

Same rules as Homework 1. **Assume** all vector spaces are **finite dimensional** for ease of mind. There are many results here which do transfer to the world of infinite dimensional vector spaces, but, I'll leave that for another day. We denote $V^* = L(V, \mathbb{F})$.

Problem 161 Your signature below indicates you have:

(a.) I read the handout from Berberian: _____.

(b.) I read Chapter 10 of Cook's Lecture Notes: _____.

Problem 162 Consider $T \in L(V, W)$. If $U \leq V$ then we can attempt to define a linear transformation $S : V/U \rightarrow W$ by the rule:

$$S(x + U) = T(x).$$

- (i.) is S a function? If this is not generally true then what condition do we need to place on U in order that S be a function?
- (ii.) if need be apply the condition found in part (i.), if T is injective does this imply S is injective? What condition is needed to make injectivity of T transfer to S ?
- (iii.) if need be apply the condition found in part (i.), if T is surjective does this imply S is surjective? What condition is needed to make surjectivity of T transfer to S ?

Problem 163 Let V be a vector space over $\mathbb{F}$ and $M, N \leq V$. Prove the **2nd isomorphism theorem**:

$$M/(M \cap N) \approx (M + N)/N$$

Hint: consider the restriction of $\pi : V \rightarrow V/N$ to M . Find the kernel and range of $\pi|_M$.

Problem 164 Prove the **3rd isomorphism theorem**: If V is a vector space over $\mathbb{F}$

such that $U \leq N \leq V$ then $\frac{V/U}{N/U} \approx \frac{V}{N}$

Problem 165 Let V and W be vector spaces over $\mathbb{F}$ and $M \leq V$ and $N \leq W$. Prove

$$\frac{V \times W}{M \times N} \approx \frac{V}{M} \times \frac{W}{N}.$$

Hint: Consider $T : V \times W \rightarrow V/M \times W/N$ defined by $T(x, y) = (x + M, y + N)$.

Problem 166 The notation $\boxplus$ denotes the **external direct product** of vector spaces; given V, W vector spaces the point-set $V \times W$ with the usual operations $c(v_1, w_1) + (v_2, w_2) = (cv_1 + v_2, cw_1 + w_2)$ is denoted $V \boxplus W$. **Prove:** If $V = V_1 \oplus V_2$ and $S = S_1 \oplus S_2$ such that $S_1 \leq V_1$ and $S_2 \leq V_2$ then

$$\frac{V}{S} = \frac{V_1 \oplus V_2}{S_1 \oplus S_2} \approx \frac{V_1}{S_1} \boxplus \frac{V_2}{S_2}.$$

Problem 167 Prove the following: for V a vector space over a field $\mathbb{F}$:

- (a.) for any nonzero vector $v \in V$ there exists a linear functional $\alpha \in V^*$ for which $\alpha(v) \neq 0$
- (b.) a vector $v \in V$ is zero if and only if $\alpha(v) = 0$ for all $\alpha \in V^*$.

Problem 168 (continuation of last problem) Prove the following: for V a vector space over a field $\mathbb{F}$:

- (c.) if $\alpha \in V^*$ and $\alpha(x) \neq 0$ then $V = \text{span}(x) \oplus \ker(\alpha)$
- (c.) if $\alpha, \beta \in V^*$ are nonzero then $\ker(\alpha) = \ker(\beta)$ iff $\alpha = k\beta$ for some $k \in \mathbb{F}$

Problem 169 Given $V = S \oplus T$, prove $\text{ann}(S) \oplus \text{ann}(T) = (S \oplus T)^*$.

Incidentally, another common notation for the annihilator is given by $\text{ann}(S) = S^0$.

Problem 170 Show the first isomorphism theorem implies the rank nullity theorem for $T : V \rightarrow W$. That is show the first isomorphism theorem implies $\dim(\ker(T)) + \dim(\text{range}(T)) = \dim(V)$. (you are free to use Proposition 10.1.22 of page 341 in my notes)

Problem 171 Suppose (V, g) forms a geometry and β is a basis for V for which G is the matrix of g . Furthermore, suppose the linear mapping $L : V \rightarrow V$ is a g -orthogonal map such that A is its matrix; $[L(x)]_\beta = A[x]_\beta$ or simply $[L]_{\beta, \beta} = A$. Show $A^T G A = G$.

Problem 172 (Gwyneth's Musical Morphism Problem) Let $g : \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$ be a metric with

matrix $G = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -3 \end{bmatrix}$. If $v = \sum_{i=1}^3 v^i e_i = (a, b, c)$ then calculate v_i for $i = 1, 2, 3$.

Also, show $g(v, v) = \sum_{i=1}^3 v^i v_i$ (you can show it in terms of a, b, c or v^1, v^2, v^3 whatever you prefer)

Problem 173 Let M be a symmetric matrix and define $\Upsilon(A, B) = AB + BA$ for all $A, B \in \mathbb{R}^{n \times n}$ show Υ is a symmetric, bilinear form.

Problem 174 Suppose (V, g) is a real geometry. Show (V^*, g^*) is also a real geometry given we define $g^*(\alpha, \beta) = g(\sharp\alpha, \sharp\beta)$.

Problem 175 Let (V, g) be a real geometry. Prove $\sharp \circ \flat = Id_V$ and $\flat \circ \sharp = Id_{V^*}$. See my notes for the necessary definitions.

Problem 176 Prove property (ii.) of Theorem 10.4.4.

Problem 177 Let V be a real vector space and $x, y \in V$. Define $x \otimes y : V^* \times V^* \rightarrow \mathbb{R}$ according to the rule $(x \otimes y)(\alpha, \beta) = \alpha(x)\beta(y)$. Show $x \otimes y$ is a bilinear mapping on $V^* \times V^*$.

Problem 178 Continuing the construction in the last problem, if V has basis $\beta = \{v_1, \dots, v_n\}$ show $\Upsilon = \{v_i \otimes v_j \mid 1 \leq i, j \leq n\}$ serves as a basis for $\mathcal{B}(V^*)$. That is, show Υ is LI and that any bilinear mapping $V^* \times V^* \rightarrow \mathbb{R}$ can be expressed as a linear combination of the Υ maps.

Problem 179 Suppose A, N are square matrices and N is nilpotent of order k . Show $A \otimes N$ is nilpotent of order k .

Problem 180 Let $T : V \times V \times V^* \rightarrow \mathbb{R}$ be a multilinear mapping. Determine if $S = T \circ (\sharp, \sharp, b)$ is also a multilinear mapping. Also, find the coordinate transformation rules for T and S . Here we assume (V, g) is a real geometry.

MISSION 10 SOLUTION

P162 $T: V \rightarrow W$ linear and $U \leq V$.

define $S: V/U \rightarrow W$ by $S(x+U) = T(x)$.

(a.) S is into W since $T(x) \in W$ so the codomain of S is fine. However, for S to be single-valued we need $x_1 + U = x_2 + U \Rightarrow S(x_1 + U) = S(x_2 + U)$

But, $x_1 + U = x_2 + U \Rightarrow x_2 - x_1 \in U$ hence $x_2 = x_1 + u$ for some $u \in U$ and thus,

$$S(x_1 + U) = T(x_1)$$

vs.

$$S(x_2 + U) = T(x_2) = T(x_1 + u) = T(x_1) + T(u)$$

We need $T(u) = 0$ in order that S be single-valued.

Hence $\boxed{U \subset \text{Ker}(T)}$ is a necessary condition
(for S to be a function)

Assume $U \subset \text{Ker}(T)$,

(b.) Suppose T is injective. Consider $S(x+U) = S(y+U)$

$$\Rightarrow T(x) = T(y) \Rightarrow x = y \text{ by injectivity of } T$$

thus $x+U = y+U$ and we find S is injective.

Remark: seems like less than injectivity of T will also work, ..., how much less...

(c.) Suppose T is surjective. Let $w \in W$ then $\exists v \in V$ for which $T(v) = w$. Observe for $w \in W$ we also have $S(v+U) = T(v) = w$ $\therefore S$ surjective. //

P163 Let $\varphi: M+N \longrightarrow \frac{M}{M \cap N}$

be defined by $\varphi(m+n) = m + M \cap N$

observe φ is linear and into $\frac{M}{M \cap N}$. It remains to show φ is well-defined. Suppose $m_1 + n_1 = m_2 + n_2$ then $m_2 - m_1 = n_1 - n_2$. Is $m_1 + M \cap N = m_2 + M \cap N$?

Notice $m_2 - m_1 = n_1 - n_2 \Rightarrow m_2 - m_1 \in M \cap N$

thus $m_2 + M \cap N = m_1 + M \cap N \Rightarrow \varphi(m_1 + n_1) = \varphi(m_2 + n_2)$.

Thus φ is well-defined.

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Let $m + M \cap N$ then $\varphi(m) = m + M \cap N \therefore \varphi$ is onto.

Calculate, $\text{Ker}(\varphi) = \{m+n \mid \varphi(m+n) = m + M \cap N = M \cap N\}$
 $= \{m+n \mid m \in M \cap N\}$
 $= \{m+n \mid m \in N \text{ and } n \in N\}$
 $= \{\tilde{n} \mid \tilde{n} \in N\}$
 $= N.$

Thus $\frac{M+N}{N} \approx \frac{M}{M \cap N}$ by 1st Isomorphism Th^m.

P164 $U \leq N \leq V$ show $\frac{V/U}{N/U} \approx \frac{V}{N}$

Let $\varphi: V/U \rightarrow V/N$ be defined by $\varphi(v+U) = v+N$
 or $\varphi(x+U) = x+N$. Once more φ is
 linear and into. I'll show linearity (this does make sense in part
 by the well-defⁿ argument I make)

$$\begin{aligned}\varphi(c(x+U) + y+U) &= \varphi(cx+y+U) \\ &= cx+y+N \\ &= c(x+N) + y+N \\ &= c\varphi(x+U) + \varphi(y+U).\end{aligned}$$

Thus, if φ is a function, then φ is linear transformation.

Suppose $x_1 + U = x_2 + U \Rightarrow x_2 - x_1 \in U \leq N$

thus $x_2 - x_1 \in N$ and $x_1 + N = x_2 + N$

but, this is precisely $\varphi(x_1+U) = \varphi(x_2+U)$

$\therefore \varphi$ is well-defined.

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Let $x+N \in V/N$ and observe $\varphi(x+U) = x+N$
 thus φ is a surjection onto V/N . Moreover,

$$\begin{aligned}\text{Ker } \varphi &= \{x+U \mid \varphi(x+U) = x+N = N\} \\ &= \{x+U \mid x \in N\} \\ &= N/U\end{aligned}$$

Thus, by 1st isomorphism Th^m, $\frac{V/U}{N/U} \approx \frac{V}{N}$.

P165 Let $T: V \times W \rightarrow \frac{V}{M} \times \frac{W}{N}$

be defined by $T(x, y) = (x+M, y+N)$.

Observe T is linear. Calculate the kernel,

$$\begin{aligned}\text{Ker}(T) &= \{ (x, y) \in V \times W \mid (x+M, y+N) = (M, N) \} \\ &= \{ (x, y) \mid x \in M, y \in N \} \\ &= M \times N\end{aligned}$$

$$\therefore \frac{V \times W}{M \times N} \approx \frac{V}{M} \times \frac{W}{N}$$

as the map T is clearly surjective.

(Surjectivity Proof: if $(x+M, y+N) \in \frac{V}{M} \times \frac{W}{N}$

then $T(x, y) = (x+M, y+N) \therefore T$ onto.)

P166 Let $V = V_1 \oplus V_2$ with $S_1 \leq V_1$ and $S_2 \leq V_2$

and $S = S_1 \oplus S_2$. Define $T: V \rightarrow \frac{V_1}{S_1} \times \frac{V_2}{S_2} = \underbrace{\frac{V_1}{S_1} \oplus \frac{V_2}{S_2}}_{\text{external direct sum.}}$

by $T(X_1 + X_2) = (X_1 + S_1, X_2 + S_2)$ for $\begin{matrix} X_1 \in V_1 \\ X_2 \in V_2 \end{matrix}$

observe T is linear and

$$\begin{aligned}\text{Ker } T &= \{ X_1 + X_2 \in V_1 \oplus V_2 \mid (X_1 + S_1, X_2 + S_2) = \underbrace{(S_1, S_2)}_{\text{zero in } \frac{V_1}{S_1} \oplus \frac{V_2}{S_2}} \} \\ &= \{ X_1 + X_2 \mid X_1 \in S_1, X_2 \in S_2 \} \\ &= S_1 + S_2 \\ &= S_1 \oplus S_2 \quad (\text{given } S_1 \cap S_2 = \{0\}).\end{aligned}$$

Thus, as T is a surjection (left to reader) we find

$$\frac{V_1 \oplus V_2}{S_1 \oplus S_2} \approx \frac{V_1}{S_1} \oplus \frac{V_2}{S_2} \quad \text{by 1st isomorphism Thm.}$$

P167 Let $V(\mathbb{F})$ be nontrivial vector space.

(a.) if $v \neq 0$ is vector in V then $\exists \alpha \in V^*$ for which $\alpha(v) \neq 0$

Extend v to basis $\beta = \{v_1, v_2, \dots, v_n\}$ (set $v_1 = v$)
then $\beta^* = \{v^1, v^2, \dots, v^n\} \subset V^*$ and $\alpha = v^1$
fits the demands; $\alpha(v) = v^1(v_1) = 1$.

(b.) Suppose $v = 0$ then $\alpha(0) = 0 \quad \forall \alpha \in V^*$.

Suppose $\alpha(v) = 0 \quad \forall \alpha \in V^*$. If $v = \sum c_i v_i$

then $\alpha(v) = \sum_{i=1}^n c_i \alpha(v_i) = 0 \quad \forall \alpha \in V^*$

choose $\alpha = v^j$ to obtain $v^j(v) = \sum_{i=1}^n c_i \underbrace{v^j(v_i)}_{\delta_{ij}} = c_j$

hence $c_j = 0$ for each $j=1, 2, \dots, n \Rightarrow v = 0$.

We conclude $\alpha(v) = 0 \quad \forall \alpha \in V^* \Leftrightarrow v = 0$.

P168 if $\alpha \in V^*$ and $\alpha(x) \neq 0$ then $V = \text{span}\{x\} \oplus \ker(\alpha)$

Notice, if $y \in \text{span}\{x\} \cap \ker(\alpha)$ then $\alpha(y) = 0$ and

$y = kx$ for some $k \in \mathbb{F} \Rightarrow \alpha(y) = k\alpha(x) = 0 \Rightarrow \underline{k=0}$

thus $\text{span}\{x\} \cap \ker(\alpha) = \{0\}$. It remains to show $V = \text{span}\{x\} + \ker(\alpha)$.

Notice, for $v \in V$ we have the following decomposition,

$$v = \frac{\alpha(v)}{\alpha(x)} x + \left(v - \frac{\alpha(v)}{\alpha(x)} x \right)$$

and note $\alpha\left(v - \frac{\alpha(v)}{\alpha(x)} x\right) = \alpha(v) - \frac{\alpha(v)}{\alpha(x)} \alpha(x) = 0$

thus $v - \frac{\alpha(v)}{\alpha(x)} x \in \ker(\alpha) \therefore v \in \text{span}\{x\} + \ker(\alpha)$ by x

hence $V = \text{span}\{x\} \oplus \ker(\alpha)$.

the way in which the expression V/S

theorem Let V be a vector space and $f \in V^*$. Then

$$\approx \frac{V}{T}$$

by $\tau(v+S) = v+T$. We leave it to the reader to verify that τ is a surjective linear transformation whose kernel is T . This completes the first isomorphism theorem. $\square$

the way in which the expression V/S

and let S be a subspace of V . Suppose $S_i \subseteq V_i$. Then

$$\approx \frac{V_1}{S_1} \oplus \frac{V_2}{S_2}$$

is defined by

$$+ S_1, v_2 + S_2)$$

if $V = V_1 \oplus V_2$ is direct. We leave it to the reader to verify that τ is a linear transformation, whose kernel is T . This completes the second isomorphism theorem. $\square$

the field F (thought of as a vector space

over F . A linear transformation f on the vector space V over the field F is called a **linear functional** if f maps V into F . (In this section we use the term linear function.) The dual space of V is denoted by V^* and is called the

dual space of V . Since there is another type of dual space for vector spaces, where continuity of linear functionals is discussed, the so-called *continuous dual* space, until then, the term "dual space" will

To help distinguish linear functionals from other types of linear transformations, we will usually denote linear functionals by lowercase italic letters, such as f , g and h .

Example 3.1 The map $f: F[x] \rightarrow F$ defined by $f(p(x)) = p(0)$ is a linear functional, known as **evaluation at 0**. $\square$

Example 3.2 Let $C[a, b]$ denote the vector space of all continuous functions on $[a, b] \subseteq \mathbb{R}$. Let $f: C[a, b] \rightarrow \mathbb{R}$ be defined by

$$f(\alpha(x)) = \int_a^b \alpha(x) dx$$

Then $f \in C[a, b]^*$. $\square$

For any $f \in V^*$, the rank plus nullity theorem is

$$\dim(\ker(f)) + \dim(\operatorname{im}(f)) = \dim(V)$$

But since $\operatorname{im}(f) \subseteq F$, we have either $\operatorname{im}(f) = \{0\}$, in which case f is the zero linear functional, or $\operatorname{im}(f) = F$, in which case f is surjective. In other words, a nonzero linear functional is surjective. Moreover, if $f \neq 0$, then

$$\operatorname{codim}(\ker(f)) = \dim\left(\frac{V}{\ker(f)}\right) = 1$$

and if $\dim(V) < \infty$, then

$$\dim(\ker(f)) = \dim(V) - 1$$

Thus, in dimensional terms, the kernel of a linear functional is a very "large" subspace of the domain V .

The following theorem will prove very useful.

Theorem 3.10

- 1) For any nonzero vector $v \in V$, there exists a linear functional $f \in V^*$ for which $f(v) \neq 0$.
- 2) A vector $v \in V$ is zero if and only if $f(v) = 0$ for all $f \in V^*$.
- 3) Let $f \in V^*$. If $f(x) \neq 0$, then

$$V = \langle x \rangle \oplus \ker(f)$$

- 4) Two nonzero linear functionals $f, g \in V^*$ have the same kernel if and only if there is a nonzero scalar λ such that $f = \lambda g$.

Proof. For part 3), if $0 \neq v \in \langle x \rangle \cap \ker(f)$, then $f(v) = 0$ and $v = ax$ for $0 \neq a \in F$, whence $f(x) = 0$, which is false. Hence, $\langle x \rangle \cap \ker(f) = \{0\}$ and the direct sum $S = \langle x \rangle \oplus \ker(f)$ exists. Also, for any $v \in V$ we have

$$v = \frac{f(v)}{f(x)}x + \left(v - \frac{f(v)}{f(x)}x\right) \in \langle x \rangle + \ker(f)$$

and so $V = \langle x \rangle \oplus \ker(f)$.

For part 4), if $f = \lambda g$ for $\lambda \neq 0$, then $\ker(f) = \ker(g)$. Conversely, if $K = \ker(f) = \ker(g)$, then for $x \notin K$ we have by part 3),

$$V = \langle x \rangle \oplus K$$

Of course, $f|_K = \lambda g|_K$ for any λ . Therefore, if $\lambda = f(x)/g(x)$, it follows that $\lambda g(x) = f(x)$ and hence $f = \lambda g$. $\square$

Dual Bases

Let V be a vector space with basis $\mathcal{B} = \{v_i \mid i \in I\}$. For each $i \in I$, we can define a linear functional $v_i^* \in V^*$ by the orthogonality condition

$$v_i^*(v_j) = \delta_{i,j}$$

where $\delta_{i,j}$ is the Kronecker delta function, defined by

$$\delta_{i,j} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

Then the set $\mathcal{B}^* = \{v_i^* \mid i \in I\}$ is linearly independent, since applying the equation

$$0 = a_{i_1}v_{i_1}^* + \cdots + a_{i_n}v_{i_n}^*$$

to the basis vector v_{i_k} gives

$$0 = \sum_{j=1}^n a_{i_j}v_{i_j}^*(v_{i_k}) = \sum_{j=1}^n a_{i_j}\delta_{i_j,i_k} = a_{i_k}$$

for all i_k .

Theorem 3.11 Let V be a vector space with basis $\mathcal{B} = \{v_i \mid i \in I\}$.

- 1) The set $\mathcal{B}^* = \{v_i^* \mid i \in I\}$ is linearly independent.
- 2) If V is finite-dimensional, then $\mathcal{B}^*$ is a basis for V^* , called the **dual basis** of $\mathcal{B}$.

Proof. For part 2), for any $f \in V^*$, we have

$$\sum_j f(v_j)v_j^*(v_i) = \sum_j f(v_j)\delta_{i,j} = f(v_i)$$

and so $f = \sum f(v_j)v_j^*$ is in the span of $\mathcal{B}^*$. Hence, $\mathcal{B}^*$ is a basis for V^* . $\square$

P169 If $V = S \oplus T$ then show $\text{ann}(S) \oplus \text{ann}(T) = (S \oplus T)^*$

$$\begin{aligned} \text{Recall, } \dim V &= \dim(S) + \dim(\text{ann}(S)) \\ \text{and } \dim V &= \dim(T) + \dim(\text{ann}(T)) \end{aligned} \quad \left. \vphantom{\begin{aligned} \text{Recall, } \dim V &= \dim(S) + \dim(\text{ann}(S)) \\ \text{and } \dim V &= \dim(T) + \dim(\text{ann}(T)) \end{aligned}} \right\} \text{ by } \boxed{\text{P153}}$$

We also know $\dim V = \dim S + \dim T$. Observe,

$$\dim(\text{ann}(S)) + \dim(\text{ann}(T)) = (\dim V - \dim S) + (\dim V - \dim T)$$

$$\Rightarrow \underline{\dim(\text{ann}(S)) + \dim(\text{ann}(T)) = \dim V = \dim V^*}$$

However, if $\alpha \in \text{ann}(S) \cap \text{ann}(T)$ then

$$\begin{aligned} \alpha(x) &= \alpha(s+t) : \text{ since } x \in V = S \oplus T \\ &= \alpha(s) + \alpha(t) \quad \exists s \in S, t \in T \\ &= 0 + 0 \quad \text{such that } x = s+t. \\ &= 0 \end{aligned}$$

$$\text{Thus } \alpha(x) = 0 \quad \forall x \in V \Rightarrow \underline{\text{ann}(S) \cap \text{ann}(T) = \{0\}}^*$$

$$\text{Recall, } \dim(U+W) = \dim(U) + \dim(W) - \dim(U \cap W)$$

apply to our current problem,

$$\dim(\text{ann}(S) + \text{ann}(T)) = \dim(\text{ann}(S)) + \dim(\text{ann}(T)) - 0$$

$$\therefore \dim(\text{ann}(S) + \text{ann}(T)) = \dim V^*$$

$$\Rightarrow \text{ann}(S) + \text{ann}(T) = V^* \quad \& \text{ by } *$$

$$\text{we conclude } \underline{\text{ann}(S) \oplus \text{ann}(T) = V^*}$$

P170 Consider $T: V \rightarrow W$ linear

$$\text{then 1st isomorphism Th}^{\circ} \text{ says } V/\text{Ker}(T) \cong T(V)$$

$$\text{thus } \underline{\dim(V/\text{Ker } T)} = \dim(T(V))$$

Rank-Nullity Thⁿ!

$$\dim V - \dim \text{Ker } T = \dim(T(V)) \therefore \underline{\dim V = \dim(\text{Ker } T) + \dim(T(V))}$$

(by Prop 10.1.22)

P171 Let (V, g) form a geometry and β a basis of V for which G is the matrix of g . Suppose $L: V \rightarrow V$ is a g -orthogonal map with matrix A ($\underbrace{[L(x)]_\beta = A[x]_\beta}$)
 Observe, $g(L(x), L(y)) = g(x, y)$ $[L]_{\beta\beta} = A$

$$\Rightarrow [L(x)]_\beta^T G [L(y)]_\beta = [x]_\beta^T G [y]_\beta$$

$$\Rightarrow (A[x]_\beta)^T G A[y]_\beta = [x]_\beta^T G [y]_\beta$$

$$\Rightarrow \underline{[x]_\beta^T A^T G A [y]_\beta = [x]_\beta^T G [y]_\beta} \quad *$$

Since L is g -orthogonal we have $*$ $\forall x, y \in V$.

If $\beta = \{v_1, \dots, v_n\}$ then setting $x = v_i$ and $y = v_j$

yields $[x]_\beta = e_i$ and $[y]_\beta = e_j$ and $*$ shows $(A^T G A)_{ij} = G_{ij}$

thus $A^T G A = G$.

P172 $g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$ with $g(v, w) = v^T \begin{bmatrix} 1 & -2 \\ & -3 \end{bmatrix} w$

Let $v = (v^1, v^2, v^3) = (a, b, c)$ then

$$v_i = \sum_{j=1}^3 g_{ij} v^j$$

$$= g_{i1} v^1 + g_{i2} v^2 + g_{i3} v^3$$

$$\Rightarrow \boxed{(v_1, v_2, v_3) = (a, -2b, -3c)}$$

Observe,

$$g(v, v) = [v^1, v^2, v^3] \begin{bmatrix} 1 & -2 \\ & -3 \end{bmatrix} \begin{bmatrix} v^1 \\ v^2 \\ v^3 \end{bmatrix} = \underline{(v^1)^2 - 2(v^2)^2 - 3(v^3)^2}$$

Hence, $g(v, v) = a^2 - 2b^2 - 3c^2$ whereas

$$\sum_{i=1}^3 v^i v_i = v^1 v_1 + v^2 v_2 + v^3 v_3 = \underline{a^2 - 2b^2 - 3c^2} \quad //$$

$$\begin{matrix} G \\ \rightarrow G^{-1} = \begin{bmatrix} 1 & & \\ & 1/2 & \\ & & 1/3 \end{bmatrix} \end{matrix}$$

But, didn't need it, btw,

if $\alpha = a e^1 + b e^2 + c e^3$
 then $(\alpha^1, \alpha^2, \alpha^3) = (a, -\frac{b}{2}, -\frac{c}{3})$

P172 generally,

$$\sum_{i=1}^n v^i v_i = \sum_{i=1}^n v^i \sum_{j=1}^n g_{ij} v^j = \sum_{i,j=1}^n v^i g_{ij} v^j = g(v, v) \quad \uparrow \text{by } *$$

and, for $\beta = \{f_1, \dots, f_n\}$ where $g_{ij} = g(f_i, f_j)$

$$g(v, w) = g\left(\sum_i v^i f_i, \sum_j w^j f_j\right) = \sum_{i,j} v^i w^j g(f_i, f_j) = \sum_{i,j} v^i w^j g_{ij} \quad *$$

Remark: Notice v^i, v_i are #'s in this problem.

Elsewhere, we have used $v_1, \dots, v_n \in V$ & $v'_1, \dots, v'_n \in V^*$

P173 $\mathcal{T}(A, B) = AB + BA \quad \forall A, B \in \mathbb{R}^{n \times n}$

Observe $\mathcal{T}(B, A) = BA + AB = AB + BA = \mathcal{T}(A, B) \therefore \mathcal{T}$ symmetric.

Then $\mathcal{T}(c, A+C, B) = (c, A+C)B + B(c, A+C)$

$$= c, AB + CB + c, BA + BC$$

$$= c, (AB + BA) + CB + BC$$

$$= c, \mathcal{T}(A, B) + \mathcal{T}(c, B)$$

Moreover, by symmetry, $\mathcal{T}(B, c, A+C) = c, \mathcal{T}(B, A) + \mathcal{T}(B, c)$

thus $\mathcal{T} : \mathbb{R}^{n \times n} \times \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^{n \times n}$ is a symmetric bilinear form.

Suppose $g : V \times V \rightarrow \mathbb{R}$ is a metric for $\mathcal{G}$.

P174 Let $g^* : V^* \times V^* \rightarrow \mathbb{R}$ be defined by $g^*(\alpha, \beta) = g(\# \alpha, \# \beta)$

for all $(\alpha, \beta) \in V^* \times V^*$ where $\# : V^* \rightarrow V$ is the usual musical morphism (in coordinates $\#(\sum_i \alpha_i v^i) = \sum_{i,j} \alpha_i g^{ij} v_j$)

Observe, $g^*(\alpha, \beta) = g(\# \alpha, \# \beta) = g(\# \beta, \# \alpha) = g^*(\beta, \alpha) \therefore$ symmetric.

Also, $g^*(c\alpha + \gamma, \beta) = g(\#(c\alpha + \gamma), \# \beta)$

$$= g(c\# \alpha + \# \gamma, \# \beta)$$

$$= c g(\# \alpha, \# \beta) + g(\# \gamma, \# \beta)$$

$$= c g^*(\alpha, \beta) + g^*(\gamma, \beta) \therefore g^* \text{ bilinear}$$

it remains to show g^* is nondegenerate $\rightarrow$

P174 continued

to prove nondegeneracy we can calculate the matrix of g^* and relate it to the matrix of g . Let $\{V_1, \dots, V_n\}$ have dual basis $\{V^1, \dots, V^n\}$ then $g_{ij} = g(V_i, V_j)$. Calculate $V_i = \sum_{j=1}^n \delta_{ij} V^j$

thus $(V_i)^j = \delta_{ij}$ describe components of V_i . Thus,

$$b(V_i) = \sum_{h,l} (V_i)^k g_{kl} V^l = \sum_{h,l} \delta_{ik} g_{hl} V^l$$

$$\therefore b(V_i) = \sum_l g_{il} V^l \quad \#$$

Oh, well, that's not what I need (for this problem)

Observe $V^i = \sum_{j=1}^n \delta_{ij} V^j \therefore (V^i)_j = \delta_{ij}$ thus

$$\#(V^i) = \sum_{h,l} \delta_{ih} g^{kl} V_l = \sum_l g^{il} V_l = \#(V^i) \quad **$$

Thus,

$$\begin{aligned} g^*(V^i, V^j) &= g(\#(V^i), \#(V^j)) \\ &= g\left(\sum_l g^{il} V_l, \sum_k g^{jk} V_k\right) \\ &= \sum_{l,k} g^{il} g^{jk} \underbrace{g(V_l, V_k)}_{g_{lk}} \\ &= \sum_l g^{il} \delta_{jl} \\ &= g^{ij} \Rightarrow \end{aligned}$$

$\therefore (V^*, g^*)$ forms a real geometry.

P175 we'll use $\#$ and $\#^*$

to prove $\# \circ b = id_V$, $b \circ \# = id_{V^*}$

g^* has matrix G^{-1} when g has matrix G (provided we use dual basis for V^* relative to given basis of V)
 $\therefore g^*$ is nondegenerate

P175 following notation of P174

$$\begin{aligned}(\# \circ b)(v_i) &= \#(b(v_i)) \\&= \# \left(\sum_{\lambda} g_{i\lambda} v^{\lambda} \right) \\&= \sum_{\lambda} g_{i\lambda} \#(v^{\lambda}) \\&= \sum_{\lambda} g_{i\lambda} \sum_{\mu} g^{\lambda\mu} v_{\mu} \\&= \sum_{\lambda, \mu} g_{i\lambda} g^{\lambda\mu} v_{\mu} \\&= \sum_{\mu} \delta_{i\mu} v_{\mu} \\&= v_i \quad \Rightarrow \quad \underline{\# \circ b = id_V} \quad \text{as } \{v_1, \dots, v_n\} \\&\quad \text{is basis}\end{aligned}$$

Likewise,

$$\begin{aligned}(b \circ \#)(v^i) &= b(\#(v^i)) \\&= b \left(\sum_{\mu} g^{i\mu} v_{\mu} \right) \\&= \sum_{\mu} g^{i\mu} b(v_{\mu}) \\&= \sum_{\mu} g^{i\mu} \sum_{\ell} g_{\mu\ell} v^{\ell} \\&= \sum_{\mu, \ell} g^{i\mu} g_{\mu\ell} v^{\ell} \\&= \sum_{\ell} \delta_{i\ell} v^{\ell} \\&= v^i \quad \Rightarrow \quad \underline{b \circ \# = id_{V^*}}\end{aligned}$$

as we shown the
identity holds for the
basis $\{v_1, \dots, v_n\}$ for V^*

P176 prove $X \otimes (z + w) = X \otimes z + X \otimes w$

for $X \in V$ and $z, w \in W$ where $V \otimes W = L(V^*, W)$

$$\begin{aligned}(X \otimes (z + w))(\alpha) &= \alpha(X)(z + w) && : \text{by def}^n (X \otimes y)(\alpha) = \alpha(X)y \text{ etc.} \\&= \alpha(X)z + \alpha(X)w && : \text{distributing in } W \\&= (X \otimes z)(\alpha) + (X \otimes w)(\alpha) && : \text{def}^n \text{ of } \otimes \text{ on} \\& && \text{vectors here.} \\&= (X \otimes z + X \otimes w)(\alpha) && : \text{addition of maps.}\end{aligned}$$

Thus $X \otimes (z + w) = X \otimes z + X \otimes w$ as claimed. //

P177 $X \otimes y: V^* \times V^* \rightarrow \mathbb{R}$ is defined by

$$(X \otimes y)(\alpha, \beta) = \alpha(X)\beta(y). \text{ Consider,}$$

$$(X \otimes y)(c\alpha_1 + \alpha_2, \beta) = (c\alpha_1 + \alpha_2)(X)\beta(y) = \text{def}^n$$

$$= (c\alpha_1(X) + \alpha_2(X))\beta(y) = \text{def}^n \text{ of adding functions}$$

$$= c\alpha_1(X)\beta(y) + \alpha_2(X)\beta(y)$$

$$= c(X \otimes y)(\alpha_1, \beta) + (X \otimes y)(\alpha_2, \beta)$$

Likewise,

$$(X \otimes y)(\alpha, c\beta_1 + \beta_2) = \alpha(X)(c\beta_1 + \beta_2)(y)$$

$$= \alpha(X)(c\beta_1(y) + \beta_2(y))$$

$$= c\alpha(X)\beta_1(y) + \alpha(X)\beta_2(y)$$

$$= c(X \otimes y)(\alpha, \beta_1) + (X \otimes y)(\alpha, \beta_2)$$

Thus $\underbrace{X \otimes y}_{\text{bilinear map on } V^* \times V^*} \in \mathcal{B}(V^*) = \mathcal{B}(V^* \times V^*, \mathbb{R})$.

P178 V has basis $\beta = \{v_1, \dots, v_n\}$ then prove

$\mathcal{T} = \{v_i \otimes v_j \mid 1 \leq i, j \leq n\}$ serves as basis for $\mathcal{B}(V^*)$

Suppose $\sum_{i,j=1}^n c_{ij} v_i \otimes v_j = 0$ then evaluate on (v^k, v^l)

where $v^k, v^l \in \beta^* \subset V^*$ defined as usual $v^k(v_i) = \delta_{ki}$
and $v^l(v_j) = \delta_{lj}$ etc. Thus,

$$\begin{aligned} 0 &= \left(\sum_{i,j} c_{ij} v_i \otimes v_j \right) (v^k, v^l) = \sum_{i,j} c_{ij} (v_i \otimes v_j)(v^k, v^l) \\ &= \sum_{i,j} c_{ij} v^k(v_i) v^l(v_j) \\ &= \sum_{i,j} c_{ij} \delta_{ki} \delta_{lj} \\ &= c_{kl} \Rightarrow c_{ij} = 0 \quad \forall i, j \\ &\Rightarrow \underline{\mathcal{T} \text{ is LI.}} \end{aligned}$$

If $b: V^* \times V^* \rightarrow \mathbb{R}$ is bilinear then

$$b(\alpha, \beta) = b\left(\sum_i \alpha_i v^i, \sum_j \beta_j v^j\right)$$

$$= \sum_{i,j} \alpha_i \beta_j b(v^i, v^j)$$

$$= \sum_{i,j} b(v^i, v^j) \alpha(v_i) \beta(v_j)$$

$$= \left(\sum_{i,j} b(v^i, v^j) v_i \otimes v_j \right) (\alpha, \beta) \quad \forall \alpha, \beta \in V^*$$

$$\therefore b = \sum_{i,j} b(v^i, v^j) v_i \otimes v_j \therefore \underline{\text{span}(\mathcal{T}) = \mathcal{B}(V^*)}$$

(we already showed $\mathcal{T} \subseteq \mathcal{B}(V^*)$ in P177) (the calculation here shows $\mathcal{B}(V^*) \subseteq \text{span}(\mathcal{T})$)
hence $\text{span} \mathcal{T} = \mathcal{B}(V^*)$.

P179 Suppose A, N are square matrices for which $N^k = 0$ yet $N^{k-1} \neq 0$. Consider,

$$\begin{aligned}
 (A \otimes N)^p &= \underbrace{(A \otimes N)(A \otimes N) \dots (A \otimes N)}_{p\text{-fold copies}} \\
 &= (A^2 \otimes N^2)(A \otimes N) \dots (A \otimes N) \\
 &\vdots \\
 &= A^p \otimes N^p \quad \underbrace{\hspace{10em}}_{(p-2)\text{-copies}}
 \end{aligned}$$

} can make rigorous by induction on p if you wish.

Thus, $(A \otimes N)^{k-1} = A^{k-1} \otimes N^{k-1} \neq 0$ (provided $A^{k-1} \neq 0$)

and $(A \otimes N)^k = A^k \otimes N^k = A^k \otimes 0 = 0$.

Thus, $(A \otimes N)^k = 0$ and $(A \otimes N)^{k-1} \neq 0$ provided $A^{k-1} \neq 0$.

This much I can say, $A \otimes N$ is nilpotent of degree at most k . (if $A^2 = 0$ & $A \neq 0$ then $(A \otimes N)^2 = A^2 \otimes N^2 = 0$)

Generally $A \otimes N$ is nilpotent if either A or N is nilpotent and the degree of $A \otimes N$ will be the smallest degree of nilpotent A or N .

P180 Let $T: V \times V \times V^* \rightarrow \mathbb{R}$ be multilinear

$$T = \sum_{i,j,k} T_{ij}^k V^i \otimes V^j \otimes V_k$$

← follows from calculations much like I've shown for bilinear case in this solⁿ

where $T_{ij}^k = T(V_i, V_j, V^k)$.

If $\bar{V}^i = \sum \Lambda^i_j V^j$ then $\bar{V}_i = \sum (\Lambda^{-1})_i^j V_j$

and thus,

$$\begin{aligned} \bar{T}_{ij}^k &= T(\bar{V}_i, \bar{V}_j, \bar{V}^k) \\ &= T\left(\sum_l (\Lambda^{-1})_i^l V_l, \sum_m (\Lambda^{-1})_j^m V_m, \sum_n \Lambda^k_n V^n\right) \\ &= \sum_{l,m,n} (\Lambda^{-1})_i^l (\Lambda^{-1})_j^m \Lambda^k_n \underbrace{T(V_l, V_m, V^n)}_{T_{lm}^n} \\ &= \sum_{l,m,n} (\Lambda^{-1})_i^l (\Lambda^{-1})_j^m \Lambda^k_n T_{lm}^n \end{aligned}$$

coord. change rule for components of T

Yes, $S = T \circ (\#, \#, b)$

is multilinear as it is composite of linear & multilinear map

and $S: V^* \times V^* \times V \xrightarrow{(\#, \#, b)} V \times V \times V^* \xrightarrow{T} \mathbb{R}$

$$S = \sum_{i,j,k} S^{ij}_k V_i \otimes V_j \otimes V^k$$

and by a calculation much like that given for T ,

$$S(\bar{V}^i, \bar{V}^j, V_k) = \bar{S}^{ij}_k = \sum_{l,m,n} \Lambda^i_l \Lambda^j_m (\Lambda^{-1})_k^n S^{lm}_n$$

coord. change rule for components of S .