

Problems are typically taken from either Jeffrey Lee's text *Manifolds and Differential Geometry* (MDG) or John Lee's text *Smooth Manifolds* (SM). I've also written a few problems. Most problems 5pts here.

- Problem 73** SM Exercise 19-9 page 495. (local coframe criterion, if you can get part of it good, if all great)
- Problem 74** SM Exercise 19-10 page 495. (this problem is ideal)
- Problem 75** SM Exercise 19-15 page 499. (flows and integral submanifold verification)
- Problem 76** SM Problem 19-2 page 512. (involutivity in view of calculus and algebra of forms)
- Problem 77** SM Problem 19-3 page 512. (integrating factor, Pfaff's Theorem)
- Problem 78** SM Problem 19-4 page 512. (find a flat chart, I hope this isn't too tricky)
- Problem 79** SM Problem 19-5 page 513. (find integral submanifold)
- Problem 80** Let G be a Lie group and suppose $\mathfrak{h} \leq \mathfrak{g}$. Explain how the Lie subalgebra $\mathfrak{h}$ can be used to define an involutive distribution on G .
- Problem 81** Give five example homogeneous spaces from Chapter 21 of John Lee's text.

MISSION 8 SOLUTION

P73 Exercise 19-9, prove Proposition 19.8

D a smooth rank k distribution on n -manifold M and let $\omega^1, \dots, \omega^{n-k}$ be smooth defining forms for D on an open subset $U \subseteq M$. TFAE

(a.) D is involutive on U

(b.) $d\omega^1, \dots, d\omega^{n-k}$ annihilate D (on U)

(c.) $\exists$ smooth 1-forms $\{\alpha_j^i \mid i, j = 1, 2, \dots, n-k\}$

such that $d\omega^i = \sum_{j=1}^{n-k} \omega^j \wedge \alpha_j^i$ for $i = 1, \dots, n-k$

Th^m 19.7 $D \subseteq TM$ a smooth distribution. Then D is involutive iff $\{ \text{If } \eta \text{ is any smooth 1-form that annihilates } D \text{ on an open subset } U \subseteq M, \text{ then } d\eta \text{ also annihilates } D \text{ on } U \}$

Assume (a.) If D involutive on U then $\omega^1, \dots, \omega^{n-k}$ are smooth defining forms which annihilate D . Thus Th^m 19.7 yields $d\omega^1, \dots, d\omega^{n-k}$ also annihilate D . (on U)
 $\therefore (a) \Rightarrow (b).$

Suppose (b.), suppose $d\omega^1, \dots, d\omega^{n-k}$ annihilate D .

Then by Lemma 19.6 taking $\eta = d\omega^i$ we find

$\exists$ smooth 1-forms ($P = 2$ so $P-1 = 1$) $\beta_j^i = \alpha_j^i$ for

which $d\omega^i = \sum_{j=1}^{n-k} \omega^j \wedge \alpha_j^i$ thus $(b) \Rightarrow (c).$

Assume (c.) hence $*$ holds true on U for some smooth 1-forms α_j^i . Notice $*$ implies $d\omega^1, \dots, d\omega^{n-k}$ annihilate D on U (it remains to show D is involutive on $U \subseteq M$)

P74 Exercise 19-10/

For any smooth dist. $D \subseteq TM$, show $\mathcal{I}(D)$ is an ideal in Ω^*M

Defⁿ: An ideal in Ω^*M is a linear subspace $\mathcal{I} \subseteq \Omega^*(M)$ that is closed under wedge products of Ω^*M elements;
 $\omega \in \mathcal{I} \Rightarrow \eta \wedge \omega \in \mathcal{I} \quad \forall \eta \in \Omega^*M$.

Suppose D has annihilating one-forms $\omega^1, \dots, \omega^{n-k}$.
 Let $\gamma \in \mathcal{I}(D)$ then γ annihilates D
 thus, by Lemma 19.6, $\exists$ smooth forms β^i
 such that $\gamma = \sum_{i=1}^{n-k} \omega^i \wedge \beta^i$. Let

$\eta \in \Omega^*(M)$ and consider $\eta \wedge \gamma$. We find

$$\begin{aligned} \eta \wedge \gamma &= \eta \wedge \left(\sum_{i=1}^{n-k} \omega^i \wedge \beta^i \right) \\ &= \sum_{i=1}^{n-k} \eta \wedge \omega^i \wedge \beta^i \\ &= \sum_{i=1}^{n-k} \omega^i \wedge \underbrace{(-1)^{\deg(\eta)} \eta \wedge \beta^i}_{\text{smooth form}} \end{aligned}$$

Thus $\eta \wedge \gamma \in \mathcal{I}(D)$ by Lemma 19.6 once more. Thus $\mathcal{I}(D)$ is an ideal in Ω^*M //

P 75

$$V = \partial_x + y \partial_z \quad \alpha_t(x, y, z) = (x+t, y, z+ty)$$

$$W = \partial_y + x \partial_z \quad \beta_t(x, y, z) = (x, y+t, z+tx)$$

Have flows as above and also that level sets $z - xy$ are integral manifolds of D .

(Ex 19-15, p. 499 of Lee)

$$V: \frac{dx}{dt} = 1 \quad \text{and} \quad \frac{dy}{dt} = 0 \quad \text{and} \quad \frac{dz}{dt} = y \quad \left(\text{DE}_g^{n/1} \text{ for } \int\text{-curve of } V \right)$$

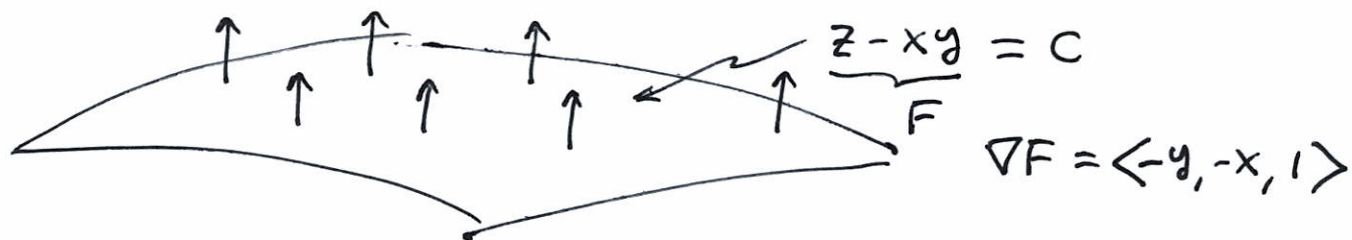
$$x = x_0 + t \quad y = y_0 \quad z = y_0 t + z_0$$

$$\therefore \underline{\alpha_t(x, y, z) = (x+t, y, z+yt)}$$

$$W: \frac{dx}{dt} = 0 \quad \text{and} \quad \frac{dy}{dt} = 1 \quad \text{and} \quad \frac{dz}{dt} = x \quad \left(\text{DE}_g^{n/1} \text{ for } \int\text{-curve of } W \right)$$

$$x = x_0 \quad y = t + y_0 \quad z = x_0 t + z_0$$

$$\underline{\beta_t(x, y, z) = (x, y+t, z+tx)}$$



$$\langle V, \nabla F \rangle = \langle \langle 1, 0, y \rangle, \langle -y, -x, 1 \rangle \rangle = -y + y = 0$$

$$\langle W, \nabla F \rangle = \langle \langle 0, 1, x \rangle, \langle -y, -x, 1 \rangle \rangle = -x + x = 0$$

Thus $V, W \perp \nabla F$

$\Rightarrow V, W$ are tangent to $z - xy = C$.

$\therefore z - xy = C$ are integral manifolds of D .

P76) Problem 19-2

Let D be smooth, rank k distribution on smooth n -manifold M , and $\omega^1, \omega^2, \dots, \omega^{n-k}$ are smooth local defining forms for D on $U \subseteq M$. Show D is involutive on U iff the following identity holds for each $i=1, \dots, n-k$,

$$d\omega^i \wedge \omega^1 \wedge \dots \wedge \omega^{n-k} = 0$$

$\Rightarrow$ If D is involutive then as $\omega^1, \dots, \omega^{n-k}$ annihilate D on U we have also $d\omega^i$ annihilate D on U by Prop. 19.8 b. But then $d\omega^i = \sum_{j=1}^{n-k} \omega^j \wedge \alpha_j^i$ by Prop. 19.8 c

and so

$$d\omega^i \wedge \omega^1 \wedge \dots \wedge \omega^{n-k} = \left(\sum_{j=1}^{n-k} \omega^j \wedge \alpha_j^i \right) \wedge \underbrace{\omega^1 \wedge \dots \wedge \omega^{n-k}}_*$$

$$= 0$$

since $\omega^j \wedge \omega^j = 0$
and every term in the sum has duplicate ω^j in $*$.

$\Leftarrow$ Assume that

$$d\omega^i \wedge \omega^1 \wedge \dots \wedge \omega^{n-k} = 0$$

Since $\omega^1, \dots, \omega^{n-k}$ are LI at a pt, we find $d\omega^i$ must linearly depend on $\omega^1, \dots, \omega^{n-k}$ since $d\omega^i, \omega^1, \dots, \omega^{n-k}$ is linearly dependent by the given eqⁿ. Thus $\exists \alpha_j^i$ smooth one-forms for which $d\omega^i = \sum \omega^j \wedge \alpha_j^i$ for $i=1, 2, \dots, n-k$. Thus D is involutive by Prop. 19.8 c. //

PROBLEM 19-3

Let ω be smooth 1-form on M . A smooth positive function μ on some open subset $U \subseteq M$ is called an integrating factor for ω if $\mu\omega$ is exact on U .

- (a.) If $\omega \neq 0$ on M , then ω admits $\int$ -factor in nbhd of each pt iff $d\omega \wedge \omega \equiv 0$
- (b.) If $\dim M = 2$, then every nonvanishing smooth 1-form has an integrating factor in nbhd of each pt.

(a.) $\Rightarrow$ If $\exists \mu$ s.t. $\mu\omega = d\alpha$ on U then notice $d\mu \wedge \omega + \mu d\omega = d(d\alpha) = 0$
 thus $d\omega = -\frac{1}{\mu} d\mu \wedge \omega$ and $d\omega \wedge \omega = 0$ on U
 Thus $d\omega \wedge \omega \equiv 0$ since U was arbitrary.

$\Leftarrow$ Suppose $d\omega \wedge \omega \equiv 0$. (see Prop 19.8 b I think)

Then it follows that the distribution with local annihilating form ω is involutive on M .

Hence, by Frobenius Th^m, this $(n-1)$ -dimensional distribution on TM is completely integrable. Thus

$\exists (n-1)$ -dim'l integrable manifolds, aligned with D .

At a given local, we can write the $\int$ -manifold D as level surface $F(x) = 0$ and $dF = 0$ on D

(Lemma 19.6) Then $dF = \omega \wedge \mu$ for 0-form μ and $\mu > 0$
 can be imposed by replacing F with $-F$ if needed. //

($\eta = dF$)
 ($\beta = \mu$)

(b.) For $\dim M = 2$, $d\omega \wedge \omega = 0$ since $\Lambda^3 M \equiv 0$
 thus, by (a.) there exists integrating factor in some nbhd of each pt. on M .

Example 19.14: — (calculations here intend to help with
 P78, currently unsolved,
 Problem 19-4 in Lee) —

D spanned by X and Y

$$X = x \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + x(y+1) \frac{\partial}{\partial z}$$

$$Y = \frac{\partial}{\partial x} + y \frac{\partial}{\partial z}$$

we can calculate $[X, Y] = -Y$.

• Goal, find flat chart at origin

$$\left. \begin{aligned} - X|_0 &= \frac{\partial}{\partial y} \quad \text{and} \quad Y|_0 = \frac{\partial}{\partial x} \end{aligned} \right\} \text{complementary to } \frac{\partial}{\partial z}$$

$$\pi: \mathbb{R}^3 \longrightarrow \mathbb{R}^2 \text{ by } \pi(x, y, z) = (x, y)$$

$$d\pi|_{D(x, y, z)}: D(x, y, z) \longrightarrow T_{(x, y)} \mathbb{R}^2$$

• if we can find smooth local sections V, W that
 are π -related to $\partial/\partial x$ and $\partial/\partial y$ respectively
 so... V, W must be commuting

$$d\pi(V) = \frac{\partial}{\partial x}$$

$$d\pi(W) = \frac{\partial}{\partial y}$$

$$d\pi_p(V) = \frac{\partial}{\partial x} \Big|_{\pi(p)}$$

$$d\pi_p(W) = \frac{\partial}{\partial y} \Big|_{\pi(p)}$$

$$d\pi(\partial_x) = \partial_x$$

$$d\pi(\partial_y) = \partial_y$$

$$d\pi(\partial_z) = 0$$

all from $\pi(x, y, z) = (x, y)$
 so we have freedom to
 put whatever next to ∂_z

p. 182 F -related

$$X(f \circ F) = (Yf) \circ F$$

$$X(f \circ F)(p) = dF_p(X_p)(f)$$

$$dF_p(X_p) = Y_{F(p)}$$

X & Y are
 F -related

$$V = \frac{\partial}{\partial x} + a \frac{\partial}{\partial z}$$

$$W = \frac{\partial}{\partial y} + b \frac{\partial}{\partial z}$$

$$[V, W] = [\partial_x + a \partial_z, \partial_y + b \partial_z]$$

$$= ([V, W]_x) \partial_x + ([V, W]_y) \partial_y + ([V, W]_z) \partial_z$$

$$[V, W]f = (\partial_x + a \partial_z)(\partial_y f + b \partial_z f) - (\partial_y + b \partial_z)(\partial_x f + a \partial_z f)$$

$$= \cancel{\partial_x^2 y f} + \underbrace{(\partial_x b)(\partial_z f)} + \cancel{b \partial_x \partial_z f}$$

$$+ a \underbrace{\partial_z \partial_y f} + \underbrace{a(\partial_z b)(\partial_z f)} + \underline{a b \partial_z^2 f}$$

$$- \cancel{\partial_y \partial_x f} - \underbrace{(\partial_y a)(\partial_z f)} - a \underline{\partial_y \partial_z f} - \cancel{b \partial_z \partial_x f}$$

$$- b \underbrace{(\partial_z a)(\partial_z f)} - \underline{b a \partial_z^2 f}$$

$$= \underbrace{(\partial_x b + a \partial_z b - \partial_y a - b \partial_z a)} \partial_z f$$

needs to be zero for $[V, W] = 0$

Lee suggests setting $a = u = y$
 $b = v = x$

$$V = \frac{\partial}{\partial x} + y \frac{\partial}{\partial z}$$

find flow from $\frac{dx}{dt} = 1, \frac{dy}{dt} = 0, \frac{dz}{dt} = y$

$$W = \frac{\partial}{\partial y} + x \frac{\partial}{\partial z}$$

$\frac{dx}{dt} = 0$
 $\frac{dy}{dt} = 1$
 $\frac{dz}{dt} = x$

$$\begin{cases} x = x_0 + t \\ y = y_0 \\ z = y_0 t + z_0 \end{cases}$$

$$\beta_t(x, y, z) = (x, y+t, tx+z)$$

$$\alpha_t(x, y, z) = (x+t, y, yt+z)$$

following procedure of Example 9.47

$$\begin{aligned}\Phi(u, v, w) &= (\alpha_u \circ \beta_v)(0, 0, w) \\ &= \alpha_u(\beta_v(0, 0, w)) \\ &= \alpha_u(0, v, w) \\ &= (u, v, w + uv)\end{aligned}$$

using flow
formulas
from last pg ↗

$$\Phi(u, v, w) = (x, y, z) = (u, v, w + uv)$$

$\begin{aligned} &\nearrow x = u \\ &\longrightarrow y = v \\ &\searrow z = w + xy \\ &\quad \underline{w = z - xy} \end{aligned}$

$$\Phi^{-1}(x, y, z) = (x, y, z - xy)$$

Show level set of $z - xy$ is $\int$ -manifold of D .

$$F(x, y, z) = z - xy = c$$

$$\omega = dz - y dx + x dy$$

$$\omega(\mathbf{x}) = x(y+1) - yx - x = 0$$

$$\omega(\mathbf{y}) = -y + y = 0$$

$$\therefore \omega(f\mathbf{x} + g\mathbf{y}) = 0$$

$$\Rightarrow \omega|_D = 0$$

$\therefore D$ is
integral to
 $F = c$

$$X = y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y}$$

$$Y = z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z}$$

$$\frac{dx}{dt} = 0 \quad \frac{dz}{dt} = y \quad \frac{dy}{dt} = -z$$

$$-y'' = y$$

$$y = y_0 \cos(t)$$

$$z = +y_0 \sin(t) + z_0$$

$$\gamma_X(t) = (x_0, y_0 \cos t, z_0 + y_0 \sin t)$$

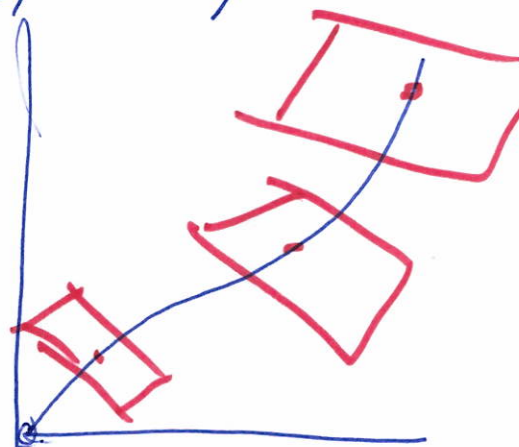
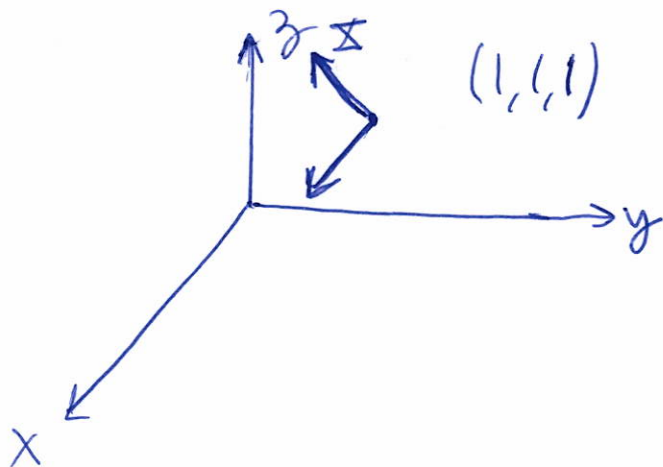
$$\gamma_X(0) = (x_0, y_0, z_0)$$

$$\alpha_u(x, y, z) = (x, y \cos u, z + y \sin u)$$

$$\beta_v(x, y, z) = (x + z \sin v, y, z \cos v)$$

$$\Phi(u, v, w)$$

$$\Phi(u, v, w) = (\alpha_u \circ \beta_v)(w, w, w)$$



$$\textcircled{1} \quad w(\Sigma) = 0 \quad w = ax + by + cz$$

$$\textcircled{2} \quad w(\Upsilon) = 0$$

$$\textcircled{1} \quad yc - zb = 0 \quad yc = bz \hookrightarrow \underline{c = \frac{z}{y}b}$$

$$\textcircled{2} \quad az - cx = 0 \quad cx = az \hookrightarrow a = \frac{x}{z}c$$

$$a = \frac{x}{z} \frac{z}{y} b = \frac{x}{y} b$$

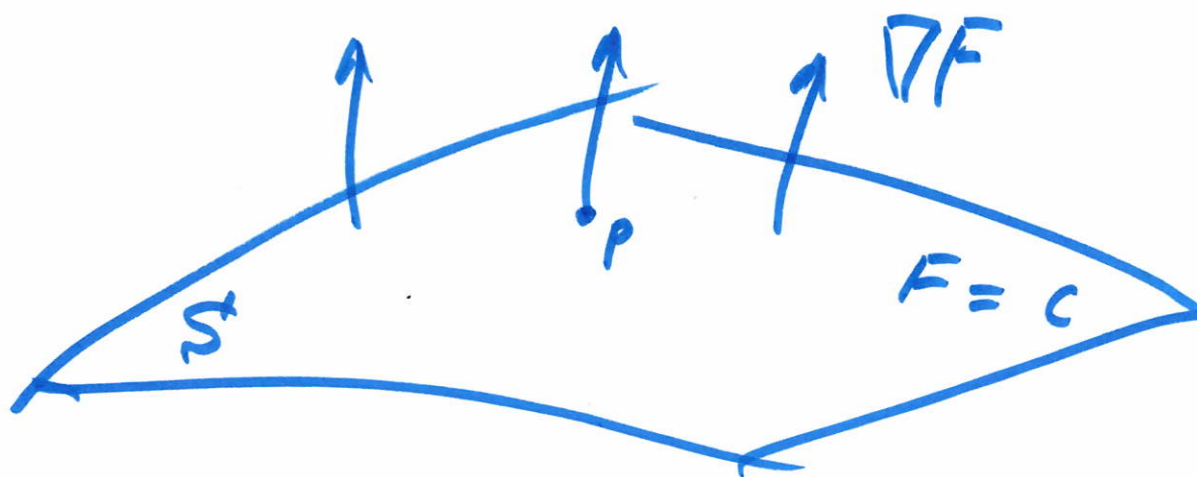
$$w = ax + by + cz$$

$$= \left(\frac{x}{y}\right) b dx + b dy + \frac{z}{y} b dz$$

$$= \frac{b}{\cancel{xy}} \left(\frac{x}{y} dx + dy + \frac{z}{y} dz \right)$$

$$= \frac{b}{y} (x dx + y dy + z dz)$$

$$= \frac{b}{2y} d(x^2 + y^2 + z^2)$$



$$T_p S = (\nabla F)(p)^\perp$$

$$= \text{ann}(W_p)$$

$$= \text{span} \{ \Sigma_u, \Sigma_v \} \leftarrow \text{at } p$$

$p = \Sigma(u, v)$

$$S = \{ (x, y, z) \mid F(x, y, z) = c \} \text{ level surface}$$

$$= \{ \Sigma(u, v) \mid (u, v) \in D \} \text{ parameter}$$

~~is~~

$D \leftarrow$ two-dim'd dist.

$$\Sigma_u, \Sigma_v \in D_p \quad \forall (u, v) \in D$$

$p = \Sigma(u, v)$

$$D_p = \text{ann}(W_p)$$

P79 Problem 19-5

Let D be the distribution on $\mathbb{R}^3$ spanned by

$$X = \frac{\partial}{\partial x} + yz \frac{\partial}{\partial z} \quad Y = \frac{\partial}{\partial y}$$

(a.) find an integral submanifold of D passing through $(0,0,0)$.

(b.) Is D involutive? Explain answer in light of part (a.)

(a.) Consider $S = \{ (x, y, 0) \mid x, y \in \mathbb{R} \}$ (the xy -plane)

then $X|_S = \frac{\partial}{\partial x}$ and $Y|_S = \frac{\partial}{\partial y}$ which are

clearly tangent to $T_p S$ which has basis $\partial_x|_p, \partial_y|_p$

In short S is an integral submanifold of D passing through $(0,0,0)$.

(b.) We can calculate

$$[X, Y] = -z \frac{\partial}{\partial z} \notin D$$

thus D is not involutive on $\mathbb{R}^3$. However,

if we restrict D to S then $D|_S$ is

involutive and in this rather silly case

S itself is the integrable submanifold

(I suppose any subset of S would also do)

Remark: existence of an integral submanifold to D at some point does not imply the existence of integral submanifolds everywhere else. This problem illustrates this phenomenon.

P80 Let G be a Lie group and suppose

$\mathcal{H} \subseteq \mathfrak{g}$. Explain how the Lie subalgebra $\mathcal{H}$ can be used to define an involutive distribution on G

$$T_e G \cong \mathfrak{g} \cong \text{LIVF}(G)$$

We can construct $\mathcal{H} \subseteq \text{LIVF}(G)$ by pushing forward $\mathcal{H} \subseteq T_e G = \mathfrak{g}$. Ok, so, $\exists$ subset of $T_e G$ which is isomorphic to $\mathcal{H}$ as a Lie subalgebra and for $v_0 \in \mathcal{H} \subseteq T_e G$ define $\ell(v_0) \in \mathcal{H}(G)$ by

$$\ell(v_0)(g) = d_e L_g(v_0) \in T_g G$$

But then we could prove if $\ell(v_0), \ell(w_0) \in \mathcal{H}$ then,

$$[\ell(v_0), \ell(w_0)] = \ell[v_0, w_0]$$

and as $v_0, w_0 \in \mathcal{H} \Rightarrow [v_0, w_0] \in \mathcal{H}$ we

find $[\ell(v_0), \ell(w_0)] \in \mathcal{H}$. Thus $\mathcal{H}$ is involutive.

P81 See p. 553 $O(n) = \{A \in \mathbb{R}^{n \times n} \mid A^T A = I\}$

$$S^{n-1} \approx O(n)/O(n-1) \quad \mathbb{R}^n \approx E(n)/O(n) \quad S^{2n-1} \approx \frac{U(n)}{U(n-1)}$$

$$n \geq 2, \quad S^{n-1} \approx SO(n)/SO(n-1) \quad U \approx \frac{SL(2, \mathbb{R})}{SO(2)}$$