

(#3.) Check properties 2.12 of the Lie Product

The "Lie product" $LG \times LG \rightarrow LG$ where $(X, Y) \mapsto [X, Y]$ is bilinear and hence makes LG a $\mathbb{R}$ -algebra also

(i.) $[X, X] = 0$ hence $[X, Y] = -[Y, X]$ (Skew)

(ii.) $[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0$ (Jacobi)

$LG \equiv L(VF)$ on G & the bracket is the usual vector field bracket $[X, Y]f = X(Y(f)) - Y(X(f))$

Proof: Bilinearity: $[\alpha X + \beta Y, Z] = \alpha [X, Z] + \beta [Y, Z]$

Let $f \in C^\infty(G)$ then for $X, Y, Z \in LG$ we find

$$\begin{aligned} [\alpha X + \beta Y, Z]f &= (\alpha X + \beta Y)(Z(f)) - Z((\alpha X + \beta Y)(f)) \\ &= \alpha X(Z(f)) + \beta Y(Z(f)) - Z(\alpha X(f) + \beta Y(f)) \\ &= \alpha (X(Z(f)) - Z(X(f))) + \beta (Y(Z(f)) - Z(Y(f))) \\ &= \alpha [X, Z]f + \beta [Y, Z]f \\ &= (\alpha [X, Z] + \beta [Y, Z])f \quad \forall f \in C^\infty(G) \end{aligned}$$

$$\therefore [\alpha X + \beta Y, Z] = \alpha [X, Z] + \beta [Y, Z] \quad \forall \alpha, \beta \in \mathbb{R}$$

$$\text{Likewise } [X, \alpha Y + \beta Z] = \alpha [X, Y] + \beta [X, Z] \quad \forall \alpha, \beta \in \mathbb{R} \text{ \& } X, Y, Z \in LG.$$

Skew: $[X, X]f = X(X(f)) - X(X(f)) = 0(f)$

$$\therefore [X, X] = 0 \quad \forall X \in LG. \text{ Then } X, Y \in LG$$

$\Rightarrow X - Y \in LG$ as we proved in lecture thus

$$[X - Y, X - Y] = 0$$

$$\Rightarrow [X, X - Y] + [-Y, X - Y] = 0$$

$$\Rightarrow [X, X] - [X, Y] - [Y, X] + [Y, Y] = 0$$

$$\Rightarrow [X, Y] = -[Y, X] \quad \forall X, Y \in LG.$$

Jacobi: $([X, Y], Z] + [[Y, Z], X] + [[Z, X], Y])f \stackrel{?}{=} 0$

$$[X, Y]Z(f) - Z([X, Y]f) + [Y, Z]X(f) - X([Y, Z]f) + [Z, X]Y(f) - Y([Z, X]f) = 0$$

$$\begin{aligned} &X(Y(Z(f))) - Y(X(Z(f))) - Z(X(Y(f))) + Y(Z(X(f))) \\ &- X(Y(Z(f))) - Z(Y(X(f))) - Y(X(Z(f))) - Z(X(Y(f))) \\ &+ Y(Z(X(f))) - X(Y(Z(f))) - Y(X(Z(f))) - Z(X(Y(f))) \\ &- Y(Z(X(f))) - X(Y(Z(f))) - Y(X(Z(f))) - Z(X(Y(f))) \end{aligned}$$

Jacobi Holds.

(#5) Check that the Lie algebras of $SO(n)$, $U(n)$, $SL(n, \mathbb{R})$, $SL(n, \mathbb{C})$, and $Sp(n)$ are closed under the Lie product of matrices

$$L(SO(n)) = so(n) = \{a \in gl(n, \mathbb{R}) \mid a^T = -a\}. \text{ Let } a, b \in so(n)$$

$$[a, b]^T = (ab)^T - (ba)^T = b^T a^T - a^T b^T$$

$$= -b(-a) - (-a)(-b)$$

$$= -(ab - ba)$$

$$= -[a, b] \therefore [a, b] \in so(n).$$

Let $C \in SO(n)$ then $C^T C = I$ thus $C^T = C^{-1}$ then

let $a \in so(n)$ and consider,

$$(C a C^{-1})^T = (C^{-1})^T a^T C^T$$

$$= C^{TT} (-a) C^{-1}$$

$$= -C a C^{-1} \therefore C a C^{-1} \in so(n)$$

$$G_J = \{A \mid A^T J A = J\} \quad (\text{or } T \text{ for } \mathbb{R})$$

$$\mathfrak{g}_J = \{a \mid a^T J + J a = 0\} \quad (\text{or } T \text{ for } \mathbb{R})$$

$$[a, b]^T J + J [a, b] = ((ab)^T - (ba)^T) J + J (ab - ba)$$

$$= (b^T a^T J - a^T b^T J + J ab - J ba)$$

$$= (b^T (-J a) - a^T (-J b) + J ab - J ba)$$

$$= \cancel{J ba} - \cancel{J ab} + \cancel{J ab} - \cancel{J ba}$$

$$= 0 \therefore [a, b] \in \mathfrak{g}_J$$

derivation works for T or $\dagger$.

Let $C \in G_J$ so $C^T J C = J \Rightarrow C^T J = J C^{-1}$. Let $a \in \mathfrak{g}_J$ and consider that $J C = (C^T)^{-1} J$ as well so,

$$(C a C^{-1})^T J + J (C a C^{-1}) = (C^{-1})^T a^T C^T J + J C a C^{-1}$$

$$= (C^{-1})^T a^T J C^{-1} + J C a C^{-1}$$

$$= - (C^{-1})^T J a C^{-1} + J C a C^{-1}$$

$$= - \cancel{J C a C^{-1}} + \cancel{J C a C^{-1}}$$

$$= 0 \therefore C a C^{-1} \in \mathfrak{g}_J$$

This covers all the cases listed just choose appropriate J and either T or $\dagger$, Except the special linear cases 2

OK
but this
sp is
based on
H and is
a little
different

Check that $\mathfrak{sl}(n, \mathbb{R})$ & $\mathfrak{sl}(n, \mathbb{C})$ are closed under the commutator bracket & conjugation via their corresponding Lie groups $SL(n, \mathbb{R})$ & $SL(n, \mathbb{C})$. In the arguments below $\mathbb{K} = \mathbb{R}$ or $\mathbb{C}$.

$$\mathfrak{sl}(n, \mathbb{K}) = \{a \in \mathfrak{gl}(n, \mathbb{K}) \mid \text{tr}(a) = 0\}$$

Let $a, b \in \mathfrak{sl}(n, \mathbb{K})$ then

$$\text{tr}[a, b] = \text{tr}(ab - ba)$$

$$= \text{tr}(ab) - \text{tr}(ba)$$

$$= \text{tr}(ab) - \text{tr}(ab)$$

$$= 0 \quad \therefore \mathfrak{sl}(n, \mathbb{K}) \text{ is closed under } [,].$$

Next recall $SL(n, \mathbb{K}) = \{A \in \mathfrak{gl}(n, \mathbb{K}) \mid \det(A) = 1\}$

Let $C \in SL(n, \mathbb{K})$ then $\det(C) = 1 \therefore C^{-1}$ exists &

let $a \in \mathfrak{sl}(n, \mathbb{K})$ then

$$\text{trace}(C a C^{-1}) = \text{tr}(C^{-1} C a)$$

$$= \text{tr}(a)$$

$$= 0 \quad \therefore C a C^{-1} \in \mathfrak{sl}(n, \mathbb{K}).$$

Remark: $\mathfrak{so}(n)$ is invariant under conjugation by $O(n)$ as well, we never used $\det(C) = 1$ in that earlier argument.

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We define $\mathfrak{so}(3) = \{A \in \mathfrak{gl}(n, \mathbb{R}) \mid A^T = -A\}$. We can write an arbitrary $A \in \mathfrak{so}(3)$ via $A_1, A_2, A_3 \in \mathbb{R}$,

$$A = \begin{bmatrix} 0 & -A_3 & A_2 \\ A_3 & 0 & -A_1 \\ -A_2 & A_1 & 0 \end{bmatrix} = A_i \epsilon_{ijk} E_{kj}$$

where $i, j, k = 1, 2, 3$ and we mean to use repeated index convention so $\sum$'s are implied, also $\epsilon_{123} = 1$ and ϵ_{ijk} is completely antisymmetric. Let $A, B \in \mathfrak{so}(3)$,

$$\begin{aligned} [A, B] &= [A_i \epsilon_{ijk} E_{kj}, B_l \epsilon_{lmn} E_{nm}] \\ &= A_i B_l \epsilon_{ijk} \epsilon_{lmn} [E_{kj}, E_{nm}] \quad \leftarrow \text{This bracket is defined on } \mathfrak{gl}(3) \text{ since } E_{ij} \in \mathfrak{so}(3), \text{ so } \mathfrak{so}(3) \text{ bracket is same as } \mathfrak{gl}(3) \text{ bracket.} \\ &= A_i B_l \epsilon_{ijk} \epsilon_{lmn} (\delta_{jn} E_{km} - \delta_{mk} E_{nj}) \\ &= A_i B_l \epsilon_{ijk} \epsilon_{lmj} E_{km} - A_i B_l \epsilon_{ijk} \epsilon_{lkn} E_{nj} \\ &= A_i B_l (-\epsilon_{ikj} \epsilon_{lmj}) E_{km} - A_i B_l (-\epsilon_{ijk} \epsilon_{lnk}) E_{nj} \\ &= A_i B_l (-\delta_{il} \delta_{km} + \delta_{kl} \delta_{im}) E_{km} - A_i B_l (-\delta_{il} \delta_{jn} + \delta_{jl} \delta_{in}) E_{nj} \\ &= -A_i B_i E_{kk} + A_m B_k E_{km} + A_l B_l E_{nn} - A_n B_j E_{nj} \\ &= (A_i B_j - A_j B_i) E_{ji} = A_i B_j (E_{ji} - E_{ij}) \end{aligned}$$

Lemma(I): $[A, B] = A_i B_j (E_{ji} - E_{ij})$. Proof above $\rangle$

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We define $\varphi: \mathfrak{so}(3) \rightarrow \mathbb{R}^3$ on $A = A_i \epsilon_{ijk} E_{kj} \in \mathfrak{so}(3)$ by

$$\varphi(A) \equiv A_i e_i$$

We show φ is linear. Let $A, B \in \mathfrak{so}(3)$ and let $c \in \mathbb{R}$ as usual $A = A_i \epsilon_{ijk} E_{kj}$ and $B = B_l \epsilon_{lmn} E_{nm}$. Note,

$$\begin{aligned}\varphi(A + cB) &= \varphi(A_i \epsilon_{ijk} E_{kj} + c B_l \epsilon_{lmn} E_{nm}) \\ &= \varphi((A_i + cB_i) \epsilon_{ijk} E_{kj}) \\ &= (A_i + cB_i) e_i \\ &= A_i e_i + c(B_i e_i) \\ &= \varphi(A_i \epsilon_{ijk} E_{kj}) + c \varphi(B_i \epsilon_{ijk} E_{kj}) \\ &= \varphi(A) + c \varphi(B).\end{aligned}$$

We observe that $\{\epsilon_{ijk} E_{kj}\}_{i=1}^3 = \{E_{32} - E_{23}, E_{13} - E_{31}, E_{21} - E_{12}\}$ is a basis for $\mathfrak{so}(3)$ as they are clearly LI and span as we have pointed out before $A \in \mathfrak{so}(3) \Rightarrow A = A_i \epsilon_{ijk} E_{kj}$. Notice that for $m=1,2,3$ we have

$$\begin{aligned}\varphi(\epsilon_{mjk} E_{kj}) &= \varphi(\delta_{mi} \epsilon_{ijk} E_{kj}) \\ &= \delta_{mi} e_i \quad (\text{Here } A_i = \delta_{mi}) \\ &= e_m.\end{aligned}$$

Thus φ maps the basis of $\mathfrak{so}(3)$ to the basis of $\mathbb{R}^3$. $\therefore$ φ is a linear isomorphism.

$$\text{Lemma II: } \varphi(E_{nm} - E_{mn}) = \epsilon_{mni} e_i$$

Proof: By definition $\varphi(\epsilon_{ijk} E_{kj}) = e_i$. Now multiply (and sum) by ϵ_{mni} and recall φ is linear,

$$\begin{aligned} \epsilon_{mni} \varphi(\epsilon_{ijk} E_{kj}) &= \varphi(\epsilon_{mni} \epsilon_{ijk} E_{kj}) \\ &= \varphi((\delta_{mj} \delta_{nk} - \delta_{nj} \delta_{mk}) E_{kj}) \\ &= \varphi(E_{nm} - E_{mn}) = \epsilon_{mni} e_i. \end{aligned}$$

$$\text{Claim: } \varphi([A, B]) = \varphi(A) \times \varphi(B). \text{ for } A, B \in \mathcal{A}\mathcal{O}(3).$$

Proof: Begin by noting $\varphi(A) = A_i e_i$ and $\varphi(B) = B_j e_j$. So that $\varphi(A) \times \varphi(B) = A_i B_j \epsilon_{ijk} e_k$. Consider,

$$\begin{aligned} \varphi([A, B]) &= \varphi(A_m B_n [E_{nm} - E_{mn}]) : \text{by Lemma I.} \\ &= A_i B_j \varphi(E_{nm} - E_{mn}) : \text{linearity of } \varphi. \\ &= A_i B_j \epsilon_{mni} e_i : \text{by Lemma II.} \\ &= \varphi(A) \times \varphi(B). \end{aligned}$$

OK
notation
error

pg. 22 # 8 continued (Working towards $\varphi(A \times A^{-1}) = A \varphi(x) \quad \forall x \in \mathfrak{so}(3) \text{ \& } A \in \text{SO}(3)$).

We begin by noting that one can calculate the determinant via $e^1 A e^2 A e^3 A = \det(A) e^1 e^2 e^3$ where I'm using e^i as the i^{th} standard row-vector. Notice that $A = A_{mn} E_{mn}$ thus $e^i A_{mn} E_{mn} = A_{mn} e^i E_{mn}$ and since $e^i E_{mn} = \delta_m^i e^n \Rightarrow e^i A = A_{jn} e^n$ hence

$$\begin{aligned} e^1 A e^2 A e^3 A &= A_{1i} e^i \wedge A_{2j} e^j \wedge A_{3k} e^k \\ &= A_{1i} A_{2j} A_{3k} e^i e^j e^k \\ &= A_{1i} A_{2j} A_{3k} \epsilon_{ijk} e^1 e^2 e^3 \\ &= \det(A) e^1 e^2 e^3 \end{aligned}$$

So for the disinterested reader we could just begin with,

$$\boxed{\det(A) = A_{1i} A_{2j} A_{3k} \epsilon_{ijk}}$$

This suggest we should rearrange the problem so there are three A 's on the same side. In the following we use the fact φ is an isomorphism repeatedly, also for all $x \in \mathfrak{so}(3)$ and $A \in \text{SO}(3)$ we proved previously $A \times A^{-1} \in \mathfrak{so}(3)$ so we may take φ of it,

$$\begin{aligned} \varphi(A \times A^{-1}) &= A \varphi(x) \iff A \times A^{-1} = \varphi^{-1}(A \varphi(x)) \\ &\iff x = A^{-1} \varphi^{-1}(A \varphi(x)) A \end{aligned}$$

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We collect a few results,

$$[A\phi(x)]_i = A_{ij} \phi(x)_j, \quad \phi(x)_j = x_j \\ \therefore [A\phi(x)]_i = A_{ij} x_j$$

$$A\phi(x) = (A_{mn} x_n) e_m$$

$$\phi^{-1}(A\phi(x)) = A_{mn} x_n \phi^{-1}(e_m) = A_{mn} x_n \epsilon_{mjk} E_{kj}$$

$$\begin{aligned} (A^{-1} \phi^{-1}(A\phi(x)))_{ab} &= (A^{-1})_{ap} (\phi^{-1}(A\phi(x)))_{pb} \\ &= A_{pa} A_{mn} x_n \epsilon_{mbp}, \quad \text{since } A^{-1} = A^T. \end{aligned}$$

$$\begin{aligned} (A^{-1} \phi^{-1}(A\phi(x)) A)_{az} &= (A^{-1} \phi^{-1}(A\phi(x)))_{ab} A_{bz} \\ &= A_{pa} A_{mn} x_n \epsilon_{mbp} A_{bz} \end{aligned}$$

Thus we have reduced the question of $\phi(A\phi^{-1}(x)) \stackrel{?}{=} A\phi(x)$ to the following component form of $x \stackrel{?}{=} A^{-1} \phi^{-1}(A\phi(x)) A$ where we consider the $(az)^{\text{th}}$ component of that matrix eqⁿ, notice $(x)_{az} = (x_\mu \epsilon_{\mu\alpha\beta} E_{\beta\alpha})_{az} = x_\mu \epsilon_{\mu za}$ hence, $\phi(x) = (x_\mu)$

$$\epsilon_{mbp} A_{mn} A_{bz} A_{pa} x_n \stackrel{?}{=} x_\mu \epsilon_{\mu za}$$

We claim this is true due to the fact $A \in SO(3)$
 $\Rightarrow \det(A) = 1 \quad \therefore \phi(A\phi^{-1}(x)) = A\phi(x) \quad \forall x \in SO(3)$
 $\& A \in SO(3).$

We prove this claim on next page.

Claim: $\epsilon_{mbp} A_{mn} A_{bz} A_{pa} X_n = X_p \epsilon_{pza}$ where A_{mn} are the components of $A \in SO(3)$.

Proof: Notice $\{z, a\}$ are the free indices, we must prove the eqⁿ holds for all choices of $\{z, a\} \subset \{1, 2, 3\}$

CASE I: Suppose $z = a$, no sum over repeated z below,

RHS : $X_p \epsilon_{pzz} = 0.$

LHS : $\epsilon_{mbp} A_{mn} A_{bz} A_{pz} = -\epsilon_{mpb} A_{mn} A_{bz} A_{pz} : \epsilon_{mbp} = -\epsilon_{mpb}$
 $= -\epsilon_{mpb} A_{mn} A_{pz} A_{bz}$
 $= -\epsilon_{mbp} A_{mn} A_{bz} A_{pz} : \text{switched } (p \leftrightarrow b)$
 $= 0.$

CASE II: Suppose $z \neq a$,

(fixed but arbitrary)

RHS : $X_p \epsilon_{pza} = \epsilon_{vza} X_v$, no sum over v and $\{v, z, a\} = \{1, 2, 3\}$

LHS : $\epsilon_{mbp} A_{mn} A_{bz} A_{pa} X_n = \epsilon_{mbp} A_{mv} A_{bz} A_{pa} X_v$

must be v which is the remaining index value not taken by z or a . Other terms will be zero

because either z or a will be repeated in the n -slot, this will make $A_{mn} A_{bz} A_{pa}$ symmetric

in either mb or mp yet this is summed against antisymmetric in $mp \neq mb \Rightarrow \epsilon_{mbp} \Rightarrow \text{zero}.$

only nontrivial term. again we have chosen v so that

$\{v, z, a\} = \{1, 2, 3\}$

(no ordering intended.)

Coefficient of x_z is $\epsilon_{mbp} A_{mz} A_{bz} A_{pa}$
 $= \text{zero}$

Coefficient of x_a is also zero

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CASE II: Continued. Recall $\{v, z, a\} = \{1, 2, 3\}$ they are three distinct indices. Again no sum over v intended,

$$\epsilon_{vza} X_v \stackrel{(?)}{=} \epsilon_{mbp} A_{mv} A_{bz} A_{pa} X_v$$

$$X_1 = \epsilon_{123} X_1 = \epsilon_{mbp} A_{m1} A_{b2} A_{p3} X_1 = \det(A) X_1 = X_1.$$

$$\begin{aligned} X_2 = \epsilon_{231} X_2 &= \epsilon_{mbp} A_{m2} A_{b3} A_{p1} X_2 \\ &= \epsilon_{pmb} A_{p1} A_{m2} A_{b3} X_2 \\ &= \det(A) X_2 = X_2. \end{aligned}$$

$$\begin{aligned} X_3 = \epsilon_{312} X_3 &= \epsilon_{mbp} A_{m3} A_{b1} A_{p2} X_3 \\ &= \epsilon_{bpm} A_{b1} A_{p2} A_{m3} X_3 \\ &= \det(A) X_3 = X_3. \end{aligned}$$

$$\begin{aligned} -X_3 = \epsilon_{321} X_3 &= \epsilon_{mbp} A_{m3} A_{b2} A_{p1} X_3 \\ &= -\epsilon_{pbm} A_{p1} A_{b2} A_{m3} X_3 \\ &= -\det(A) X_3 = -X_3. \end{aligned}$$

$$\begin{aligned} -X_2 = \epsilon_{213} X_2 &= \epsilon_{mbp} A_{m2} A_{b1} A_{p3} X_2 \\ &= -\epsilon_{bmp} A_{b1} A_{m2} A_{p3} X_2 \\ &= -\det(A) X_2 = -X_2. \end{aligned}$$

$$\begin{aligned} -X_1 = \epsilon_{132} X_1 &= \epsilon_{mbp} A_{m1} A_{b3} A_{p2} X_1 \\ &= -\epsilon_{mpb} A_{m1} A_{p2} A_{b3} X_1 \\ &= -\det(A) X_1 = -X_1. \end{aligned}$$

$$\therefore \epsilon_{vza} X_v = \epsilon_{mbp} A_{mv} A_{bz} A_{pa} X_v$$

for all
distinct
 $\{v, z, a\}$.

Hence the Claim is verified. //