (\hat{z} \times \hat{x}) = +\epsilon_0 EB \hat{y} = \vec{P}$$

Assumeably this is a large capacitor so we may ignore fringing effects

$$\text{thus } \vec{P}_{total} = (\text{Volume})(+\epsilon_0 EB \hat{y}) = \boxed{Ad\epsilon_0 EB \hat{y} = \vec{P}_{total}}$$

$$(b) \begin{array}{c} \text{---} \\ R \uparrow I \\ \text{---} \end{array} \quad \uparrow z \quad I = I_0 e^{-t/\tau} \quad \text{where } \tau = RC = R \frac{A\epsilon_0}{d}$$

$$V_0 = I_0 R, \quad V_0 = Ed \Rightarrow I_0 = \frac{V_0}{R} = \frac{Ed}{R}$$

$$\therefore I = \frac{Ed}{R} \exp\left\{-t \frac{d}{RA\epsilon_0}\right\}$$

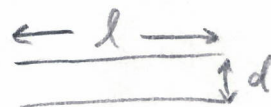
$$\begin{aligned} \vec{F} &= I \vec{l} \times \vec{B} \\ &= \frac{Ed}{R} e^{-t/\tau} (d \hat{y} \times B \hat{x}) = -\frac{BED^2}{R} e^{-t/\tau} \hat{y} \end{aligned}$$

$$\Delta \vec{P} = \vec{P}_f - \vec{P}_i = \int d\vec{P} = \int_0^\infty \frac{d\vec{P}}{dt} dt = \int_0^\infty \vec{F} dt = \frac{BED^2}{R} \hat{y} \int_0^\infty e^{-t/\tau} dt$$

$$= \frac{\tau BED^2}{R} \hat{y} \left(-e^{-t/\tau} \Big|_0^\infty \right) = \left(R \frac{A\epsilon_0}{d} \right) \left(\frac{BED^2}{R} \right) \hat{y} = \boxed{BEAd\epsilon_0 \hat{y} = \vec{P}_{total}}$$

(impulse) ΔP

$$(c) \quad \mathcal{E} = -\frac{d\Phi}{dt} \quad \text{and} \quad \mathcal{E} = E_i l$$



$$\mathcal{E} = -\frac{d\Phi}{dt} = -l \frac{dB}{dt} = E_i l \Rightarrow E_i = -d \frac{dB}{dt}$$

$$F_y = qE_i = C V E_i = \frac{A\epsilon_0}{d} Ed \left(-d \frac{dB}{dt} \right) = \frac{dP_y}{dt} \Rightarrow A\epsilon_0 d(dB) = dP_y$$

$$\Rightarrow \boxed{\vec{P} = BEAd\epsilon_0 \hat{y}} = \Delta P \text{ (impulse)}$$

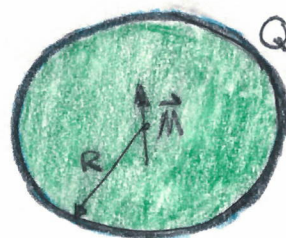
A better way to view parts b,c is to just consider $\vec{E}_{final}$, $\vec{B}_{final}$ and $\vec{E}_{initial}$, $\vec{B}_{initial}$. then it is trivial to find ΔP , however some gather the problem is too easy that way.

8.8

(a) As there is no charge on inside and $B \neq B(t)$ there is no induced or coulombic $\vec{E}$

$$\therefore \vec{E} = \vec{0} \text{ for } r < R.$$

$\therefore$ it is sufficient to consider only outside fields since $\vec{l}_{em} = \epsilon_0 [\vec{r} \times (\vec{E} \times \vec{B})] = \epsilon_0 [\vec{r} \times (\vec{0} \times \vec{B})] = \vec{0}!$



Outside, $r > R$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \hat{r} : \text{nothing revolutionary here.}$$

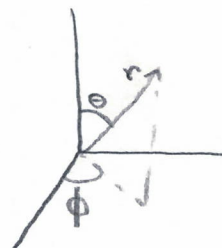
$$\vec{B} = \frac{\mu_0 m}{4\pi r^3} \{2\cos\theta \hat{r} + (\sin\theta) \hat{\theta}\}$$

$$m = M \frac{4}{3}\pi R^3, \text{ as if there were just one dipole at origin}$$

$$\vec{l}_{em} = \epsilon_0 \left[\vec{r} \times \left\{ \left(\frac{Q}{4\pi\epsilon_0 r^2} \right) \hat{r} \times \left(\frac{\mu_0 m}{4\pi r^3} \right) [2\cos\theta \hat{r} + (\sin\theta) \hat{\theta}] \right\} \right]$$

$$= \frac{Q \mu_0 m}{(4\pi)^2 r^5} \left[\vec{r} \times (\hat{r} \times (\sin\theta) \hat{\theta}) \right]$$

$$= \frac{Q \mu_0 m}{(4\pi)^2 r^4} \left[\hat{r} \times \sin\theta (-\hat{\phi}) \right]$$



$$\vec{l}_{em} = -\frac{\sin\theta Q \mu_0 m}{16\pi^2 r^4} \hat{\theta} \implies$$

$$L = \frac{2}{9} M Q \mu_0 R^2 \hat{z}$$

we neglected the dependence of $\hat{\theta}$ on r, θ, ϕ .

Now integrate for $r > R$ for total, $\vec{l} \rightarrow L$ and $\vec{\theta} \rightarrow \hat{z}$

$$\vec{l}_{em} = \int_{r>R} \frac{-\sin\theta Q \mu_0 m}{16\pi^2 r^4} r^2 \sin\theta d\theta d\phi \hat{\theta}$$

$$= \frac{-Q \mu_0 m}{16\pi^2} \int_R^\infty \frac{dr}{r^2} \int_0^\pi \sin^2\theta d\theta \int_0^{2\pi} d\phi \hat{\theta}$$

$$= \frac{-Q \mu_0 m}{16\pi^2} \left(\frac{1}{R} \right) \left(\frac{\pi}{2} \right) (2\pi) \hat{\theta}$$

$$= -\frac{Q \mu_0}{R} \frac{1}{16} M \frac{4}{3} \pi R^3 \hat{\theta} =$$

$$\frac{-\mu_0 Q M R^2 \pi \hat{\theta}}{12} = \vec{l}_{em} \text{ total}$$

show correct int. over $\hat{z}$ not $\hat{\theta}$.

9.13

 Calculate the exact reflection and transmission coefficients. ($\mu_1 = \mu_2 = \mu_0$ not allowed)
 Confirm $R + T = 1$.

$$\tilde{E}_{or} = \left(\frac{1-\beta}{1+\beta} \right) \tilde{E}_{oi}$$

$$\text{where } \beta \equiv \frac{\mu_1 v_1}{\mu_2 v_2} = \frac{\mu_1 n_2}{\mu_2 n_1}$$

$$\tilde{E}_{ot} = \left(\frac{2}{1+\beta} \right) \tilde{E}_{oi}$$

(Eq's 9.82, 9.81 from pg. 385)

$$I = \frac{1}{2} \epsilon v E_o^2$$

$$R = \frac{I_r}{I_i} = \frac{\frac{1}{2} \epsilon_1 v_1 E_{or}^2}{\frac{1}{2} \epsilon_1 v_1 E_{oi}^2} = \frac{\left(\frac{1-\beta}{1+\beta} \right)^2 E_{oi}^2}{E_{oi}^2} = \left(\frac{1-\beta}{1+\beta} \right)^2 = R$$

$$\beta \equiv \frac{\mu_1 v_1}{\mu_2 v_2} = \frac{\mu_1 n_2}{\mu_2 n_1}$$

 Writing out β would be just the same answer!

$$T = \frac{I_t}{I_i} = \frac{\frac{1}{2} \epsilon_2 v_2 E_{ot}^2}{\frac{1}{2} \epsilon_1 v_1 E_{oi}^2} = \frac{\epsilon_2 v_2 \left(\frac{2}{1+\beta} \right)^2 E_{oi}^2}{\epsilon_1 v_1 E_{oi}^2} = \frac{\epsilon_2 v_2}{\epsilon_1 v_1} \left(\frac{2}{1+\beta} \right)^2 = T$$

$$R + T = \left(\frac{1-\beta}{1+\beta} \right)^2 + \frac{\epsilon_2 v_2}{\epsilon_1 v_1} \left(\frac{2}{1+\beta} \right)^2$$

$$= \frac{\epsilon_1 v_1 (1-\beta)^2 + 4(\epsilon_2 v_2)}{(1+\beta)^2 \epsilon_1 v_1}$$

$$= \frac{\frac{1}{\mu_1^2} v_1 (1-\beta)^2 + 4 \left(\frac{1}{\mu_2^2} v_2 \right)}{(1+\beta)^2 \frac{1}{\mu_1^2} v_1}$$

$$= \frac{\frac{1}{\mu_1 v_1} (1-\beta)^2 + 4\beta \frac{1}{\mu_1 v_1}}{\frac{1}{\mu_1 v_1} (1+\beta)^2}$$

$$= \frac{(1-\beta)^2 + 4\beta}{(1+\beta)^2}$$

$$= \frac{1 - 2\beta + \beta^2 + 4\beta}{1 + 2\beta + \beta^2}$$

$$= \frac{1 + 2\beta + \beta^2}{1 + 2\beta + \beta^2}$$

$$= 1 \quad \therefore R + T = 1$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0} \Rightarrow v^2 = \frac{1}{\mu \epsilon}$$

$$\therefore \epsilon = \frac{1}{\mu v^2}$$

$$\beta = \frac{\mu_1 v_1}{\mu_2 v_2} \Rightarrow \mu_2 v_2 = \frac{\mu_1 v_1}{\beta}$$

$$T = \frac{\epsilon_2 v_2}{\epsilon_1 v_1}$$

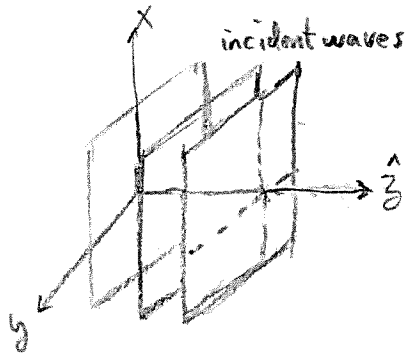
9.14

$$\vec{E}_R = \vec{E}_{or} e^{i(-kz - \omega t)} [\cos \theta_R \hat{x} + \sin \theta_R \hat{y}]$$

$$\vec{E}_T = \vec{E}_{ot} e^{i(k_2 z - \omega t)} [\cos \theta_T \hat{x} + \sin \theta_T \hat{y}]$$

$$\epsilon_1 E_R \Big|_y = \epsilon_2 E_T \Big|_y \Rightarrow \epsilon_1 \vec{E}_{or} e^{i(\omega t)} \sin \theta_R = \epsilon_2 \vec{E}_{ot} e^{i(\omega t)} \sin \theta_T$$

$$\epsilon_1 \vec{E}_{or} \sin \theta_R = \epsilon_2 \vec{E}_{ot} \sin \theta_T$$



DIRECTION OF B is $\hat{k} \times \hat{n}$,

$$\hat{k}_R \times \hat{n}_R = -\hat{z} \times [\cos \theta_R \hat{x} + \sin \theta_R \hat{y}] = -\cos \theta_R \hat{y} + \sin \theta_R \hat{x}$$

$$\hat{k}_T \times \hat{n}_T = \hat{z} \times [\cos \theta_T \hat{x} + \sin \theta_T \hat{y}] = \cos \theta_T \hat{y} - \sin \theta_T \hat{x}$$

$$\frac{1}{\mu_1} B_1 \Big|_x = \frac{1}{\mu_2} B_2 \Big|_x \Rightarrow \frac{1}{\mu_1} \frac{1}{v_1} \vec{E}_{or} \sin \theta_R = -\frac{1}{\mu_2 v_2} \vec{E}_{ot} \sin \theta_T$$

$$\left. \begin{array}{l} \epsilon_1 = \mu_1^2 \\ \epsilon_2 = \mu_2^2 \end{array} \right\} \begin{array}{l} n = \frac{c}{v} \\ v^2 = \frac{1}{\mu \epsilon} \end{array} \left\{ \begin{array}{l} \Downarrow \\ n_1 \vec{E}_{or} \sin \theta_R = -n_2 \vec{E}_{ot} \sin \theta_T \end{array} \right.$$

$$(i) \epsilon_1 \vec{E}_{or} \sin \theta_R = \epsilon_2 \vec{E}_{ot} \sin \theta_T$$

$$(ii) n_1 \vec{E}_{or} \sin \theta_R = -n_2 \vec{E}_{ot} \sin \theta_T$$

$$(i) \epsilon = n^2 \Rightarrow n_1^2 \vec{E}_{or} \sin \theta_R = n_2^2 \vec{E}_{ot} \sin \theta_T$$

Now if $\sin \theta_T$ AND $\sin \theta_R \neq 0 \Rightarrow n_1 = n_1^2$ and $n_2 = -n_2^2$
as $n_2 \in \mathbb{R}$ $n_2 \neq -n_2^2$ unless $n_2 = 0$ (not possible here $\frac{v}{c} \neq 0$)

$$\therefore \sin \theta_R = 0 \text{ and } \sin \theta_T = 0 \therefore \boxed{\theta_R = \theta_T = 0}$$

20/20

Q.1 Show f_1, f_2, f_3 do not satisfy wave eq. Show f_4, f_5 do

(i) $f_1 = Ae^{-b(z-vt)^2}$

SPACE
 $\frac{\partial^2 f_1}{\partial z^2} = \frac{\partial}{\partial z} \left(Ae^{-b(z-vt)^2} \left(-b \frac{\partial}{\partial z} (z-vt)^2 \right) \right) = \frac{\partial}{\partial z} \left(-Ab \frac{\partial}{\partial z} (z-vt)^2 e^{-b(z-vt)^2} \right)$
 $= -\partial Ab e^{-b(z-vt)^2} \left(1 + (z-vt)(-\partial b(z-vt)) \right)$
 $= -\partial Ab e^{-b(z-vt)^2} (1 - \partial b(z-vt)^2)$

TIME
 $\frac{1}{v^2} \frac{\partial^2 f_1}{\partial t^2} = \frac{1}{v^2} \frac{\partial}{\partial t} \left(-\partial Ab (z-vt)(-v) e^{-b(z-vt)^2} \right) = \frac{1}{v^2} \left(\partial Ab v e^{-b(z-vt)^2} (-v + (z-vt)(\partial v b(z-vt))) \right)$
 $= \frac{1}{v^2} \left(v^2 \partial Ab e^{-b(z-vt)^2} (-1 + \partial b(z-vt)^2) \right)$
 $= -\partial Ab e^{-b(z-vt)^2} (1 - \partial b(z-vt)^2) \therefore \frac{\partial^2 f_1}{\partial z^2} = \frac{1}{v^2} \frac{\partial^2 f_1}{\partial t^2} !$

(ii) SPACE
 $\frac{\partial^2 f_2}{\partial z^2} = \frac{\partial^2}{\partial z^2} (A \sin[b(z-vt)]) = \frac{\partial}{\partial z} (Ab \cos[b(z-vt)]) = -Ab^2 \sin[b(z-vt)]$

TIME
 $\frac{1}{v^2} \frac{\partial^2 f_2}{\partial t^2} = \frac{\partial^2}{\partial t^2} (A \sin[b(z-vt)]) = \frac{1}{v^2} \frac{\partial}{\partial t} (-Ab v \cos[b(z-vt)]) = \frac{1}{v^2} \{-Ab v (-bv) (-\sin[b(z-vt)])\}$
 $= -Ab^2 \sin[b(z-vt)] \therefore \frac{\partial^2 f_2}{\partial z^2} = \frac{1}{v^2} \frac{\partial^2 f_2}{\partial t^2}$

(iii) SPACE
 $\frac{\partial^2 f_3}{\partial z^2} = \frac{\partial^2}{\partial z^2} \left(\frac{A}{b(z-vt)^2 + 1} \right) = A \frac{\partial}{\partial z} \left(-[b(z-vt)^2 + 1]^{-2} (\partial b(z-vt)) \right)$
 $= A \left\{ \partial [b(z-vt)^2 + 1]^{-3} (\partial b(z-vt))^2 - \partial b [b(z-vt)^2 + 1]^{-2} \right\}$

TIME
 $\frac{1}{v^2} \frac{\partial^2 f_3}{\partial t^2} = \frac{\partial^2}{\partial t^2} \left(\frac{A}{b(z-vt)^2 + 1} \right) = \frac{A}{v^2} \frac{\partial}{\partial t} \left(-[b(z-vt)^2 + 1]^{-2} (-\partial b v (z-vt)) \right)$
 $= \frac{A}{v^2} \left\{ -\partial [b(z-vt)^2 + 1]^{-3} (-\partial b v (z-vt) \partial b v (z-vt)) - \partial b v^2 [b(z-vt)^2 + 1]^{-2} \right\}$
 $= A \left\{ \partial [b(z-vt)^2 + 1]^{-3} (\partial b(z-vt))^2 - \partial b [b(z-vt)^2 + 1]^{-2} \right\}$
 $\therefore \frac{\partial^2 f_3}{\partial z^2} = \frac{1}{v^2} \frac{\partial^2 f_3}{\partial t^2}$