

LECTURE 31: DIAGONALIZATION OF QUADRATIC FORMS

①

Let's begin with what we mean by "quadratic form"

Defⁿ/ If $Q: \mathbb{R}^n \rightarrow \mathbb{R}$ is given by $Q(v) = v^T A v$ where A is a symmetric matrix then we say Q is a quadratic form with matrix $[Q] = A$.

We insist the matrix of Q is symmetric so that we know $A = [Q]$ is orthogonally diagonalizable.

$$\boxed{E1} \quad Q(x, y) = x^2 + y^2 + 2xy = [x, y] \underbrace{\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}}_{[Q]} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\boxed{E2} \quad Q(x, y, z) = x^2 + 2y^2 + 3z^2 + 6xz - 4yz$$
$$= [x, y, z] \underbrace{\begin{bmatrix} 1 & 0 & 3 \\ 0 & 2 & -2 \\ 3 & -2 & 3 \end{bmatrix}}_{[Q]} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$\boxed{E3} \quad Q(x) = x_1^2 + 3x_3^2 + 5x_5^2 - x_1 x_5 \quad \text{for } x \in \mathbb{R}^5$$

gives $[Q] = \begin{bmatrix} 1 & 0 & 0 & 0 & -\frac{1}{2} \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ -\frac{1}{2} & 0 & 0 & 0 & 5 \end{bmatrix}$ and $Q(x) = x^T [Q] x$.

$$\boxed{E4} \quad Q(x, y, z) = x^2 - y^2 + 3xz$$
$$= [x, y, z] \underbrace{\begin{bmatrix} 1 & 0 & \frac{3}{2} \\ 0 & -1 & 0 \\ \frac{3}{2} & 0 & 0 \end{bmatrix}}_{[Q]} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Thm/ If $Q: \mathbb{R}^n \rightarrow \mathbb{R}$ is quadratic form with matrix $A = [Q]$ and $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n$ is an orthonormal eigenbasis for A which defines eigencoordinates $(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n) = \bar{x}$ by $\bar{x} = [\bar{\beta}]^T x$ where $\bar{\beta} = \{\bar{v}_1, \dots, \bar{v}_n\}$ then

$$Q(x) = \lambda_1 \bar{x}_1^2 + \lambda_2 \bar{x}_2^2 + \dots + \lambda_n \bar{x}_n^2$$

where $\lambda_1, \lambda_2, \dots, \lambda_n$ are e-values of v_1, \dots, v_n respective.

Proof: Suppose $Q(x) = x^T A x$ where $A^T = A$. Let $\bar{\beta} = \{\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n\}$ be the orthonormal e-basis with e-values $\lambda_1, \lambda_2, \dots, \lambda_n$ for A as given by the real spectral Th^m. Recall $[\bar{\beta}]^T A [\bar{\beta}] = \text{Diag}(\lambda_1, \dots, \lambda_n) = D$.

Consider,

$$\begin{aligned} Q(x) &= x^T A x \\ &= x^T [\bar{\beta}] [\bar{\beta}]^T A [\bar{\beta}] [\bar{\beta}]^T x \\ &= ([\bar{\beta}]^T x) D ([\bar{\beta}]^T x) \\ &= \bar{x}^T D \bar{x} \\ &= [\bar{x}_1, \dots, \bar{x}_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \begin{bmatrix} \bar{x}_1 \\ \vdots \\ \bar{x}_n \end{bmatrix} \\ &= \underline{\lambda_1 \bar{x}_1^2 + \lambda_2 \bar{x}_2^2 + \dots + \lambda_n \bar{x}_n^2} \quad \bullet // \end{aligned}$$

Level Curves of the form $ax^2 + 2bx + cy^2 = k$

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$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 \quad \text{ellipse}$$

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = \pm 1 \quad \text{hyperbola}$$

$$\frac{x^2}{a^2} = 1 \quad \text{pair of lines (vertical)}$$

$$\frac{y^2}{b^2} = 1 \quad \text{pair of horizontal lines}$$

The curves above show the different cases which can arise for the solution set of $ax^2 + 2bx + cy^2 = 1$. If we allow $k = 0$ or $k = -1$ we may get no solution ($x^2 + y^2 = -1$) or pair of lines ($x^2 - y^2 = 0$ gives $y = \pm x$). Observe

$$ax^2 + 2bx + cy^2 = [x, y] \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \lambda_1 \bar{x}^2 + \lambda_2 \bar{y}^2$$

we can relate

$$ax^2 + 2bx + cy^2 = 1$$

to either an ellipse, hyperbola or pair of lines. If

we picture \bar{x}, \bar{y} - coordinate axes then sketching is easy on basis of past graphing of ellipses, hyperbolas and lines.

ES $Q(x,y) = 4xy = 1$

Write the equation above using eigencoordinates (\bar{x}, \bar{y}) and graph the \bar{x}, \bar{y} axes and the curve, what is it?

$A = \begin{bmatrix} 0 & 2 \\ 2 & 0 \end{bmatrix} \rightarrow \det \begin{bmatrix} -\lambda & 2 \\ 2 & -\lambda \end{bmatrix} = \lambda^2 - 4 = (\lambda+2)(\lambda-2) = 0$
 $\therefore \lambda_1 = -2, \lambda_2 = 2$

$\lambda_1 = -2 \mid A + 2I = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \rightarrow v_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ (e-vector with $\lambda_1 = -2$)

$\lambda_2 = 2 \mid A - 2I = \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix} \rightarrow v_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ($\lambda_2 = 2$ e-vector)

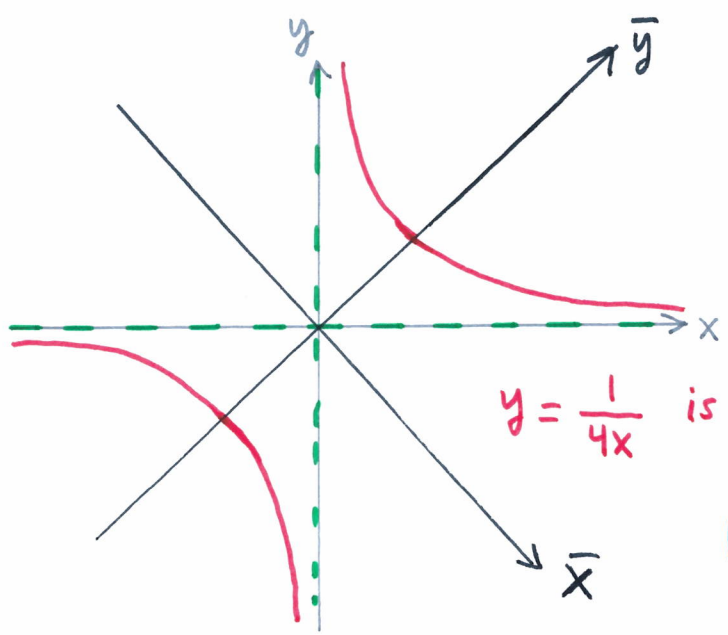
$[\beta] = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \Rightarrow [\beta]^{-1} = [\beta]^T = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$

Thus $\begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} x-y \\ x+y \end{bmatrix}, \bar{x} = \frac{x-y}{\sqrt{2}}, \bar{y} = \frac{x+y}{\sqrt{2}}$

and $\begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} \bar{x} + \bar{y} \\ -\bar{x} + \bar{y} \end{bmatrix}, x = \frac{\bar{x} + \bar{y}}{\sqrt{2}}, y = \frac{\bar{y} - \bar{x}}{\sqrt{2}}$

Observe $4xy = 1 \Rightarrow 4 \left[\frac{\bar{x} + \bar{y}}{\sqrt{2}} \right] \left[\frac{\bar{y} - \bar{x}}{\sqrt{2}} \right] = 2(\bar{y}^2 - \bar{x}^2) = 1$

hyperbola, with asymptotes $\bar{y} = \pm \bar{x}$
a.k.a. $y=0, x=0$.



$y = \frac{1}{4x}$ is a hyperbola

(Remark: $\bar{x} > 0$ in V_1 -direction
 $\bar{y} > 0$ in V_2 -direction)

E6

Consider $Q(x,y) = x^2 - 2xy + 3y^2 = 1$
describe the curve, no need to explicitly
change coordinates, but find the formula
for $Q(x,y) = 1$ in eigencoordinates \bar{x}, \bar{y}

$$[Q] = \begin{bmatrix} 1 & -1 \\ -1 & 3 \end{bmatrix}$$

$$\det \begin{bmatrix} 1-\lambda & -1 \\ -1 & 3-\lambda \end{bmatrix} = (\lambda-1)(\lambda-3) - 1 = \lambda^2 - 4\lambda + 2 \\ = (\lambda-2)^2 - 2 \\ = (\lambda-2+\sqrt{2})(\lambda-2-\sqrt{2})$$

We find $\lambda_1 = 2 - \sqrt{2}$

$$\lambda_1 = 2 - \sqrt{2} \quad \text{and} \quad \lambda_2 = 2 + \sqrt{2}$$

Thus,

$$Q(x,y) = (2 - \sqrt{2})\bar{x}^2 + (2 + \sqrt{2})\bar{y}^2 = 1$$

ellipse since $\lambda_1, \lambda_2 > 0$.

E7

Describe the curve $x^2 + 4xy - 3y^2 = 1$

$$x^2 + 4xy - 3y^2 = [x, y] \underbrace{\begin{bmatrix} 1 & 2 \\ 2 & -3 \end{bmatrix}}_A \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\det(A - \lambda I) = \det \begin{pmatrix} 1-\lambda & 2 \\ 2 & -3-\lambda \end{pmatrix} = (\lambda-1)(\lambda+3) - 4 \\ = \lambda^2 + 2\lambda - 7 \\ = (\lambda+1)^2 - 8 \\ = (\lambda+1+\sqrt{8})(\lambda+1-\sqrt{8})$$

Thus $\lambda = -1 \pm \sqrt{8}$ are e-values for A,

$$x^2 + 4xy - 3y^2 = (\sqrt{8}-1)\bar{x}^2 + (-1-\sqrt{8})\bar{y}^2 = 1$$

hyperbola

OPTIMIZATION OF MULTIVARIATE FUNCTIONS

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If we consider $f: \mathbb{R}^n \rightarrow \mathbb{R}$ then the multivariate Taylor's T_h^m gives a multivariate power series for $f(x)$ about some point $P \in \mathbb{R}^n$. *quadratic form!*

$$f(x) = f(P) + \nabla f(P) \cdot (x-P) + \frac{1}{2} Q(x-P) + \dots$$

Here we have just written the expansion to 2nd order,

$$\nabla f(P) = \left\langle \frac{\partial f}{\partial x_1}(P), \frac{\partial f}{\partial x_2}(P), \dots, \frac{\partial f}{\partial x_n}(P) \right\rangle \text{ (gradient)}$$

$$[Q] = \left[\frac{\partial^2 f}{\partial x_i \partial x_j}(P) \right] \text{ (Hessian Matrix)}$$

Extreme values for f occur locally at points P where $\nabla f(P) = 0$ (critical point). If we write $x - P = h$ at such a point then

$$\begin{aligned} f(P+h) &= f(P) + \frac{1}{2} Q(h) + \dots \\ &= f(P) + \frac{1}{2} (\lambda_1 \bar{h}_1^2 + \lambda_2 \bar{h}_2^2 + \dots + \lambda_n \bar{h}_n^2) + \dots \end{aligned}$$

$f(P)$ is local max if $\lambda_1, \lambda_2, \dots, \lambda_n < 0$

$f(P)$ is local min if $\lambda_1, \lambda_2, \dots, \lambda_n > 0$

If any $\lambda_j = 0$ then we cannot use quadratic analysis to discern nature of extremal point.

The $n = 2$ case is covered in Calculus III,

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$$[Q] = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{xy} & f_{yy} \end{bmatrix} = A$$

$$\det \begin{bmatrix} f_{xx} - \lambda & f_{xy} \\ f_{xy} & f_{yy} - \lambda \end{bmatrix} = (\lambda - f_{xx})(\lambda - f_{yy}) - f_{xy}^2 \\ = \lambda^2 - (f_{xx} + f_{yy})\lambda + f_{xx}f_{yy} - f_{xy}^2$$

$$\det(A) = f_{xx}f_{yy} - f_{xy}^2 = \lambda_1\lambda_2$$

$$\text{trace}(A) = f_{xx} + f_{yy} = \lambda_1 + \lambda_2$$

LOCAL MINIMUM: $\lambda_1, \lambda_2 > 0 \Rightarrow \lambda_1\lambda_2 = D > 0$

LOCAL MAXIMUM: $\lambda_1, \lambda_2 < 0 \Rightarrow \lambda_1\lambda_2 = D > 0$

SADDLE PT.: $\left. \begin{array}{l} \lambda_1 < 0, \lambda_2 > 0 \\ \lambda_1 > 0, \lambda_2 < 0 \end{array} \right\} \lambda_1\lambda_2 = D < 0$

$$\lambda_1, \lambda_2 > 0 \Rightarrow f_{xx} + f_{yy} > 0 \Rightarrow f_{xx} > 0 \text{ (min.)}$$

$$\lambda_1, \lambda_2 < 0 \Rightarrow f_{xx} + f_{yy} < 0 \Rightarrow f_{xx} < 0 \text{ (max.)}$$

We recover the usual 2nd derivative test from Calc III.

Notice, $n \geq 3$ allows no such nice test

since $\det [Q] = \lambda_1\lambda_2\lambda_3$ positive or negative

does not nicely reveal signs of $\lambda_1, \lambda_2, \lambda_3$

separately. But, with linear algebra we get

the test's replacement: find e-values of $[Q]$

if all positive then min, if all negative then max.

CONSTRAINED OPTIMIZATION ON n -sphere

8

The unit-circle is the 1-sphere S^1 given by $x^2 + y^2 = 1$.

The unit-sphere is the 2-sphere S^2 given by $x^2 + y^2 + z^2 = 1$

The 3-sphere S^3 is given by $x_1^2 + x_2^2 + x_3^2 + x_4^2 = 1$

Generally,

$$\text{Def}^n / S^n = \{x \in \mathbb{R}^{n+1} \mid x \cdot x = 1\} \subseteq \mathbb{R}^{n+1}$$

Thⁿ / any quadratic form on \mathbb{R}^{n+1} is uniquely extended from its values on S^n . Moreover, the maximum and minimum values of $Q: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ restricted to S^n are specified by the largest and smallest eigenvalues of $[Q]$

Proof: given any $x \in \mathbb{R}^{n+1}$ with $x \neq 0$ we can write $x = \|x\| \hat{x}$ where $\hat{x} = \frac{1}{\|x\|} x$ is the unit-vector in the direction of x . Notice $\hat{x} \cdot \hat{x} = \frac{1}{\|x\|^2} x \cdot x = \frac{x \cdot x}{x \cdot x} = 1$, thus $\hat{x} \in S^n$. If $Q(x) = x^T A x$ then,

$$\begin{aligned} Q(x) &= (\|x\| \hat{x})^T A \|x\| \hat{x} \\ &= \|x\|^2 \hat{x}^T A \hat{x} \\ &= \|x\|^2 Q(\hat{x}) \end{aligned}$$

values of $Q|_{S^n}$
fix the action
of Q on all of
space.

Since $A^T = A$ the real spectral Thⁿ gives unit-vectors $v_1, v_2, \dots, v_{n+1} \in S^n$ and so $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_{n+1}$ if $u \in S^n$ and $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_{n+1}$

$$Q(u) = \lambda_1 \bar{u}_1^2 + \lambda_2 \bar{u}_2^2 + \dots + \lambda_{n+1} \bar{u}_{n+1}^2$$

has $Q(\pm v_1) = \lambda_1 \leq Q(u) \leq Q(\pm v_{n+1}) = \lambda_{n+1}$.

E8 $Q(v) = v^T A v$ with $A = \begin{bmatrix} 0 & -1 & 1 \\ -1 & 2 & -1 \\ 1 & -1 & 0 \end{bmatrix}$

has eigenvectors $v_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$, $v_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $v_3 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$

with $\lambda_1 = -1$, $\lambda_2 = 0$, $\lambda_3 = 3$. It

follows that $-1 \leq 2y^2 - 2xy + 2xz - 2yz \leq 3$

for all $(x, y, z) \in S^2$. We can check,

$v = (x, y, z) = \frac{\pm 1}{\sqrt{2}} (1, 0, -1)$ gives $Q(v) = \frac{2(-1)(1)}{2} = -1$.

$v = \frac{\pm 1}{\sqrt{6}} v_3 = \frac{\pm 1}{\sqrt{6}} (1, -2, 1)$ gives $Q(v) = \frac{8+4+2+4}{6} = 3$.

E9 $Q(x, y, z) = 11x^2 + 11y^2 + 3z^2 - 12xy + 4xz + 4yz$

has matrix $[Q] = \begin{bmatrix} 11 & -6 & 2 \\ -6 & 11 & 2 \\ 2 & 2 & 3 \end{bmatrix}$ with $\lambda_1 = 1$,

$\lambda_2 = 7$ and $\lambda_3 = 17$. It follows that

$1 \leq 11x^2 + 11y^2 + 3z^2 - 12xy + 4xz + 4yz \leq 17$

for all $(x, y, z) \in S^2$.

Remark: Since $Q(cx) = (cx)^T A cx = c^2 x^T A x = c^2 Q(x)$

it follows $Q(\|x\| \hat{x}) = \|x\|^2 Q(\hat{x}) = Q(x)$ so for $\|x\| \leq 1$

we find $Q(x) = \|x\|^2 Q(\hat{x}) \leq Q(\hat{x})$. This means

the inequalities in **E8** and **E9** extend to the

interior of S^2 , that is $0 \leq x^2 + y^2 + z^2 \leq 1$.

unit-ball

Of course this is also true for higher dim'l examples, the e-values for $Q(x) = x^T A x$ give min/max for values of $Q(x)$ for any $x \in \mathbb{R}^{n+1}$ with $\|x\| \leq 1$.