

LECTURE 20: GENERAL RELATIVITY: TETRAD FORMALISM ALA CARTAN

①

Typically we've used $T_p M = \text{span} \left\{ \frac{\partial}{\partial x^i} \right\}$ or $\frac{\partial}{\partial x^i} : C^\infty(U) \rightarrow C^\infty(U)$ to describe vectors at a point $p \in M$ or vector fields on $U \subseteq M$ where $X^i : U \rightarrow \mathbb{R}^n$ is a coordinate chart on U . In G.R. we have $n=4$ and we use X^μ to indicate $\mu = 0, 1, 2, 3$ subject our usual conventions. In short, $\partial_\mu = \frac{\partial}{\partial x^\mu}$ and dx^μ give bases for tangent and cotangent spaces to our spacetime manifold. For a general coord. system the metric tensor's components $g_{\mu\nu} = g(\partial_\mu, \partial_\nu)$ need not be anything too nice (well g is a metric, so $\det(g_{\mu\nu}) \neq 0$ and $g_{\mu\nu} = g_{\nu\mu}$ etc... so they're are some conditions!)

∂_μ vector fields e_a are called a tetrad if $a = 0, 1, 2, 3$ satisfy $g(e_a, e_b) = \eta_{ab}$ where $\eta_{ab} = -\delta_{a,0}\delta_{b,0} + \delta_{a,1}\delta_{b,1} + \delta_{a,2}\delta_{b,2} + \delta_{a,3}\delta_{b,3}$. Throughout some $U \subseteq M$. We also say $\{e_a\}$ form a vielbein on U .

$$(\eta_{ab}) = \begin{bmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

Remark: it is not generally possible to find a tetrad which covers all of a manifold.

Vielbein many legs
For instance the sphere does not permit the assignment of an every where non zero smooth vect. field
The tetrad is a local construction.

Remark: Carroll uses \hat{e}_a whereas I'll use e_a and add parentheses if in doubt about interpretation for formula...

(2)

Defⁿ $e_p = \partial_p = \frac{\partial}{\partial x^p}$ (coordinate derivations)
 e_a (satisfy $g(e_a, e_b) = \eta_{ab}$, might be ~~non-coord. deriv~~ impossible to write e_a as coord. derivatives on their domain.

Defⁿ $e_p = e_p^a e_a$ and $e_a = e^r_a e_r$
 The $(n \times n)$ -invertible matrix (e_p^a) is also called the tetrad since it is the coordinates of e_p in the e_a -basis likewise, (e^r_a) ~~are~~ the coordinates of e_a in the e_r -basis.

Observe $e_p = e_p^a e_a = e_p^a e^r_a e_r \Rightarrow \underline{e_p^a e^r_a = \delta_p^r}$ (1)

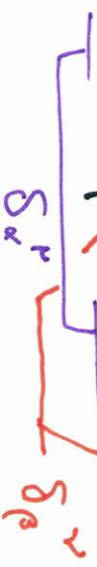
Likewise, $e_a = e^r_a e_r = e^r_a e_p^b e_b \Rightarrow \underline{e^r_a e_p^b = \delta_a^b}$ (2)

Furthermore, $g(e_a, e_b) = \eta_{ab}$

$g(e^r_a e_r, e^s_b e_s) = \eta_{ab}$

$e^r_a e^s_b g(e_r, e_s) = \eta_{ab} \Rightarrow \underline{e^r_a e^s_b g_{rs} = \eta_{ab}}$ (3)

Finally, $e^a_\alpha e^b_\rho e^r_a e^s_b g_{rs} = e^a_\alpha e^b_\rho \eta_{ab} \Rightarrow \underline{g_{\alpha\rho} = e^a_\alpha e^b_\rho \eta_{ab}}$ (4)



Th²/ If e_a is tetrad frame with $g(e_a, e_b) = \eta_{ab}$ and we define coordinate change matrices e_p^a and e^r_a to convert from tetrad e_a to coord. frame $e_p = \frac{\partial}{\partial x^p}$ then meaning

$e_p = e_p^a e_a$ and $e_a = e^r_a e_r$ then,

- ① $e_p^a e^r_a = \delta_p^r$
- ② $e^r_a e_p^b = \delta_a^b$
- ③ $\eta_{ab} = e^r_a e^s_b g_{rs}$
- ④ $g_{rs} = e_p^a e_q^b \eta_{ab}$

Remark: a, b are "Lorentz indices" whereas p, r are general indices. The condition $e_p^a = \frac{\partial}{\partial x^p}$ was not used to derive ①, ②, ③, ④ so this is more general than advertised.

or better "yet curved" indices

Def³/ compatible basis of one-forms to given e_p can be denoted Θ^r where $\Theta^r(e_s) = \delta^r_s$ serves to define Θ^r as a linear function of vectors (at a point, or on a subset in which case we'd call Θ^r a one-form-field) Likewise, $\Theta^a(e_b) = \delta^a_b$. Alternatively, $\Theta^r = dx^r$, $e_p = \partial_p$ and $dx^r(\partial_s) = \delta^r_s$

Remark: the coordinate derivations $\frac{\partial}{\partial x^p}$ and differentials dx^r give examples of frame and compatible coframe; $dx^r(\frac{\partial}{\partial x^s}) = \delta^r_s = \delta^r_s$.

Coordinate Change for the Cotrans

(4)

$$\Theta^a(e_b) = \delta_b^a \quad \Rightarrow \quad \Theta^a(e_\nu^b e_\mu) = \delta_b^a$$

$$\Rightarrow e_\nu^b \Theta^a(e_\mu) = \delta_b^a$$

$$\Rightarrow e_\nu^b e_\mu^{\nu'} \Theta^a(e_\mu) = \delta_b^a e_\nu^{\nu'}$$

$$\Rightarrow \Theta^a(e_\nu) = e_\nu^a$$

Likewise,

$$\Theta^{\nu'}(e_\nu) = \delta_\nu^{\nu'} \quad \Rightarrow \quad \Theta^{\nu'}(e_\nu^a e_\mu) = \delta_\nu^{\nu'}$$

$$\Rightarrow e_\nu^a e_\mu^{\nu'} \Theta^{\nu'}(e_\mu) = e_\nu^a \delta_\nu^{\nu'}$$

$$\Rightarrow \Theta^{\nu'}(e_b) = e_b^{\nu'}$$

Thⁿ with notation as given above, $\Theta^{\nu'} = e_\nu^{\nu'} \Theta^a$ and $\Theta^a = e_\nu^a \Theta^{\nu'}$

Proof: $\Theta^{\nu'} = \Theta^{\nu'}(e_a) e^a = e_\nu^{\nu'} e^a$

$$\Theta^a = \Theta^a(e_\nu) e^{\nu'} = e_\nu^a e^{\nu'}. //$$

(here I'm using $\alpha: V \rightarrow \mathbb{R}$ has $\alpha = \sum c_i e_i$ then

$$\alpha(e_i) = \sum c_j e_j(e_i) = \sum c_j \delta_j^i = c_i \quad \therefore c_j = \alpha(e_j)$$

hence $\alpha = \sum_i \alpha(e_i) e^i$ is an identity linking frame/cotrans (basis expansions)

FLAT AND CURVED INDEX JUGGLING (5)

A vector V can be written $V = V^\mu e_\mu$ or $V = V^a e_a$ then the components of V are related by the vielbein

$$V = V^\mu e_\mu = V^\mu e_\mu^a e_a = V^a e_a \Rightarrow V^a = e_\mu^a V^\mu$$

$$V = V^a e_a = V^a e^r_a e_r = V^r e_r \Rightarrow V^r = e^r_a V^a$$

Higher tensors work similarly,

$$T^a_b = T(e^a, e_b) = T(e_\mu^a e^\mu, e^\nu_b e_\nu) = e_\mu^a e^\nu_b T(e^\mu, e_\nu) = e_\mu^a e^\nu_b T^\mu_\nu = e_\mu^a e^\nu_b T^\mu_\nu$$

Following the pattern, (consistent with what we derived earlier) (2 or \mathbb{R}^2 in 3)

$$g_{\mu\nu} = e_\mu^a e_\nu^b g_{ab} \quad \text{or} \quad g_{ab} = e^r_a e^s_b g_{rs}$$

$\left\{ \begin{array}{l} \mathbb{R}^n / \text{Thinking of tensor } e = e_\nu^a dx^\nu \otimes e_a \text{ we can see vielbeins as} \\ \text{components of this tensor. (weird to use diff. coord. in this fashion...)} \end{array} \right\}$

$$e^r_a = g^{\mu\nu} \eta_{ab} e_\nu^b$$

$$\begin{aligned} \theta^r(e_a) &= e^r_a \quad \text{from (4)} \\ \theta^b(e_\nu) &= e_\nu^b \quad \text{from (4)} \end{aligned}$$



$$\begin{aligned}
 e^\mu_a &= \theta^r(e_a) = e^r_b \theta^b(e^r_a e_r) \\
 &= e^r_b e^r_a \theta^b(e_r) \\
 &= e^r_b \underbrace{e^r_a e_r}_{\delta^b_a} = e^r_a \cdot \text{YEP.}
 \end{aligned}$$

$$g^{\mu\nu} g_{\nu\sigma} = \delta^\mu_\sigma \Rightarrow g^{\mu\nu}(e_\nu^a e_\sigma^b \eta_{ab}) = \delta^\mu_\sigma$$

$$\Rightarrow e^r_c \underbrace{g^{\mu\nu} e_\nu^a e_\sigma^b}_{\delta^b_c} \eta_{ab} = e^r_c \delta^\mu_\sigma = e^r_c$$

$$\Rightarrow g^{\mu\nu} \eta_{ac} e_\nu^a = e^r_c$$

$$\Rightarrow g^{\mu\nu} \eta_{ab} e_\nu^a = e^r_b$$

$$\Rightarrow g^{\mu\nu} \eta_{ab} e_\nu^b = e^r_a$$

LOCAL LORENTZ TRANSFORMATIONS VS. GENERAL COORD. TRANSFORMATIONS

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Given a tetrad over some region of spacetime we can form a host of other tetrads by performing LLT's

Defⁿ e_a and $e_{a'}$ are related by LLT if $g(e_a, e_b) = \eta_{ab}$

and $g(e_{a'}, e_{b'}) = \eta_{a'b'}$ where both η_{ab} and $\eta_{a'b'}$ denote Minkowski metric.

Notation: $e_{a'} = \Lambda^a_{a'} e_a$ or to be more explicit, $e_{a'}(x) = \Lambda^a_{a'}(x) e_a(x)$

The terminology Lorentz is justified,

$$\eta_{a'b'} = g(e_{a'}, e_{b'})$$

$$= g(\Lambda^a_{a'} e_a, \Lambda^b_{b'} e_b)$$

$$= \Lambda^a_{a'} \Lambda^b_{b'} g(e_a, e_b)$$

$$= \Lambda^a_{a'} \Lambda^b_{b'} \eta_{ab}$$

General Coord. Transformation (GCT's)

need not preserve form of metric,

Coroll^y mentions we can use mixture of flat and curved indices,

$$T^{-a'y'}_{b'y'} = \Lambda^a_{a'} \frac{\partial x^{a'}}{\partial x^a} \Lambda^b_{b'} \frac{\partial x^{b'}}{\partial x^b} T^{-a''b''}_{b''y''}$$

(matrix $\Lambda^a_{a'}$ can vary with x , oh it's a matrix of functions)

Notation: $e_a = \Lambda^{a'}_a e_{a'}$ where

we have $\Lambda^a_{b'} \Lambda^{b'}_b = \delta^a_b$ and

$$\text{also } \Lambda^{a'}_b \Lambda^{b'}_{a'} = \delta^{a'}_{b'}$$

Oh, now to the eqⁿs of construction which form GR but differentiation well, covariant diff. requires some care \rightarrow

SPIN CONNECTION: (for Lorentz indices)

$$\text{Def: } \nabla_\mu \Sigma^a_b = \partial_\mu \Sigma^a_b + \omega_\mu^a_c \Sigma^c_b - \omega_\mu^c_b \Sigma^a_c$$

How do the spin connection coefficients $\omega_\mu^a_b$ relate to $\Gamma_{\mu\lambda}^\nu$ coefficients? We calculate as does Carroll on p. 486 in Appendix J, for vector Σ ,

$$\nabla \Sigma = (\nabla_\mu \Sigma^\nu) dx^\mu \otimes \partial_\nu = (\partial_\mu \Sigma^\nu + \Gamma_{\mu\lambda}^\nu \Sigma^\lambda) dx^\mu \otimes \partial_\nu$$

In mixed basis,

$$\begin{aligned} \nabla \Sigma &= (\nabla_\mu \Sigma^a) dx^\mu \otimes e_a = (\partial_\mu \Sigma^a + \omega_\mu^a_b \Sigma^b) dx^\mu \otimes e_a \\ &= (\partial_\mu (e_\nu^a \Sigma^\nu) + \omega_\mu^a_b e_\nu^b \Sigma^\nu) dx^\mu \otimes (e^{\lambda}_a \partial_\lambda) \\ &= [(\partial_\mu \Sigma^\nu) e_\nu^a e^{\lambda}_a + \partial_\mu (e_\nu^a) \Sigma^\nu e^{\lambda}_a + \omega_\mu^a_b e_\nu^b e^{\lambda}_a \Sigma^\nu] dx^\mu \otimes \partial_\lambda \\ &= [\partial_\mu \Sigma^\lambda + \Sigma^\nu \partial_\mu (e_\nu^a) e^{\lambda}_a + \omega_\mu^a_b e_\nu^b e^{\lambda}_a \Sigma^\nu] dx^\mu \otimes \partial_\lambda \\ &= [\partial_\mu \Sigma^\nu + (\partial_\mu (e_\lambda^a) e^{\nu}_a + \omega_\mu^a_b e_\lambda^b e^{\nu}_a) \Sigma^\lambda] dx^\mu \otimes \partial_\nu \end{aligned}$$

Comparing with * we find $\Gamma_{\mu\lambda}^\nu = e^{\nu}_a \partial_\mu (e_\lambda^a) + \omega_\mu^a_b e_\lambda^b e^{\nu}_a$

We found $\Gamma_{\mu\lambda}^{\nu} = e^{\nu}{}_{\alpha} \partial_{\mu} (e_{\lambda}{}^{\alpha}) + \omega_{\mu}{}^{\alpha}{}_{\beta} e_{\lambda}{}^{\beta} e^{\nu}{}_{\alpha}$ (9)

$$e_{\lambda}{}^{\beta} e^{\nu}{}_{\alpha} \omega_{\mu}{}^{\alpha}{}_{\beta} = \Gamma_{\mu\lambda}^{\nu} - e^{\nu}{}_{\alpha} \partial_{\mu} (e_{\lambda}{}^{\alpha})$$

Multiply by inverse tetrads,

$$(e^{\lambda}{}_{\alpha'} e_{\nu}{}^{\beta'}) (e_{\lambda}{}^{\beta} e^{\nu}{}_{\alpha} \omega_{\mu}{}^{\alpha}{}_{\beta}) = (e^{\lambda}{}_{\alpha'} e_{\nu}{}^{\beta'}) (\underbrace{\Gamma_{\mu\lambda}^{\nu} - e^{\nu}{}_{\alpha} \partial_{\mu} (e_{\lambda}{}^{\alpha})}_{S_{\alpha}^{\beta'}})$$

$$S_{\alpha}^{\beta} S_{\alpha'}^{\beta'} \omega_{\mu}{}^{\alpha}{}_{\beta} = \omega_{\mu}{}^{\beta'}{}_{\alpha'} = e^{\lambda}{}_{\alpha'} e_{\nu}{}^{\beta'} \Gamma_{\mu\lambda}^{\nu} - e^{\lambda}{}_{\alpha'} \partial_{\mu} (e_{\lambda}{}^{\beta'})$$

$$\therefore \omega_{\mu}{}^{\alpha}{}_{\beta} = e_{\nu}{}^{\alpha} e^{\lambda}{}_{\beta} \Gamma_{\mu\lambda}^{\nu} - e^{\lambda}{}_{\beta} \partial_{\mu} (e_{\lambda}{}^{\alpha})$$

$\Gamma_{\mu\lambda}^{\nu} / \nabla_{\mu} e_{\nu}{}^{\alpha} = 0$

(Carroll mentions this is sometimes known as the tetrad postulate) *

Proof: $\nabla_{\mu} e_{\nu}{}^{\alpha} = \partial_{\mu} e_{\nu}{}^{\alpha} - \Gamma_{\mu\nu}^{\lambda} e_{\lambda}{}^{\alpha} + \omega_{\mu}{}^{\alpha}{}_{\beta'} e_{\nu}{}^{\beta'}$

Then $e^{\lambda}{}_{\beta} \partial_{\mu} (e_{\lambda}{}^{\alpha}) = -\omega_{\mu}{}^{\alpha}{}_{\beta} + e_{\nu}{}^{\alpha} e^{\lambda}{}_{\beta} \Gamma_{\mu\lambda}^{\nu}$ from *

multiply by $e^{\nu}{}_{\beta}$

summing over ν

$$\begin{aligned} e^{\nu}{}_{\beta} \nabla_{\mu} e_{\nu}{}^{\alpha} &= e^{\nu}{}_{\beta} \partial_{\mu} e_{\nu}{}^{\alpha} - \Gamma_{\mu\nu}^{\lambda} e^{\nu}{}_{\beta} e_{\lambda}{}^{\alpha} + \underbrace{e^{\nu}{}_{\beta} \omega_{\mu}{}^{\alpha}{}_{\beta'}}_{e^{\nu}{}_{\beta} \partial_{\mu} (e_{\lambda}{}^{\alpha})} \\ &= \underbrace{e^{\nu}{}_{\beta} \partial_{\mu} e_{\nu}{}^{\alpha}}_{e^{\nu}{}_{\beta} \partial_{\mu} (e_{\lambda}{}^{\alpha})} - \Gamma_{\mu\nu}^{\lambda} e^{\nu}{}_{\beta} e_{\lambda}{}^{\alpha} + \omega_{\mu}{}^{\alpha}{}_{\beta} \\ &= -\omega_{\mu}{}^{\alpha}{}_{\beta} + e_{\nu}{}^{\alpha} e^{\lambda}{}_{\beta} \Gamma_{\mu\lambda}^{\nu} - \Gamma_{\mu\nu}^{\lambda} e^{\nu}{}_{\beta} e_{\lambda}{}^{\alpha} + \omega_{\mu}{}^{\alpha}{}_{\beta} \\ &= 0 \Rightarrow \nabla_{\mu} e_{\nu}{}^{\alpha} = 0. // \end{aligned}$$

Defn/ $(\omega \wedge \Sigma)_{\mu\nu}{}^a = \omega_{\mu}{}^a \wedge \Sigma_{\nu}{}^b - \omega_{\nu}{}^a \wedge \Sigma_{\mu}{}^b$
wedge product of spin-connection with vector-valued one-form.

We should apply this formalism to torsion and curvature.

$T_{\mu\nu}{}^a$ vector-valued two form
 $R^a{}_{b\mu\nu}$ $(1,1)$ -tensor valued two form.

Notation

$$\theta^a = e^a, \quad \theta^\mu = dx^\mu$$

$$e^a = e_{\mu}{}^a dx^\mu \quad \text{and}$$

$$\omega^a{}_b = \omega_{\mu}{}^a{}_b dx^\mu$$

$$T^a = de^a + \omega^a{}_b \wedge e^b$$

$$R^a{}_b = d\omega^a{}_b + \omega^a{}_c \wedge \omega^c{}_b$$

"CARTAN'S STRUCTURE EQUATIONS"

Consider,

$$T_{\mu\nu}{}^\lambda = e^\lambda{}_a T_{\mu\nu}{}^a$$

$$= e^\lambda{}_a (\partial_\mu e_\nu{}^a - \partial_\nu e_\mu{}^a + \omega_{\mu}{}^a{}_b e_\nu{}^b - \omega_{\nu}{}^a{}_b e_\mu{}^b)$$

$$= e^\lambda{}_a \partial_\mu e_\nu{}^a + e^\lambda{}_a e_\nu{}^b \omega_{\mu}{}^a{}_b - (e^\lambda{}_a \partial_\nu e_\mu{}^a + e^\lambda{}_a e_\mu{}^b \omega_{\nu}{}^a{}_b)$$

$$= \Gamma_{\mu\nu}{}^\lambda - \Gamma_{\nu\mu}{}^\lambda \quad (\text{see top of pg. 9, we derived on 8})$$

$$\mathcal{R}^m{}_n / dT^a + \omega^a{}_b \wedge T^b = R^a{}_b \wedge e^b = 0$$

Bianchi Identities.

Proof: differentiate CARTAN'S STRUCTURE EQUATIONS and use $d^2 = 0$.

Deriving Bianchi Identities with exterior calculus

Given: $T^a = de^a + \omega^a_b \wedge e^b$ & $R^a_b = d\omega^a_b + \omega^a_c \wedge \omega^c_b$ *

Differentiate, remember $d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^{|\alpha|} \alpha \wedge d\beta$

$dT^a = d(de^a) + d\omega^a_b \wedge e^b - \omega^a_b \wedge de^b$ Graded Leibniz Rule swap indices for de

$d\omega^a_b = R^a_b - \omega^a_c \wedge \omega^c_b$ solving * for $d\omega^a_b$

$dT^a = (R^a_b - \omega^a_c \wedge \omega^c_b) \wedge e^b - \omega^a_b \wedge (T^b - \omega^b_c \wedge e^c)$

$dT^a = R^a_b \wedge e^b - \omega^a_c \wedge \omega^c_b \wedge e^b - \omega^a_b \wedge T^b + \omega^a_b \wedge \omega^b_c \wedge e^c$

$dT^a + \omega^a_b \wedge T^b = R^a_b \wedge e^b$

Differentiate *

$dR^a_b = d(d\omega^a_b) + (d\omega^a_c) \wedge \omega^c_b - \omega^a_c \wedge (d\omega^c_b)$

$dR^a_b = (R^a_c - \omega^a_{a'} \wedge \omega^{a'c}) \wedge \omega^c_b - \omega^a_c \wedge (R^c_b - \omega^c_{a'} \wedge \omega^{a'b})$

$dR^a_b = R^a_c \wedge \omega^c_b - \omega^a_c \wedge R^c_b$

$dR^a_b + \omega^a_c \wedge R^c_b - R^a_c \wedge \omega^c_b = 0$

I'll follow Carroll and resist urge to further look at covariant der. of metric. (13)
 Notice we have yet to impose torsion-free requirement or metric compatibility of the connection.

$$T = 0 \rightarrow T^a = de^a + \omega^a_b \wedge e^b = 0$$

$$\therefore \boxed{de^a = -\omega^a_b \wedge e^b}$$

torsion free condition

$$\nabla g = 0 \rightarrow \nabla_\mu \eta_{ab} = \cancel{\partial_\mu \eta_{ab}} - \omega^c_\mu \eta_{cb} - \omega^c_\mu \eta_{ac} = 0$$

$$\Rightarrow \omega^c_\mu \eta_{cb} = -\omega^c_\mu \eta_{ac}$$

$$\Rightarrow \boxed{\omega^c_{\mu b} = -\omega^c_{\mu a}}$$

EXAMPLE: SPATIALLY FLAT, EXPANDING UNIVERSE

$$ds^2 = -dt^2 + a^2(x) \delta_{ij} dx^i dx^j = \eta_{ab} e^a \otimes e^b$$

$$e^0 = dt \quad de^0 = d(dt) = 0 = -\omega^0_b \wedge e^b$$

$$e^i = a dx^i \quad de^i = da \wedge dx^i = -\omega^i_b \wedge e^b$$

Now, $da = (\partial_\mu a) dx^\mu = \dot{a} dt$ since $\partial_i a = 0$ as a is funct. of t alone.

$$0 = -\omega^0_b \wedge e^b \quad \& \quad \dot{a} dt \wedge dx^i = -\omega^i_b \wedge e^b$$

$$= -\omega^i_j \wedge dt - \omega^i_a \wedge dx^a$$

$$e^0 = dt$$

$$e^i = a dx^i$$

$$a = a(x)$$

Metric compat. condition

$$\omega_{\mu\nu\alpha} = -\omega_{\mu\alpha\nu}$$

$$\omega_{00} = 0$$

$$\omega_{ij} = -\omega_{ji}$$

$$\omega_{0j} = -\omega_{j0}$$

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Raising index; $\omega^a{}_b = \eta^{ac} \omega_{cb}$

$$\omega^0{}_0 = \eta^{0c} \omega_{c0} = -\omega_{00} = 0 \quad \therefore \boxed{\omega^0{}_0 = 0}$$

$$\omega^0{}_j = \eta^{0c} \omega_{cj} = -\omega_{0j} \quad \boxed{\omega^0{}_j = \omega^i{}_j}$$

$$\omega^i{}_0 = \eta^{ic} \omega_{c0} = \omega_{j0} = -\omega_{0j}$$

$$\omega^i{}_j = \eta^{ic} \omega_{cj} = \omega_{ij}$$

$$\omega^j{}_i = \eta^{jc} \omega_{ci} = \omega_{ji} = -\omega_{ij}$$

$$\boxed{\omega^i{}_j = -\omega^j{}_i}$$

$$\underline{de^a = -\omega^a{}_b \wedge e^b}$$

$$de^0 = d(dt) = 0 = -\omega^0{}_b \wedge e^b \Rightarrow 0 = -\omega^0{}_j \wedge (a dx^j) \quad \textcircled{1}$$

$$de^i = da \wedge dx^i = -\omega^i{}_b \wedge e^b \Rightarrow \dot{a} dt \wedge dx^i = -\omega^i{}_0 \wedge dt - \omega^i{}_j \wedge (a dx^j) \quad \textcircled{2}$$

From ① $\omega^0{}_j = A_j dt + A_i dx^i \Rightarrow (A_j dt + A_i dx^i) \wedge (a dx^j) = A_j dt \wedge dx^i + A_i dx^i \wedge dx^j = 0$

Consequently only A_j nontrivial, $\omega^0{}_j = A_j dx^i$ plug into ②

$$\dot{a} dt \wedge dx^i = -A_j dx^i \wedge dt - \omega^i{}_j \wedge (a dx^j)$$

$$= A_j dt \wedge dx^i - a \omega^i{}_j \wedge dx^j \Rightarrow \underline{A_i = \dot{a} \text{ and } \omega^i{}_j = 0}$$

possible solution.

We found, $\omega^0_0 = 0$, $\omega^0_j = \dot{a} dx^j = \omega^j_0$, $\omega^i_j = 0$ (15)

Spin connection for $ds^2 = -dt^2 + a^2(t) \delta_{ij} dx^i dx^j$

We wish to calculate,

$$R^a_b = d\omega^a_b + \omega^a_c \wedge \omega^c_b$$

Hence calculate:

$$\begin{aligned} d\omega^0_0 &= 0 & \omega^0_c \wedge \omega^c_0 &= 0 \\ d\omega^0_j &= d\dot{a} \wedge dx^j = \ddot{a} dt \wedge dx^j = d\omega^j_0 & \omega^i_c \wedge \omega^c_0 &= 0 \\ d\omega^i_j &= 0 & \omega^i_c \wedge \omega^c_j &= \dot{a}^2 dx^i \wedge dx^j \end{aligned}$$

Therefore,

$$\begin{aligned} R^0_0 &= 0 \\ R^0_j &= \ddot{a} dt \wedge dx^j \\ R^i_0 &= \ddot{a} dt \wedge dx^i \\ R^i_j &= \dot{a}^2 dx^i \wedge dx^j \end{aligned}$$

To compare with earlier work need to convert to curved index quantities,

$$R^{\rho}_{\sigma\mu\nu} = e^{\rho}_a e_{\sigma}^b R^a_{b\mu\nu}$$

$$e^\mu(e_b) = dx^\mu(e_b) = e^\mu_b \quad \neq e^a(\partial_\nu) = e_\nu^a$$

Alternatively, $dx^\mu = e^\mu_a e^a$ and $e^a = e_\mu^a dx^\mu$

$$dx^\mu = e^\mu_0 dt + e^\mu_i (a dx^i) \quad \text{and} \quad e^a = e_0^a dt + e_i^a dx^i$$

$$(e^\mu_a) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1/a & 0 & 0 \\ 0 & 0 & 1/a & 0 \\ 0 & 0 & 0 & 1/a \end{bmatrix}$$

$$(e_\mu^a) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & a & 0 & 0 \\ 0 & 0 & a & 0 \\ 0 & 0 & 0 & a \end{bmatrix}$$

$$\underline{R}^\rho{}_{\sigma\mu\nu} = e^\rho_a e_\sigma^b R^a{}_{b\mu\nu}$$

Remark: the μ vs a notation breaks down here, so I added the = to distinguish.

$$R^0{}_0 = 0$$

$$R^0{}_{0\rho\nu} = 0$$

$$R^0{}_i = \ddot{a} dt \wedge dx^i$$

$$R^0{}_{i\rho\nu} = \ddot{a} (\delta_\rho^0 \delta_\nu^i - \delta_\nu^0 \delta_\rho^i)$$

$$R^i{}_0 = \ddot{a} dt \wedge dx^i$$

$$R^i{}_{0\rho\nu} = \ddot{a} (\delta_\rho^0 \delta_\nu^i - \delta_\nu^0 \delta_\rho^i)$$

$$R^i{}_j = \ddot{a}^2 dx^i \wedge dx^j$$

$$R^i{}_{j\rho\nu} = \ddot{a}^2 (\delta_\rho^i \delta_\nu^j - \delta_\nu^i \delta_\rho^j)$$

$$\therefore R^0{}_{j0l} = \ddot{a} (\delta_0^0 \delta_l^j - \delta_l^0 \delta_0^j) = \ddot{a} \delta_l^j$$

$$\underline{R}^0{}_{j0l} = e^0_a e_j^b R^a{}_{b0l} = a R^0{}_{j0l} = a \ddot{a} \delta_l^j$$

Continuing in the calculations from (16) we can show,

(17)

$$\begin{aligned}
 \underline{R^i{}_{oko}} &= e^i{}_a e_o{}_b R^a{}_{bko} \\
 &= \left(\frac{1}{a} \delta_a^i\right) (1 \delta_o^b) R^a{}_{bko} \\
 &= \frac{1}{a} R^i{}_{oko} \\
 &= \frac{1}{a} \ddot{a} (\delta_k^o \delta_o^i - \delta_o^o \delta_k^i) \\
 &= -\frac{1}{a} \ddot{a} \delta_k^i
 \end{aligned}$$

$$\begin{aligned}
 \underline{R^i{}_{jkr}} &= e^i{}_a e_j{}_b R^a{}_{bkr} \\
 &= \left(\frac{1}{a} \delta_a^i\right) (a \delta_j^b) R^a{}_{bkr} \\
 &= R^i{}_{jkr} \\
 &= a^2 (\delta_k^i \delta_r^j - \delta_r^i \delta_k^j)
 \end{aligned}$$

Remark: See Pg. 333 in Carroll and set $\mathbb{R} = 0$

Defⁿ as before, $R_{\alpha\beta\gamma\delta} = R^\lambda{}_{\alpha\lambda\gamma}$ define the Ricci Tensor. Hence ∇

$$\begin{aligned}
 R_{oo} &= R^\lambda{}_{\alpha\lambda o} = -\frac{\ddot{a}}{a} \delta_i^i = -\frac{3\ddot{a}}{a} \quad \& \quad R_{io} = R^\lambda{}_{i\lambda o} = 0 \\
 R_{ij} &= R^\lambda{}_{i\lambda j} = R^o{}_{ioj} + R^k{}_{ikj} = a \ddot{a} \delta_{ij} + a^2 (3 \delta_{ij} - \delta_{ij})
 \end{aligned}$$