Please follow the format which was announced in Blackboard. Thanks!

Your PRINTED NAME indicates you have read through Chapter 7 of the notes:

- **Problem 73** Suppose V and W are vector spaces over \mathbb{F} and $S, T : V \to W$ are linear transformations. Show S + cT is a linear transformation for any $c \in \mathbb{F}$.
- **Problem 74** Let T(x, y, z) = (x + z, y + z, x + z) for all $(x, y, z) \in \mathbb{R}^3$. Find the standard matrix of T. Calculate $\operatorname{Ker}(T)$ and $\operatorname{Range}(T)$. If possible, find T^{-1} .
- **Problem 75** Let $T(x_1, x_2, x_3, x_4) = (x_1 2x_2, x_3 4x_4)$ for all $(x_1, x_2, x_3, x_4) \in \mathbb{R}^4$. Find the standard matrix of T. Find bases for Ker(T) and Range(T).
- **Problem 76** Suppose $T: \mathbb{R}^3 \to \mathbb{R}^3$ is a linear transformation such that T(1,1,1) = (8,6,7) and T(1,2,2) = (5,3,0) and T(1,2,1) = (9,0,0). Find the standard matrix of T.
- **Problem 77** Suppose S is a linear transformation on $P_2(\mathbb{R})$ for which $S(t^2-t)=1$ and $S(t^2+t)=3t+2$ and S(1)=0. Find the formula for $S(at^2+bt+c)$.
- **Problem 78** Let $\beta = \{v_1, \dots, v_n\}$ form a basis for V over a field \mathbb{F} . Recall, for each $x \in V$, we defined $[x]_{\beta}$ to be the unique vector $(c_1, \dots, c_n) \in \mathbb{F}^n$ for which $x = c_1v_1 + \dots + c_nv_n$. Show $\Phi_{\beta}: V \to \mathbb{F}^n$ defined by $\Phi_{\beta}(x) = [x]_{\beta}$ for each $x \in V$ defines a linear transformation.
- **Problem 79** Suppose T(x, y) = (x + y, x y, 3y) and define S(u, v, w) = (2u + 3v, u w).
 - (a.) Calculate the formula for $(S \circ T)(x,y)$ from the definition of function composition,
 - **(b.)** Find [T] and [S] and $[S \circ T]$,
 - (c.) Verify that $[S \circ T] = [S][T]$.
- **Problem 80** Let $T: \mathbb{C} \to \mathbb{C}$ be the function defined by T(x+iy) = x-iy. Find the matrix of T with respect to the basis $\beta = \{1, i\}$. (here we view \mathbb{C} as a real vector space with basis β)
- **Problem 81** Let $L_w(z) = wz$ where $w, z \in \mathbb{C}$. If w = a + ib then find the matrix if L_w with respect to the basis $\{1, i\}$ for \mathbb{C} (viewed as a two-dimensional real vector space). Is it possible to choose some w such that $L_w = T$ where T(x + iy) = x iy?
- **Problem 82** Let $T(A) = AE_{12}$ where $E_{12} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$. Show $T : \mathbb{R}^{2\times 2} \to \mathbb{R}^{2\times 2}$ is a linear transformation. Also, find $[T]_{\beta,\beta}$ where $\beta = \{E_{11}, E_{12}, E_{21}, E_{22}\}$.
- **Problem 83** Let T(f(x)) = f(x) f'(x) for each $f(x) \in P_2(\mathbb{R})$.
 - (a.) Find a basis β for the Ker(T),
 - **(b.)** extend β to a basis γ for $P_2(\mathbb{R})$ by adjoining appropriate vectors from $\{1, x, x^2\}$,
 - (c.) Calculate $[T]_{\gamma,\gamma}$.
- **Problem 84** Suppose $T: P_4(\mathbb{R}) \to P_2(\mathbb{R})$ is defined by T(f(x)) = f''(x). Prove T is surjective, however T is not injective.

- **Problem 85** If $W \leq V$ and $T: V \to V$ is a linear transformation such that $T(W) \subset W$ then we define $T_W: W \to W$ to be the restriction of T to W with codomain modified to W; $T_W: W \to W$ where $T_W(x) = T(x)$ for each $x \in W$. If such W exists then it is known as an **invariant subspace** of T. Let $T: \mathbb{R}^{2\times 2} \to \mathbb{R}^{2\times 2}$ be defined by $T(A) = A A^T$ for each $A \in \mathbb{R}^{2\times 2}$.
 - (a.) Show $W_1 = \{A \in \mathbb{R}^{2 \times 2} \mid A^T = A\}$ forms and invariant subspace of T. Calculate T_{W_1} and $[T_{W_1}]_{\gamma_1,\gamma_1}$ where $\gamma_1 = \{E_{11}, E_{22}, E_{12} + E_{21}\}$
 - (b.) Show $W_2 = \{A \in \mathbb{R}^{2 \times 2} \mid A^T = -A\}$ forms and invariant subspace of T. Calculate T_{W_2} and $[T_{W_2}]_{\gamma_2,\gamma_2}$ where $\gamma_2 = \{E_{12} E_{21}\}$
 - (c.) Consider $\beta = \gamma_1 \cup \gamma_2 = \{E_{11}, E_{22}, E_{12} + E_{21}, E_{12} E_{21}\}$ calculate $[T]_{\beta,\beta}$.
- **Problem 86** Find an explicit isomorphism from the subspace of 3×3 real symmetric matrices and \mathbb{C}^3 . Notice, I must mean \mathbb{C}^3 as a vector space over \mathbb{R} for this question to be reasonable.
- **Problem 87** We define **hyperbolic numbers** $\mathcal{H} = \{x + jy \mid x, y \in \mathbb{R}\}$ where $j^2 = 1$. In particular, we add and multiply in the natural fashion:

$$(a + bj) + (x + jy) = a + x + j(b + y)$$

$$(a+bj)(x+jy) = ax + by + j(ay + bx)$$

for all $a+jb, x+jy \in \mathcal{H}$. Scalar multiplication is a special case of the vector multiplication in \mathcal{H} ; c(a+bj)=ca+j(cb). It is straightforward to verify \mathcal{H} forms a vector space over \mathbb{R} . Prove $\Psi(x+jy)=\begin{bmatrix} x & y \\ y & x \end{bmatrix}$ is a vector space isomorphism from \mathcal{H} to $V=\Psi(\mathcal{H})$ viewed as a subset of $\mathbb{R}^{2\times 2}$ with respect to the usual addition and scalar multiplication of matrices. Also, show:

$$\Psi((x+jy)(a+jb)) = \Psi(a+jy)\Psi(a+jb)$$

Remark: a vector space V paired with a multiplication is called an **algebra**. For example, \mathbb{C} is an algebra since \mathbb{C} is a vector space where we also have a natural method to multiply vectors. Likewise, $\mathbb{R}^{n\times n}$ or $\mathbb{C}^{n\times n}$ form algebras with respect to the usual matrix multiplication. When given two algebras it is interesting to ask if they are isomorphic as algebras. This requires they have the same linear structure (which is the sense of isomorphism this course focuses primarily upon) and the multiplication is preserved in the natural fashion. To be precise, if A has multiplication \star and B has multiplication \circ then $\Psi: A \to B$ is an algebra isomorphism if

$$\Psi(x+cy) = \Psi(x) + c\Psi(y), \qquad \Psi(x\star y) = \Psi(x)\circ\Psi(y)$$

for all $x, y \in \mathcal{A}$ and $c \in \mathbb{F}$. We also insist that when \mathcal{A} has a multiplicative identity $1_{\mathcal{A}}$ and likewise $1_{\mathcal{B}}$ for \mathcal{B} then $\Psi(1_{\mathcal{A}}) = 1_{\mathcal{B}}$. In the above problem, we see $\Psi(1) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ hence Ψ is an algebra isomorphism of hyperbolic numbers and the subspace of 2×2 matrices of the special form $\begin{bmatrix} x & y \\ y & x \end{bmatrix}$. This discussion echos Example 7.3.17 in my notes.

Problem 88 Let V be a finite dimensional vector space over \mathbb{F} of dimension n. Prove $\mathcal{L}(V)$ is isomorphic to $\mathbb{F}^{n\times n}$ as algebras over \mathbb{F} . In particular, find an isomorphism which preserves addition, scalar multiplication, and has $\Psi(T \circ S) = \Psi(T)\Psi(S)$ for all $T, S : V \to V$ and has $\Psi(Id_V) = I$. Here the product $\Psi(T)\Psi(S)$ is that of matrix multiplication.

Hint: think about how to create maps from $V \to V$ which naturally correspond to the matrix units E_{ij} . Remember, we know $\mathbb{F}^{n \times n}$ has basis formed by E_{ij} for $1 \le i, j \le n$. Probably picking a basis for V is a good starting point. If you're lost, try n = 1 or n = 2 to get started

- **Problem 89** Let $SL(3,\mathbb{R}) = \{A \in \mathbb{R}^{3\times 3} \mid \det(A) = 1\}$. Suppose T(x) = Ax. Show T preserves the volume of a parallel-piped.
- **Problem 90** Consider $\beta = \{1, e_1, e_2, e_1 \land e_2\}$ serve to generate $V = \text{span}(\beta)$ as a real vector space of dimension 4. I'll arrange the \wedge products in a table:

\wedge	1	e_1	e_2	$e_1 \wedge e_2$
1	1	e_1	e_2	$e_1 \wedge e_2$
e_1	e_1	0	$e_1 \wedge e_2$	0
e_2	e_2	$-e_1 \wedge e_2$	0	0
$e_1 \wedge e_2$	$e_1 \wedge e_2$	0	0	0

Linear transformations on V naturally correspond to 4×4 matrices. Notice, we can define the left multiplication maps with respect to the wedge product: $L_x(y) = x \wedge y$. Then, the set of $[L_x]_{\beta,\beta} \in \mathbb{R}^{4\times 4}$. I'll set it up:

$$[L_x]_{\beta,\beta} = [[L_x(1)]_{\beta}|[L_x(e_1)]_{\beta}|[L_x(e_2)]_{\beta}|[L_x(e_1 \wedge e_2)]_{\beta}]$$

= $[[x]_{\beta}|[x \wedge e_1]_{\beta}|[x \wedge e_2]_{\beta}|[x \wedge e_1 \wedge e_2]_{\beta}]$

For example,

$$[L_{e_1}]_{\beta,\beta} = [[e_1]_{\beta}|[e_1 \wedge e_1]_{\beta}|[e_1 \wedge e_2]_{\beta}|[e_2 \wedge e_1 \wedge e_2]_{\beta}] = [[e_1]_{\beta}|0|[e_1 \wedge e_2]_{\beta}|0] = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

- (a.) Complete my work by finding $[L_{e_2}]_{\beta,\beta}$, $[L_{e_1 \wedge e_2}]_{\beta,\beta}$ and the far more relaxing $[L_1]_{\beta,\beta}$.
- (b.) Check that $([L_{e_1}]_{\beta,\beta})^2 = 0$, $([L_{e_2}]_{\beta,\beta})^2 = 0$ and $[L_{e_1}]_{\beta,\beta}[L_{e_2}]_{\beta,\beta} = [L_{e_1 \wedge e_2}]_{\beta,\beta}$ whereas $[L_{e_2}]_{\beta,\beta}[L_{e_1}]_{\beta,\beta} = -[L_{e_1 \wedge e_2}]_{\beta,\beta}$

Remark: I know that part (b.) will work out since we can easily calculate in general that $L_x \circ L_y(z) = L_x(y \wedge z) = x \wedge y \wedge z = L_{x \wedge y}(z)$. The neat thing here is that if you forget about the abstract $e_1 \wedge e_2$ and just think about these 4×4 matrices then you can see that the algebra of the wedge product on \mathbb{R}^2 is easily implemented with 4×4 matrices. Generally, we can follow much the same construction to build the wedge product algebra on \mathbb{R}^n by representing it on $2^n \times 2^n$ matrices. That said, that's not really how I think about the wedge product. Ask me in office hours sometime if you'd like to know more.