Please follow the format which was announced in Blackboard. Thanks!

Your PRINTED NAME indicates you have read through Chapter 4 and 5 of the notes:

- **Problem 37** What condition is needed for $(a, b, c) \in \text{span}\{(1, 2, 0), (1, 0, 1)\}$?
- **Problem 38** Is $(1, 2, 3, 4, 5, 6) \in \text{span}((1, 1, 1, 1, 1, 1), (0, 1, 0, 1, 0, 2), (6, 5, 4, 3, 2, 1))$? Use technology paired with the CCP to answer this question.
- **Problem 39** Find a matrix A for which $rref[A] = \begin{bmatrix} 1 & 0 & 2 & 3 & 0 \\ 0 & 1 & 4 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ and $col_1(A) = [7, 5, 3]^T$ and $col_2(A) = [2, 0, 2]^T$. Is your answer unique?
- **Problem 40** Plot the vectors $a = \langle 1, 2 \rangle$ and $b = \langle -1, 3 \rangle$ in the *xy*-plane. Calculate $\det(a|b)$ and $\det(b|a)$. Explain the significance of the sign and magnitude of your answers.
- **Problem 41** Let a = (1, 2, 2) and b = (1, 0, 7) and c = (1, -3, -6). Calculate the volume of the parallel-piped with sides a, b, c.
- **Problem 42** Find all values of k for which $S(k) = \{(k, 2, 2), (2, k, 1), (3, 3, 3)\}$ a LI set.
- Problem 43 Remember, we have many properties to use in addition to the cofactor formulae,
 - (a.) Calculate det(A) where $A = \begin{bmatrix} 2 & 2 & 0 \\ 0 & 2 & 2 \\ 5 & 3 & 1 \end{bmatrix}$
 - **(b.)** Calculate det(B) where $B = \begin{bmatrix} 2 & 4 & 2 & 3 & 1 \\ 0 & 8 & 6 & 7 & 2 \\ 0 & 10 & 3 & 9 & 0 \\ 0 & 7 & 0 & 4 & 0 \\ 0 & 5 & 0 & 0 & 0 \end{bmatrix}$
 - (c.) Let A, B be as given in the previous problems. If $M = \begin{bmatrix} 2A & 0 \\ 0 & 3B \end{bmatrix}$ then calculate $\det(M)$ via application of properties of determinants given in the lecture notes and the results of the previous pair of problems.
- **Problem 44** Let a=(1,1,1) and b=(0,1,1). Form $M=[a|b]\in\mathbb{R}^{3\times 2}$. Let \widehat{M}_i be the submatrix of M formed by taking M and removing the i-th row of M. For example, $\widehat{M}_3=\begin{bmatrix}1&0\\1&1\end{bmatrix}$. Calculate:
 - (a.) $\det(\widehat{M}_1)$
 - **(b.)** $\det(\widehat{M}_2)$
 - (c.) $\det(\widehat{M}_3)$

Problem 45 Let a=(1,1,1,1) and b=(0,1,1,0) and c=(2,3,3,2). Form $M=[a|b|c]\in\mathbb{R}^{4\times 3}$. Let \widehat{M}_i be the submatrix of M formed by taking M and removing the i-th row of M. For example, $\widehat{M}_4=\begin{bmatrix}1&0&2\\1&1&3\\1&1&3\end{bmatrix}$. Calculate:

- (a.) $\det(\widehat{M}_1)$
- **(b.)** $\det(\widehat{M}_2)$
- (c.) $\det(\widehat{M}_3)$
- (d.) $\det(\widehat{M}_4)$

Remark: Apparently we can use determinants to test LI of subsets of k-vectors in \mathbb{R}^n where k < n. Based on the calculations in the two problems above, we conjecture $S \subseteq \mathbb{R}^n$ is linearly independent if and only if there exists i for which $\det(\widehat{[S]}_i) \neq 0$. This means we need to calculate a number of determinants to decide the LI of a set via direct computation.

Problem 46 In this problem I give you a brief introduction into the **exterior algebra**. These calculations can be made rigorous, but, that is beside the point here. We can define \wedge of vectors. Given two vectors a, b the $a \wedge b$ is a so-called 2-vector. Likewise, $a \wedge b \wedge c$ is a 3-vector. This **wedge product** enjoys the usual distributive laws with respect to addition and scalar multiplication of vectors,

$$(sa+tb) \wedge c = sa \wedge c + tb \wedge c$$
 & $a \wedge (sb+tc) = sa \wedge b + ta \wedge c$.

It is also assocative,

$$a \wedge (b \wedge c) = (a \wedge b) \wedge c$$

However, $a \wedge b = -b \wedge a$ for any pair of vectors. In particular $a \wedge a = 0$. If we have many vectors then we generate a negative sign for each transposition of vectors:

$$a \wedge b \wedge c = -a \wedge c \wedge b = c \wedge a \wedge b = -c \wedge b \wedge a = b \wedge c \wedge a = -b \wedge a \wedge c$$

For more vectors, similar calculations hold:

$$v_1 \wedge \cdots \wedge v_{k-1} \wedge v_k \wedge v_{k+1} \wedge \cdots \wedge v_m = (-1)^k v_k \wedge v_1 \wedge \cdots \wedge v_{k-1} \wedge v_{k+1} \wedge \cdots \wedge v_m.$$

- (a.) Let $a = e_1 + e_3$ and $b = e_1 + e_2$ and $c = 2e_1 + e_2 + e_3$. Calculate $a \wedge b \wedge c$.
- **(b.)** Let $a = e_1 + e_2 + e_3$ and $b = e_1 + e_2$ and $c = e_3$. Calculate $a \wedge b \wedge c$
- (c.) Show that if $S = \{v_1, v_2, \dots, v_k\}$ is linearly dependent then $v_1 \wedge v_2 \wedge \dots \wedge v_k = 0$

Remark: in fact, if $v_1 \wedge v_2 \wedge \cdots \wedge v_k \neq 0$ then $\{v_1, v_2, \dots, v_k\}$ is LI. I haven't asked you to prove that as it requires me to discuss more of the construction of \wedge than I am currently interested in describing. We may return to this topic once we have a few more tools.

Problem 47 Now I'll focus on \mathbb{R}^3 where the algebra is most familar. We define correspondence between 2-vectors and vectors by:

$$\Phi_{\langle v_1, v_2, v_3 \rangle} = v_1 e_2 \wedge e_3 + v_2 e_3 \wedge e_1 + v_3 e_1 \wedge e_2.$$

In case you have not had Math 231 (again, so sorry if you were cheated out of this important course in your education) you should know the **dot-product** of two vectors gives a number whose size roughly describes how parallel the given vectors are:

$$\langle a_1, a_2, a_3 \rangle \cdot \langle b_1, b_2, b_3 \rangle = a_1 b_1 + a_2 b_2 + a_3 b_3$$

and the **cross-product** is a vector which points in the direct perpendicular to the given vectors according to the **right-hand-rule**. The vector $a \times b$ is longest when a and b are perpendicular and $a \times b = 0$ when a and b are colinear. Anyway, all you need here is that:

$$\langle a_1, a_2, a_3 \rangle \times \langle b_1, b_2, b_3 \rangle = \langle a_2b_3 - a_3b_2, a_3b_1 - a_1b_3, a_1b_2 - a_2b_1 \rangle$$

- (a.) Let $a = (a_1, a_2, a_3)$ and $b = (b_1, b_2, b_3)$ and show $a \wedge b = \Phi_{a \times b}$.
- **(b.)** Consider vectors $a, b, c \in \mathbb{R}^3$, show $a \wedge b \wedge c = a \cdot (b \times c)e_1 \wedge e_2 \wedge e_3$.

Remark: Can you see how the components of $a \times b$ (and hence the coefficients of $a \wedge b$) relate to subdeterminants of [a|b]?

Problem 48 Background: One of my favorite applications of Cramer's Rule is found in advanced calculus. In particular, when dealing with several nonlinear equations in multiple unknowns then the question arises when you can solve for certain variables in terms of the other variables. Furthermore, if you can solve for the variable then what are the partial derivatives of the given dependent variable in terms of the independent variables? This question arises in many contexts of applied mathematics and especially thermodynamics.

The calculational procedure is fairly simple:

- (1.) take the total differential of the given equations which constrain the variables,
- (2.) solve for the differentials of the desired dependent variables.

This is a problem of linear algebra because (1.) returns an equation which is linear in the differentials. Moreover, (2.) is nicely accomplished by Cramer's Rule.

I'll state your problem: find partial derivatives of u in terms of x, y given that:

$$u^{2} + v^{2} - x^{2} - y^{2} + z^{2} = 1,$$

 $v + z - xy = 0$
 $xv + yz = 0$

I'll do the calculus part: (I take the total differential of the given constraint equations)

$$2udu + 2vdv - 2xdx - 2ydy + 2zdz = 0,$$

$$dv + dz - ydx - xdy = 0$$

$$vdx + xdv + zdy + ydz = 0$$

Complete the calculation via the following steps:

(a.) rearrange the equation with differentials into the form

$$\begin{bmatrix} * & * & * \\ * & * & * \\ * & * & * \end{bmatrix} \begin{bmatrix} du \\ dv \\ dz \end{bmatrix} = \begin{bmatrix} (*)dx + (*)dy \\ (*)dx + (*)dy \\ (*)dx + (*)dy \end{bmatrix}$$

(here the *'s simply denote particular expressions involving u, v, x, y, z)

- (b.) solve for du via Cramer's Rule on the system you found in (a.)
- (c.) Calculus tells us that $du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy$. Compare with your result in (b.) to calculate the desired partial derivatives $\frac{\partial u}{\partial x}$ and $\frac{\partial u}{\partial y}$.
- **Problem 49** Let $A = \begin{bmatrix} M & 0 \\ 0 & N \end{bmatrix}$ where $M = \begin{bmatrix} 2 & 3 \\ -3 & 2 \end{bmatrix}$ and $N = \begin{bmatrix} 7 & 8 \\ 0 & 9 \end{bmatrix}$. Find all $x \in \mathbb{C}$ for which the matrix A xI is **not** invertible.
- **Problem 50** We say square matrices A and B are **similar** if there is an invertible matrix P for which $B = PAP^{-1}$. Suppose A has $\det(A) = 2$ whereas B has $\det(B) = 7$. Is it possible that A is similar to B? Explain your claim.
- **Problem 51** Show $\{e_1, e_1 + e_2, e_1 + e_2 + e_3, \dots, e_1 + e_2 + \dots + e_n\}$ is a LI subset of \mathbb{R}^n for any $n \in \mathbb{N}$.
- **Problem 52** Prove part (4.) of Theorem 2.3.11 in my notes.
- **Problem 53** Find a careful description of $S = \{A \in \mathbb{R}^{n \times n} \mid AB = BA \text{ for all } B \in \mathbb{R}^{n \times n} \}.$
- **Problem 54** Find all cubic polynomials whose graphs contain the points (1,2),(2,2).