

HOMEWORK 4: SPANNING, LINEAR INDEPENDENCE, BASES, CCP etc...

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FROM SPENCE, WISEL & FRIEDBERG // Elementary Linear Algebra 2nd Ed.

§1.6 # 4, 26, 30, 44, 69 // §1.7 # 24, 36 // §2.3 # 68, 82 // §4.4 # 14, 28 //

§7.1 # 31 // §7.3 # 4

§1.6 # 4 Is $[2, -1, 3]^T \in \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix} \right\}$?

In other words, do $\exists x, y, z \in \mathbb{R}$ such that

$$x \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + z \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix}$$

We know how to solve such problems (if it's consistent !)

$$\text{rref} \left[\begin{array}{ccc|c} 1 & -1 & 1 & 2 \\ 0 & 1 & 1 & -1 \\ 1 & 1 & 3 & 3 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] \leftarrow \text{inconsistent system notice the 3rd row.}$$

$\therefore [2, -1, 3]^T$ is not in the span.

§1.6 # 26 Is $\left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 1 \end{bmatrix} \right\}$ a generating set for $\mathbb{R}^{3 \times 1}$?

Observe $\text{rref} \begin{bmatrix} -1 & -1 & 1 \\ 2 & 1 & -3 \\ 1 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$, thus $A = \begin{bmatrix} -1 & 1 & 1 \\ 2 & 1 & -3 \\ 1 & 3 & 1 \end{bmatrix}$

is not invertible $\Rightarrow \exists \vec{b} \in \mathbb{R}^{3 \times 1}$ such that $A\vec{x} = \vec{b}$ has no solⁿ.

Let me add a bit more to this solⁿ. Let's find out which vectors in $\mathbb{R}^{3 \times 1}$ are generally not in the span. In other words find \vec{b} such that $A\vec{x} = \vec{b}$ is inconsistent, $\vec{b} = [a, b, c]^T$

$$A\vec{x} = \vec{b} \Leftrightarrow \left[\begin{array}{ccc|c} -1 & -1 & 1 & a \\ 2 & 1 & -3 & b \\ 1 & 3 & 1 & c \end{array} \right] \xrightarrow[r_3+r_1]{r_2+2r_1} \left[\begin{array}{ccc|c} -1 & -1 & 1 & a \\ 0 & -1 & -1 & b+2a \\ 0 & 2 & 2 & c+a \end{array} \right] \xrightarrow{r_3+2r_2} \left[\begin{array}{ccc|c} -1 & -1 & 1 & a \\ 0 & -1 & -1 & b+2a \\ 0 & 0 & 0 & c+a+2(b+2a) \end{array} \right]$$

Now we could continue row-reductions until we found $\text{rref}(A)$ but there's no need. We can see that if $c+a+2(b+2a) \neq 0$ then the system $A\vec{x} = \vec{b}$ will be inconsistent. Consider,

$$c+a+2(b+2a) = 5a+2b+c = 1 \leftarrow \text{a choice, just for discussion's sake. choose } a=b=0.$$

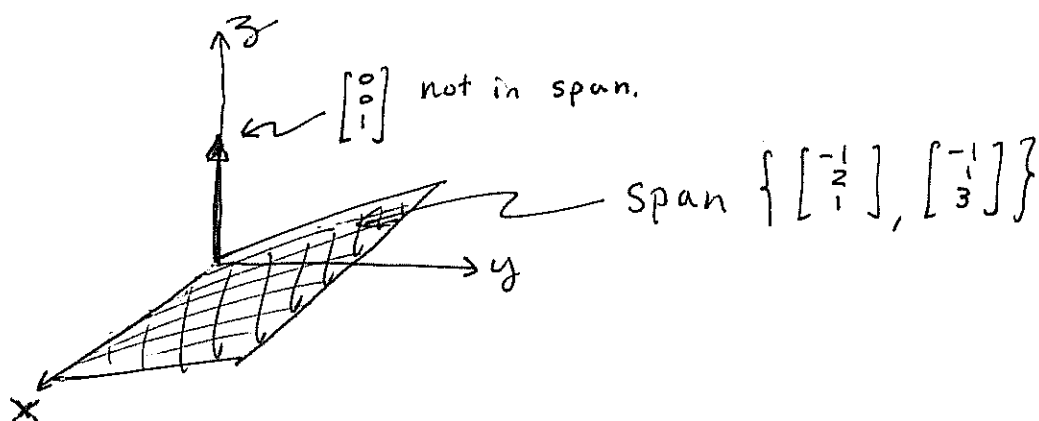
$$\Rightarrow \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \notin \text{span} \left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 1 \end{bmatrix} \right\}$$

continued \rightarrow

Extra comment continued

(2)

I just gave evidence that $\begin{bmatrix} 0 \\ 1 \end{bmatrix} \notin \text{span} \left\{ \begin{bmatrix} -1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 3 \end{bmatrix} \right\}$.



As you can see from this heuristic picture there are many vectors which are not in the plane spanned by the given generating set.

§1.6 #30 Is $A\vec{x} = \vec{b}$ consistent for all $b \in \mathbb{R}^{2 \times 1}$ given $A = \begin{bmatrix} 1 & -2 \\ 2 & -4 \end{bmatrix}$?

Many sol^{ns} are possible. Here's one, note

$$\det(A) = \det \begin{bmatrix} 1 & -2 \\ 2 & -4 \end{bmatrix} = -4 + 4 = 0 \quad \therefore A^{-1} \text{ does not exist} \\ \Rightarrow \exists \vec{b} \text{ such that } A\vec{x} = \vec{b} \text{ is inconsistent.}$$

Therefore, to answer the given question, no.

↙ (I again illustrate how to find vectors not in the span) ↘

This was not asked for, but I'll again show how to find the b which is not mapped to by Ax ,

$$[A|\vec{b}] = \left[\begin{array}{cc|c} 1 & -2 & a \\ 2 & -4 & b \end{array} \right] \xrightarrow{r_2 - 2r_1} \left[\begin{array}{cc|c} 1 & -2 & a \\ 0 & 0 & b - 2a \end{array} \right]$$

any choice of a, b for which $b - 2a \neq 0$ gives inconsistent system.

For example, $\vec{b} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ makes

$A\vec{x} = \vec{b}$ inconsistent.

§ 1.6 # 44 Let $S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$ find a subset \tilde{S} of S for which $\text{span}(S) = \text{span}(\tilde{S})$

I'll use the CCP and associated wisdom, the principle observation is that the pivot columns are LI, calculate then

$$\text{rref} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{bmatrix} = R$$

pivot columns of A pivot cols.

note then, by CCP,

$$\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

from R same linear combo. works for A.

$$\text{col}_4(R) = \text{col}_3(R) - \text{col}_2(R)$$

Clearly $\text{col}_4(A) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ is redundant and we can

use $\tilde{S} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$

§ 1.6 # 69 Let S_1, S_2 be finite subsets of $\mathbb{R}^{n \times 1}$ such that $S_1 \subset S_2$. Prove that if S_1 is a generating set of $\mathbb{R}^{n \times 1}$ then so is S_2

We are given that each $v \in \mathbb{R}^{n \times 1}$ is a linear combination of the vectors in S_1 and also $S_1 \subset S_2$. Let us denote $S_1 = \{v_1, v_2, \dots, v_k\}$. If $w \in \mathbb{R}^{n \times 1}$ then $\exists w_1, w_2, \dots, w_k \in \mathbb{R}$ such that $w = w_1 v_1 + w_2 v_2 + \dots + w_k v_k$. Notice that $v_i \in S_1 \Rightarrow v_i \in S_2$ for each $i=1, 2, \dots, k$ since $S_1 \subset S_2$.

Hence $w \in \text{span}(S_2)$ since $w = w_1 v_1 + \dots + w_k v_k$ is a linear combination of vectors in S_2 . Thus every vector in $\mathbb{R}^{n \times 1}$ is a linear combination of vectors in S_2 . It follows that S_2 is a generating set for $\mathbb{R}^{n \times 1}$.

§1.7#24) Is $S = \left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \right\}$ a LI set?

Note that $\text{rref} \begin{bmatrix} 1 & -1 & 2 \\ -1 & 0 & 1 \\ 1 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ thus S is LI since we know the pivot columns of a matrix are LI.

§1.7#36) Write a vector in S as a linear combination of other vectors in S given that $S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ -4 \\ -5 \end{bmatrix} \right\}$

We'll use the CCP to do this efficiently. Note

$$\text{rref}(A) = \text{rref} \begin{bmatrix} 1 & 2 & 5 \\ 0 & -1 & -4 \\ 3 & 1 & -5 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & 4 \\ 0 & 0 & 0 \end{bmatrix} = R$$

Notice $\text{col}_3(R) = -3\text{col}_1(R) + 4\text{col}_2(R)$ (you can just see this by inspection!) then by CCP we know

$$\text{col}_3(A) = -3\text{col}_1(A) + 4\text{col}_2(A) \quad \text{or} \quad \underline{\begin{bmatrix} 5 \\ -4 \\ -5 \end{bmatrix}} = -3 \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} + 4 \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

Remark: other answers are possible, however they just amount to rewriting the underlined eqⁿ above.

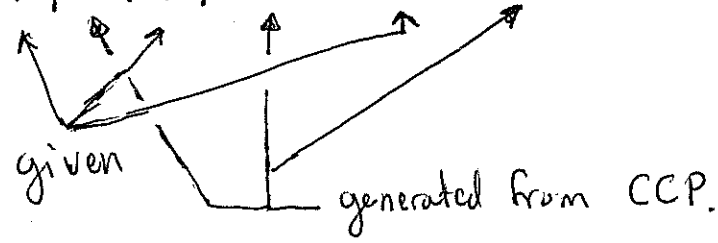
§2.3#68) Find A given that $\text{rref}(A) = \begin{bmatrix} 1 & 2 & 0 & -3 & 0 & 1 \\ 0 & 0 & 1 & 2 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} = R$
and $\text{col}_1(A) = \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix}$, $\text{col}_3(A) = \begin{bmatrix} -1 \\ 2 \\ 0 \\ 1 \end{bmatrix}$, $\text{col}_5(A) = \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix}$

Again the CCP is key. Observe that:

$$\text{col}_2(R) = 2\text{col}_1(R), \quad \text{col}_4(R) = -3\text{col}_1(R) + 2\text{col}_3(R), \quad \text{col}_6(R) = \text{col}_1(R) + 2\text{col}_3(R) + 3\text{col}_5(R)$$

Then the same correspondences hold for columns of A so we find,

$$A = \begin{bmatrix} 2 & 4 & 1 & -6+2 & 2 & 2+2+6 \\ 0 & 0 & -1 & -2 & 3 & 0-2 \\ -1 & -2 & 2 & 3+4 & 0 & -1+4+0 \\ 1 & 2 & 0 & -3 & 1 & 1+0+3 \end{bmatrix} = \underline{\begin{bmatrix} 2 & 4 & 1 & -4 & 2 & 10 \\ 0 & 0 & -1 & -2 & 3 & 7 \\ -1 & -2 & 2 & 7 & 0 & 3 \\ 1 & 2 & 0 & -3 & 1 & 4 \end{bmatrix}}$$



§2.3#82 Given $B = \begin{bmatrix} 1 & 0 & 1 & -3 & -1 & 4 \\ 2 & -1 & 3 & -8 & -1 & 9 \\ -1 & 1 & -2 & 5 & 1 & -6 \\ 0 & 1 & -1 & 2 & 1 & -3 \end{bmatrix}$

write $\text{col}_6(B)$ as a linear combination of the pivot columns of B .

We can calculate,

$$\text{rref}(B) = \begin{bmatrix} 1 & 0 & 1 & -3 & 0 & 3 \\ 0 & 1 & -1 & 2 & 0 & -2 \\ 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{col}_6(B) = 3\text{col}_1(B) - 2\text{col}_2(B) - \text{col}_5(B)$$

$$\therefore \begin{bmatrix} 4 \\ 9 \\ -6 \\ -3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \\ -1 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} -1 \\ -1 \\ 1 \\ 1 \end{bmatrix}$$

(oops, §4.4#14 is on 6) 2

§4.4# Find unique representation of $\vec{u} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ as linear combination of $b_1 = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$, $b_2 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$, $b_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

We wish to solve $\vec{u} = x b_1 + y b_2 + z b_3$, use our usual notation,

$$\begin{bmatrix} 1 & 1 & 0 \\ -1 & 0 & 1 \\ 2 & 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & | & a \\ -1 & 0 & 1 & | & b \\ 2 & 2 & 1 & | & c \end{bmatrix}$$

$$\begin{matrix} \xrightarrow{r_2+r_1} \\ \xrightarrow{r_3-2r_1} \end{matrix} \begin{bmatrix} 1 & 1 & 0 & | & a \\ 0 & 1 & 1 & | & a+b \\ 0 & 0 & 1 & | & c-2a \end{bmatrix} \xrightarrow{r_1-r_2} \begin{bmatrix} 1 & 0 & -1 & | & a-(a+b) \\ 0 & 1 & 1 & | & a+b \\ 0 & 0 & 1 & | & c-2a \end{bmatrix}$$

$$\begin{matrix} \xrightarrow{r_1+r_3} \\ \xrightarrow{r_2-r_3} \end{matrix} \begin{bmatrix} 1 & 0 & 0 & | & -b+c-2a \\ 0 & 1 & 0 & | & a+b-(c-2a) \\ 0 & 0 & 1 & | & c-2a \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & | & -2a-b+c \\ 0 & 1 & 0 & | & 3a+b-c \\ 0 & 0 & 1 & | & -2a+c \end{bmatrix}$$

Thus we read $x = -2a - b + c$, $y = 3a + b - c$, $z = -2a + c$ and

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = (-2a - b + c) \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + (3a + b - c) \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} + (-2a + c) \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

Remark: we just found $[V]_{\beta} = [-2a - b + c, 3a + b - c, -2a + c]^T$ given $V = [a, b, c]^T$ and $\beta = \{b_1, b_2, b_3\}$. Also I believe you can check $[b_1 | b_2 | b_3]^{-1} = \begin{bmatrix} -2 & -1 & 1 \\ 3 & 1 & -1 \\ -2 & 0 & -1 \end{bmatrix}$.

§4.4#14

6

(a.) Prove $\beta = \left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$ is a basis for $\mathbb{R}^{3 \times 1}$

(b.) Find $[v]_{\beta}$ given $v = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} - 4 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

(a.) I'll be lazy, $\det \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = 1(0) + 1(-2) + 1(-2) = -4 \neq 0$

thus $A = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ is invertible and $Ax = b$ is consistent

for every $b \in \mathbb{R}^{3 \times 1}$ so $\text{span } \beta = \mathbb{R}^{3 \times 1}$. Linear independence follows for a variety of reasons. I'll name two

(i) - if β had a linear dependence then A would have linear dep. columns $\Rightarrow \det(A) = 0$
 But, we just calculated $\det(A) \neq 0$ so we find a contradiction and can conclude β is LI.

(ii) - $A \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = 0 \Rightarrow A^{-1}A \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = A^{-1}0 \Rightarrow \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = 0$

Hence, by prop. which gave equivalent setⁿ of LI, we find β is LI since

$$A \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 0 \Rightarrow c_1 = c_2 = c_3 = 0.$$

$$(b.) v = 1 \cdot \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + 0 \cdot \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} - 4 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$= [\beta][v]_{\beta} \quad \text{if} \quad \underline{[v]_{\beta} = [1, 0, -4]^T}.$$

§7.1#31 Prove $\text{span}\{1+x, 1-x, 1+x^2, 1-x^2\} = P_2$

It is immediately obvious $\text{span}\{1+x, 1-x, 1+x^2, 1-x^2\} \subseteq P_2$.
However, the reverse inclusion requires some calculation.

Let $ax^2 + bx + c \in P_2$ where $a, b, c \in \mathbb{R}$, note

$$\begin{aligned}
 ax^2 + bx + c &= a\left[\frac{1}{2}(1+x^2) - \frac{1}{2}(1-x^2)\right] + 2 \\
 &\leftarrow + b\left[\frac{1}{2}(1+x) - \frac{1}{2}(1-x)\right] + 2 \\
 &\leftarrow + c\left[\frac{1}{2}(1+x) + (1-x)\right] \in \text{span}\{1+x, 1-x, 1+x^2, 1-x^2\} \\
 &\therefore P_2 \subseteq \text{span}\{1+x, 1-x, 1+x^2, 1-x^2\}
 \end{aligned}$$

We conclude $P_2 = \text{span}\{1+x, 1-x, 1+x^2, 1-x^2\}$.

Remark: You might wonder how did I see that $x^2 = \frac{1}{2}(1+x^2) - \frac{1}{2}(1-x^2)$ and $x = \frac{1}{2}(1+x) - \frac{1}{2}(1-x)$ and $1 = \frac{1}{2}(1+x) + \frac{1}{2}(1-x)$? Personally, I can just see it by inspection in this case. So what if you don't just "see" it, how would you go about solving this?

You try to solve

$$ax^2 + bx + c = c_1(1+x) + c_2(1-x) + c_3(1+x^2) + c_4(1-x^2)$$

for arbitrary a, b, c . This gives

$$\left. \begin{aligned}
 a &= c_3 + c_4 \\
 b &= c_1 - c_2 \\
 c &= c_1 + c_2 + c_3 + c_4
 \end{aligned} \right\} \begin{array}{l} \text{these} \\ \text{can be solved} \\ \text{in many ways.} \end{array}$$

§7.3#4) Is $S = \left\{ \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 3 \\ 3 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix} \right\}$ LI?

Assume that:

$$c_1 \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 & 3 \\ 3 & 1 \end{bmatrix} + c_3 \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad (*)$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} c_1 + c_2 + c_3 & 2c_1 + 3c_2 + 2c_3 & & 0 & 0 & \\ 2c_1 + 3c_2 + 3c_3 & c_1 + c_2 + c_3 & & 0 & 0 & \end{array} \right] = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{aligned} \Rightarrow \quad & c_1 + c_2 + c_3 = 0 \\ & 2c_1 + 3c_2 + 2c_3 = 0 \\ & 2c_1 + 3c_2 + 3c_3 = 0 \\ & c_1 + c_2 + c_3 = 0 \end{aligned}$$

redundant, just repeats of the eq^s from the (1,1) or

$$\begin{array}{ccc} c_1 & c_2 & c_3 \\ \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & 3 & 2 & 0 \\ 2 & 3 & 3 & 0 \end{array} \right] \xrightarrow{\substack{r_2 - 2r_1 \\ r_3 - 2r_1}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{array} \right] \end{array}$$

$$\xrightarrow{\substack{r_1 - r_2 \\ r_3 - r_2}} \left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

$$\Rightarrow \text{rref} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & 3 & 2 & 0 \\ 2 & 3 & 3 & 0 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \Rightarrow \underline{\underline{\begin{matrix} c_1 = 0 \\ c_2 = 0 \\ c_3 = 0 \end{matrix}}}$$

Thus S is a linearly independent set.

(I'm using Proposition 4.4.3 in my notes which is often a convenient criteria to test for LI)