

## THEORY OF LINEAR ODE's

These notes are based on chapters 4 & 6 of your text, rather than revisiting the 2<sup>nd</sup> order case alone, we treat it as a subcase of the n<sup>th</sup> order ODE theory. I have notes on 2<sup>nd</sup> order linear constant coefficient ODE's from ma 241, those are posted for review, although we will again discuss them here. Chapter 4 of the text does an excellent job on the 2<sup>nd</sup> order case alone.

Defn/  $Y^{(n)}(x) + P_1(x) Y^{(n-1)}(x) + \dots + P_n(x) Y(x) = g(x)$  (\*)  
 is a linear ordinary differential eq<sup>n</sup> in standard form.

- We usually assume  $P_i(x)$  and  $g(x)$  are continuous on some interval  $I \subseteq \mathbb{R}$ .
- When  $P_1(x), P_2(x), \dots, P_n(x)$  are all constants w.r.t.  $x$  this is said to be an n<sup>th</sup> order constant coefficient ODE.
- When  $g(x) \equiv 0$  this is a homogeneous ODE, otherwise if  $g(x) \neq 0$  for some  $x \in I$  (not necessarily all of  $I$ , just a point or two will do it) we say the DE  $g(x)$  is nonhomogeneous
- When  $g(x)$  is nontrivial we define the auxiliary eq<sup>n</sup> to be,

$$Y^{(n)}(x) + P_1(x) Y^{(n-1)}(x) + \dots + P_n(x) Y(x) = 0$$

Sol<sup>n</sup>'s to the auxiliary eq<sup>n</sup> play an important role in finding sol<sup>n</sup>'s to the DE  $g(x)$ . It is important to note that sol<sup>n</sup>'s to the auxiliary eq<sup>n</sup> are not sol<sup>n</sup>'s to  $(*)$ .

Th<sup>n</sup> Suppose that  $P_1, P_2, \dots, P_n, g$  are continuous functions on  $(a, b)$  that contains  $x_0$ . Then the following IVP has a unique sol<sup>a</sup> on  $(a, b)$ .

$$\boxed{Y^{(n)}(x) + P_1(x)Y^{(n-1)} + \dots + P_n(x)Y(x) = g(x)} \quad (*)$$

$$Y(x_0) = \gamma_0$$

$$Y'(x_0) = \gamma_1$$

$$\vdots$$

$$Y^{(n-1)}(x_0) = \gamma_{n-1}$$

$\left. \begin{array}{l} \\ \\ \end{array} \right\}$  initial conditions

This is the "existence and uniqueness" theorem. It's a little involved to prove, and it doesn't really tell us how to find the sol<sup>a</sup> either. However, it's nice to know that a problem can be solved and we can use this Th<sup>n</sup> to prove other important facts.

### OPERATORS

An operator is a generalization of our notion of ordinary functions. An operator takes functions and maps them to new functions

"usual"  
function

$$x \longrightarrow \boxed{f} \longrightarrow f(x)$$

$$x \in \mathbb{R}$$

$$f(x) \in \mathbb{R}$$

operator  
 $D$

$$f \longrightarrow \boxed{D} \longrightarrow Df$$

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

$$Df: \mathbb{R} \rightarrow \mathbb{R}$$

Technically,  $D$  is also a function-valued function of functions, we call it an operator to draw attention to that fact. We can rewrite a DEg<sup>b</sup> as an operator eq<sup>b</sup>, define

$$L \equiv D^n + P_1 D^{n-1} + \dots + P_n \quad (\text{note } D^n = \underbrace{D \circ D \circ \dots \circ D}_{\text{composition}})$$

Then (\*) is simply  $L[y] = g$ . It is customary to use  $[ ]$  to emphasize the input is a function and  $L$  is an operator which means  $L[y]$  is a new function.

The operator  $L$  is a linear operator. Meaning

Def<sup>n</sup> of  
Linear Operator

- |   |
|---|
| 1.) $L[Y_1 + Y_2 + \dots + Y_m] = L[Y_1] + L[Y_2] + \dots + L[Y_m]$ |
| 2.) $L[cY] = cL[Y]$ for any constant $c$ .                          |

Remark: calculus is full of linear operations, indefinite integration, differentiation, Laplace Transform, ...

Now suppose we have a homogeneous linear  $n^{\text{th}}$  ODE in standard form on some interval  $I$ . We can compactly write it as  $L[Y] = 0$  or putting in the  $x$ -dependence  $L[Y](x) = 0$ . Further suppose we have 2 sol<sup>ns</sup>  $Y_1$  and  $Y_2$  notice,

$$\begin{aligned} L[C_1 Y_1 + C_2 Y_2] &= L[C_1 Y_1] + L[C_2 Y_2] && \text{used 1.} \\ &= C_1 L[Y_1] + C_2 L[Y_2] && \text{used 2.} \\ &= C_1(0) + C_2(0) && \text{using } Y_1, Y_2 \text{ are sol\text{'s}.} \\ &= 0. \end{aligned}$$

This proves  $C_1 Y_1 + C_2 Y_2$  is also a sol<sup>n</sup>. So then we might wonder how many "independent" sol<sup>ns</sup> are there for an  $n^{\text{th}}$  order homog. linear ODE?

PROPOSITION: Every sol<sup>n</sup> to  $L[Y](x) = 0$  has the form  $Y = C_1 Y_1 + C_2 Y_2 + \dots + C_n Y_n$ , where  $L[Y_i](x) = 0$   $i=1,2,\dots,n$

- in other words an  $n^{\text{th}}$  order linear ODE has a general sol<sup>n</sup> formed from  $n$ -fundamental sol<sup>ns</sup>  $Y_1, \dots, Y_n$ . Also  $\{Y_1, Y_2, \dots, Y_n\}$  is the fundamental sol<sup>n</sup> set. Well, we need to require that  $Y_1, Y_2, \dots, Y_n$  are really not just the same function, I mean they should be genuinely independent like  $x$  and  $e^x$  or  $\sin(x)$  and  $3$  as opposed to say  $x$  and  $3x$ , those are the same. (the functions  $Y_1, \dots, Y_n$  must be linearly independent, jumping ahead a bit.)

Proof of Prop.: Study  $[D^n + P_1 D^{n-1} + \dots + P_n][Y] = 0$ . Suppose that we have an arbitrary sol<sup>12</sup>  $\phi(x)$  on  $(a, b)$ . We seek to show  $\phi(x) = C_1 Y_1 + C_2 Y_2 + \dots + C_n Y_n$  for appropriate choice of  $C_1, C_2, \dots, C_n$  (constants). Let  $x_0 \in (a, b)$  and consider that if we can satisfy the system of eq<sup>13</sup>,

$$C_1 Y_1(x_0) + C_2 Y_2(x_0) + \dots + C_n Y_n(x_0) = \phi(x_0)$$

$$C_1 Y'_1(x_0) + C_2 Y'_2(x_0) + \dots + C_n Y'_n(x_0) = \phi'(x_0)$$

$$\vdots \\ C_1 Y^{(n-1)}(x_0) + C_2 Y^{(n-1)}_2(x_0) + \dots + C_n Y^{(n-1)}_n(x_0) = \phi^{(n-1)}(x_0)$$

then by the existence & uniqueness Th<sup>m</sup> we'll be able to conclude that  $\phi(x) = C_1 Y_1 + \dots + C_n Y_n$  as they both solve the same IVP. We can rewrite  $(**)$  in matrix form

$$AC = \begin{bmatrix} Y_1(x_0) & Y_2(x_0) & \dots & Y_n(x_0) \\ \vdots & & & \vdots \\ Y_1^{(n-1)}(x_0) & Y_2^{(n-1)}(x_0) & \dots & Y_n^{(n-1)}(x_0) \end{bmatrix} \begin{bmatrix} C_1 \\ \vdots \\ C_n \end{bmatrix} = \begin{bmatrix} \phi(x_0) \\ \vdots \\ \phi^{(n-1)}(x_0) \end{bmatrix} = b$$

This is a system of  $n$ -equations with  $n$ -unknowns  $C_1, C_2, \dots, C_n$ . It has a unique sol<sup>14</sup> (no matter what  $\phi(x_0), \dots, \phi^{(n-1)}(x_0)$  might be) provided the matrix  $A$  has  $\det(A) \neq 0$ .

$$\det(A) = \begin{vmatrix} Y_1(x_0) & Y_2(x_0) & \dots & Y_n(x_0) \\ \vdots & & & \vdots \\ Y_1^{(n-1)}(x_0) & Y_2^{(n-1)}(x_0) & \dots & Y_n^{(n-1)}(x_0) \end{vmatrix} \neq 0 \quad \begin{array}{l} \text{(we're using a} \\ \text{well known fact} \\ \text{from linear algebra)} \end{array}$$

So we can conclude that if  $Y_1, Y_2, \dots, Y_n$  satisfy this condition they will construct the general sol<sup>15</sup> to  $L[Y] = 0$ .

Def<sup>o</sup>/  $f_1, f_2, \dots, f_n$  be  $n$ -functions which are at least  $(n-1)$ -times differentiable. Then

$$W[f_1, f_2, \dots, f_n](x) = \begin{vmatrix} f_1(x) & \dots & f_n(x) \\ \vdots & & \vdots \\ f_1^{(n-1)}(x) & \dots & f_n^{(n-1)}(x) \end{vmatrix} \quad \begin{array}{l} \text{Wronskian} \\ \text{of} \\ f_1, f_2, \dots, f_n \end{array}$$

Th<sup>n</sup>/ Let  $y_1, y_2, \dots, y_n$  be  $n$ -sol<sup>o</sup>'s on  $(a, b)$  of

$$y^{(n)}(x) + p_1(x)y^{(n-1)}(x) + \dots + p_n(x)y(x) = 0 \quad (*)$$

where  $p_i(x)$  are continuous on  $(a, b)$ . If at some point  $x_0 \in (a, b)$  these sol<sup>o</sup>'s have a non-zero Wronskian

$$W[y_1, y_2, \dots, y_n](x_0) \neq 0$$

then every sol<sup>o</sup> of  $(*)$  can be expressed in the form

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x)$$

- This theorem summarizes what we learned from the proposition, namely that there are at most  $n$ -different sol<sup>o</sup>'s to an  $n^{\text{th}}$  order homogeneous ODE. But what do I really mean by different?

Def<sup>b</sup>/ The  $n$ -functions  $f_1, f_2, \dots, f_n$  are linearly independent on an interval  $I$  iff

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0 \Rightarrow c_1 = c_2 = \dots = c_n = 0.$$

otherwise we say  $f_1, f_2, \dots, f_n$  are linearly dependent.

Examples

$$\begin{aligned} f_1(x) &= \sin(x) \\ f_2(x) &= \cos(x) \end{aligned} \quad \left. \begin{array}{l} c_1 \sin(x) + c_2 \cos(x) = 0 \\ \Rightarrow c_1 = 0 \text{ and } c_2 = 0. \end{array} \right.$$

$$\begin{aligned} f_1(x) &= x \\ f_2(x) &= 5x \end{aligned} \quad \left. \begin{array}{l} c_1 x + c_2 5x = 0 \\ \Rightarrow (c_1 + 5c_2)x = 0 \\ \Rightarrow c_1 = -5c_2 \quad (\text{need not be zero!}) \end{array} \right.$$

Remark: If two functions are linearly dependent then they are the same sol<sup>o</sup> for most intents and purposes (modulo IVPs where  $c_1, c_2, \dots$  are fixed)

Remark: If  $f_1, f_2, \dots, f_n$  are sol<sup>o</sup>'s to some homogeneous  $n^{\text{th}}$  order ODE then  $W[f_1, \dots, f_n](x) \neq 0 \Rightarrow$  they are linearly independent. However this only works for common solutions, if  $g_1, g_2, \dots, g_n$  are just  $n$ -functions then the Wronskian tells us nothing about linear independence. (We'll encounter this in §6.4 with " $W_R(x)$ ")

## LINEARLY INDEPENDENT Functions

$$\{1, x, x^2, \dots, x^n\}$$

$$\{1, \cos x, \sin x, \cos 2x, \sin 2x, \dots, \cos nx, \sin nx\}$$

$$\{e^{ax}, \dots, e^{anx}\}$$

These sets are linearly independent. I borrowed those from the text, I think it's also good to know more sets of LI functions

$$\{x, x \sin x, x e^x, x^2 e^x\}$$

$$\{\cosh(x), \cos(x), \sinh(x), \sin(x)\}$$

The examples are endless really. One thing we should pause and consider is that linear independent functions allow us to equate coefficients. For example,

$$15 \sin(x) + 38 \cos(x) + 7 = (A+B) \sin(x) + C$$

yields three equations,

$$\begin{aligned} 15 &= A+B \\ 38 &= 0 \\ 7 &= C \end{aligned} \quad \left. \begin{array}{l} \text{equating coeff.} \\ \text{of the functions} \end{array} \right\} \quad \left. \begin{array}{l} \sin(x) \\ \cos(x) \\ 1 \end{array} \right\}$$

We'll use this idea many times. It is an essential algebraic notion that rests on the linear independence of functions involved if you think about it.

Th<sup>n</sup>(NONHOMOGENEOUS LINEAR ODEs). Given  $P_1, P_2, \dots, P_n, g$  contin. on  $(a, b)$ ,

$$Y^{(n)}(x) + P_1(x) Y^{(n-1)}(x) + \dots + P_n(x) Y(x) = g(x) \quad (\star)$$

and.  $\{Y_1, Y_2, \dots, Y_n\}$  the fundamental sol<sup>n</sup> set to the auxillary eq<sup>n</sup>

$$Y^{(n)}(x) + P_1(x) Y^{(n-1)}(x) + \dots + P_n(x) Y(x) = 0$$

We may form any sol<sup>n</sup> on  $(a, b)$  in the form

$$Y(x) = Y_p(x) + C_1 Y_1(x) + \dots + C_n Y_n(x) \quad (\text{general sol}^n)$$

Where  $Y_p$  is a sol<sup>n</sup> to  $(\star)$  which we call the particular sol<sup>n</sup>.

Remark: We can solve nonhomogeneous DEg<sup>n</sup>'s by first solving the corresponding auxillary DEg<sup>n</sup> then simply add  $Y_p$  to that. The real trouble is finding  $Y_p$ .

## DIFFERENTIAL OPERATORS

The differential operator  $D = \frac{d}{dx}$  has nice properties

$$1.) D[fg] = D[f] \cdot g + f \cdot D[g]$$

$$2.) D[x] = 1$$

3.)  $D$  is a linear operator.

I mean multiplication  
of functions here.

So we've seen that  $e^{\lambda x}$  solves  $(D-\lambda)y = 0$  but what about  $(D-\lambda)^2 y = 0$  where the squared means composition of operators  $(D-\lambda) \circ (D-\lambda)y = 0$ . Consider then that  $e^{\lambda x}$  is certainly one sol<sup>o</sup> since,

$$(D-\lambda)^2 y = (D-\lambda)(D-\lambda)y = (D-\lambda)(0) = 0.$$

Claim:  $y = xe^{\lambda x}$  is a 2<sup>nd</sup> sol<sup>o</sup> to  $(D-\lambda)^2 y = 0$ .

Proof: Will use properties 1. and 2. of  $D$ ,

$$\begin{aligned} (D-\lambda)^2 xe^{\lambda x} &= (D-\lambda)(D(xe^{\lambda x}) - \lambda xe^{\lambda x}) \\ &= (D-\lambda)((Dx) \cdot e^{\lambda x} + x \cdot (De^{\lambda x}) - \lambda xe^{\lambda x}) \\ &= (D-\lambda)(e^{\lambda x} + x\lambda e^{\lambda x} - \lambda xe^{\lambda x}) \\ &= (D-\lambda)e^{\lambda x} \\ &= 0 \end{aligned}$$

And it's not hard to see that this works for  $\lambda \in \mathbb{C}$ .

Claim:  $y = x^2 e^{\lambda x}$  is a sol<sup>o</sup> to  $(D-\lambda)^3 y = 0$ .

Proof: Use what we already know

$$\begin{aligned} (D-\lambda)^3 x^2 e^{\lambda x} &= (D-\lambda)^2 ((Dx^2) e^{\lambda x} + x^2 De^{\lambda x} - 3x^2 e^{\lambda x}) \\ &= (D-\lambda)^2 (2xe^{\lambda x}) \\ &= 2(D-\lambda)^2 (xe^{\lambda x}) \\ &= 0 \quad \text{by our previous claim.} \end{aligned}$$

Claim:  $(D-\lambda)^n y$  has  $n$ -sol<sup>o</sup>'s they are  
 $y_1 = e^{\lambda x}, y_2 = xe^{\lambda x}, \dots, y_n = x^{n-1} e^{\lambda x}$

Remark: These could be complex if  $\lambda$  were complex, we will see how to extract real sol<sup>o</sup>'s from the complex sol<sup>o</sup>'s soon.

## USEFUL FACTS ABOUT OPERATORS AND COMPLEX NUMBERS

Consider again the operator  $L = D - \lambda I$ . This operator acts on functions of  $x$  as follows,

$$L[Y] = DY - \lambda Y$$

$$L[Y](x) = Y'(x) - \lambda Y$$

What function satisfies  $L[Y] = 0$ ? I claim that  $e^{\lambda x}$  will do the trick,

$$L[e^{\lambda x}](x) = \frac{d}{dx}(e^{\lambda x}) - \lambda e^{\lambda x} = \lambda e^{\lambda x} - \lambda e^{\lambda x} = 0.$$

This calculation certainly makes sense if  $\lambda \in \mathbb{R}$ , but in fact it also is reasonable for  $\lambda \in \mathbb{C}$ . We pause to discuss the meaning of  $e^{\lambda x}$  when  $\lambda \in \mathbb{C}$ .

- We always assume  $x$  is a real variable.

Def/<sup>2</sup> Let  $a, b \in \mathbb{R}$  and  $a+ib \in \mathbb{C}$  where  $i = \sqrt{-1}$

$$e^{a+ib} = e^a e^{ib} \quad \text{where } e^{ib} \equiv \cos b + i \sin b$$

these  $e^{ib}$ 's define what is meant by the exponential of a complex number

Terminology: Functions which map  $\mathbb{R} \rightarrow \mathbb{C}$  are complex-valued functions of a real variable. For example,

$$\tilde{f}(x) = a(x) + ib(x)$$

Here  $a, b$  are functions from  $\mathbb{R} \rightarrow \mathbb{R}$ , I use the  $\sim$  to emphasize  $\tilde{f}(x)$  is complex.

- DIFFERENTIATING COMPLEX-VALUED FUNCTIONS

$$\frac{d}{dx}(\tilde{f}(x)) = \frac{d}{dx}(a(x) + ib(x)) = \frac{da}{dx} + i \frac{db}{dx}$$

$$\tilde{f}'(x) = a'(x) + ib'(x)$$

Just like differentiating  $\vec{r}(t)$  from ma 242, we differentiate each component function ( $\vec{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle$ .)

## COMPLEX VALUED FUNCTIONS OF A REAL VARIABLE

Def<sup>n</sup>/  $\tilde{f}(x) = a(x) + i b(x)$  has real and imaginary components which are both real-valued functions

$$\operatorname{Re}\{\tilde{f}\} = a \quad \text{and} \quad \operatorname{Im}\{\tilde{f}\} = b$$

Now let's go back and verify my claim that  $(D - \lambda)e^{2x} = 0$  even when  $\lambda \in \mathbb{C}$ . Let  $\lambda = a + ib$  notice  $\operatorname{Re}\{\lambda\} = a$  and  $\operatorname{Im}\{\lambda\} = b$ ,

$$\begin{aligned} (D - \lambda)e^{2x} &= \left( \frac{d}{dx} - \lambda \right) e^{(a+ib)x} \\ &= \frac{d}{dx} [e^{ax} (\cos bx + i \sin bx)] - \lambda e^{2x} \\ &= ae^{ax} (\cos bx + i \sin bx) + e^{ax} (-bsin bx + bi \cos bx) - \lambda e^{2x} \\ &= e^{ax} (a \cos bx + ia \sin bx - b \sin bx + ib \cos bx) - \lambda e^{2x} \\ &= (a + ib) e^{ax} (\cos bx + i \sin bx) - \lambda e^{2x} \\ &= \lambda e^{2x} - \lambda e^{2x} = 0 \quad \underline{\text{as claimed.}} \end{aligned}$$

*Used  
-1 = i · i*

Remark: If you take ma 513 you'll learn how to differentiate w.r.t. a complex variable, complex numbers for us are just an algebraic convenience we will ultimately be interested in real-valued functions of a real variable.

FACT: If  $L[\tilde{y}](x) = 0$  then the real and imaginary parts are so<sup>l<sup>o</sup>s</sup> as well;  $L[\operatorname{Re}\{\tilde{y}\}](x) = 0$  and  $L[\operatorname{Im}\{\tilde{y}\}](x) = 0$ . I've assumed that  $L$  is a linear operator with property

$$L[\tilde{c}_1 y_1 + \tilde{c}_2 y_2] = \tilde{c}_1 L[y_1] + \tilde{c}_2 L[y_2]$$

for  $\tilde{c}_1, \tilde{c}_2 \in \mathbb{C}$ . When  $L = D^n + P_1 D^{n-1} + \dots + P_n$  we certainly have this property. ( $L$  is "complex linear")

## ALGEBRA REFRESHER

Let  $P(x) = x^n + a_{n-1}x^{n-1} + \dots + a_2x^2 + a_1x + a_0$  be a polynomial with real coefficients  $a_{n-1}, \dots, a_2, a_1, a_0$ . Then the fundamental Th<sup>m</sup> of algebra says  $\exists n$ -roots say  $\lambda_1, \lambda_2, \dots, \lambda_n$  that satisfy  $P(\lambda_i) = 0$ . These may be repeated and/or complex. This means we can factor

$$P(x) = (x - \lambda_1)^{m_1}(x - \lambda_2)^{m_2} \cdots (x - \lambda_d)^{m_d}$$

Where  $m_1 + m_2 + \dots + m_d = n$ . Now in the event some  $\lambda_k = a+ib$  is a sol<sup>z</sup> it follows that  $\lambda_k^* = a-ib$  is likewise a sol<sup>z</sup>. That is complex roots come in conjugate pairs. This is a straight-forward consequence of the assumption the coefficients are real, if we didn't have the conjugate root then the factorization once multiplied out would give non-real coeff. On the other hand notice ( $a, b \in \mathbb{R}$ )

$$\begin{aligned} (x - (a+ib))(x - (a-ib)) &= x^2 - x(a-ib) - (a+ib)x + (a+ib)(a-ib) \\ &= x^2 - 2ax + ibx - ibx + a^2 - i^2b \\ &= x^2 - 2ax + a^2 + b^2 \end{aligned}$$

an irreducible quadratic.

This is the beauty of conjugate pairs, they make the  $i$  factors cancel out. Anyway this means that we can factor any polynomial with real coefficients into a bunch of real linear factors and irred. quad. factors (possibly repeated)

$$P(x) = \underbrace{(x - \lambda_1)^{m_1} \cdots (x - \lambda_r)^{m_r}}_{\lambda_1, \dots, \lambda_r \in \mathbb{R}} \underbrace{(x^2 + B_1x + C_1)^{n_1} \cdots (x^2 + B_sx + C_s)^{n_s}}_{B_1^2 - 4C_1, \dots, B_s^2 - 4C_s < 0}$$

irreducible quad. factors.

With  $n = m_1 + \dots + m_r + 2n_1 + \dots + 2n_s$ .

- This is the factorization that most explicitly reveals the aspects of  $P(x)$  we need to use.

FIND REAL sol<sup>n</sup>'s to  $(D-\lambda)^n(D-\lambda^*)^n Y = 0$

$$\begin{aligned}\lambda &= a+ib \\ \bar{\lambda} &= a-ib\end{aligned}$$

We know that  $(D-\lambda)^n Y = 0$  has sol<sup>n</sup>'s  
 $\tilde{Y}_1 = e^{\lambda x}$ ,  $\tilde{Y}_2 = xe^{\lambda x}$ , ...,  $\tilde{Y}_n = x^{n-1} e^{\lambda x}$   
but  $\lambda = a+ib$  so these are complex,

$$\begin{aligned}\tilde{Y}_1 &= e^{ax} \cos bx + ie^{ax} \sin bx \\ \tilde{Y}_2 &= xe^{ax} \cos bx + ix e^{ax} \sin bx \\ \vdots \\ \tilde{Y}_n &= x^{n-1} e^{ax} \cos bx + ix^{n-1} e^{ax} \sin bx\end{aligned}$$

Notice  $(D-\lambda^*)^n Y^*$  likewise has sol<sup>n</sup>'s with  $\lambda^* = a-ib$

$$\begin{aligned}\tilde{Y}_1^* &= e^{ax} \cos bx - ie^{ax} \sin bx \\ \vdots \\ \tilde{Y}_n^* &= x^{n-1} e^{ax} \cos bx - ix^{n-1} e^{ax} \sin bx\end{aligned}$$

This means that  $(D-\lambda)^n$  and  $(D-\lambda^*)^n$  both possess real sol<sup>n</sup>'s

$$\boxed{\{e^{ax} \cos bx, e^{ax} \sin bx, \dots, x^{n-1} e^{ax} \cos bx, x^{n-1} e^{ax} \sin bx\}}$$

of which we can count  $2n$ -sol<sup>n</sup>'s in total.

Summary: we have found how to assemble real sol<sup>n</sup>'s in the complex case and we already saw how to find sol<sup>n</sup>'s in the real case with repeats. So we now have all we need to detail the general sol<sup>n</sup> to.

$$Y^{(n)}(x) + P_1(x) Y^{(n-1)}(x) + \dots + P_n(x) Y(x) = 0$$

- Although to be careful we ought to prove these sol<sup>n</sup>'s we have found are indeed linearly independent. You should know how to prove LI for specific examples, you could use the Wronskian to check LI since these functions are all sol<sup>n</sup>'s to a common DEg<sup>n</sup>.

## Solving $n^{\text{th}}$ order constant coefficient linear ODEs

We wish to solve the following DEq<sup>2</sup>:

$$Y^{(n)}(x) + a_1 Y^{(n-1)}(x) + \cdots + a_{n-1} Y'(x) + a_n Y(x) = 0 \quad \text{Eq } (1)$$

Here we assume  $a_1, \dots, a_{n-1}, a_n$  are real constants which certainly are continuous on all of  $\mathbb{R}$  so once we have  $n$ -initial conditions we know by existence/uniqueness Th<sup>m</sup> the sol<sup>1</sup> will exist and be defined for all  $\mathbb{R}$ . So let's find it, recast Eq<sup>1</sup>(1) as an operator eq<sup>2</sup>

$$(D^n + a_1 D^{n-1} + \cdots + a_{n-1} D + a_n) Y \equiv L[Y] = 0 \quad \text{Eq } (2)$$

Notice that the linear operator  $L$  is a polynomial in the operator  $D \equiv \frac{d}{dx}$ .

$$L = P(D) = D^n + a_1 D^{n-1} + \cdots + a_n$$

This polynomial  $P$  has real coefficients  $a_1, \dots, a_n$  so we can factor it as discussed in ALGEBRA REFRESHER

$$0 = L[Y] = (D - \lambda_1)^{m_1} \cdots (D - \lambda_r)^{m_r} (D^2 + B_1 D + C_1)^{n_1} \cdots (D^2 + B_s D + C_s)^{n_s} Y$$

Solving this eq<sup>2</sup> is easy with what we know. Notice that all we need for  $Y$  to be a sol<sup>2</sup> is that one of the factors annihilate it. In total we get  $n$ -LI sol<sup>1</sup>'s from the various factors

**linear factors**  $(D - \lambda_i)^{m_i} \Rightarrow y_1 = e^{\lambda_i x}, \dots, y_{m_i} = x^{m_i-1} e^{\lambda_i x}$

**irreducible quad. factors**  $(D^2 - B_i D + C_i)^{n_i} = (D - (\alpha + i\beta))^{n_i} (D - (\alpha - i\beta))^{n_i}$   
 $\Rightarrow y_{M+1} = e^{\alpha x} \cos \beta x, y_{M+2} = e^{\alpha x} \sin \beta x$   
 $y_{M+3} = x e^{\alpha x} \cos \beta x, y_{M+4} = x e^{\alpha x} \sin \beta x, \dots$

Where I made up  $M \equiv m_1 + m_2 + \cdots + m_r$  to keep the labeling correct. So we find in total  $n$ -LI sol<sup>1</sup>'s to Eq<sup>1</sup>(1), we'll write the general sol<sup>n</sup> in all its glory on the next page  $\square$

Let us write the general sol<sup>2</sup> to Eq<sup>2</sup>(1),

$$\begin{aligned}
 Y = & C_1 e^{\lambda_1 x} + C_2 x e^{\lambda_1 x} + \cdots + C_{m_1} x^{m_1-1} e^{\lambda_1 x} + \cdots \\
 & + C_{M-m_r} e^{\lambda_{m_r} x} + \cdots + C_M x^{m_r-1} e^{\lambda_{m_r} x} + \\
 & + C_{M+1} e^{\alpha_1 x} \cos \beta_1 x + C_{M+2} e^{\alpha_1 x} \sin \beta_1 x + \cdots \\
 & + C_{M+2n_1-1} x^{n_1-1} e^{\alpha_1 x} \cos \beta_1 x + C_{M+2n_1} x^{n_1-1} e^{\alpha_1 x} \sin \beta_1 x + \cdots \\
 & + C_{n-2n_s} e^{\alpha_s x} \cos \beta_s x + C_{n-2n_s+1} e^{\alpha_s x} \sin \beta_s x + \cdots \\
 & + C_{n-1} x^{n_s-1} e^{\alpha_s x} \cos \beta_s x + C_n x^{n_s-1} e^{\alpha_s x} \sin \beta_s x
 \end{aligned}$$

Remark: I don't remember this formula, instead I use the principles that led us to it to assemble sol<sup>2</sup>'s for particular examples.

Remark: there are only many possible sol<sup>2</sup>'s until we are supplied the needed n - initial conditions.

Auxillary Eq<sup>2</sup>:

We have used operator arguments to assemble this sol<sup>2</sup> but we could just as well supposed that  $e^{\lambda x}$  was a sol<sup>2</sup> to find

$$L[e^{\lambda x}] = P(\lambda) e^{\lambda x}$$

Where this is the same polynomial we found in D. Clearly  $L[e^{\lambda x}] = 0$  iff  $P(\lambda) = 0$ . In practice I prefer to factor the auxillary eq<sup>2</sup> in terms of  $\lambda$  as opposed to a polynomial in D.

- (The text uses "r" instead of " $\lambda$ " so be warned.) •
- I'll factor  $P(\lambda)$  to find  $\lambda_1, \lambda_2, \dots, \lambda_r$  and  $\alpha_1, \beta_1, \dots, \alpha_s, \beta_s$  and the multiplicities.

EXAMPLES

**E1**  $y'''(x) = 0 \Rightarrow Y = C_1 + C_2 x + C_3 x^2$  (since  $e^{0 \cdot x} = 1$ )

**E2**  $y'' + y = 0$   
 $\lambda^2 + 1 = 0 \Rightarrow \lambda = \pm i = \alpha \pm i\beta$   
identify  $\alpha = 0 \neq \beta = 1 \therefore Y = C_1 \cos(x) + C_2 \sin(x)$

**E3**  $y''' + 3y'' + 3y' + y = 0$   
 $\lambda^3 + 3\lambda^2 + 3\lambda + 1 = 0$   
 $(\lambda + 1)^3 = 0$   
 $\lambda = -1$  with multiplicity 3.  $Y = C_1 e^{-x} + C_2 x e^{-x} + C_3 x^2 e^{-x}$

**E4**  $y''' + 2y'' + y = 0$   
 $\lambda^4 + 2\lambda^2 + 1 = 0$   
 $(\lambda^2 + 1)^2 = 0$   
 $\lambda = \pm i$  with multiplicity 2.  
 $\therefore Y = C_1 \cos x + C_2 \sin x + C_3 x \cos x + C_4 x \sin x$

**E5**  $y''' + 5y'' + 6y' = 0$   
 $\lambda^3 + 5\lambda^2 + 6\lambda = 0$   
 $\lambda(\lambda^2 + 5\lambda + 6) = \lambda(\lambda + 2)(\lambda + 3) = 0$   
 $\Rightarrow \lambda_1 = 0, \lambda_2 = -2, \lambda_3 = -3$   
 $\therefore Y = C_1 + C_2 e^{-3x} + C_3 e^{-2x}$

**E6**  $y' = y$   
 $\lambda = 1 \therefore Y = C_1 e^x$

**E7**  $y'' - y = 0$   
 $\lambda^2 - 1 = 0 \Rightarrow \lambda = \pm 1 \Rightarrow Y = C_1 e^x + C_2 e^{-x}$

Remark: Consider what we've done, we've changed the problem of unravelling a complicated differential eq<sup>n</sup> to the relatively easy problem of factoring a polynomial. Algebra has replaced calculus here, it's really quite amazing that constant coefficient linear ODEs are easy.