

GENERAL SOLUTION OF THE n^{th} ORDER CONSTANT COEFFICIENT ODE $_g^2$

- PAGES (17) $\rightarrow$ (30) OF MY NOTES EXPLORE THIS QUESTION AND MORE, THE PURPOSE OF THESE NOTES IS TO EMPHASIZE THE LOGIC WITHIN THOSE NOTES, HERE I'LL SIMPLY COLLECT THE MAIN IDEAS AND ASSEMBLE THEM TO DERIVE THE SOL n TO THE n^{th} ORDER LINEAR CONST. COEFF. ODE.

GOAL: Given that $a_0, a_1, a_2, \dots, a_n$ are real constants find general sol n of

$$a_n \frac{d^n y}{dx^n} + a_{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots + a_2 \frac{d^2 y}{dx^2} + a_1 \frac{dy}{dx} + a_0 y = 0 \quad \text{Eq}^2 \text{ (I)}$$

EXAMPLE: $y'' + 5y' + 6y = 0$

$$\lambda^2 + 5\lambda + 6 = 0$$

$$(\lambda + 3)(\lambda + 2) = 0 \quad \therefore \lambda_1 = -3, \lambda_2 = -2$$

therefore (by things we'll derive today)

$$y = C_1 e^{-3x} + C_2 e^{-2x}$$

Many of you did these in calc II

OBSERVATION (1): Eq 2 (I) can be rewritten as an operator eq n ; $L[y] = 0$
where $L = a_n D^n + a_{n-1} D^{n-1} + \dots + a_2 D^2 + a_1 D + a_0$ with $D \equiv d/dx$.

EXAMPLE: $y'' + 5y' + 6y = 0 \iff (D^2 + 5D + 6)y = 0$
 $\iff L = D^2 + 5D + 6$ and $L[y] = 0$.

CLAIM (1): THE L FROM Eq 2 (I) CAN BE FACTORED INTO n -factors
 $L = L_1 \circ L_2 \circ \dots \circ L_n$ so $L[y] = L_1(L_2(\dots(L_n(y))\dots)) = 0$.

EXAMPLE: $L = D^2 + 5D + 6 = (D + 3)(D + 2) = L_1 L_2$

OBSERVATION ②: If $L_k[y] = 0$ for some particular k with $1 \leq k \leq n$ then y is also a solⁿ to $L[y] = L_1 L_2 \dots L_n[y] = 0$.

Example: $y_1 = e^{-3x}$ solves $L_1[y] = (D+3)[y] = 0$
 since $(D+3)[e^{-3x}] = -3e^{-3x} + 3e^{-3x} = 0$. Notice
 that $L[e^{-3x}] = (D+2)(D+3)e^{-3x} = (D+2)(0) = 0$.

Remark: OBSERVATION ② says that we can break-up the n^{th} order ODE into n -parts. If we can solve $L_k[y] = 0$ for $k=1, 2, \dots, n$ then we'll get n -solⁿs to $E_y \equiv \mathbb{I}$.

CLAIM ②: ACTUALLY A FEW CLAIMS,

(i.) A linear combination of solⁿs to $L[y] = 0$ is a solⁿ.
 $L[y_k] = 0 \quad k=1, 2, 3, \dots, n \Rightarrow L[c_1 y_1 + c_2 y_2 + \dots + c_n y_n] = 0$
 where $c_1, c_2, \dots, c_n$ are constants.

(ii.) The general solⁿ to $L[y] = 0$ has the form

$$y = c_1 y_1 + c_2 y_2 + \dots + c_n y_n$$

where $y_1, y_2, \dots, y_n$ are n - "linearly independent" functions.

Example: $L = (D+3)(D+2) = L_1 L_2$ has $L_1[e^{-3x}] = 0$ and $L_2[e^{-2x}] = 0$
 so $L[e^{-3x}] = 0$ and $L[e^{-2x}] = 0 \Rightarrow y = c_1 e^{-3x} + c_2 e^{-2x}$ solves $L[y] = 0$.
 Moreover, since $y_1 = e^{-3x}$ and $y_2 = e^{-2x}$ are linearly independent
 we have the general solⁿ.

Remark: linear independence is an important concept which we elaborate on further in future lectures. For now, simply take it to mean that the functions are distinct (they have graphs which have different shapes).

OBSERVATION ③: The L from $E_y^2(\mathbb{I})$ may be factored into the form

$$L = a_n (D - \lambda_n)(D - \lambda_{n-1}) \cdots (D - \lambda_3)(D - \lambda_2)(D - \lambda_1)$$

where $\lambda_1, \lambda_2, \dots, \lambda_n$ are n -constants. These constants may be real or complex and possibly $\lambda_1 = \lambda_2$ etc.... If there are complex roots then they come in conjugate pairs. (if $\lambda_1 = 3+i$ then $\lambda_2 = 3-i$ for example)

CLAIM ③: for any $\lambda \in \mathbb{C}$, $(D - \lambda)[y] = 0$ has the solⁿ. $y = e^{\lambda x}$

Proof: $(D - \lambda)[e^{\lambda x}] = \frac{d}{dx}(e^{\lambda x}) - \lambda e^{\lambda x}$
 $= \lambda e^{\lambda x} - \lambda e^{\lambda x}$
 $= 0. //$

: I explain the details of when $\lambda \in \mathbb{C}$ on pg. 295. Short story, in $\mathbb{C}$ calculus works the same for functions $f: \mathbb{R} \rightarrow \mathbb{C}$.

CLAIM ④: $(D - \lambda)^2[y] = 0$ has the solⁿ $y_2 = x e^{\lambda x}$ and $y_1 = e^{\lambda x}$

Proof: $(D - \lambda)^2[x e^{\lambda x}] = (D - \lambda)\left[\frac{d}{dx}(x e^{\lambda x}) - \lambda x e^{\lambda x}\right]$
 $= (D - \lambda)[e^{\lambda x} + x \lambda e^{\lambda x} - \lambda x e^{\lambda x}]$
 $= (D - \lambda)[e^{\lambda x}]$
 $= 0. //$

CLAIM ⑤: $(D - \lambda)^m[y] = 0$ has m -solⁿ's

$$y_m = x^{m-1} e^{\lambda x}, y_{m-1} = x^{m-2} e^{\lambda x}, \dots, y_2 = x e^{\lambda x}, y_1 = e^{\lambda x}$$

Remark: these solⁿ's $y_m, y_{m-1}, \dots, y_2, y_1$ are linearly independent.

Sometimes they are complex solⁿ's, we wish to find real solⁿ's. This requires a little discussion $\rightarrow$

CLAIM: ⑥ If y is a complex-valued solⁿ to $L[y] = 0$ where $y = \operatorname{Re}(y) + i \operatorname{Im}(y)$ then both $y_1 = \operatorname{Re}(y)$ and $y_2 = \operatorname{Im}(y)$ are real-valued solⁿ's to $L[y] = 0$. Hence, every complex solⁿ has two (linearly independent) real solⁿ's.

Example: $y'' + y = 0 \Leftrightarrow (D^2 + 1)[y] = 0$
 $\Leftrightarrow (D - i)(D + i)[y] = 0$

now $(D - i)[y]$ has solⁿ $y = e^{ix}$. By Euler's Identity we have that $e^{ix} = \cos(x) + i \sin(x)$. Thus

$$y = \cos(x) + i \sin(x)$$

we can read off that $\operatorname{Re}(y) = \cos(x)$ & $\operatorname{Im}(y) = \sin(x)$.

These real solⁿ's give us the general solⁿ $y = C_1 \cos(x) + C_2 \sin(x)$.

What about $(D + i)$ you ask? Well that factor gives the same solⁿ's since $(D + i)[y] = 0 \Rightarrow y = e^{-ix}$.

then $y = e^{-ix} = \cos(-x) + i \sin(-x) = \cos(x) - i \sin(x)$

and we can read-off $\operatorname{Re}(y) = \cos(x)$ and $\operatorname{Im}(y) = -\sin(x)$.

These are the "same" (upto linear independence) functions we already found from $(D - i)$.

— Digression to answer common question. —

PROPERTIES OF COMPLEX EXPONENTIAL

If $\lambda = \alpha + i\beta$ then we find

$$e^{\lambda x} = e^{(\alpha + i\beta)x} = e^{\alpha x} e^{i\beta x} = e^{\alpha x} (\cos \beta x + i \sin \beta x)$$

then $e^{\lambda x} = e^{\alpha x} \cos \beta x + i e^{\alpha x} \sin \beta x$ and we can see

$\operatorname{Re}(e^{\lambda x}) = e^{\alpha x} \cos \beta x$	$\operatorname{Im}(e^{\lambda x}) = e^{\alpha x} \sin \beta x$
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(see the Intro. to Complex Notes for more details on Euler's Identity)

Remark: CLAIM 6 for $\lambda = \alpha + i\beta$ (here α, β are assumed to be real) we find two real solⁿ's hidden inside $y = e^{\lambda x}$ namely

$$y_1 = \operatorname{Re} y = e^{\alpha x} \cos \beta x$$

$$y_2 = \operatorname{Im} y = e^{\alpha x} \sin \beta x$$

the general solⁿ to $(D-\lambda)(D-\lambda^*)[y]=0$ is $y = C_1 e^{\alpha x} \cos \beta x + C_2 e^{\alpha x} \sin \beta x$.

(Here $\lambda^* = \alpha - i\beta$, the factor $(D-\lambda^*)$ has same solⁿ's as $D-\lambda$ so it is sufficient to find the solⁿ's to $D-\lambda$.)

— again the digression —

CLAIM 7 If we have a complex solⁿ $y = x^m e^{\lambda x}$

then there are two real solⁿ's hidden inside y , namely $\operatorname{Re} y$ and $\operatorname{Im} y$ which we can easily calculate

$$y_1 = \operatorname{Re} y = x^m e^{\alpha x} \cos \beta x$$

$$y_2 = \operatorname{Im} y = x^m e^{\alpha x} \sin \beta x$$

where again we have assumed $\lambda = \alpha + i\beta$ for $\alpha, \beta \in \mathbb{R}$.

Concluding Thoughts: we see. Egⁿ ① can be rewritten in terms of a polynomial in $D = d/dx$ that is $L = P(D)$ where $P(D) = a_n D^n + \dots + a_2 D^2 + a_1 D + a_0$. Then we factor P which of course reflects the zeroes of $P(D)$. For different types of factors we get either $e^{\alpha x}$, $x^m e^{\alpha x}$, $e^{\alpha x} \cos \beta x$, $e^{\alpha x} \sin \beta x$ or $x^m e^{\alpha x} \cos \beta x$ or $x^m e^{\alpha x} \sin \beta x$. There will be n of these functions which we can then use to form the general solⁿ.

Observation: We can factor $P(\lambda)$ instead of $P(D)$, get same roots!

$$\begin{aligned} P(e^{\lambda x}) &= a_n D^n e^{\lambda x} + \dots + a_2 D^2 e^{\lambda x} + a_1 D e^{\lambda x} + a_0 e^{\lambda x} \\ &= a_n \lambda^n e^{\lambda x} + \dots + a_2 \lambda^2 e^{\lambda x} + a_1 \lambda e^{\lambda x} + a_0 e^{\lambda x} \\ &= (a_n \lambda^n + \dots + a_2 \lambda^2 + a_1 \lambda + a_0) e^{\lambda x} \\ &= P(\lambda) e^{\lambda x} \therefore \boxed{P(e^{\lambda x}) = 0 \iff P(\lambda) = 0} \end{aligned}$$