Ma 430 : PROBLEMS ABOUT EUCLIDEAN STRUCTURES & ROTATIONS & MORE

PROBLEM 12) We defined $O(3) = \{A \in \mathbb{R}^{3\times3} \mid A^TA = I\}$ prove the following a.) O(3) is a group with operation matrix multiplication. You may assume matrix multiplication is associative.

b.) SO(3) = { A ∈ O(3) | deb(A) = 1 }. Show that SO(3) is a group.

c.) Let $\forall l = -I = (\frac{1}{8} - \frac{1}{6} - \frac{1}{6})$ then define the coset of SO(3) $SO(3) = \frac{1}{8} + \frac{1}$

PROBLEM 13 Define $R = \{\varphi \mid \varphi : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ is a rigid motion } \}.$ Show that R is a group with respect to the operation of function composition. You may assume that function composition is associative.

PROBLEM H Let $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ be any 2×2 real matrix. Assume that det (A) = 1. Show that A is orthogonal iff $A = \begin{pmatrix} a & b \\ -b & a \end{pmatrix}$. Then show that this is the case iff there is some angle Θ such that $A = \begin{pmatrix} \cos \Theta & \sin \Theta \\ -\sin \Theta & \cos \Theta \end{pmatrix}$. This problem shows every special orthogonal matrix is a rotation in 2-dim.

PROBLEM 15 Let $f: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ be defined by $f(x_1, x_2, x_3) = (\frac{\sqrt{3}}{2}x_1 + \frac{1}{2}x_3, x_2, -\frac{1}{2}x_1 + \frac{\sqrt{3}}{2}x_3)$

- (a.) use the definition of an orthogonal transformation to show that f is orthogonal
- (b.) Find the matrix A of f (meaning find A such that f(x) = Ax) then show by matrix multiplication that $A^TA = I$.
- (C.) find an angle Θ such that $A = \begin{pmatrix} \cos \Theta & 0 & \sin \Theta \\ 0 & 1 & 0 \\ -\sin \Theta & 0 & \cos \Theta \end{pmatrix}$



A. Assume that the surface of the earth is represented by the (xy)-plane and that the acceleration of gravity is -gk. If a projectile of mass m is launched from the origin with initial speed v_o at an angle α with the horizontal then find

(a) the position of the projectile as a function of t (b) the time it takes to attain maximum height

(c) the range of the projectile (d) Show that the angle α which gives maximum range is $\alpha = 45^{\circ}$.

Assume throughout the problem that the initial velocity vector lies in the (yz)-plane.

4. A train moves due north at a constant speed v. It passes a carousel one mile due west of the carousel at 1:00 p.m. Consider two coordinate systems with origin the central point about which the carousel rotates. The first system, $x = (x_1, x_2)$ is oriented in the usual East-West, North-South fash-

about which the carousel rotates. The first system, $x = (x_1, x_2)$ is oriented in the usual East-West, North-South fashion, but the second system is attached to the carousel which is rotating counterclockwise with constant angular speed ω with respect to x. The rotating system is denoted by $y_t = (y_{t1}, y_{t2})$ and at 1:00 p.m. t = 0 and $y_t = y_0 = x$.

- (a) Find the position of the train as a function of t as measured by x.
- (b) Find the position of the train as a function of t as observed by y.
- (c) Find the velocity of the train in both systems.
- (d) At 1:00 pm a car is located at (nearly!) the same point as the train and is traveling northeast at a constant speed u. Find the equation of motion of the car in both systems.
- (e) If the train carries a coordinate system $z_t = (z_{t1}, z_{t2})$ which is oriented like x and which lies one mile due west of the origin of x at t = 0 find the equation of motion of a point on the rim of the carousel relative to z. To be explicit assume the point on the rim of the carousel has y-coordinates (a, 0) for all t.