

Same rules as Homework 1.

Problem 47 Your signature below indicates you have:

- (a.) I read what Cook has posted of Chapter 3 of the Lecture Notes: _____.
- (b.) I read most of Sections 5-10 of Curtis: _____.

Problem 48 Prove (4.) of Theorem 3.1.13 in my Lecture notes. You are free to assume that (1.), (2.), (3.) and the Law of Cancellation are already established facts.

Problem 49 Let $W = \{A \in \mathbb{F}^{n \times n} \mid A^T = -A\}$. Show that $W \leq \mathbb{F}^{n \times n}$. (aww man, another subspace test problem)

Problem 50 Suppose $\beta = \{v_1, \dots, v_n\}$ forms a basis for the vector space V over the field $\mathbb{F}$. Show that $[cx + y]_\beta = c[x]_\beta + [y]_\beta$ for all $x, y \in V$ and $c \in \mathbb{F}$.

Problem 51 Find a basis β for $W = \{A \in \mathbb{R}^{3 \times 3} \mid A^T = -A\}$.

Also, calculate $[A]_\beta$ given $A = \begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{bmatrix}$.

There are infinitely many correct answers here, sorry Daniel.

Problem 52 Find a basis for $W = \{A \in \mathbb{F}^{n \times n} \mid A^T = A\}$ as a vector space over $\mathbb{F}$. Calculate $\dim_{\mathbb{F}}(W)$. (you can set $\mathbb{F} = \mathbb{R}$ if you wish to keep it real)

Problem 53 Let $W = \{p(t) \in \mathbb{R}[t] \mid p^{(n)}(1) = 0 \text{ for } n = 3, 4, 5, \dots\}$. Prove W is a subspace of $\mathbb{R}[t]$ by explicitly finding S for which $W = \text{span}(S)$.

Problem 54 Let $A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 3 & 3 & 3 & 3 \end{bmatrix}$. Find bases for the column, row and null space of A . For the column and row space use actual columns and rows of A to form the bases.

Problem 55 Let $A = \begin{bmatrix} \bar{1} & \bar{0} \\ \bar{2} & \bar{1} \\ \bar{9} & \bar{1} \end{bmatrix} \in (\mathbb{Z}/11\mathbb{Z})^{3 \times 2}$. Find bases for the column, row and null space of A .

Problem 56 Consider $W = \text{span}_{\mathbb{C}}\{1, x, x^2\}$ as a vector space over $\mathbb{R}$. Find a basis for W .

Problem 57 Let $\beta = \{x^2, (1+x)^2\}$, and define $W = \text{span}(\beta)$ as a subspace of $P_2(\mathbb{R})$. If $f(x) = ax^2 + bx + c \in W$ then find $[f(x)]_\beta$.

Problem 58 Curtis §5 #3 on page 37. Your solution should focus on the LI of the proposed basis. Prove $\{1, x, x^2, \dots, x^n\}$ is a LI set.

Problem 59 Curtis §6 #5 on page 48. (linear dependence in polynomials)

- Problem 60** Curtis §7 #4 on page 52. (subspace intersection calculation)
- Problem 61** Curtis §7 #5 on page 52. (subspace intersection proof question)
- Problem 62** Curtis §8 #2 on page 61. (solvability of system)
- Problem 63** Curtis §8 #4 on page 62 (I'd like you to use my Proposition 3.8.4 or something similar)
- Problem 64** Curtis §9 #6 on page 69 (a result in the algebraic geometry of lines)
- Problem 65** Curtis §10 #2 on page 73 (interesting reverse of our usual calculation)
- Problem 66** Curtis §10 #7 on page 74 (hyperplanes as solution sets)
- Problem 67** Curtis §10 #8 on page 74 (basis for intersection of subspace)
- Problem 68** Prove Theorem 3.7.4 in my notes. In particular, show the following is true:
If V is a vector space over a field $\mathbb{F}$ and $U \leq V$ and $W \leq V$ then $U \cap W \leq V$.
- Problem 69** Prove Theorem 3.7.6 in my notes. In particular, show the following is true:
If V is a vector space over a field $\mathbb{F}$ and $U \leq V$ and $W \leq V$ then $U + W \leq V$.
Furthermore, $U + W$ is the smallest subspace which contains $U \cup W$.
- Problem 70** Prove Proposition 3.4.4 of the Lecture Notes: that is, prove the following:
Let V be a vector space over a field $\mathbb{F}$ and $S \subseteq V$. S is a linearly independent set of vectors iff if there exist $a_i, b_i \in \mathbb{F}$ for $i \in \mathbb{N}_k$ for which

$$a_1v_1 + a_2v_2 + \cdots + a_kv_k = b_1v_1 + b_2v_2 + \cdots + b_kv_k$$

then $a_i = b_i$ for each $i = 1, 2, \dots, k$. In other words, we can equate coefficients of a set of vectors iff the set of vectors is a LI set.

MISSION 4 SOLUTION

P48 See my notes.

P49 $W = \{A \in \mathbb{F}^{n \times n} \mid A^T = -A\}$. Show $W \subseteq \mathbb{F}^{n \times n}$

Observe $0^T = 0 = -0 \therefore 0 \in W \neq \emptyset$. Let $A, B \in W$.

and note $(A+B)^T = A^T + B^T = -A - B = -(A+B) \therefore A+B \in W$.

Likewise, if $\alpha \in \mathbb{F}$ and $A \in W$ then by prop. of transpose we also find $(\alpha A)^T = \alpha A^T = \alpha(-A) = -(\alpha A) \therefore \alpha A \in W$.

Thus $W \subseteq \mathbb{F}^{n \times n}$ by the subspace test Th^m //

P50 Let $\beta = \{v_1, \dots, v_n\}$ form a basis for $V(\mathbb{F})$.

If $x, y \in V$ then $\exists \alpha_i, \beta_i \in \mathbb{F}$ for $i \in \mathbb{N}_n$ such that $x = \sum_{i=1}^n \alpha_i v_i$ and $y = \sum_{i=1}^n \beta_i v_i$. By

defⁿ of coordinate chart, $[x]_\beta = (\alpha_1, \dots, \alpha_n)$ and

$[y]_\beta = (\beta_1, \dots, \beta_n)$. Notice,

$$\begin{aligned} c x + y &= c \sum_{i=1}^n \alpha_i v_i + \sum_{i=1}^n \beta_i v_i \\ &= \sum_{i=1}^n (c\alpha_i + \beta_i) v_i \end{aligned}$$

Thus $[cx + y]_\beta = (c\alpha_1 + \beta_1, \dots, c\alpha_n + \beta_n)$.

Finally, note,

$$(c\alpha_1 + \beta_1, \dots, c\alpha_n + \beta_n) = c(\alpha_1, \dots, \alpha_n) + (\beta_1, \dots, \beta_n)$$

$$\Rightarrow \underline{[cx + y]_\beta = c[x]_\beta + [y]_\beta \quad \forall x, y \in V, c \in \mathbb{F}} //$$

Could write less. $\curvearrowright$

P50 Concise solⁿ

Let $\beta = \{v_i\}_{i=1}^n$ form basis for V . Let $x, y \in V(\mathbb{F})$
and suppose $\exists \alpha_i, \beta_i \in \mathbb{F}$ such that $x = \sum_{i=1}^n \alpha_i v_i$ & $y = \sum_{i=1}^n \beta_i v_i$

Note, $x + cy = \sum_{i=1}^n \alpha_i v_i + c \sum_{i=1}^n \beta_i v_i = \sum_{i=1}^n (\alpha_i + c\beta_i) v_i$ by
properties of finite sums. Thus $([x+cy]_\beta)_i = \underline{\alpha_i + c\beta_i} \quad \forall i \in \mathbb{N}_n$

But, $([x]_\beta + c[y]_\beta)_i = ([x]_\beta)_i + c([y]_\beta)_i = \underline{\alpha_i + c\beta_i} \quad \text{by } \textcircled{II}$
defⁿ of word. map $\therefore$ comparing $\textcircled{I}$ and $\textcircled{II}$ we find

$$[x+cy]_\beta = [x]_\beta + c[y]_\beta \quad \forall c \in \mathbb{F} \text{ and } x, y \in V.$$

Remark: maybe the less concise solⁿ is just as good here.

P51 $W = \{A \in \mathbb{R}^{3 \times 3} \mid A^T = -A\}$ find basis β for W & calculate
 $[A]_\beta$ for $A = \begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{bmatrix}$

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = -\begin{bmatrix} a & d & g \\ b & e & h \\ c & f & i \end{bmatrix} = -A^T$$

Thus, $a = -a, b = -d, c = -g, e = -e, i = -i, f = -h$

These yield $a = e = i = 0$ and $d = -b, g = -c, h = -f$

$$A = \begin{bmatrix} 0 & a & c \\ -a & 0 & f \\ -c & -f & 0 \end{bmatrix} = a \underbrace{\begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}}_{g_1} + c \underbrace{\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}}_{g_2} + f \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}}_{g_3}$$

Let $\beta = \{g_1, g_2, g_3\}$ notice

that $\text{span } \beta = W$ by calculation above and from

$$c_1 g_1 + c_2 g_2 + c_3 g_3 = \begin{bmatrix} 0 & c_1 & c_2 \\ -c_1 & 0 & c_3 \\ -c_2 & -c_3 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow c_1 = c_2 = c_3 = 0$$

$\therefore \beta$ is LI & $\text{span } \beta = W \therefore \beta$ is basis for W .

$$\begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{bmatrix} = 1 \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + 2 \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \Rightarrow [A]_\beta = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

P52 $W = \{A \in \mathbb{F}^{n \times n} / A^T = A\}$ find β for W & $\dim_{\mathbb{F}} W = ?$

$$A \in W \Rightarrow A^T = A \Rightarrow A_{ij} = A_{ji} \quad \forall i, j \in \mathbb{N}_n.$$

Consider, $A = \sum_{i,j=1}^n A_{ij} E_{ij}$ hence, think about it,

$$A = \sum_{i < j} A_{ij} E_{ij} + \sum_{i=j} A_{ij} E_{ij} + \sum_{i > j} A_{ij} E_{ij}$$

$$= \sum_{i < j} A_{ij} E_{ij} + \sum_{i > j} A_{ji} E_{ij} + \sum_{i=1}^n A_{ii} E_{ii}$$

$$= \underbrace{\sum_{k < l} A_{kl} E_{kl}}_{\substack{i=k \\ j=l}} + \underbrace{\sum_{l > k} A_{kl} E_{lk}}_{\substack{i=l \\ j=k}} + \sum_{i=1}^n A_{ii} E_{ii}$$

$$= \sum_{k < l} A_{kl} (E_{kl} + E_{lk}) + \sum_{i=1}^n A_{ii} E_{ii} \quad (*)$$

$$\text{Let } \beta = \{E_{kl} + E_{lk} \mid 1 \leq k < l \leq n\} \cup \{E_{ii}\}_{i=1}^n$$

We have $\beta \subseteq W$ hence $\text{span } \beta \subseteq W$ $\left(\begin{array}{l} (E_{kl} + E_{lk})^T = E_{kl} + E_{lk} \\ E_{ii}^T = E_{ii} \end{array} \right)$
and $W \subseteq \text{span } \beta$ by our calculation (*)

Thus, $W = \text{span } \beta$. If we set

$$\sum_{k < l} c_{kl} (E_{kl} + E_{lk}) + \sum_{i=1}^n c_{ii} E_{ii} = 0$$

$$\Rightarrow \begin{bmatrix} c_{11} & c_{12} & \dots & c_{1n} \\ c_{21} & c_{22} & \dots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{in} & \dots & \dots & c_{nn} \end{bmatrix} = \begin{bmatrix} 0 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 0 \end{bmatrix} \Rightarrow \begin{array}{l} c_{kl} = 0 \quad k < l \\ c_{ii} = 0 \quad \forall i \in \mathbb{N}_n \end{array}$$

Thus β is L.I. (you could argue this from (*) also!)

Now, COUNT. In total $n^2 - n$ are off-diagonal

$$\text{But only need } \frac{1}{2} \Rightarrow \underbrace{\frac{n^2 - n}{2}}_{k < l} + \underbrace{n}_{ii} = \boxed{\frac{n^2 + n}{2} = \dim_{\mathbb{F}}(W)}$$

PS3 $W = \{ p(x) \in \mathbb{R}[x] \mid p^{(n)}(1) = 0 \text{ for } n=3,4,5,\dots \}$

By Taylor's Th^m, at $a=1$,

$$p(x) = \sum_{n=0}^{\infty} \frac{p^{(n)}(1)}{n!} (x-1)^n$$

$$= p(1) + p'(1)(x-1) + \frac{1}{2} p''(1)(x-1)^2$$

Thus, $\boxed{W = \text{span} \{1, x-1, (x-1)^2\} \subseteq \mathbb{R}[x]}$.

Alternate Solⁿ

$$p(x) = c_0 + c_1 x + c_2 x^2 + c_3 x^3 + \dots + c_n x^n$$

$$p'(x) = c_1 + 2c_2 x + 3c_3 x^2 + \dots + n c_n x^{n-1}$$

$$p''(x) = 2c_2 + 6c_3 x + \dots + n(n-1)c_n x^{n-2}$$

$$p'''(x) = 6c_3 + 24c_4 x + \dots + n(n-1)(n-2)c_n x^{n-3} = 0$$

$$\Rightarrow c_3 = c_4 = \dots = c_n = 0$$

$$\therefore p(x) = c_0 + c_1 x + c_2 x^2 \in \text{span} \{1, x, x^2\}$$

We can also argue $\underline{W = \text{span} \{1, x, x^2\} \subseteq \mathbb{R}[x]}$.

Q: WHICH WAY IS BEST?


A: I DON'T KNOW.... GUESS METHOD I
 IS NICE IF YOU
 KNOW YOUR CALCULUS II.

P54

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 3 & 3 & 3 & 3 \end{bmatrix} \xrightarrow{r_4 - 3r_1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{r_3/2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \text{rref}(A)$$

We find $\text{Col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \\ 3 \end{bmatrix} \right\}$
BASIS for Col(A).

$$A^T = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 1 & 0 & 0 & 3 \\ 1 & 0 & 2 & 3 \\ 1 & 0 & 2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \text{rref}(A^T)$$

↑ pivot columns
of A^T give
us which rows
of A to use

$\text{Row}(A) = \text{span} \left\{ [1, 0, 0, 3], [1, 0, 2, 3] \right\}$
BASIS FOR Row(A)

Remark: you COULD ANSWER THIS W/O CALCULATION!
 I MERELY CALCULATE TO ILLUSTRATE A METHOD
 WHICH WORKS FOR MUCHO-LESS-NICE-CHOICE OF A...

$$X \in \text{Null}(A) \Rightarrow AX = 0$$

$$\text{for } X = (x_1, x_2, x_3, x_4) \text{ from } \text{rref}(A|0) = \left[\begin{array}{cccc|c} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\text{we read } x_1 + x_2 = 0 \text{ \& } x_3 + x_4 = 0$$

$$\therefore X = (-x_2, x_2, -x_4, x_4) = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

It follows $\text{Null}(A) = \text{span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix} \right\}$
BASIS FOR Null(A).

P55

$$A = \begin{bmatrix} \bar{1} & \bar{0} \\ \bar{2} & \bar{1} \\ \bar{9} & \bar{1} \end{bmatrix} \in (\mathbb{Z}/11\mathbb{Z})^{3 \times 2}$$

find basis for Column, Row
& Null space of A.

Observe $\text{col}_1(A) \neq k \text{col}_2(A) \therefore \{\text{col}_1(A), \text{col}_2(A)\} \perp I$

Hence $\{(\bar{1}, \bar{2}, \bar{9}), (\bar{0}, \bar{1}, \bar{1})\}$ forms basis for $\text{Col}(A)$.

Likewise $[\bar{1}, \bar{0}] \neq k [\bar{2}, \bar{1}]$ for any $k \in \mathbb{Z}/11\mathbb{Z}$

$\therefore \{[\bar{1}, \bar{0}], [\bar{2}, \bar{1}]\}$ forms basis for $\text{Row}(A)$.

Since we know $\dim(\text{Row}(A)) = \dim(\text{Col}(A)) = 2$.

Remark: I did all this w/o calculation so far!

I might be able to guess basis for $\text{Null}(A)$

But, I'll behave and exhibit the method,

$$A = \begin{bmatrix} \bar{1} & \bar{0} \\ \bar{2} & \bar{1} \\ \bar{9} & \bar{1} \end{bmatrix} \xrightarrow[r_3 - 9r_1]{r_2 - 2r_1} \begin{bmatrix} \bar{1} & \bar{0} \\ \bar{0} & \bar{1} \\ \bar{0} & \bar{1} \end{bmatrix} \xrightarrow{r_3 - r_2} \begin{bmatrix} \bar{1} & \bar{0} \\ \bar{0} & \bar{1} \\ \bar{0} & \bar{0} \end{bmatrix} \Rightarrow \underline{AV = 0 \Leftrightarrow V = 0}$$

Well, this was dumb. I didn't need to do this!

$$\text{rank}(A) + \dim(A) = 2 \quad \text{and} \quad \text{rank}(A) = 2 \therefore \dim(A) = 0$$

which means $\text{Null}(A) = \{0\} \Rightarrow \boxed{\emptyset \text{ is basis for null space of } A}$

(or you can say
~~A~~ basis for $\text{Null}(A)$)

I'm not sure about
how our defⁿs
fall on this
question (U)

P56 $W = \text{span}_{\mathbb{C}} \{1, x, x^2\}$ as V -space over $\mathbb{R}$

$$g(x) \in W \Rightarrow \exists \underbrace{a_1 + ib_1, a_2 + ib_2, a_3 + ib_3}_{a_1, b_1, a_2, b_2, a_3, b_3 \in \mathbb{R}} \in \mathbb{C}$$

$$\text{Such that, } g(x) = (a_1 + ib_1)(1) + (a_2 + ib_2)x + (a_3 + ib_3)x^2 \\ = a_1 + ib_1 + a_2x + b_2(ix) + a_3x^2 + b_3(ix^2)$$

$$\text{Hence } g(x) \in \text{span}_{\mathbb{R}} \{1, i, x, ix, x^2, ix^2\}$$

$$\text{More over, } c_1(1) + c_2(i) + c_3(x) + c_4(ix) + c_5(x^2) + c_6(ix^2) = 0 \quad (*)$$

$$\text{Set } x=0, \quad c_1 + ic_2 = 0 \Rightarrow \underline{c_1 = 0} \text{ \& } \underline{c_2 = 0}.$$

$$\text{Differentiate } (*) \text{ w.r.t. } x, \quad c_3 + ic_4 + 2xc_5 + 2ixc_6 = 0 \quad (**)$$

$$\text{Set } x=0, \quad c_3 + ic_4 = 0 \Rightarrow \underline{c_3 = 0} \text{ \& } \underline{c_4 = 0}.$$

$$\text{Differentiate } (**) \text{ again, } 2c_5 + 2ic_6 = 0 \Rightarrow \underline{c_5 = 0}, \text{ \& } \underline{c_6 = 0}$$

$$\therefore \boxed{\{1, i, x, ix, x^2, ix^2\} \text{ forms basis of } W}$$

P57 $\beta = \{x^2, (1+x)^2\}$ and define $W = \text{span}_{\mathbb{R}} \beta \leq P_2(\mathbb{R})$

$$\text{Let } f(x) = ax^2 + bx + c \in W \text{ find } [f(x)]_{\beta}$$

$$\text{Comment, } x^2 \neq k(1+x^2) \Rightarrow \beta \text{ L.I.} \Rightarrow \beta \text{ BASIS of } W \\ \text{as } W = \text{span } \beta.$$

$$\text{Solve, } c_1x^2 + c_2(1+x)^2 = ax^2 + bx + c$$

$$\Rightarrow c_1x^2 + c_2(1+2x+x^2) = ax^2 + bx + c$$

$$(c_1 + c_2)x^2 + 2c_2x + c_2 = ax^2 + bx + c$$

We deduce from equating coeff. of $1, x, x^2$ (use P58 if you wish)

$$1: \quad c_2 = c \Rightarrow \underline{c_2 = c}.$$

$$x: \quad 2c_2 = b$$

$$x^2: \quad c_1 + c_2 = a \Rightarrow \underline{c_1 = a - c_2 = a - c}$$

$$(\text{Notice, } c_2 = c = \frac{b}{2} \text{ so can have } [f(x)]_{\beta} = \begin{bmatrix} a - b/2 \\ b/2 \end{bmatrix} \text{ etc...})$$

$$\boxed{[f(x)]_{\beta} = \begin{bmatrix} a - c \\ c \end{bmatrix}}$$

P58 I'll focus on showing $\{1, x, x^2, \dots, x^n\}$ is LI set.

ok
solⁿ

Consider $C_0 + C_1 x + C_2 x^2 + \dots + C_n x^n = 0$ (*)

set $x=0$ in (*) to obtain $C_0 = 0$. Next differentiate w.r.t. x to obtain from *,

$$C_1 + 2C_2 x + \dots + nC_n x^{n-1} = 0 \quad (**)$$

Set $x=0$ and obtain $C_1 = 0$. Diff. again,

$$2C_2 + \dots + n(n-1)C_n x^{n-2} = 0$$

Set $x=0$ and obtain $2C_2 = 0$. Continuing

in this fashion obtain $C_3 = 0, C_4 = 0, \dots, C_n = 0$

Hence $\{1, x, x^2, \dots, x^n\}$ is LI set.

//

Better solⁿ

(By induction we can show this claim carefully,

Let $\{1, x, x^2, \dots, x^n\}$ being LI form the induction claim for $n \in \mathbb{N}$:)

For $n=1$, $\{1, x\}$ is LI since $1 = kx \quad \forall x \in \mathbb{R}$ is clearly absurd hence $\{1, x\}$ is not lin. dep.

Suppose inductively, $\{1, x, \dots, x^n\}$ is LI and consider

$\{1, x, \dots, x^n, x^{n+1}\}$. Set $C_0 + C_1 x + C_2 x^2 + \dots + C_n x^n + C_{n+1} x^{n+1} = 0$ *

Let $x=0$ and obtain $C_0 = 0$. from *. Next, we

differentiate, $C_1 + 2C_2 x + \dots + nC_n x^{n-1} + C_{n+1}(n+1)x^n = 0$ **

But, by LI of $\{1, x, \dots, x^n\}$ we obtain

$$C_1 = 0, 2C_2 = 0, \dots, nC_n = 0, (n+1)C_{n+1} = 0$$

Thus, $C_0 = 0, C_1 = 0, C_2 = 0, \dots, C_n = 0, C_{n+1} = 0$.

Thus $\{1, \dots, x^{n+1}\}$ is LI and we find $\{1, x, \dots, x^n\}$ LI $\forall n \in \mathbb{N}$ by induction. //

PS9 §6 #5 on p. 48/

(a.) $S = \{x^2 + 2x + 1, 2x + 1, 2x^2 - 2x - 1\}$ LI?

Consider,

$$a(x^2 + 2x + 1) + b(2x + 1) + c(2x^2 - 2x - 1) = 0$$

$$\Rightarrow (a + 2c)x^2 + (2a + 2b - 2c)x + a + b - c = 0$$

(using PS8) $\Rightarrow a + 2c = 0, 2a + 2b - 2c = 0, a + b - c = 0$
($\neq$ P70 together)

Consider,
$$\begin{array}{ccc} a & b & c \\ \begin{bmatrix} 1 & 0 & 2 \\ 2 & 2 & -2 \\ 1 & 1 & -1 \end{bmatrix} & \xrightarrow[\substack{r_2 - 2r_1 \\ r_3 - r_1}]{r_2 - 2r_1} & \begin{bmatrix} 1 & 0 & 2 \\ 0 & 2 & -6 \\ 0 & 1 & -3 \end{bmatrix} \xrightarrow{r_2 - 2r_3} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 1 & -3 \end{bmatrix} \end{array}$$

Ok, $\exists$ nontrivial sol^s. I just need one set $c = 1$
then $a = -2$ and $b = 3$. Check it,

$$\boxed{-2(x^2 + 2x + 1) + 3(2x + 1) + 2x^2 - 2x - 1 = 0}$$

a linear dependence of S .

(b.) $U = \{1, x-1, (x-1)^2, (x-1)^3\}$ LI?

$$\text{Set } c_1 + c_2(x-1) + c_3(x-1)^2 + c_4(x-1)^3 = 0$$

Set $x=1$ to obtain $c_1 = 0$. Differentiate,

$$c_2 + 2c_3(x-1) + 3c_4(x-1)^2 = 0$$

Set $x=1$ to obtain $c_2 = 0$. Differentiate,

$$2c_3 + 6c_4(x-1) = 0$$

Set $x=1$ to obtain $2c_3 = 0 \Rightarrow \underline{c_3 = 0}$. Finally,

$$6c_4(x-1) = 0 \text{ thus set } x=2 \Rightarrow 6c_4 = 0$$

$\therefore c_4 = 0$. We conclude $\{1, x-1, (x-1)^2, (x-1)^3\}$ is LI.

P60 §7 #4 on pg. 52

Let $S, T \leq \mathbb{R}^3$ and $\dim(S) = \dim(T) = 2$.

Prove $\dim(S \cap T) \geq 1$

I'll attempt to see this from the Th^m,

$$\dim(S+T) + \dim(S \cap T) = \dim(S) + \dim(T) \quad *$$

$$\text{Thus, } \dim(S \cap T) = 4 - \dim(S+T)$$

Since $S+T \leq \mathbb{R}^3 \Rightarrow \dim(S+T) \leq 3$ (Th^m in my notes)

$$\therefore \dim(S \cap T) = 4 - \dim(S+T) \geq 4 - 3 = 1.$$

P61 §7 #5 on p. 52

$$\begin{aligned} \text{Let } a_1 &= \langle 2, 1, 0, -1 \rangle \\ a_2 &= \langle 4, 8, -4, -3 \rangle \\ a_3 &= \langle 1, -3, 2, 0 \rangle \\ a_4 &= \langle 1, 10, -6, -2 \rangle \\ a_5 &= \langle -2, 0, 6, 1 \rangle \\ a_6 &= \langle 3, -1, 2, 4 \rangle \end{aligned}$$

Find:

$\dim S$

$\dim T$

$\dim T+S$

$\dim T \cap S$ by * above.

$$\text{Let } S = \text{span}\{a_1, a_2, a_3, a_4\} \text{ \& } T = \text{span}\{a_4, a_5, a_6\}$$

I used the website www.math.odu.edu

$$\text{rref}[a_1 \ a_2 \ a_3 \ a_4] = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{CCP}} \Rightarrow a_4 = -a_1 + a_2 - a_3$$

$\{a_1, a_2, a_3\}$ LI, $\boxed{\dim S = 3}$.

$$\text{rref}[a_4 \ a_5 \ a_6] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \boxed{\dim T = 3} \text{ again by CCP.}$$

$$\text{rref}[a_1 \ a_2 \ a_3 \ a_4 \ a_5 \ a_6] = \begin{bmatrix} 1 & 0 & 0 & -1 & 0 & 33\frac{1}{3} \\ 0 & 1 & 0 & 1 & 0 & -11\frac{8}{3} \\ 0 & 0 & 1 & -1 & 0 & -20\frac{2}{3} \\ 0 & 0 & 0 & 0 & 1 & -10\frac{1}{3} \end{bmatrix}$$

By CCP, $\{a_1, a_2, a_3, a_5\}$ is LI $\Rightarrow \boxed{\dim(T+S) = 4}$

We calculate, $\dim(S \cap T) = \dim S + \dim T - \dim(T+S) = 6 - 4 = \boxed{2}$

P62 §8 #2 on pg. 61

For which values of α does the following system have solⁿs?

$$3x_1 - x_2 + \alpha x_3 = 1$$

$$3x_1 - x_2 + x_3 = 5$$

Subtract eq^s to obtain $\alpha x_3 - x_3 = -4$

Thus $(\alpha - 1)x_3 = -4$. Oh, I'll behave,

$$\left[\begin{array}{ccc|c} 3 & -1 & \alpha & 1 \\ 3 & -1 & 1 & 5 \end{array} \right] \xrightarrow{r_2 - r_1} \left[\begin{array}{ccc|c} 3 & -1 & \alpha & 1 \\ 0 & 0 & 1 - \alpha & 4 \end{array} \right] = M$$

If $\alpha \neq 1$ then, can reduce,

$$M \rightarrow \left[\begin{array}{ccc|c} 1 & -1/3 & \alpha/3 & 1/3 \\ 0 & 0 & 1 & 4/(1-\alpha) \end{array} \right] \quad (\text{consistent})$$

Hence for all $\alpha \neq 1$ the system has a solⁿ.

Moreover, $x_3 = \frac{-4}{\alpha - 1}$ etc.. (not that it asked for that)

P63 §8 #4 on pg. 62 of CURTIS

Prove that a system of homog. eq^s $x_1 c_1 + x_2 c_2 + \dots + x_n c_n = 0$ (*)
in n -unknowns has a nontrivial solⁿ iff $\text{rank}[c_1 | c_2 | \dots | c_n] < n$.

Observe (*) is shorthand for m -eq^s in n -unknowns where $c_1, c_2, \dots, c_n \in \mathbb{R}^m$ (or $\mathbb{F}^m$ I suppose). Thus (*) is same as $AX = 0$ for $A = [c_1 | c_2 | \dots | c_n] \in \mathbb{F}^{m \times n}$.

I'll use Th^m 3.7.3; for $A \in \mathbb{F}^{m \times n}$, $n = \text{rank}(A) + \text{nullity}(A)$
 $\text{nullity}(A) = \dim(\text{Null}(A))$ and $\text{Null}(A) = \{x \in \mathbb{F}^n \mid Ax = 0\}$.

Thus, to say $\exists x \neq 0$ solⁿ to $AX = 0$ is equivalent to asserting $\text{nullity}(A) \geq 1$. However, as $n = \text{rank}(A) + \text{nullity}(A)$

$$\text{rank}(A) < n \Rightarrow \text{nullity}(A) \geq 1 \quad \therefore Ax = 0 \text{ has nontrivial solⁿ}. \quad \square$$

Remark: sorry about the less than helpful hint here.

P64 §9#6 on p. 69

Let $(\alpha, \beta) \neq (\gamma, \delta)$ be distinct points in $\mathbb{R}^2$.

Prove $\exists A, B, C$ not all zero such that $(\alpha, \beta), (\gamma, \delta)$ solve

$$Ax + By + C = 0$$

and if both points also solve $A'x + B'y + C' = 0$

then $\exists \lambda \in \mathbb{R}$ such that $\langle A', B', C' \rangle = \lambda \langle A, B, C \rangle$.

Given a line in $\mathbb{R}^2$ is solⁿ set to $Ax + By + C = 0$

for some $A, B, C \in \mathbb{R}$ (not all zero), show $(\alpha, \beta), (\gamma, \delta)$

distinct lie on a unique line.

There are many methods to find A, B, C . One approach, use two-point formula for line, for $\gamma \neq \alpha$,

$$y - \delta = \left(\frac{\delta - \beta}{\gamma - \alpha} \right) (x - \gamma) = \left(\frac{\delta - \beta}{\gamma - \alpha} \right) x - \gamma \left(\frac{\delta - \beta}{\gamma - \alpha} \right)$$

Hence,

$$\left(\frac{\beta - \delta}{\gamma - \alpha} \right) x + y - \delta + \gamma \left(\frac{\delta - \beta}{\gamma - \alpha} \right) = 0$$

I'll clean this up a bit, as $\gamma \neq \alpha$ multiply by $\gamma - \alpha \neq 0$,

$$(\beta - \delta)x + (\gamma - \alpha)y - \delta(\gamma - \alpha) + \gamma(\delta - \beta) = 0$$

$$\underbrace{(\beta - \delta)}_A x + \underbrace{(\gamma - \alpha)}_B y + \underbrace{\alpha\delta - \gamma\beta}_C = 0 \quad (*)$$

Let's check (*). Plug in $x = \alpha, y = \beta$

$$\underbrace{(\beta - \delta)}_{\{}} \alpha + \underbrace{(\gamma - \alpha)}_{\{}} \beta + \underbrace{\alpha\delta - \gamma\beta}_{=} = 0.$$

Likewise, $x = \gamma, y = \delta$ solve it

$$\underbrace{(\beta - \delta)}_{\{}} \gamma + \underbrace{(\gamma - \alpha)}_{\{}} \delta + \underbrace{\alpha\delta - \gamma\beta}_{=} = 0.$$

P 64 continued

Suppose $\exists A', B', c'$ for which $A'x + B'y + c' = 0$
has $(\alpha, \beta), (\gamma, \delta)$ as sol's $[(\alpha, \beta) \neq (\gamma, \delta) \text{ still imposed}]$.

$$A'\alpha + B'\beta + c' = 0$$

$$A'\gamma + B'\delta + c' = 0$$

$$A\alpha + B\beta + c = 0$$

$$A\gamma + B\delta + c = 0$$

How to relate A, A'
 $B, B', C, c' ?$

P65 § 10 #2

Find homog. system whose solⁿ set is generated by

$$\langle 3, -1, 1, 2 \rangle, \langle 4, -1, -2, 3 \rangle, \langle 10, -3, 0, 7 \rangle, \langle -1, 1, -7, 0 \rangle$$

Then find nonhomogeneous system whose solⁿ set is a linear manifold with the given vectors in the directing set and with base point $\langle 1, 1, 1, 1 \rangle$

$$\text{Let } V_1 = (3, -1, 1, 2) \quad \text{and} \quad A = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix} \in \mathbb{R}^{m \times 4}$$
$$V_2 = (4, -1, -2, 3)$$
$$V_3 = (10, -3, 0, 7)$$
$$V_4 = (-1, 1, -7, 0)$$

We want to find A s.t. $AV_1 = 0, AV_2 = 0, AV_3 = 0, AV_4 = 0$
which is to say $a_j V_k = 0$ for $j=1, 2, \dots, m$ and $k=1, 2, 3, 4$.

It's easier to solve

$$a_j V_1 = 0, \quad a_j V_2 = 0, \quad a_j V_3 = 0, \quad a_j V_4 = 0$$

$$\Rightarrow a_j [V_1 | V_2 | V_3 | V_4] = [0, 0, 0, 0]$$

Simply transpose to find a problem we have tools to solve!

$$\begin{bmatrix} V_1^T \\ V_2^T \\ V_3^T \\ V_4^T \end{bmatrix} a_j^T = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{Calculate } \text{ref} \begin{bmatrix} 3 & -1 & 1 & 2 \\ 4 & -1 & -2 & 3 \\ 10 & -3 & 0 & 7 \\ -1 & 1 & -7 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -3 & 1 \\ 0 & 1 & -10 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

If $a_j = [a_{j1}, a_{j2}, a_{j3}, a_{j4}]$ then the calculation above reveals $a_{j1} = 3a_{j3} - a_{j4}$ and $a_{j2} = 10a_{j3} - a_{j4}$

p65 continued

The solⁿ to our problem is given by

$$a_j = [3a_{j3} - a_{j4}, 10a_{j3} - a_{j4}, a_{j3}, a_{j4}] \\ = a_{j3} [3, 10, 1, 0] + a_{j4} [-1, -1, 0, 1]$$

Apparently, two eq^s will do nicely,

$$\begin{bmatrix} 3 & 10 & 1 & 0 \\ -1 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

← an example of the desired homogeneous solⁿ.

Has solⁿs which include v_1, v_2, v_3, v_4 .

Finding the nonhomogeneous system with $(1, 1, 1, 1)$ in solⁿ set is not hard! Consider,

$$\begin{bmatrix} 3 & 10 & 1 & 0 \\ -1 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 14 \\ 1 \end{bmatrix}$$

Thus

$$\begin{bmatrix} 3 & 10 & 1 & 0 \\ -1 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 14 \\ 1 \end{bmatrix}$$

← the desired nonhomogeneous system.

Remark: to find linear manifold $P+S$ as solⁿ set we can take the generating set β for $S' = \text{span } \beta$ and calculate $\text{rref}[\beta]^T$. This will show us how to realize S' as a solⁿ set of a homog. system. Then simply plug in P to find the nonhomog. system. - (in other words, you can generalize my solⁿ here) -

P66 §10 #7 on pg. 74

Suppose $P \neq Q$ are vectors in a linear manifold V .
show the line through P & Q is contained in V

We are given $V = P_0 + S'$ for some subspace S' .

Furthermore $P, Q \in V \Rightarrow \exists s_1, s_2 \in S'$ s.t. $P = P_0 + s_1$ & $Q = P_0 + s_2$.

A line through P & Q is parametrized by $r = P + t(Q - P)$
for $t \in \mathbb{R}$. Observe,

$$r = P + t(Q - P)$$

$$= (1+t)P + tQ$$

$$= (1+t)(P_0 + s_1) + t(P_0 + s_2)$$

$$= P_0 - \cancel{tP_0} + (1+t)s_1 + \cancel{tP_0} + ts_2$$

$$= P_0 + (1+t)s_1 + ts_2$$

$$= P_0 + S_3 \quad \text{as } \underbrace{(1+t)s_1 + ts_2}_{*} = S_3 \in S' \leftarrow \text{subspace}$$

so we know

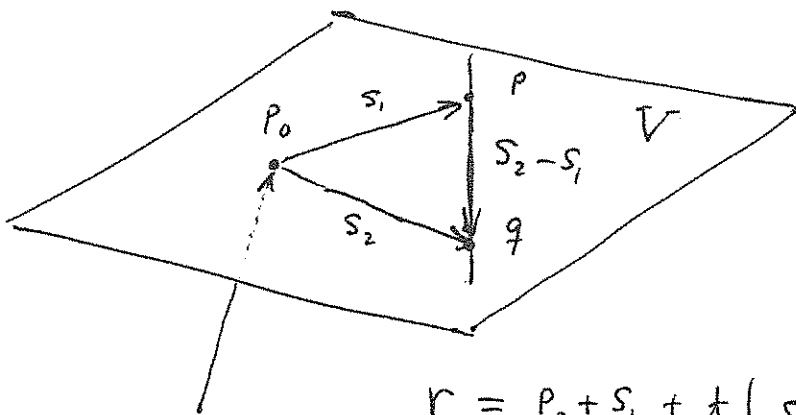
$s_1, s_2 \in S'$

implies the
linear combo *
once more in S'

Thus $r \in V$ for each $t \in \mathbb{R}$

and this shows the line connecting

P & Q is contained in V .



$$r = P_0 + s_1 + t(s_2 - s_1)$$

(you can see this in picture)

P67 § 10 # 8 on p. 74

Consider subspaces S & T of $\mathbb{R}^n$. These are sol^n sets of

$$S: a_1 \cdot x = 0, \dots, a_r \cdot x = 0$$

$$T: b_1 \cdot x = 0, \dots, b_s \cdot x = 0$$

Prove that $S \cap T$ is sol^n set to both systems at once.

Also, find basis for $S \cap T$ where S & T are given by

$$S = \text{Span}\{V_1, V_2, V_3, V_4\}$$

$$T = \text{Span}\{V_4, V_5, V_6\}$$

Remark: $a_1, a_2, a_3, a_4, a_5, a_6$ in Ex #5 of §7 are not same as those given at start of this problem. I relabeled as $V_1, V_2, \dots, V_6$

$$V_1 = \langle 2, 1, 0, -1 \rangle$$

$$V_2 = \langle 4, 8, -4, -3 \rangle$$

$$V_3 = \langle 1, -3, 2, 0 \rangle$$

$$V_4 = \langle 1, 10, -6, -2 \rangle$$

$$V_5 = \langle -2, 0, 6, 1 \rangle$$

$$V_6 = \langle 3, -1, 2, 4 \rangle$$

Let $x \in S \cap T$ then $x \in S$ and $x \in T$ thus

$$a_1 \cdot x = 0, \dots, a_r \cdot x = 0 \text{ as } x \in S \text{ and}$$

$$b_1 \cdot x = 0, \dots, b_s \cdot x = 0 \text{ as } x \in T. \text{ Thus } x \text{ solves}$$

both systems at once.

We have $S \cap T$ is the sol^n set of

$$\left. \begin{array}{l} a_1 \cdot x = 0 \\ a_2 \cdot x = 0 \\ \vdots \\ a_r \cdot x = 0 \\ b_1 \cdot x = 0 \\ b_2 \cdot x = 0 \\ \vdots \\ b_s \cdot x = 0 \end{array} \right\} \rightarrow \begin{bmatrix} A \\ B \end{bmatrix} x = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

In this notation $S = \text{Null}(A)$ whereas $T = \text{Null}(B)$.

we've shown $S \cap T = \text{Null}\left(\begin{bmatrix} A \\ B \end{bmatrix}\right)$. In order to

use this for the Ex #5 data we need to realize S & T as sol^n sets,

P 67 continued

$$S^T = \text{span} \{v_1, v_2, v_3, v_4\} = \text{Null}(A)$$

$$\text{rref} \begin{bmatrix} \frac{v_1^T}{v_2^T} \\ \frac{v_3^T}{v_4^T} \end{bmatrix} = \text{rref} \begin{bmatrix} 2 & 1 & 0 & -1 \\ 4 & 8 & -4 & -3 \\ 1 & -3 & 2 & 0 \\ 1 & 10 & -6 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & -1/2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1/4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\left. \begin{aligned} a_{j1} &= \frac{1}{2} a_{j4} \\ a_{j2} &= 0 \\ a_{j3} &= -\frac{1}{4} a_{j4} \end{aligned} \right\} \begin{aligned} a_j &= [a_{j1}, a_{j2}, a_{j3}, a_{j4}] \\ &= [\frac{1}{2} a_{j4}, 0, -\frac{1}{4} a_{j4}, a_{j4}] \\ &= a_{j4} \underbrace{[\frac{1}{2}, 0, -\frac{1}{4}, 1]}_A \end{aligned}$$

//

$$T = \text{span} \{v_4, v_5, v_6\} = \text{Null}(B)$$

$$\text{rref} \begin{bmatrix} \frac{v_4^T}{v_5^T} \\ \frac{v_6^T}{v_6^T} \end{bmatrix} = \text{rref} \begin{bmatrix} 1 & 10 & -6 & -2 \\ -2 & 0 & 6 & 1 \\ 3 & -1 & 2 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1/2 \end{bmatrix}$$

$$\left. \begin{aligned} b_{j1} &= -b_{j4} \\ b_{j2} &= 0 \\ b_{j3} &= -\frac{1}{2} b_{j4} \end{aligned} \right\} \begin{aligned} b_j &= [-b_{j4}, 0, -\frac{1}{2} b_{j4}, b_{j4}] \\ &= b_{j4} \underbrace{[-1, 0, -\frac{1}{2}, 1]}_B \end{aligned}$$

Thus, the SNT is given by

$$\text{Null} \left(\begin{bmatrix} A \\ B \end{bmatrix} \right) = \text{Null} \begin{bmatrix} \frac{1}{2} & 0 & -\frac{1}{4} & 1 \\ -1 & 0 & -\frac{1}{2} & 1 \end{bmatrix} = \text{Null} \begin{bmatrix} 2 & 0 & -1 & 4 \\ -2 & 0 & -1 & 2 \end{bmatrix}$$

$$\text{rref} \begin{bmatrix} 2 & 0 & -1 & 4 \\ -2 & 0 & -1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 1/2 \\ 0 & 0 & 1 & -3 \end{bmatrix} \therefore x \in \text{SNT}$$

$$\text{has } x_1 = -\frac{1}{2} x_4, x_3 = 3x_4 \therefore x = \begin{bmatrix} -x_4/2 \\ x_2 \\ 3x_4 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1/2 \\ 0 \\ 3 \\ 1 \end{bmatrix}$$

p67 continued

We find $S_{NT} = \text{span} \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1/2 \\ 0 \\ 3 \\ 1 \end{bmatrix} \right\}$ (this is in agreement with P61)

P68 Suppose $U \leq V$ and $W \leq V$ where V is vector space over $\mathbb{F}$.

Consider $0 \in U$ and $0 \in W$ thus $0 \in U \cap W \neq \emptyset$.

Let $x, y \in U \cap W$ and $c \in \mathbb{F}$. Then $x, y \in U$ and $x, y \in W$. But, $U \leq V \Rightarrow cx + y \in U$ and $W \leq V \Rightarrow cx + y \in W$. Thus $cx + y \in U \cap W$ and hence $cx, x + y \in U \cap W \therefore U \cap W \leq V$ by Subspace Test $\mathcal{T}^m$.

P69 Let $V(\mathbb{F})$ be vector space and $U \leq V$ and $W \leq V$.

Consider $U + W = \{x + y \mid x \in U, y \in W\}$. Observe $0 \in U$ and $0 \in W$ thus $0 + 0 = 0 \in U + W \neq \emptyset$.

Consider $z, w \in U + W$ and $\alpha \in \mathbb{F}$. Then, by defⁿ of $U + W$, $\exists a, b \in U$ and $c, d \in W$ s.t. $z = a + c$ & $w = b + d$.

Observe, $\alpha z + w = \alpha(a + c) + b + d = \underline{(\alpha a + b) + (\alpha c + d)}$. *

Note, $\alpha a + b \in U$ and $\alpha c + d \in W$ as $a, b \in U \leq V$

and $c, d \in W \leq V$. Thus * shows $\alpha z + w \in U + W$.

Hence, $\alpha z, z + w \in U + W$ and we conclude $U + W \leq V$ by the Subspace Test $\mathcal{T}^m$. It remains to show $U + W$ is smallest subspace which contains $U \cup W$.



P69

Note, $U \cup W$ is clearly a subset of $U+W$ since $x \in U \cup W \Rightarrow \underline{x \in U}_{(1)}$ or $\underline{x \in W}_{(2)}$ and $x+0$ is clearly in $U+W$ in both cases, (1) & (2).

Let $H \leq V$ such that $U \cup W \subseteq H$. Hence if $x \in U$ and $y \in W$ then $x, y \in H$ and thus $x+y \in H$. But, every element in $U+W$ can be written as $x+y$ for $x \in U, y \in W$ thus $U+W \subseteq H \Rightarrow U+W$ is smallest subspace containing $U \cup W$.

P70 Suppose S is LI subset of V (IF). Also, suppose $\exists a_i, b_i \in IF$ for $i \in \mathbb{N}_n$ and $V_1, \dots, V_n \in S$ such that

$$a_1 V_1 + \dots + a_n V_n = b_1 V_1 + \dots + b_n V_n$$

Then, by algebra,

$$(a_1 - b_1)V_1 + \dots + (a_n - b_n)V_n = 0$$

hence $a_1 - b_1 = 0, \dots, a_n - b_n = 0$ by LI of S . Thus $a_1 = b_1, \dots, a_n = b_n$ and we've shown S allows for equating coefficients.

Conversely, suppose S allows us to equate coefficients.

If $V_1, V_2, \dots, V_n \in S$ and $c_1 V_1 + c_2 V_2 + \dots + c_n V_n = 0$

then note $c_1 V_1 + \dots + c_n V_n = 0 \cdot V_1 + \dots + 0 \cdot V_n (= 0)$ thus

equating coefficients yields $c_1 = 0, \dots, c_n = 0 \therefore S$ is LI. //

Remark: we oft find use of equating coefficients in our study of calculus. Thinking back on calculus II there is much linear algebra in the partial-fractions technique...