

LECTURE 16 : MAGNETIC FIELDS

We begin our study of magnetostatics. We'll describe how steady currents give rise to magnetic fields and how magnetic fields place a force on moving charge. We begin with the Lorentz force.

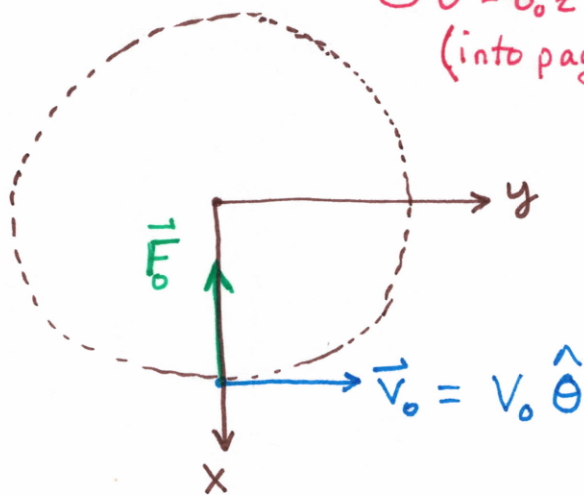
$$\vec{F} = Q(\vec{v} \times \vec{B})$$

If $\vec{E}$ and $\vec{B}$ are both involved then $\vec{F} = Q(\vec{E} + \vec{v} \times \vec{B})$

Griffiths mentions this law is due to Oliver Heaviside

[E1] Given constant magnetic field $\vec{B} = -B_0 \hat{z}$

If we have a charge Q with initial velocity $\vec{v}_0 = v_0 \hat{y}$ then the resulting motion is circular. To keep things nice, let's assume the initial position is at $y_0 = z_0 = 0$ with $x_0 = \frac{mv_0}{B_0 Q}$



$$\vec{F} = Q(\vec{v} \times \vec{B}) = Q(v_0 \hat{y} \times (-B_0 \hat{z})) = -QB_0 v_0 \hat{r}$$

$$-\frac{mv_0^2}{R} \hat{r} = -QB_0 v_0 \hat{r} \Rightarrow \boxed{R = \frac{mv_0}{QB_0}}$$

cyclotron formula

Remark : this formula assumes $v \ll c$, relativistically there is a correction.

PRODUCT RULES FOR $\vec{A} \times \vec{B}$ (from front cover of GRIFFITHS)

$$(6.) \quad \nabla \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B})$$

$$(8.) \quad \nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} - (\vec{A} \cdot \nabla) \vec{B} + \vec{A} (\nabla \cdot \vec{B}) - \vec{B} (\nabla \cdot \vec{A})$$

Both of these flow from $\vec{A} \times \vec{B} = \sum_n \epsilon_{ijk} A_i B_j \hat{x}_n$
and $\sum_n \epsilon_{ijk} \epsilon_{klm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$ and the product rule.

$$\begin{aligned} \nabla \cdot (\vec{A} \times \vec{B}) &= \sum_n \partial_n (\vec{A} \times \vec{B})_n \\ &= \sum_n \partial_n \left(\sum_{i,j} \epsilon_{ijn} A_i B_j \right) \\ &= \sum_{i,j,n} \epsilon_{ijn} \partial_n (A_i B_j) \\ &= \sum_{i,j,n} \epsilon_{ijn} (\partial_n A_i) B_j + \sum_{i,j,n} \epsilon_{ijn} A_i (\partial_n B_j) \\ &= \sum_j \left(\underbrace{\sum_n \epsilon_{n i j} \partial_n A_i}_{(\nabla \times \vec{A})_j} \right) B_j - \sum_i \left(\underbrace{\sum_{n,j} \epsilon_{n j i} \partial_n B_j}_{(\nabla \times \vec{B})_i} \right) A_i \\ &= (\nabla \times \vec{A}) \cdot \vec{B} - (\nabla \times \vec{B}) \cdot \vec{A} \\ &= \underline{\vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B})}. \quad (6.) \end{aligned}$$

Continuing

$$\nabla \times (\vec{A} \times \vec{B}) = \sum_{i,j,k} \epsilon_{ijk} \partial_i (\vec{A} \times \vec{B})_j \hat{x}_k$$

$$= \sum_{i,j,k} \epsilon_{ijk} \partial_i \left(\sum_{l,m} \epsilon_{lmj} A_l B_m \right) \hat{x}_k$$

$$= \sum_{i,j,k,l,m} \epsilon_{ijk} \epsilon_{lmj} \left[(\partial_i A_l) B_m + A_l (\partial_i B_m) \right] \hat{x}_k$$

$$= \sum_{i,j,k,l,m} -\epsilon_{ikj} \epsilon_{lmj} \left[(\partial_i A_l) B_m + A_l (\partial_i B_m) \right] \hat{x}_k$$

$$= \sum_{i,k,l,m} -(\delta_{il} \delta_{km} - \delta_{im} \delta_{kl}) \left[(\partial_i A_l) B_m + A_l (\partial_i B_m) \right] \hat{x}_k$$

$$= \sum_{i,k,l,m} \left(\delta_{im} \delta_{kl} (\partial_i A_l) B_m - \delta_{il} \delta_{km} (\partial_i A_l) B_m - \delta_{il} \delta_{km} A_l (\partial_i B_m) + \delta_{im} \delta_{kl} A_l (\partial_i B_m) \right) \hat{x}_k$$

$$= \sum_{i,k} \left(\underline{(\partial_i A_k) B_i} - \underline{(\partial_i A_i) B_k} - \underline{A_i \partial_i B_k} + \underline{A_k \partial_i B_i} \right) \hat{x}_k$$

$$= \sum_{i,k} \left(\underline{B_i \partial_i A_k} - \underline{A_i \partial_i B_k} + \underline{A_k \partial_i B_i} - \underline{(\partial_i A_i) B_k} \right) \hat{x}_k$$

$$= \underline{(\vec{B} \cdot \nabla) \vec{A} - (\vec{A} \cdot \nabla) \vec{B} + \vec{A} (\nabla \cdot \vec{B}) - \vec{B} (\nabla \cdot \vec{A})} \quad (8.)$$

DERIVATION OF AMPERE'S LAW & NO MAGNETIC MONOPOLES

We begin by assuming the Biot-Savart law for a general volume current $\vec{J}$,

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}') \times \hat{\vec{r}}}{r^2} d\tau'$$

Where $\vec{r} = \vec{r} - \vec{r}' = (x-x')\hat{x} + (y-y')\hat{y} + (z-z')\hat{z}$
and $d\tau' = dx' dy' dz'$ (primed coord. for source current,
unprimed coord. at the field point $\vec{r} = (x, y, z)$)

$$\begin{aligned}\nabla \cdot \vec{B} &= \frac{\mu_0}{4\pi} \int \nabla \cdot \left[\vec{J} \times \frac{\hat{\vec{r}}}{r^2} \right] d\tau' \\ &= \frac{\mu_0}{4\pi} \int \left[\underbrace{\frac{\hat{\vec{r}}}{r^2} \cdot (\nabla \times \vec{J})}_0 - \underbrace{\vec{J} \cdot \nabla \times \left(\frac{\hat{\vec{r}}}{r^2} \right)}_0 \right] d\tau' \\ &\quad \vec{J} = \vec{J}(\vec{r}') \quad \text{Lemma from previous Lecture}\end{aligned}$$

$$\nabla \cdot \vec{B} = 0 \quad (\text{no magnetic monopoles})$$

Continuing, the curl of $\vec{B}$ is specified by the calculation which follows. We assume Biot-Savart Law as our starting point and continue to use $\vec{r} = \vec{r} - \vec{r}'$ where $\vec{J}(\vec{r}')$ has no $\vec{r}$ -dependence and $\nabla = \hat{x}\partial_x + \hat{y}\partial_y + \hat{z}\partial_z$,

$$\nabla \times (\vec{J} \times \frac{\hat{r}}{r^2}) = \underbrace{\left(\frac{\hat{r}}{r^2} \cdot \nabla\right) \vec{J}}_0 - \underbrace{(\vec{J} \cdot \nabla) \frac{\hat{r}}{r^2}}_0 + \underbrace{\vec{J} (\nabla \cdot \frac{\hat{r}}{r^2})}_0 - \underbrace{\frac{\hat{r}}{r^2} \nabla \cdot \vec{J}}_0$$

Recall, $\nabla \cdot \left(\frac{\hat{r}}{r^2}\right) = 4\pi \delta^3(\vec{r})$ then Biot-Savart,

$$\begin{aligned} \nabla \times \vec{B} &= \frac{\mu_0}{4\pi} \int \nabla \times (\vec{J} \times \frac{\hat{r}}{r^2}) d\tau' \\ &= \frac{\mu_0}{4\pi} \int \vec{J}(\vec{r}') \cdot \underbrace{4\pi \delta^3(\vec{r} - \vec{r}')} d\tau' - \underbrace{\frac{\mu_0}{4\pi} \int (\vec{J} \cdot \nabla) \frac{\hat{r}}{r^2} d\tau'}_{\text{can show this is zero see lemma}} \\ &= \mu_0 \vec{J}(\vec{r}) \end{aligned}$$

$$\boxed{\nabla \times \vec{B} = \mu_0 \vec{J} \quad \text{Ampere's Law}}$$

$$\boxed{\text{Lemma: } -\int (\vec{J} \cdot \nabla) \frac{\hat{r}}{r^2} d\tau' = 0}$$

Observe $-(\vec{J} \cdot \nabla) \left(\frac{\hat{r}}{r^2}\right) = (\vec{J} \cdot \nabla') \left(\frac{\hat{r}}{r^2}\right)$ since $\nabla' = \hat{x}' \frac{\partial}{\partial x'} + \hat{y}' \frac{\partial}{\partial y'} + \hat{z}' \frac{\partial}{\partial z'}$

and $\frac{\hat{r}}{r^2} = \frac{\langle x-x', y-y', z-z' \rangle}{[(x-x')^2 + (y-y')^2 + (z-z')^2]^{3/2}}$ so switching from

$\nabla = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$ for ∇' carries a minus.



Lemma proof unrivied

$$\begin{aligned} -(\vec{J} \cdot \nabla) \frac{\hat{\lambda}}{\lambda^2} &= (\vec{J} \cdot \nabla') \left(\frac{\hat{\lambda}}{\lambda^2} \right) \\ &= (\vec{J} \cdot \nabla') \left[\frac{1}{\lambda^3} (\vec{r} - \vec{r}') \right] \\ &= (\vec{J} \cdot \nabla') \left\langle \frac{x-x'}{\lambda^3}, \frac{y-y'}{\lambda^3}, \frac{z-z'}{\lambda^3} \right\rangle \\ &= \left\langle \underbrace{(\vec{J} \cdot \nabla') \left(\frac{x-x'}{\lambda^3} \right)}, (\vec{J} \cdot \nabla') \left(\frac{y-y'}{\lambda^3} \right), (\vec{J} \cdot \nabla') \left(\frac{z-z'}{\lambda^3} \right) \right\rangle \\ &\quad \nabla' \cdot \left[\frac{(x-x')}{\lambda^3} \vec{J}(\vec{r}') \right] - \underbrace{\left(\frac{x-x'}{\lambda^3} \right) \nabla' \cdot \vec{J}(\vec{r}')}_{\text{zero for steady currents}} \end{aligned}$$

$$-(\vec{J} \cdot \nabla) \frac{\hat{\lambda}}{\lambda^2} = \left\langle \nabla' \cdot \left(\frac{x-x'}{\lambda^3} \vec{J} \right), \nabla' \cdot \left(\frac{y-y'}{\lambda^3} \vec{J} \right), \nabla' \cdot \left(\frac{z-z'}{\lambda^3} \vec{J} \right) \right\rangle$$

consequently,

$$\begin{aligned} -\int_V (\vec{J} \cdot \nabla) \left(\frac{\hat{\lambda}}{\lambda^2} \right) d\tau' &= \left\langle \int_V \nabla' \cdot \left(\frac{x-x'}{\lambda^3} \vec{J}(\vec{r}') \right) d\tau', - , - \right\rangle \\ &= \left\langle \oint_{\partial V} \left(\frac{x-x'}{\lambda^3} \right) \vec{J} \cdot d\vec{a}', \oint_{\partial V} \left(\frac{y-y'}{\lambda^3} \right) \vec{J} \cdot d\vec{a}', \oint_{\partial V} \left(\frac{z-z'}{\lambda^3} \right) \vec{J} \cdot d\vec{a}' \right\rangle \\ &= 0 \end{aligned}$$

(take V large enough so that $\vec{J} = 0$ on ∂V , we assume $\vec{J} \neq 0$ only for some finite domain, although, we'll apply this for infinite line currents soon enough. See GRIFFITHS § 5.3.1 for stand alone argument for such cases.)