

LECTURE 30: REAL SPECTRAL THEOREM

①

This theorem is easy to remember and it gives us great insight,

Th^m (REAL SPECTRAL)

Let $A \in \mathbb{R}^{n \times n}$, $A^T = A \Leftrightarrow A$ has orthonormal eigenbasis.

Proof: (\Rightarrow) Left to another course.

(\Leftarrow) Suppose $\beta = \{v_1, v_2, \dots, v_n\}$ is orthonormal and $Av_j = \lambda_j v_j$ for some $\lambda_1, \dots, \lambda_n \in \mathbb{R}$ (possibly repeated)

then $[\beta]^{-1} = [\beta]^T$ since $([\beta]^T [\beta])_{ij} = v_i \cdot v_j = \delta_{ij}$

and as we've shown in an earlier lecture,

$[\beta]^T A [\beta] = D = \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$. Therefore,

$[\beta][\beta]^T A [\beta][\beta]^T = [\beta] D [\beta]^T \Rightarrow A = [\beta] D [\beta]^T$

and we find $A^T = ([\beta]^T)^T D^T [\beta]^T = [\beta] D [\beta]^T = A$. //

Let's look at an abstract 3×3 example, I'll introduce projection matrices which we can build from the orthonormal eigenbasis.

[E1] Suppose $A \in \mathbb{R}^{3 \times 3}$ with orthonormal eigenbasis v_1, v_2, v_3 with e-values $\lambda_1, \lambda_2, \lambda_3$ respectively,

$$Av_1 = \lambda_1 v_1, \quad Av_2 = \lambda_2 v_2, \quad Av_3 = \lambda_3 v_3$$

Then construct,

$$E_1 = v_1 v_1^T \Rightarrow E_1 v_1 = v_1 v_1^T v_1 = v_1 \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \begin{array}{l} v_1 \cdot v_1 = 1 \\ v_1 \cdot v_2 = 0 \\ v_1 \cdot v_3 = 0 \end{array}$$

$$E_2 = v_2 v_2^T \quad E_1 v_2 = v_1 v_1^T v_2 = 0$$

$$E_3 = v_3 v_3^T \quad E_1 v_3 = v_1 v_1^T v_3 = 0$$

We can argue:

$$A = \lambda_1 E_1 + \lambda_2 E_2 + \lambda_3 E_3$$

Matrices like E_1, E_2, E_3 have special properties which follow from $V_i \cdot V_j = V_i^T V_j = \delta_{ij}$

(2)

Lemma: given orthonormal vectors V_1, V_2, \dots, V_n if we construct $E_i = V_i V_i^T$ for $i=1, 2, \dots, n$ then these matrices have

$$1.) E_i E_j = \delta_{ij} E_i$$

$$2.) E_1 + E_2 + \dots + E_n = I_n$$

Proof: the key is to use $V_i^T V_j = \delta_{ij}$. Consider, for (1.)

$$\begin{aligned} E_i E_j &= (V_i V_i^T)(V_j V_j^T) \\ &= V_i \delta_{ij} V_j^T \\ &= \delta_{ij} V_i V_j^T = \begin{cases} 0 & \text{if } i \neq j \\ V_i V_i^T & \text{if } i = j \end{cases} \\ &= \underline{\delta_{ij} E_i}. \end{aligned}$$

To prove (2.) we note that $A=B$ iff $AV_i = BV_i$ for $i=1, 2, \dots, n$ since V_1, \dots, V_n is basis for \mathbb{R}^n .

Consider then,

$$\begin{aligned} (E_1 + E_2 + \dots + E_n) V_j &= \sum_{i=1}^n E_i V_j \\ &= \sum_{i=1}^n V_i V_i^T V_j \\ &= \sum_{i=1}^n V_i \delta_{ij} \\ &= V_j = I_n V_j \quad \forall j=1, 2, \dots, n \end{aligned}$$

Thus $E_1 + E_2 + \dots + E_n = I_n$ as claimed. //

We also should notice $E_i v_j = v_j v_j^T v_j = \delta_{ij} v_j$
 Thus we find the eigenvalues of E_i are 0 and 1,

Proposition: $\text{Null}(E_i) = \text{span}\{v_j \mid j \neq i\} = E_{\lambda=0}$
 whereas $\text{Null}(E_i - I) = \text{span}\{v_i\}$ thus
 $\dim(\text{Null}(E_i)) = n-1$ and $\dim(\text{Null}(E_i - I)) = 1$

Therefore, we can use E_1, E_2, \dots, E_n as above
 to build a matrix A with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$

\mathbb{R}^n with $E_i = v_i v_i^T$ for v_1, v_2, \dots, v_n orthonormal
 if $\lambda_1, \lambda_2, \dots, \lambda_n \in \mathbb{R}$ then

$$A = \lambda_1 E_1 + \lambda_2 E_2 + \dots + \lambda_n E_n$$
 has eigenvectors v_1, v_2, \dots, v_n with e-values $\lambda_1, \lambda_2, \dots, \lambda_n$.

E2 following E_1 , build (3×3) matrix with
 eigenvalues 6, 7 and -2 by

$$A = 6E_1 + 7E_2 - 2E_3$$

However, this is not unique,

$$B = 7E_1 - 2E_2 + 6E_3$$

there are many ways to build a matrix
 with eigenvalues 6, 7 and -2. For
 given orthonormal basis v_1, v_2, v_3 we
 can build $E_1 = v_1 v_1^T$, $E_2 = v_2 v_2^T$, $E_3 = v_3 v_3^T$

Remark: matrices built as in **E2** will be symmetric.

Let's examine how the Lemma on p. ② works out for the standard basis $e_1, e_2, e_3, \dots, e_n$

④

$$E_1 = e_1 e_1^T = e_1 [1, 0, \dots, 0] = [e_1 | 0 | \dots | 0]$$

$$E_2 = e_2 e_2^T = e_2 [0, 1, \dots, 0] = [0 | e_2 | \dots | 0]$$

\vdots

$$E_n = e_n e_n^T = e_n [0, 0, \dots, 1] = [0 | \dots | 0 | e_n]$$

Of course $E_1 + E_2 + \dots + E_n = [e_1 | e_2 | \dots | e_n] = I_n$. Makes sense.

E3 The matrix $A = \begin{bmatrix} 0 & 0 & -4 \\ 2 & 4 & 2 \\ 2 & 0 & 6 \end{bmatrix}$ has eigenvectors

$$V_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \text{ and } V_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \text{ and } V_3 = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} \text{ with}$$

eigenvalues $\lambda_1 = 4$, $\lambda_2 = 4$ and $\lambda_3 = 2$. We

have $E_{\lambda_1=4} = \text{span}\{V_1, V_2\}$ and $E_{\lambda_3=2} = \text{span}\{V_3\}$.

• Can we obtain an orthonormal basis for $E_{\lambda_1=4}$?

Well, yes, $u_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ and $u_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ gives $E_{\lambda_1=4} = \text{span}\{u_1, u_2\}$

• Can we obtain an orthonormal basis for $E_{\lambda_3=2} = \text{span}\{(-2, 1, 1)\}$?

Again, yes, $E_{\lambda_3=2} = \text{span}\left\{\frac{1}{\sqrt{6}}(-2, 1, 1)\right\}$.

• Can we join our orthonormal basis for E_{λ_1} & E_{λ_3} to form orthonormal basis for $E_{\lambda_1} + E_{\lambda_3} = \mathbb{R}^3$?

No. $A^T \neq A$ so \nexists an orthonormal eigenbasis for A .

$$E_{\lambda_1} \cap E_{\lambda_3} = \{0\} \text{ so } E_{\lambda_1} \oplus E_{\lambda_3} = \mathbb{R}^3$$

However, $(E_{\lambda_1})^\perp \neq E_{\lambda_3}$

Th^m/ Given $A^T = A$ and suppose $\lambda_1, \lambda_2, \dots, \lambda_k$ are distinct eigenvalues with multiplicities n_1, n_2, \dots, n_k then if $E_j = \text{Null}(A - \lambda_j I)$ then $E_1 + E_2 + \dots + E_k = \mathbb{R}^n$ and $(E_j)^\perp = E_1 + \dots + E_{j-1} + E_{j+1} + \dots + E_k$ hence $E_j \cap (E_1 + \dots + E_{j-1} + E_{j+1} + \dots + E_k) = \{0\}$ and $E_1 \oplus E_2 \oplus \dots \oplus E_k = \mathbb{R}^n$ (algebraic = geometric here)

In other words, the eigenspaces of a symmetric matrix form orthogonal complements

E4 $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ has $v_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ with $\lambda_1 = 3$

whereas $\text{Null}(A) = \text{span}\{(1, -1, 0), (1, 0, -1)\}$ show the geometric multiplicity of $\lambda_2 = 0$ is $\nu_2 = 2$.

$E_2 = \text{span}\{(1, -1, 0), (1, 0, -1)\}$
not an orthonormal basis for E_2

Consider,

$$\text{Orth}_{\substack{(1,0,-1) \\ (1,-1,0)}}(1,0,-1) = (1,0,-1) - \frac{(1,-1,0) \cdot (1,0,-1)}{(1,-1,0) \cdot (1,-1,0)} (1,-1,0) = (1,0,-1) - \frac{1}{2}(1,-1,0) = (1 - \frac{1}{2}, \frac{1}{2}, -1) = \frac{1}{2}(1, 1, -2)$$

Hence

$\left\{ \frac{1}{\sqrt{2}}(1, -1, 0), \frac{1}{\sqrt{6}}(1, 1, -2) \right\}$ ← orthonormal basis for E_2

Then $\beta = \left\{ \frac{1}{\sqrt{3}}(1, 1, 1), \frac{1}{\sqrt{2}}(1, -1, 0), \frac{1}{\sqrt{6}}(1, 1, -2) \right\}$ orthonormal eigenbasis for A . (Here $A = 3v_1v_1^T + 0v_2v_2^T + 0v_3v_3^T$)

Next Lecture we apply the Real Spectral Th^m to study quadratic forms. Let's examine one example here to get started.

⑥

ES Consider the formula

$$Q(x, y, z) = 4x^2 + 3y^2 + 4z^2 + 4xy + 2xz + 4yz$$

We can write such formula as the product of $[x, y, z]$ row vector, a symmetric matrix and the column vector $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$,

$$Q(x, y, z) = [x, y, z] \underbrace{\begin{bmatrix} 4 & 2 & 1 \\ 2 & 3 & 2 \\ 1 & 2 & 4 \end{bmatrix}}_A \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

We write $Q(v) = v^T A v$. Some calculation reveals A has orthonormal eigen basis

$$\bar{\beta} = \left\{ \frac{1}{\sqrt{6}}(1, -2, 1), \frac{1}{\sqrt{2}}(1, 0, -1), \frac{1}{\sqrt{3}}(1, 1, 1) \right\}$$

with eigenvalues $\lambda_1 = 1$, $\lambda_2 = 3$, $\lambda_3 = 7$. Recall,

coordinate map $(\bar{x}, \bar{y}, \bar{z}) = \Phi_{\bar{\beta}}(x, y, z) = [\bar{\beta}]^{-1}(x, y, z)$

and since $[\bar{\beta}]^{-1} = [\bar{\beta}]^T$ as $[\bar{\beta}]^T[\bar{\beta}] = I$ for β orthonormal.

(we call such coordinates $\bar{x}, \bar{y}, \bar{z}$ eigencoordinates)

$$\begin{aligned} Q(v) &= v^T A v = v^T [\bar{\beta}][\bar{\beta}]^T A [\bar{\beta}][\bar{\beta}]^T v \\ &= ([\bar{\beta}]^T v) ([\bar{\beta}]^T A [\bar{\beta}]) ([\bar{\beta}]^T v) \\ &= [\bar{x}, \bar{y}, \bar{z}] \begin{bmatrix} 1 & & \\ & 3 & \\ & & 7 \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \\ \bar{z} \end{bmatrix} = \bar{x}^2 + 3\bar{y}^2 + 7\bar{z}^2 \end{aligned}$$

Remark: $\bar{x}^2 + 3\bar{y}^2 + 7\bar{z}^2 = 1$ is clearly an ellipsoid,

$4x^2 + 3y^2 + 4z^2 + 4xy + 2xz + 4yz = 1$ is not clearly anything. Changing to eigen coordinates uncouples terms, it removes cross-terms.