

Reading §6.4 – 6.6 of Friedberg, Insel and Spence 5th edition and Chapter 10 of my 2016 Math 321 Lecture Notes would be wise. (see Canvas for the 2016 notes)

**Problem 81** Text §6.3#22a, d page 365. (minimal solution)

**Problem 82** Text §6.4#2 page 372. (is it normal, self-adjoint, neither ?...)

**Problem 83** Text §6.4#10 page 373. (self-adjoint operator behavior)

**Problem 84** Text §6.5#25 page 393. (on reflections and rotations in plane)

**Problem 85** Note that that  $\text{trace} : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$  is a linear function hence  $\text{trace} \in (\mathbb{R}^{n \times n})^*$ . Recall  $\langle A, B \rangle = \text{trace}(AB^T)$  defines an inner product on  $\mathbb{R}^{n \times n}$ . Find the Riesz vector for the trace functional.

**Problem 86** Consider  $R_z = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$ . Find the e-values and real e-vectors of  $R_z$ . Use your work on  $R_z$  to answer the following: if  $R \in \text{SO}(3)$  with  $\text{trace}(R) = 0$ , then by what angle does  $R$  rotate?

**Problem 87** Let  $\text{SO}(3) = \{R \in \mathbb{R}^{3 \times 3} \mid R^T R = I, \det(R) = 1\}$ . Show that: If  $R \in \text{SO}(3)$  and  $R \neq I$  then  $R$  has only two e-vectors of unit length for which  $\lambda = 1$ .

**Problem 88** Find eigenvalues and orthonormal eigenvectors for  $Q(x, y) = x^2 + 4xy + y^2$ . Change the formula for  $Q$  to eigencoordinates (I used  $\bar{x}, \bar{y}$  for this concept in lecture). Geometrically, what is  $x^2 + 4xy + y^2 = 1$  ?

**Problem 89** Suppose  $Q(x, y, z) = 5x^2 + 5y^2 + 2z^2 + 8xy + 4xz + 4yz$ . Write  $Q(v) = v^T A v$  for a symmetric matrix  $A$ . Find an orthonormal eigenbasis for  $A$  and find coordinates  $\bar{x}, \bar{y}, \bar{z}$  for which  $Q(v) = \bar{x}^2 + \bar{y}^2 + 10\bar{z}^2$ .

*Hint: for this question to make sense, it must be that the matrix of  $Q$  has e-values 1, 1, 10.*

**Problem 90** There is another aspect of the real spectral theorem we should explore. For example, if  $A^T = A$  for  $A \in \mathbb{R}^{3 \times 3}$  then there exist rank one matrices  $E_1, E_2, E_3$  for which

$$A = E_1 + E_2 + E_3$$

and  $\text{Col}(E_j) = \text{Null}(A - \lambda_j I)$  for  $j = 1, 2, 3$  where  $\lambda_1, \lambda_2, \lambda_3$  are the eigenvalues of  $A$ . Suppose  $u, v, w$  form an orthonormal eigenbasis for  $A$  with eigenvalues  $\lambda_1, \lambda_2, \lambda_3$  respective. Define:

$$E_1 = \lambda_1 u u^T, \quad E_2 = \lambda_2 v v^T, \quad E_3 = \lambda_3 w w^T$$

**Show:**  $E_1 + E_2 + E_3 = A$  and  $\text{Col}(E_j) = \text{Null}(A - \lambda_j I)$  for  $j = 1, 2, 3$ .

*Hint: use the orthonormality of  $\{u, v, w\}$  and the fact you are given  $Au = \lambda_1 u$  etc.*

- Problem 91** Notice  $u = \frac{1}{\sqrt{3}}(1, -1, 1)$  and  $v = \frac{1}{\sqrt{2}}(0, 1, 1)$  and  $w = \frac{1}{\sqrt{6}}(2, 1, -1)$  form an orthonormal basis for  $\mathbb{R}^3$ . Find a matrix  $A$  with eigenvalues 12, 2, 18 by making use of the construction of the last problem.
- Problem 92** Define  $\Upsilon(A, B) = AB + BA$  for all  $A, B \in \mathbb{R}^{n \times n}$  show  $\Upsilon$  is a symmetric, bilinear form.
- Problem 93** Let  $V$  be a real vector space and  $x, y \in V$ . Define  $x \otimes y : V^* \times V^* \rightarrow \mathbb{R}$  according to the rule  $(x \otimes y)(\alpha, \beta) = \alpha(x)\beta(y)$ . Show  $x \otimes y$  is a bilinear mapping on  $V^* \times V^*$ .
- Problem 94** Continuing the construction in the last problem, if  $V$  has basis  $\beta = \{v_1, \dots, v_n\}$  show  $\Upsilon = \{v_i \otimes v_j \mid 1 \leq i, j \leq n\}$  serves as a basis for  $\mathcal{B}(V^*)$ . That is, show  $\Upsilon$  is LI and that any bilinear mapping  $V^* \times V^* \rightarrow \mathbb{R}$  can be expressed as a linear combination of the  $\Upsilon$  maps.