

Problems are typically taken from either Jeffrey Lee's text *Manifolds and Differential Geometry* (MDG) or John Lee's text *Smooth Manifolds* (SM). I've also written a few problems. Most problems 5pts here.

Problem 67 SM Exercise 14-17 page 361. (make ample use of theorems for covariant tensor pull-back, this should not be a hard exercise)

Problem 68 SM Exercise 14-31 page 369. (formula connecting a Lie Bracket and an exterior derivative)

Problem 69 SM Problem 14-1 page 373. (wedge product and linear dependence)

Problem 70 SM Problem 14-5 page 373. (Cartan's Lemma)

Problem 71 SM Problem 14-6 page 373. (two-form calculation in $\mathbb{R}^3$)

Problem 72 SM Problem 14-7 page 373. (differential form fun)

SOLUTION TO MISSION 7

P67 Ex. 14-17, p. 361

$F: M \rightarrow N$ smooth

(a.) $F^*: \Omega^k(N) \rightarrow \Omega^k(M)$ is linear over $\mathbb{R}$

(b.) $F^*(\omega \wedge \eta) = (F^*\omega) \wedge (F^*\eta)$

(c.) In any smooth chart,

$$F^*\left(\sum_I \omega_I dy^{i_1} \wedge \dots \wedge dy^{i_k}\right) = \sum_I (\omega_I \circ F) d(y^{i_1} \circ F) \wedge \dots \wedge d(y^{i_k} \circ F)$$

For $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$ we define as in Lee
pg. 355, $\omega \wedge \eta = \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta)$

Then proof of (b.) can be given

$$\begin{aligned} F^*(\omega \wedge \eta) &= F^*\left(\frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta)\right) \\ &= \frac{(k+l)!}{k!l!} \text{Alt}(F^*(\omega \otimes \eta)) \quad \begin{array}{l} \text{by} \\ \text{linearity} \\ \text{of} \\ F^* \end{array} \\ &= \frac{(k+l)!}{k!l!} \text{Alt}((F^*\omega) \otimes (F^*\eta)) \quad \begin{array}{l} \text{property} \\ \text{of} \\ F^* \end{array} \\ &= (F^*\omega) \wedge (F^*\eta) \end{aligned}$$

p67 continued (part a)

Let $a \in \mathbb{R}$ and $\beta, \gamma \in \Sigma^k(N)$ let $v_1, \dots, v_k \in T_{F(p)}M$

$$\begin{aligned}(F^*(a\beta + \gamma))(v_1, \dots, v_k) &= \\&= (a\beta + \gamma)(dF(v_1), \dots, dF(v_k)) \\&= (a\beta)(dF(v_1), \dots, dF(v_k)) + \gamma(dF(v_1), \dots, dF(v_k))\end{aligned}$$

$$= (a F^*\beta + F^*\gamma)(v_1, \dots, v_k)$$

$$\text{Thus } F^*(a\beta + \gamma) = a F^*\beta + F^*\gamma.$$

Part c) for $v_1, \dots, v_k \in T_p M$,

$$\begin{aligned}F^*\left(\sum_I \omega_I dy^{i_1} \wedge \dots \wedge dy^{i_k}\right)_p(v_1, \dots, v_k) &= \\&= \left(\sum_I \omega_I dy^{i_1} \wedge \dots \wedge dy^{i_k}\right)_{F(p)}(dF_p(v_1), \dots, dF_p(v_k)) \\&= \bigwedge \sum_I \omega_I(F(p)) dy^{i_1}(dF_p(v_1)) dy^{i_2}(dF_p(v_2)) \dots dy^{i_k}(dF_p(v_k)) \\&= \bigwedge \sum_I \omega_I(F(p)) d(y^{i_1} \circ F)(v_1) \dots d(y^{i_k} \circ F)(v_k) \\&= \left(\sum_I \omega_I(F(p)) d(y^{i_1} \circ F) \wedge \dots \wedge d(y^{i_k} \circ F)\right)(v_1, \dots, v_k)\end{aligned}$$

Then (c.) follows. I've used " $\bigwedge$ " to denote the complete antisymmetrization of the products in question this amounts to details of $\alpha_1 \wedge \alpha_2 \wedge \dots \wedge \alpha_n$. Sorry me lazy.

(Given $d\omega(X, Y) = X(\omega(Y)) - Y(\omega(X)) - \omega([X, Y])$)

Let M be smooth n -manifold, and (E_i) a smooth local frame for M and (ε^i) the dual coframe.

For each i , let b^i_{jk} denote comp. of exterior derivative of ε^i in this frame, and for each j, k let c^i_{jk} be comp. fncts of Lie Bracket $[E_j, E_k]$;

$$d\varepsilon^i = \sum_{j < k} b^i_{jk} \varepsilon^j \wedge \varepsilon^k$$

$$[E_j, E_k] = \sum_i c^i_{jk} E_i$$

Then $b^i_{jk} = -c^i_{jk}$

Let $l < m$ and consider,

$$(d\varepsilon^i)(E_l, E_m) = \sum_{j < k} b^i_{jk} \overbrace{\varepsilon^j \wedge \varepsilon^k}^{\varepsilon^j \otimes \varepsilon^k - \varepsilon^k \otimes \varepsilon^j}(E_l, E_m)$$

$$= \sum_{j < k} b^i_{jk} \delta_{jl} \delta_{km}$$

$$= b^i_{lm}$$

Likewise,

$$\begin{aligned} d\varepsilon^i(E_l, E_m) &= E_l(\overbrace{\varepsilon^i(E_m)}^{\delta_{im}}) - E_m(\overbrace{\varepsilon^i(E_l)}^{\delta_{il}}) - \varepsilon^i([E_l, E_m]) \\ &= -\varepsilon^i\left(\sum_k c^k_{lm} E_k\right) \\ &= -\sum_k c^k_{lm} \varepsilon^i(E_k) \\ &= -\sum_k c^k_{lm} \delta_{ik} = \underline{-c^i_{lm}} // \end{aligned}$$

P69 Problem 14-1, p. 373

Show covectors $\omega^1, \dots, \omega^k$ on a finite dimensional vector space are linearly dependent iff $\omega^1 \wedge \dots \wedge \omega^k = 0$

$\Rightarrow$ Suppose $\omega^j = \sum_{i \neq j} c_i \omega^i$ then consider

$$\begin{aligned} \omega^1 \wedge \dots \wedge \omega^k &= \omega^1 \wedge \dots \wedge \left(\sum_{i \neq j} c_i \omega^i \right) \wedge \dots \wedge \omega^k \\ &= \sum_{i \neq j} c_i \underbrace{\omega^1 \wedge \dots \wedge \omega^{j-1} \wedge \omega^i \wedge \omega^{j+1} \wedge \dots \wedge \omega^k}_{i \in \{1, \dots, j-1, j+1, \dots, k\}} \\ &= \sum_{i \neq j} \pm c_i \underbrace{\omega^i \wedge \omega^i}_0 \wedge \underbrace{\omega^1 \wedge \dots \wedge \omega^k}_{\text{missing } \omega^i \text{ and } \omega^j} \\ &= 0. \end{aligned}$$

$\Leftarrow$ Suppose $\omega^1 \wedge \dots \wedge \omega^k = 0$

If $\omega^1, \dots, \omega^k$ are LI then $\omega^1 \wedge \dots \wedge \omega^k \neq 0$.
 Conversely, suppose $\omega^1 \wedge \dots \wedge \omega^k = 0$.
 Then $\omega^1, \dots, \omega^k$ are LI. Suppose $\omega^1, \dots, \omega^k$ are LI.
 Then $\omega^1 \wedge \dots \wedge \omega^k \neq 0$.
 The set $\{\omega^1, \dots, \omega^k\}$ is a basis for the space of covectors.

Remark: if $\omega^1, \dots, \omega^k$ are LI then $W^* = \text{span}\{\omega^1, \dots, \omega^k\}$
 has basis $\omega^1, \dots, \omega^k$ dual to $\varepsilon_1, \dots, \varepsilon_k$ and thus
 $(\omega^1 \wedge \dots \wedge \omega^k)(\varepsilon_1, \dots, \varepsilon_k) = 1 \Rightarrow \omega^1 \wedge \dots \wedge \omega^k \neq 0 \rightarrow \leftarrow$.

P69 continued

(perhaps the argument already given is better 😊)

$\Leftarrow$ Suppose $\omega^1 \wedge \dots \wedge \omega^k = 0$

Suppose towards $\Rightarrow$ that $\omega^1, \dots, \omega^k$ are LI

Then $c_1 \omega^1 + \dots + c_k \omega^k = 0 \Rightarrow c_1 = c_2 = \dots = c_k = 0$.

Thus $[\vec{\omega}^1 | \vec{\omega}^2 | \dots | \vec{\omega}^k] \vec{c} = 0 \Rightarrow \vec{c} = 0$. *

where $\vec{\omega}^i$ is the coordinate vector of ω^i with respect to some basis for $\text{span}(\omega^1, \dots, \omega^k)$ then

$$\vec{\omega}^1 \wedge \vec{\omega}^2 \wedge \dots \wedge \vec{\omega}^k = \underbrace{\det([\vec{\omega}^1 | \vec{\omega}^2 | \dots | \vec{\omega}^k])}_{\neq 0 \text{ since } * \text{ gives invertibility of this matrix}} e_1 \wedge \dots \wedge e_k$$

Yet,

$$\omega^1 \wedge \dots \wedge \omega^k = 0$$

implies (Lemma)

$\vec{\omega}^1 \wedge \dots \wedge \vec{\omega}^k = 0 \Rightarrow \therefore \omega^1, \dots, \omega^k$ are not LI. That is, $\omega^1, \dots, \omega^k$ are linearly dependent.

Lemma: If $\alpha^1, \dots, \alpha^k$ are covectors with coordinate vectors $\vec{\alpha}^1, \dots, \vec{\alpha}^k$ in the sense $\alpha^i = \sum_j \vec{\alpha}_j^i \theta^j$ and $\alpha^1 \wedge \dots \wedge \alpha^k = 0$ then $\vec{\alpha}^1 \wedge \dots \wedge \vec{\alpha}^k = 0$.

Lemma: $\alpha^1 \wedge \dots \wedge \alpha^k = 0 \Rightarrow \vec{\alpha}^1 \wedge \dots \wedge \vec{\alpha}^k = 0$
 where $\vec{\alpha}^i$ is coordinate vector of α^i

Suppose $\alpha^i = \sum_j \vec{\alpha}_j^i \theta^j$ where $\theta^1, \dots, \theta^k$ give basis for $\text{span}\{\alpha^1, \dots, \alpha^k\}$ and if needed extend past the span, certainly we can view $\alpha^1, \dots, \alpha^k$ as subset of k -dim'd V -space. We have $\theta^1 \wedge \theta^2 \wedge \dots \wedge \theta^k \neq 0$. Consider

$$\begin{aligned} \alpha^1 \wedge \dots \wedge \alpha^k &= \left(\sum_{i_1} \vec{\alpha}_{i_1}^1 \theta^{i_1} \right) \wedge \dots \wedge \left(\sum_{i_k} \vec{\alpha}_{i_k}^k \theta^{i_k} \right) \\ &= \sum_{i_1, \dots, i_k} \vec{\alpha}_{i_1}^1 \vec{\alpha}_{i_2}^2 \dots \vec{\alpha}_{i_k}^k \theta^{i_1} \wedge \theta^{i_2} \wedge \dots \wedge \theta^{i_k} \\ &= \sum_{i_1, \dots, i_k} \vec{\alpha}_{i_1}^1 \dots \vec{\alpha}_{i_k}^k \epsilon_{i_1, \dots, i_k} \theta^1 \wedge \dots \wedge \theta^k \\ &= \det [\vec{\alpha}^1 | \vec{\alpha}^2 | \dots | \vec{\alpha}^k] \theta^1 \wedge \dots \wedge \theta^k \end{aligned} \quad *$$

If $\alpha^1 \wedge \dots \wedge \alpha^k = 0$ then by $*$ we find $\det [\vec{\alpha}^1 | \dots | \vec{\alpha}^k] = 0$. However, we also know $\vec{\alpha}^1 \wedge \dots \wedge \vec{\alpha}^k = \underbrace{\det [\vec{\alpha}^1 | \dots | \vec{\alpha}^k]}_0 e_1 \wedge \dots \wedge e_n = 0$

Thus $\vec{\alpha}^1 \wedge \dots \wedge \vec{\alpha}^k = 0$.

P70 Problem 14-5, p. 373 Cartan's Lemma

Let M be smooth n -manifold and let $(w^1, \dots, w^k)$ be an ordered k -tuple of smooth one-forms on open $U \subseteq M$ such that $(w^1|_p, \dots, w^k|_p)$ is LI for $p \in U$. Given smooth 1-forms $\alpha^1, \dots, \alpha^k$ on U such that $\sum_{i=1}^k \alpha^i \wedge w^i = 0$, show that each α^i can be written as linear comb. of $w^1, \dots, w^k$ with smooth coefficients.

Since $w^1, \dots, w^k$ LI at $p \in U$ we can extend to basis of one-forms at p , say $w^1, \dots, w^k, w^{k+1}, \dots, w^n$. Thus $\exists A_j^i, B_j^i \in \mathbb{R}$ such that any one-form at p has

$$\alpha^i = \sum_{j=1}^k A_j^i w^j + \sum_{j=k+1}^n B_j^i w^j$$

Assume $\alpha^1, \dots, \alpha^k$ are one-forms on U with $\sum_{i=1}^k \alpha^i \wedge w^i = 0$. Consider,

$$0 = \sum_{i=1}^k \alpha^i \wedge w^i = \sum_{i,j=1}^k A_j^i w^i \wedge w^j + \sum_{i=1}^k \sum_{j=k+1}^n B_j^i \underbrace{w^i \wedge w^j}_{\neq 0}$$

Thus $B_j^i = 0$ by LI of $w^1, \dots, w^k$ since $i \neq j$.

We're left to analyze the remaining terms with A_j^i , however, we don't need to, $\alpha^i = \sum A_j^i w^j$ and smoothness of coefficients follows from smoothness of α^i and w^j on $U \subseteq M$.

Remark: Mission 5, Advanced Calculus 2015, ~~P109~~ (2013) has more.
(this is also a problem in Rantala on p. 50)

P71) $\omega = x dy \wedge dz + y dz \wedge dx + z dx \wedge dy$

[Prob. 14-6, p. 375]

Let $x = \rho \cos \theta \sin \phi$, $y = \rho \sin \theta \sin \phi$, $z = \rho \cos \phi$

$$dx = \cos \theta \sin \phi d\rho - \rho \sin \theta \sin \phi d\theta + \rho \cos \theta \cos \phi d\phi$$

$$dy = \sin \theta \sin \phi d\rho + \rho \cos \theta \sin \phi d\theta + \rho \sin \theta \cos \phi d\phi$$

$$dz = \cos \phi d\rho - \rho \sin \phi d\phi$$

Then calculate

$$\begin{aligned} \textcircled{1} dy \wedge dz &= -\rho \sin \theta \sin^2 \phi d\rho \wedge d\phi + \rho \sin \theta \cos^2 \phi d\phi \wedge d\rho + \rho \cos \theta \sin \phi \cos \phi d\theta \wedge d\rho - \rho^2 \cos \theta \sin^2 \phi d\theta \wedge d\phi \\ &= \underline{\rho \sin \theta d\phi \wedge d\rho} + \underline{\rho \cos \theta \sin \phi \cos \phi d\theta \wedge d\rho} + \underline{\rho^2 \cos \theta \sin^2 \phi d\phi \wedge d\theta} \end{aligned}$$

$$\begin{aligned} \textcircled{2} dz \wedge dx &= -\rho \cos \phi \sin \phi \sin \theta d\rho \wedge d\theta + \rho \cos^2 \phi \cos \theta d\phi \wedge d\rho + \rho \sin \theta \sin^2 \phi d\phi \wedge d\rho + \rho^2 \sin^3 \phi \sin \theta d\phi \wedge d\theta \\ &= \underline{\rho \cos \phi \sin \phi \sin \theta d\theta \wedge d\rho} + \underline{\rho \cos \theta d\rho \wedge d\phi} + \underline{\rho^2 \sin^2 \phi \sin \theta d\phi \wedge d\theta} \end{aligned}$$

$$\begin{aligned} \textcircled{3} dx \wedge dy &= \rho \cos^2 \theta \sin^2 \phi d\rho \wedge d\theta + \rho \cos \theta \sin \theta \cos \phi \sin \phi d\rho \wedge d\phi - \rho \sin^2 \theta \sin^2 \phi d\theta \wedge d\rho - \rho^2 \sin^2 \theta \sin \phi \cos \phi d\theta \wedge d\phi \\ &\quad + \rho \cos \theta \sin \theta \cos \phi \sin \phi d\phi \wedge d\rho + \rho^2 \cos^2 \theta \sin \phi \cos \phi d\phi \wedge d\theta \\ &= \underline{\rho \sin^2 \phi d\rho \wedge d\theta} + \underline{\rho^2 \sin \phi \cos \phi d\phi \wedge d\theta} \quad (\text{funny}) \end{aligned}$$

Therefore,

$$\begin{aligned} \omega &= (\underline{\rho \sin \theta \cdot \rho \cos \theta \sin \phi} - \underline{\rho \sin \theta \sin \phi \cdot \rho \cos \theta}) d\phi \wedge d\rho \\ &\quad + (\underline{\rho \cos \theta \sin \phi \cos \phi \cdot \rho \cos \theta \sin \phi} + \underline{\rho \cos \phi \sin \phi \sin \theta \cdot \rho \sin \theta \sin \phi} - \rho^2 \sin^2 \phi \cos \phi) d\theta \wedge d\rho \\ &\quad + (\underline{\rho^3 \cos^2 \theta \sin^3 \phi} + \underline{\rho^3 \sin^3 \phi \sin^2 \theta} + \underline{\rho^3 \sin \phi \cos^2 \phi}) d\phi \wedge d\theta \end{aligned}$$

$$\Rightarrow \omega = \rho^3 ((\cos^2 \theta + \sin^2 \theta) \sin^3 \phi + \sin \phi \cos^2 \phi) d\phi \wedge d\theta$$

$$\therefore \boxed{\omega = \rho^3 \sin \phi d\phi \wedge d\theta}$$

p71 continued

(b.) calculate $d\omega$ in both Cartesian & Sphericals, compare

$$\omega = xdydz + ydzdx + zdx dy = \rho^3 \sin \phi d\phi d\theta$$

Hence,

$$d\omega = dx \wedge dy \wedge dz + dy \wedge dz \wedge dx + dz \wedge dx \wedge dy$$

$$\underline{d\omega = 3 dx \wedge dy \wedge dz = 3\rho^2 \sin \phi d\rho \wedge d\phi \wedge d\theta.}$$

$$(\text{Recall } \frac{\partial(x,y,z)}{\partial(\rho,\phi,\theta)} = \rho^2 \sin \phi \text{ and}$$

$$\text{notice } dx \wedge dy \wedge dz = \frac{\partial(x,y,z)}{\partial(\rho,\phi,\theta)} d\rho \wedge d\phi \wedge d\theta = \rho^2 \sin \phi d\rho \wedge d\phi \wedge d\theta)$$

likewise,

$$d\omega = 3\rho^2 d\rho \wedge \sin \phi d\phi \wedge d\theta + \rho^3 \cancel{\cos \phi d\phi \wedge d\phi \wedge d\theta}$$

$$\underline{d\omega = 3\rho^2 \sin \phi d\rho \wedge d\phi \wedge d\theta.}$$

(c.) compute pullback $(L_{S^2})^* \omega$ to S^2 using (φ, θ) coord.
for sphere S^2 on open subset where φ, θ are defined.

S^2 given by $\rho = 1$ so

$$\boxed{(L_{S^2})^* \omega = \sin \phi d\phi \wedge d\theta}$$

(d.) $(L_{S^2})^* \omega = \sin \phi d\phi \wedge d\theta \neq 0$ for $\sin \phi \neq 0$
we cover all of S^2 modulo $(0,0,\pm 1)$ and
the angle-jump for θ , let's say $(0,\infty) \times \{0\} \times \mathbb{R}$
But, ω symmetric w.r.t. x,y,z so we can define
modified sphericals modulo $(0,\pm 1,0)$ and half-plane
or $(\pm 1,0,0)$ and half-plane thus we cover all of S^2
and find $(L_{S^2})^* \omega \neq 0$ (hence it's an orientation!)

P71 comment

$$S^2 = F^{-1}\{1\}$$

$$F(x, y, z) = x^2 + y^2 + z^2$$

$$dF = 2x dx + 2y dy + 2z dz$$

$$*(dF) = 2x dy \wedge dz + 2y dz \wedge dx + 2z dx \wedge dy$$

$$\Rightarrow \omega = \frac{1}{2} * (dF) = \frac{1}{2} \Phi_{\nabla F} \left[\begin{array}{l} \text{flux-form for } \mathbb{R}^3 \\ \uparrow \text{Hodge Dual} \quad \frac{\nabla F}{2} = \langle x, y, z \rangle \end{array} \right]$$

$$d\omega = \frac{1}{2} d\Phi_{\nabla F} = \frac{1}{2} (\nabla \cdot \nabla F) dx \wedge dy \wedge dz$$

$$d\omega = 3 dx \wedge dy \wedge dz$$

P72 Problem 14-7, p. 375

In each case, calculate $d\omega$, $F^*\omega$ and verify $F^*(d\omega) = d(F^*\omega)$ for $F: M \rightarrow N$ given,

(a.) $M = N = \mathbb{R}^2$

$F(s, t) = (st, e^t)$ and $\omega = xdy$

$$d\omega = dx \wedge dy$$

$$\begin{aligned} F^*d\omega &= d(F^*x) \wedge d(F^*y) \\ &= d(st) \wedge d(e^t) \\ &= (t ds + s dt) \wedge e^t dt \\ &= \underline{te^t ds \wedge dt}. \end{aligned}$$

$$F^*\omega = (F^*x)F^*dy = st d(e^t) = \underline{ste^t dt}.$$

$$\begin{aligned} d(F^*\omega) &= d(ste^t) \wedge dt \\ &= (te^t ds + s(1+t)e^t dt) \wedge dt \\ &= \underline{te^t ds \wedge dt}. \quad \therefore \underline{F^*d\omega = d(F^*\omega)}. \end{aligned}$$

(b.) $M = \mathbb{R}^2$, $N = \mathbb{R}^3$, $\omega = y dz \wedge dx$

$F(\theta, \varphi) = ((\cos \varphi + 2)\cos \theta, (\cos \varphi + 2)\sin \theta, \sin \varphi)$

$$d\omega = dy \wedge dz \wedge dx = dx \wedge dy \wedge dz$$

$$\begin{aligned} F^*d\omega &= d((\cos \varphi + 2)\cos \theta) \wedge d((\cos \varphi + 2)\sin \theta) \wedge d(\sin \varphi) \\ &= (-\sin \varphi \cos \theta d\varphi + (\cos \varphi + 2)(-\sin \theta d\theta)) \wedge (-\sin \theta \sin \varphi d\varphi + (\cos \varphi + 2)\cos \theta d\theta) \\ &\quad \wedge (\cos \varphi d\varphi) \end{aligned}$$

$$= 0 \quad \text{since all three forms on } \mathbb{R}^2 \text{ are zero!}$$

$$\begin{aligned} F^*\omega &= (\cos \varphi + 2)\sin \theta (\cos \varphi d\varphi) \wedge (-\sin \varphi \cos \theta d\varphi + (\cos \varphi + 2)(-\sin \theta d\theta)) \\ &= (\cos \varphi + 2)^2 \sin^2 \theta \cos \varphi d\theta \wedge d\varphi \end{aligned}$$

$$\Rightarrow d(F^*\omega) = 0 \quad \therefore \underline{F^*d\omega = d(F^*\omega)}.$$

P72 continued

$$(c.) \quad M = \{ (u, v) \in \mathbb{R}^2 \mid u^2 + v^2 < 1 \}$$

$$N = \mathbb{R}^3 - \{0\}, \quad F(u, v) = (u, v, \sqrt{1-u^2-v^2})$$

$$\omega = \frac{1}{(x^2+y^2+z^2)^{3/2}} (x dy \wedge dz + y dz \wedge dx + z dx \wedge dy)$$

$$\omega = \frac{x}{\rho^3} dy \wedge dz + \frac{y}{\rho^3} dz \wedge dx + \frac{z}{\rho^3} dx \wedge dy$$

$$\omega = \frac{1}{\rho^3} (x dy \wedge dz + y dz \wedge dx + z dx \wedge dy)$$

$$\omega = \frac{1}{\rho^3} (\rho^3 \sin \phi d\phi \wedge d\theta) \quad \text{from P71 b.}$$

$$\omega = \sin \phi d\phi \wedge d\theta$$

$$\underline{d\omega = 0}, \quad \hookrightarrow \quad \underline{F^*(d\omega) = 0}$$

Likewise, $x=u, y=v, z=\sqrt{1-u^2-v^2}$ gives $x^2+y^2+z^2=1$

$$F^* \omega = u dv \wedge dz + v dz \wedge du + z du \wedge dv$$

$$= (u dv - v du) \wedge \left(\frac{1}{2z} (-2u du - 2v dv) \right) + z du \wedge dv$$

$$= \frac{-2u^2}{2z} dv \wedge du + \frac{2v^2}{2z} du \wedge dv + \frac{z^2}{z} du \wedge dv$$

$$= \left(\frac{u^2 + v^2 + z^2}{z} \right) du \wedge dv$$

$$= \frac{1}{z} (u^2 + v^2 + 1 - u^2 - v^2) du \wedge dv$$

$$= \frac{du \wedge dv}{\sqrt{1-u^2-v^2}}$$

$$\underline{d(F^* \omega) = 0 = F^*(d\omega)}.$$

Remark: ω is the Coulomb field.