

LECTURE 2 : REDUCED ROW ECHELON FORM

①

Let's define the reduced echelon form,

Defⁿ A rectangular matrix is in echelon form if

- (1.) any rows of zeros are below nonzero rows.
- (2.) leading nonzero entries are found on the top row then the leading entries below the top rows are further right than those leading entries above that row.
- (3.) all entries in a column below a leading entry are zero

Furthermore, the matrix is in reduced-row-echelon-form (rref) if the matrix is in echelon form and additionally,

- (4.) the leading entries in each non zero row is 1.

- (5.) each leading 1 is the only nonzero entry in its column.

E1

$$\begin{bmatrix} \textcircled{3} & 6 & 4 & 1 \\ 0 & 0 & \textcircled{2} & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

leading entries are $\textcircled{3}$ and $\textcircled{2}$, this matrix is in ref-form.

E2

$$\begin{bmatrix} 0 & \textcircled{1} & 0 & 3 & 0 \\ 0 & 0 & \textcircled{1} & 4 & 0 \\ 0 & 0 & 0 & 0 & \textcircled{1} \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$e_1 \quad e_2 \quad e_3$

leading entries are $\textcircled{1}$ and that leading $\textcircled{1}$ is only nonzero entry in that column.

(2)

Defⁿ/ The standard basis $e_1, e_2, \dots, e_n$ are column vectors where $(e_i)_j = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$

$$\mathbb{R}^2: e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\mathbb{R}^3: e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\mathbb{R}^4: e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, e_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

I like to understand rref in terms of the standard basis. In particular,

Remark: when a matrix is put into reduced row echelon form with k -nonzero rows then the columns with leading entries will be $e_1, e_2, e_3, \dots, e_k$ found from left to right where e_i is 1st nonzero column.

$$\boxed{E3} \quad \begin{matrix} & & e_1 & & e_2 & & e_3 & e_4 \\ \begin{bmatrix} 0 & 0 & 1 & 3 & 0 & 6 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 7 & 0 & 0 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 4 \end{bmatrix} \end{matrix}$$

we call e_1, e_2, e_3, e_4 the pivot columns

ELEMENTARY ROW OPERATIONS, GAUSS-JORDAN ALGORITHM ③

Our goal is to describe a general strategy to convert any given matrix A into $\text{ref}(A)$.

Defⁿ/ Given a matrix there are three elementary row operations

- (1.) the row swap
- (2.) rescale row by nonzero multiple
(that is multiply by nonzero #)
- (3.) replace r_j with $r_j + ar_i$
(also called row addition)

E4 $A = \begin{bmatrix} 1 & 1 & 1 \\ 3 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{r_1 \leftrightarrow r_2} \begin{bmatrix} 3 & 2 & 1 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} = R_1$

$\swarrow 2r_1$ $\searrow r_2 - 3r_1$

$\begin{bmatrix} 2 & 2 & 2 \\ 3 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} = R_2$ $\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & -2 \\ 0 & 1 & 1 \end{bmatrix} = R_3$

We say $A \sim R_1$ and $A \sim R_2$ and $A \sim R_3$. These notations indicate R_1, R_2, R_3 are row-equivalent to A

Remark: if $[A|b] \sim [R_1|b_1]$ then the original system of equations with aug. coeff. matrix $[A|b]$ has the same solution set as the system of equations with aug. coeff. mat. $[R_1|b_1]$. That is why all 3 row ops are allowed.

THEOREM: GAUSS JORDAN ALGORITHM

Given an $m \times n$ matrix A , there exists a finite sequence of elementary row operations which transforms A into $\text{ref}(A)$ where $A \sim \text{ref}(A)$.

In particular,

- 1.) use row swaps to move all zero rows to lower rows of matrix, continue to do this in any future step which produces a zero row above a non zero row.
- 2.) use row swaps if necessary to move a non zero entry to the topmost row in the leftmost non zero column.
- 3.) identify the non zero entry moved to top row from step 2 as the 1st pivot position, use row addition to zero out all entries below the pivot position.
- 4.) go to next column for which a non zero entry is in the leftmost non zero column, but not the column of the 1st pivot. Once more, use row swaps to move the 2nd non zero entry to row 2. This gives us the 2nd pivot position.
- 5.) use row addition to zero out all entries below the 2nd pivot.



Continuing,

(5)

6.) following same procedure as in 4,
find 3rd pivot position in 3rd row
and then use row addition to
zero out all entries below the 3rd pivot.

7.) this continues until we have produced
 k -pivot positions in the top k -rows
and all rows below the k^{th} row are zero.

(this completes the "forward pass")

8.) starting with the k^{th} pivot, use
row addition to zero out all entries
above the k^{th} pivot until the
 k^{th} column ~~is~~ is simply e_k after rescaling.

9.) repeat step 8.) for $(k-1)$ -th pivot
and $(k-2)$ -th etc... until you reach
the 2nd and finally 1st pivot.
At this point your pivot columns
are $e_1, e_2, \dots, e_k$ found in that
order left to right where e_i is
in the leftmost non zero column.

multiply
pivot
row to
make
leading
entry
1.

10.) conclude, the result from 9 is $\text{rref}(A)$.

(this completes the "backwards pass")

I'll try to follow the algorithm despite my fraction aversion, (6)
(pivot positions)

E5

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 2 & 1 & 1 \\ 1 & 3 & 4 \end{bmatrix} \xrightarrow[r_3 - \frac{1}{2}r_1]{r_2 - r_1} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 5/2 & 7/2 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 5/2 & 7/2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow{r_1 - \frac{2}{5}r_2} \begin{bmatrix} 2 & 0 & -2/5 \\ 0 & 5/2 & 7/2 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow[r_2 \cdot \frac{2}{5}]{r_1/2} \begin{bmatrix} 1 & 0 & -1/5 \\ 0 & 1 & 7/5 \\ 0 & 0 & 0 \end{bmatrix} = \text{rref}(A)$$

E6

$$B = \begin{bmatrix} 0 & 1 & 2 & 0 \\ 0 & 1 & 2 & 3 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow[r_3 - r_1]{r_2 - r_1} \begin{bmatrix} 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow{r_3 - r_2} \begin{bmatrix} 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{r_2/3} \begin{bmatrix} 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \text{rref}(B).$$

E7

$$M = \begin{bmatrix} 1 & 2 & 3 & 4 & 6 & 0 \\ 0 & 0 & 1 & 5 & 7 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 2 & 3 & 4 & 6 & 0 \end{bmatrix} \xrightarrow{r_4 - r_1} \begin{bmatrix} 1 & 2 & 3 & 4 & 6 & 0 \\ 0 & 0 & 1 & 5 & 7 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow[r_2 - 7r_3]{r_1 - 6r_3} \begin{bmatrix} 1 & 2 & 3 & 4 & 0 & 0 \\ 0 & 0 & 1 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{r_1 - 2r_2} \begin{bmatrix} 1 & 0 & 1 & -6 & 0 & 0 \\ 0 & 0 & 1 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \text{rref}(M)$$

(7)

E8 What condition is needed for a, b, c in order for the equations below to be consistent?

$$x - y + 3z = a$$

$$2x + 2z = b$$

$$x + 2y - 3z = c$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 3 & a \\ 2 & 0 & 2 & b \\ 1 & 2 & -3 & c \end{array} \right] \xrightarrow[r_3 - r_1]{r_2 - 2r_1} \left[\begin{array}{ccc|c} 1 & -1 & 3 & a \\ 0 & 2 & -4 & b - 2a \\ 0 & 3 & -6 & c - a \end{array} \right]$$

$$\xrightarrow[2r_3]{3r_2} \left[\begin{array}{ccc|c} 1 & -1 & 3 & a \\ 0 & 6 & -12 & 3b - 6a \\ 0 & 6 & -12 & 2c - 2a \end{array} \right] \xrightarrow{r_3 - r_2} \left[\begin{array}{ccc|c} 1 & -1 & 3 & a \\ 0 & 6 & -12 & 3b - 6a \\ 0 & 0 & 0 & 2c - 2a - (3b - 6a) \end{array} \right]$$

We need $\boxed{4a - 3b + 2c = 0}$

(otherwise we get $0 \cdot x + 0 \cdot y + 0 \cdot z = \text{nonzero}$) $\underbrace{2c - 2a - (3b - 6a)}_{4a - 3b + 2c}$

E9 We can calculate,

$$\text{rref} \left[\begin{array}{ccc|c|c} 1 & -1 & 3 & 1 & 7 \\ 2 & 0 & 2 & 2 & 7 \\ 1 & 2 & -3 & 1 & 7 \end{array} \right] = \left[\begin{array}{ccc|c|c} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right] (*)$$

these
both
follow
from *

$$\text{rref} \left[\begin{array}{ccc|c} 1 & -1 & 3 & 1 \\ 2 & 0 & 2 & 2 \\ 1 & 2 & -3 & 1 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 0 & 1 & 1 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$x - y + 3z = 1$$

$$2x + 2z = 2$$

$$x + 2y - 3z = 1$$

Has solution

$$\{(1 - z, 2z, z) \mid z \in \mathbb{R}\}$$

in consistent system $4a - 3b + 2c \neq 0$

E10 We're given that

$$\text{rref} \begin{bmatrix} 2 & 3 & 1 & 1 \\ 4 & 7 & 8 & 0 \\ 3 & 4 & 4 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 64/11 \\ 0 & 1 & 0 & -40/11 \\ 0 & 0 & 1 & 3/11 \end{bmatrix}$$

Let's interpret this reduction a few ways,

①
$$\begin{aligned} 2x + 3y + z &= 1 \\ 4x + 7y + 8z &= 0 \\ 3x + 4y + 4z &= 4 \end{aligned} \Rightarrow \text{solution is } \left(\frac{64}{11}, \frac{-40}{11}, \frac{3}{11} \right)$$

②
$$\begin{aligned} 2x + 3y &= 1 \\ 4x + 7y &= 8 \\ 3x + 4y &= 4 \end{aligned} \Leftrightarrow \text{rref} \begin{bmatrix} 2 & 3 & 1 \\ 4 & 7 & 8 \\ 3 & 4 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{aligned} 2x + 3y &= 1 \\ 4x + 7y &= 0 \\ 3x + 4y &= 4 \end{aligned} \Leftrightarrow \begin{bmatrix} 2 & 3 & 1 \\ 4 & 7 & 0 \\ 3 & 4 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 64/11 \\ 0 & 1 & -40/11 \\ 0 & 0 & 3/11 \end{bmatrix}$$

(both are inconsistent systems)

③
$$\begin{aligned} 2x_1 + 3x_2 + x_3 + x_4 &= 0 \\ 4x_1 + 7x_2 + 8x_3 &= 0 \\ 3x_1 + 4x_2 + 4x_3 + 4x_4 &= 0 \end{aligned} \Leftrightarrow \text{rref} \begin{bmatrix} 2 & 3 & 1 & 1 & 0 \\ 4 & 7 & 8 & 0 & 0 \\ 3 & 4 & 4 & 4 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 64/11 & 0 \\ 0 & 1 & 0 & -40/11 & 0 \\ 0 & 0 & 1 & 3/11 & 0 \end{bmatrix}$$

we can adjoin column of zeros, it doesn't change the rest of it.

$$x_1 = (-64/11)x_4$$

$$x_2 = (40/11)x_4$$

$$x_3 = (-3/11)x_4$$

$$\text{for any } x_4 \in \mathbb{R}$$

continued $\curvearrowright$

E10 continued

⑨

$$x_1 = -\frac{64}{11} x_4$$

$$x_2 = \frac{40}{11} x_4$$

$$x_3 = -\frac{3}{11} x_4$$

$$\begin{aligned}\text{Solution Set} &= \left\{ \left(-\frac{64}{11}x_4, \frac{40}{11}x_4, -\frac{3}{11}x_4, x_4 \right) \mid x_4 \in \mathbb{R} \right\} \\ &= \left\{ \frac{x_4}{11}(-64, 40, -3, 11) \mid x_4 \in \mathbb{R} \right\} \\ &= \left\{ t(-64, 40, -3, 11) \mid t \in \mathbb{R} \right\} \\ &= \text{span} \{ (-64, 40, -3, 11) \}\end{aligned}$$

Defⁿ/ Given vectors $v_1, v_2, \dots, v_m$ we say

$\sum_{i=1}^m c_i v_i = c_1 v_1 + c_2 v_2 + \dots + c_m v_m$ is
a linear combination of $v_1, \dots, v_m$.

$$\text{span} \{ v_1, v_2, \dots, v_m \} = \left\{ \sum_{i=1}^m c_i v_i \mid c_1, \dots, c_m \in \mathbb{R} \right\}$$

set of all possible
linear combinations of $\{v_1, \dots, v_m\}$

(10)

E11 Write the solution set of

$$x_1 + 3x_2 - 4x_3 + x_4 = 0$$

$$x_2 + 3x_3 + 4x_4 = 0$$

in terms of the span of appropriate vectors.

$$\begin{array}{cccc|c} x_1 & x_2 & x_3 & x_4 & \\ \hline 1 & 3 & -4 & 1 & 0 \\ 0 & 1 & 3 & 4 & 0 \end{array} \xrightarrow{r_2 - r_1} \begin{array}{cccc|c} 1 & 3 & -4 & 1 & 0 \\ 0 & 0 & 10 & 3 & 0 \end{array}$$

$$\xrightarrow{r_1 + \frac{4}{10}r_2} \begin{array}{cccc|c} 1 & 3 & 0 & \frac{11}{5} & 0 \\ 0 & 0 & 10 & 3 & 0 \end{array}$$

$$\xrightarrow{r_2/10} \begin{array}{cccc|c} 1 & 3 & 0 & \frac{11}{5} & 0 \\ 0 & 0 & 1 & \frac{3}{10} & 0 \end{array}$$

$$x_1 + 3x_2 + \frac{11}{5}x_4 = 0$$

$$x_3 + \frac{3}{10}x_4 = 0$$

pivotal variables $\left\{ \begin{array}{l} x_1 = -3x_2 - \frac{11}{5}x_4 \\ x_3 = -\frac{3}{10}x_4 \end{array} \right.$

x_2, x_4 are non-pivotal variables, they're free

$$\begin{aligned} \text{Sol}^n \text{ Set} &= \left\{ (-3x_2 - \frac{11}{5}x_4, x_2, -\frac{3}{10}x_4, x_4) \mid x_2, x_4 \in \mathbb{R} \right\} \\ &= \left\{ x_2(-3, 1, 0, 0) + x_4(-\frac{11}{5}, 0, -\frac{3}{10}, 1) \mid x_2, x_4 \in \mathbb{R} \right\} \\ &= \boxed{\text{span} \{ (-3, 1, 0, 0), (-\frac{11}{5}, 0, -\frac{3}{10}, 1) \}} \end{aligned}$$