

Homework 7: Dot-Products & Orthogonality

(1)

§ 6.1 # 4, 14, 38, 52, 87 // § 6.2 # 14, 22 // § 6.3 # 2, 6 // § 6.2 # 63

§ 6.1 # 4 Let $u = \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$ and $v = \begin{bmatrix} -1 \\ 4 \\ 2 \end{bmatrix}$ compute the norms of u & v and find the distance between u & v .

$$\|u\| = \sqrt{u \cdot u} = \sqrt{1^2 + 3^2 + 1^2} = \sqrt{11} = \|u\|$$

$$\|v\| = \sqrt{v \cdot v} = \sqrt{1^2 + 4^2 + 2^2} = \sqrt{21} = \|v\|$$

$$d(u, v) = \|u - v\| = \|[2, -1, -1]^T\| = \sqrt{2^2 + 1^2 + 1^2} = \sqrt{6} = d(u, v)$$

§ 6.1 # 14 Let $u = \begin{bmatrix} 1 \\ 2 \\ -3 \\ -1 \end{bmatrix}$ and $v = \begin{bmatrix} 2 \\ 3 \\ 2 \\ 0 \end{bmatrix}$. Are u & v orthogonal?

If $u \cdot v = 0$ then we would say u & v are orthogonal, consider

$$u \cdot v = [1 \ 2 \ -3 \ -1] \begin{bmatrix} 2 \\ 3 \\ 2 \\ 0 \end{bmatrix} = 2 + 6 - 6 + 0 = 2 \neq 0$$

Thus u, v are not orthogonal since $u \cdot v = 2$.

§ 6.1 # 38 Let $u = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ and $v = \begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix}$. Find $\|u\|$, $\|v\|$ and $u \cdot v$.

Illustrate the Cauchy Schwarz inequality with these vectors.

$$\|u\| = \sqrt{u \cdot u} = \sqrt{2}$$

$$\|v\| = \sqrt{v \cdot v} = \sqrt{4 + 1 + 9} = \sqrt{14}$$

$$u \cdot v = [0, 1, 1] \begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix} = 1 + 3 = 4$$

$$\text{Note } \|u\| \|v\| = \sqrt{2} \sqrt{14} = \sqrt{28} > 4 = |u \cdot v| \therefore |u \cdot v| < \|u\| \|v\|$$

§ 6.1 # 52 We're given $u, v, w \in \mathbb{R}^{n \times 1}$ such that $\|u\|=2$, $\|v\|=3$, $\|w\|=5$
 $u \cdot v = -1$, $u \cdot w = 1$ and $v \cdot w = -4$. Calculate $(u + w) \cdot v$

$$(u + w) \cdot v = u \cdot v + w \cdot v = -1 - 4 = -5$$

§6.1 #87 Let $\{v, w\}$ be a basis for a subspace $W \subseteq \mathbb{R}^{n \times 1}$ and define $z = \text{Proj}_v(w) = w - \left(\frac{v \cdot w}{v \cdot v}\right)v$. Prove that $\{v, z\}$ is an orthogonal basis for W .

Observe that $\dim(W) = 2$ since $\{v, w\}$ is a basis for W . Thus if we can show $\{v, z\}$ is LI it follows that $\{v, z\}$ is a basis. But, we could also attack LI by an indirect argument. If we can show $\{v, z\}$ is a set of nonzero orthogonal vectors then we proved that LI follows. Consider then that

1.) $v \neq 0$ since otherwise $\{v, w\}$ would not be LI which contradicts the given fact that $\{v, w\}$ is a basis for W .

2.) $z \neq 0$ since otherwise $z = 0 \Rightarrow w - \left(\frac{v \cdot w}{v \cdot v}\right)v = 0$ which again implies linear dependence of $\{v, w\}$ which contradicts the given fact $\{v, w\}$ is a basis.

Therefore, $\{v, z\}$ is a set of nonzero vectors,

$$\begin{aligned} v \cdot z &= v \cdot \left[w - \left(\frac{v \cdot w}{v \cdot v}\right)v \right] \\ &= v \cdot w - \left(\frac{v \cdot w}{v \cdot v}\right)v \cdot v \\ &= v \cdot w - v \cdot w \\ &= 0 \end{aligned}$$

$\therefore \{v, z\}$ is an orthogonal set

$\Rightarrow \{v, z\}$ is basis for W .

§6.2 #14 Let $S = \left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 5 \\ 1 \end{bmatrix} \right\}$.

$u_1 \quad u_2 \quad u_3$

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- a.) use Gram-Schmidt algorithm to find orthogonal set of vectors $\{v_1, v_2, v_3\}$ which spans $\text{span}(S)$.
- b.) normalize $\{v_1, v_2, v_3\}$ to get orthonormal basis for $\text{span}(S)$

a.) Apply Gram-Schmidt:

$$v_1 = u_1 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix}$$

$$v_2 = u_2 - \left(\frac{u_2 \cdot v_1}{v_1 \cdot v_1} \right) v_1 = \begin{bmatrix} 1 \\ 1 \\ 3 \\ 1 \end{bmatrix} - \frac{6}{6} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 1 \\ 1 \end{bmatrix}$$

$$v_3 = u_3 - \left(\frac{u_3 \cdot v_2}{v_2 \cdot v_2} \right) v_2 - \left(\frac{u_3 \cdot v_1}{v_1 \cdot v_1} \right) v_1 = \begin{bmatrix} 3 \\ 1 \\ 5 \\ 1 \end{bmatrix} - \frac{8}{6} \begin{bmatrix} 0 \\ 2 \\ 1 \\ 1 \end{bmatrix} - \frac{12}{6} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix}$$

$$\Rightarrow v_3 = \begin{bmatrix} 3 \\ 1 \\ 1 \\ 5 \end{bmatrix} - \frac{4}{3} \begin{bmatrix} 0 \\ 2 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 2 \\ -2 \\ 0 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 1 \\ 1 \end{bmatrix} - \frac{4}{3} \begin{bmatrix} 0 \\ 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1/3 \\ -1/3 \\ -1/3 \end{bmatrix}$$

$$\therefore \left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1/3 \\ -1/3 \\ -1/3 \end{bmatrix} \right\} \leftarrow \text{orthogonal set}$$

b.) normalize the vectors by dividing by their lengths

$$\left\{ \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 0 \\ 2 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{12}} \begin{bmatrix} 3 \\ 1 \\ 5 \\ 1 \end{bmatrix} \right\}$$

§6.2#22

Find the linear combination of

$$V_1 = \begin{bmatrix} 1 \\ -2 \\ 0 \\ -1 \end{bmatrix}, \quad V_2 = \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \quad V_3 = \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix} \text{ to give } V = \begin{bmatrix} 6 \\ 9 \\ 9 \\ 0 \end{bmatrix}$$

Notice that $V_1 \cdot V_2 = 0$, $V_1 \cdot V_3 = 0$, $V_2 \cdot V_3 = 0$.

Let $V = aV_1 + bV_2 + cV_3$, we wish to calculate a, b, c .

$$V \cdot V_1 = aV_1 \cdot V_1 + bV_2 \cdot V_1 + cV_3 \cdot V_1 = aV_1 \cdot V_1 = 6a$$

$$\Rightarrow 6 - 18 = 6a \Rightarrow a = \frac{-12}{6} = -2 \quad \therefore \underline{a = -2}.$$

Likewise,

$$V \cdot V_2 = bV_2 \cdot V_2 \Rightarrow 30 = b(6) \\ \Rightarrow \underline{b = 5}.$$

$$V \cdot V_3 = cV_3 \cdot V_3 \Rightarrow 6 - 18 = c(6)$$

$$\Rightarrow -12 = 6c \quad \therefore \underline{c = -2}.$$

Thus, $\boxed{V = -2V_1 + 5V_2 - 2V_3}$

$$\begin{bmatrix} 6 \\ 9 \\ 9 \\ 0 \end{bmatrix} = -2 \begin{bmatrix} 1 \\ -2 \\ 0 \\ -1 \end{bmatrix} + 5 \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

Remark: with orthogonal generating sets we can avoid row-reduction and instead take dot-products.

§6.3#2

Let $S = \{ [1, 0, 2]^T \}$ find basis for $S^\perp$

Let $\begin{bmatrix} x \\ y \\ z \end{bmatrix} \in S^\perp$ then $[1, 0, 2] \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$, thus

$$x + 2z = 0 \Rightarrow \underline{x = -2z}$$

Use y & z as free variables,

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -2z \\ y \\ z \end{bmatrix} = y \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \quad \therefore$$

$$\boxed{S^\perp = \text{span} \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \right\}}$$

Remark: this is same as calculating basis for $\text{Null} \left(\begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}^T \right)$.

§ 6.3#6) Given $S = \{ [1, -1, -5, -1]^T, [2, -1, -7, 0]^T \}$

find basis for $S^\perp$

If $[x, y, z, w] \in S^\perp$ then $[x, y, z, w] \cdot [1, -1, -5, -1] = 0$
and $[x, y, z, w] \cdot [2, -1, -7, 0] = 0$. This amounts
to finding $[x, y, z, w]^T \in \text{Null} \left(\begin{bmatrix} 1 & 2 \\ -1 & -1 \\ -5 & -7 \\ -1 & 0 \end{bmatrix}^T \right)$. We

could row reduce etc...

but these eq^s are simple enough that there's
no need for such sophistication,

$$\begin{array}{rcl} x - y - 5z - w = 0 & \swarrow & x - 2z + w = 0 \\ 2x - y - 7z = 0 & \searrow & y = x - 5z - w \end{array}$$

Use z & w as free variables,

$$x = 2z - w$$

$$y = x - 5z - w = 2z - w - 5z - w = -3z - 2w$$

$$z = z$$

$$w = w$$

It was clear there should be two free variables
once it was clear that the vector in S were
not linearly dependent, my intuition is guided
by the Th^m $\text{Span}(S) \oplus S^\perp = \mathbb{R}^{4 \times 1}$ if $\dim(\text{Span}(S)) = 2$
then $\dim(S^\perp) = 4 - 2 = 2 \Rightarrow S^\perp$ has basis with
2-vectors,

$$\begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} 2z - w \\ -3z - 2w \\ z \\ w \end{bmatrix} = z \begin{bmatrix} 2 \\ -3 \\ 1 \\ 0 \end{bmatrix} + w \begin{bmatrix} -1 \\ -2 \\ 0 \\ 1 \end{bmatrix}$$

$$\therefore S^\perp = \text{span} \left\{ \begin{bmatrix} 2 \\ -3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -2 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Remark: Again, this is the same calculation as finding a
basis for $\text{Null}([S]^T)$. Furthermore, you can check the
answer by taking dot-products of vectors in $S^\perp$ with those in S .

(6)

§ 6.2 # 63) Let $Q \in \mathbb{R}^{n \times n}$.

Prove $\{\text{col}_i(Q)\}_{i=1}^n$ is an orthonormal basis for $\mathbb{R}^{n \times 1}$
iff $Q^T Q = I_n$

Proof: Let $Q \in \mathbb{R}^{n \times n}$.

$\{\text{col}_i(Q)\}_{i=1}^n$ is an orthonormal basis for $\mathbb{R}^{n \times 1} \iff$

$$\iff \text{col}_i(Q) \cdot \text{col}_j(Q) = \delta_{ij}, \quad \forall i, j \in \mathbb{N}_n.$$

$$\iff (\text{col}_i(Q))^T \text{col}_j(Q) = \delta_{ij}, \quad \forall i, j \in \mathbb{N}_n.$$

$$\iff \text{row}_i(Q^T) \text{col}_j(Q) = \delta_{ij}, \quad \forall i, j \in \mathbb{N}_n.$$

$$\iff (Q^T Q)_{ij} = \delta_{ij}, \quad \forall i, j \in \mathbb{N}_n.$$

$$\iff Q^T Q = I_n.$$

(The problem is primarily a challenge of notation.)

Remark: If $Q^T Q = I_n$ then we say

Q is an orthogonal matrix. ~~then~~

These are interesting because if we start with an orthonormal basis $\beta = \{v_1, v_2, \dots, v_n\}$ then $\beta' = \{Qv_1, Qv_2, \dots, Qv_n\}$ will also be an orthonormal basis. There will be a problem or two in the Problem Set to explore this remark further.