

Reading §6.4 – 6.6 of Friedberg, Insel and Spence 5th edition and Chapter 10 of my 2016 Math 321 Lecture Notes would be wise. (see Canvas for the 2016 notes)

Problem 81 Text §6.3#22a, d page 365. (minimal solution)

Problem 82 Text §6.4#2 page 372. (is it normal, self-adjoint, neither ?...)

Problem 83 Text §6.4#10 page 373. (self-adjoint operator behavior)

Problem 84 Text §6.5#25 page 393. (on reflections and rotations in plane)

Problem 85 Note that that trace : $\mathbb{R}^{n \times n} \rightarrow \mathbb{R}$ is a linear function hence trace $\in (\mathbb{R}^{n \times n})^*$. Recall $\langle A, B \rangle = \text{trace}(AB^T)$ defines an inner product on $\mathbb{R}^{n \times n}$. Find the Riesz vector for the trace functional.

Problem 86 Consider $R_z = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$. Find the e-values and real e-vectors of R_z . Use your work on R_z to answer the following: if $R \in \text{SO}(3)$ with $\text{trace}(R) = 0$, then by what angle does R rotate?

Problem 87 Let $\text{SO}(3) = \{R \in \mathbb{R}^{3 \times 3} \mid R^T R = I\}$. Show that: If $R \in \text{SO}(3)$ and $R \neq I$ then R has only two e-vectors of unit length for which $\lambda = 1$.

Problem 88 Find eigenvalues and orthonormal eigenvectors for $Q(x, y) = x^2 + 4xy$. Change the formula for Q to eigencoordinates (I used $\bar{x}, \bar{y}$ for this concept in lecture). Geometrically, what is $x^2 + 4xy = 1$?

Problem 89 Suppose $Q(x, y, z) = 5x^2 + 5y^2 + 2z^2 + 8xy + 4xz + 4yz$. Write $Q(v) = v^T A v$ for a symmetric matrix A . Find an orthonormal eigenbasis for A and find coordinates $\bar{x}, \bar{y}, \bar{z}$ for which $Q(v) = \bar{x}^2 + \bar{y}^2 + 10\bar{z}^2$.
Hint: for this question to make sense, it must be that the matrix of Q has e-values 1, 1, 10.

Problem 90 There is another aspect of the real spectral theorem we should explore. For example, if $A^T = A$ for $A \in \mathbb{R}^{3 \times 3}$ then there exist rank one matrices E_1, E_2, E_3 for which

$$A = E_1 + E_2 + E_3$$

and $\text{Col}(E_j) = \text{Null}(A - \lambda_j I)$ for $j = 1, 2, 3$ where $\lambda_1, \lambda_2, \lambda_3$ are the eigenvalues of A . Suppose u, v, w form an orthonormal eigenbasis for A with eigenvalues $\lambda_1, \lambda_2, \lambda_3$ respective. Define:

$$E_1 = \lambda_1 u u^T, \quad E_2 = \lambda_2 v v^T, \quad E_3 = \lambda_3 w w^T$$

Show: $E_1 + E_2 + E_3 = A$ and $\text{Col}(E_j) = \text{Null}(A - \lambda_j I)$ for $j = 1, 2, 3$.

Hint: use the orthonormality of $\{u, v, w\}$ and the fact you are given $Au = \lambda_1 u$ etc.

Problem 91 Notice $u = \frac{1}{\sqrt{3}}(1, -1, 1)$ and $v = \frac{1}{\sqrt{2}}(0, 1, 1)$ and $w = \frac{1}{\sqrt{6}}(2, 1, -1)$ form an orthonormal basis for $\mathbb{R}^3$. Find a matrix A with eigenvalues 12, 2, 18 by making use of the construction of the last problem.

Problem 92 Define $\Upsilon(A, B) = AB + BA$ for all $A, B \in \mathbb{R}^{n \times n}$ show Υ is a symmetric, bilinear form.

Problem 93 Suppose (V, g) is a real geometry. Show (V^*, g^*) is also a real geometry given we define $g^*(\alpha, \beta) = g(\sharp\alpha, \sharp\beta)$.

Problem 94 Let (V, g) be a real geometry. Prove $\sharp \circ \flat = Id_V$ and $\flat \circ \sharp = Id_{V^*}$. See my notes for the necessary definitions.

Problem 93 Let V be a real vector space and $x, y \in V$. Define $x \otimes y : V^* \times V^* \rightarrow \mathbb{R}$ according to the rule $(x \otimes y)(\alpha, \beta) = \alpha(x)\beta(y)$. Show $x \otimes y$ is a bilinear mapping on $V^* \times V^*$.

Problem 94 Continuing the construction in the last problem, if V has basis $\beta = \{v_1, \dots, v_n\}$ show $\Upsilon = \{v_i \otimes v_j \mid 1 \leq i, j \leq n\}$ serves as a basis for $\mathcal{B}(V^*)$. That is, show Υ is LI and that any bilinear mapping $V^* \times V^* \rightarrow \mathbb{R}$ can be expressed as a linear combination of the Υ maps.

MISSION 6 SOLUTION

P81 §6.3 #22a, d p. 365 (minimal solⁿ)

$$(a.) \quad x + 2y - z = 12 \quad \hookrightarrow \underbrace{[1, 2, -1]}_A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 12$$

(Solve $(AA^T)u = b$ then $s = A^T u$ is the minimal solⁿ by Th^m 6.13)

$$AA^T u = [1, 2, -1] \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} u = 6u = 12 \quad \therefore \underline{u = 2}.$$

$$\text{Then, } s = A^T u = \boxed{(2, 4, -2)} \quad (\text{textbook solⁿ incorrect})$$

$$(d.) \quad \begin{array}{l} x + y + z - w = 1 \\ 2x - y + w = 1 \end{array} \quad \hookrightarrow \underbrace{\begin{bmatrix} 1 & 1 & 1 & -1 \\ 2 & -1 & 0 & 1 \end{bmatrix}}_A \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$AA^T = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 2 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & -1 \\ 1 & 0 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & 6 \end{bmatrix} \Rightarrow \begin{bmatrix} 4 & 0 \\ 0 & 6 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \therefore \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 1/4 \\ 1/6 \end{bmatrix}$$

$$\text{Then } s = A^T u = \begin{bmatrix} 1 & 2 \\ 1 & -1 \\ 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1/4 \\ 1/6 \end{bmatrix} = \begin{bmatrix} 1/4 + 2/6 \\ 1/4 - 1/6 \\ 1/4 \\ -1/4 + 1/6 \end{bmatrix} = \boxed{\left(7/12, 1/12, 1/4, -1/12 \right)} \\ (\text{textbook agrees this time})$$

For each T , determine if T is normal, self-adjoint or neither.
If possible find orthonormal eigenbasis for T

(a.) $T(a, b) = \underbrace{\begin{bmatrix} 2 & -2 \\ -2 & 5 \end{bmatrix}}_A \begin{bmatrix} a \\ b \end{bmatrix}$ observe $A^T = A \Rightarrow \underline{T^* = T}$ ($V = \mathbb{R}^2$)
 T self-adjoint & normal

$$\det(A - \lambda I) = \det \begin{bmatrix} 2-\lambda & -2 \\ -2 & 5-\lambda \end{bmatrix} = (\lambda-2)(\lambda-5) - 4$$

$$= \lambda^2 - 7\lambda + 6$$

$$= (\lambda-1)(\lambda-6) \therefore \underline{\lambda_1 = 1, \lambda_2 = 6}$$

$$A - I = \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix} \Rightarrow \underline{u_1 = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \end{bmatrix} \text{ has } \lambda_1 = 1}$$

$$A - 6I = \begin{bmatrix} -4 & -2 \\ -2 & -1 \end{bmatrix} \Rightarrow \underline{u_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} -1 \\ 2 \end{bmatrix} \text{ has } \lambda = 6}$$

$\{u_1, u_2\}$ is orthonormal e-basis for T .

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(b.) $V = \mathbb{R}^3$

$T(a, b, c) = \underbrace{\begin{bmatrix} -1 & 1 & 0 \\ 0 & 5 & 0 \\ 4 & -2 & 5 \end{bmatrix}}_A \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ clearly $A^T \neq A \therefore \underline{A \text{ not self-adjoint}}$

$$AA^T = \begin{bmatrix} 2 & 5 & -6 \\ 5 & 25 & -10 \\ -6 & -10 & 45 \end{bmatrix} \text{ and } A^T A = \begin{bmatrix} 17 & -9 & 20 \\ -9 & 30 & -10 \\ 20 & -10 & 25 \end{bmatrix} \therefore \underline{A \text{ is not normal.}}$$

P 82) continued

$$(c.) \quad V = \mathbb{C}, \quad T(a, b) = (2a + ib, a + 2b) = \underbrace{\begin{bmatrix} 2 & i \\ 1 & 2 \end{bmatrix}}_A \begin{bmatrix} a \\ b \end{bmatrix}$$

$$A^* = \begin{bmatrix} 2 & -i \\ 1 & 2 \end{bmatrix}^T = \begin{bmatrix} 2 & 1 \\ -i & 2 \end{bmatrix}$$

$$A^* A = \begin{bmatrix} 2 & 1 \\ -i & 2 \end{bmatrix} \begin{bmatrix} 2 & i \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 5 & 2i+2 \\ -2i+2 & 5 \end{bmatrix}$$

$$A A^* = \begin{bmatrix} 2 & i \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ -i & 2 \end{bmatrix} = \begin{bmatrix} 5 & 2+2i \\ 2-2i & 5 \end{bmatrix} = A^* A \quad \therefore \underline{A \text{ is normal}} \\ \Rightarrow \underline{T \text{ is normal}}$$

$$\det(A - \lambda I) = \det \begin{bmatrix} 2-\lambda & i \\ 1 & 2-\lambda \end{bmatrix} = \underbrace{(\lambda-2)^2 - i}_{\lambda = 2 \pm \sqrt{i}} = \lambda^2 - 4\lambda + 4 - i$$

$$\sqrt{i} = \sqrt{e^{\pi i/2}} = e^{\pi i/4} = \frac{1+i}{\sqrt{2}} \quad \lambda = 2 \pm \sqrt{i}$$

$$\text{Then } \underline{\lambda_{\pm} = 2 \pm e^{\pi i/4}}$$

$$A - \lambda_+ I = \begin{bmatrix} -e^{\pi i/4} & i \\ 1 & -e^{\pi i/4} \end{bmatrix} \Rightarrow \vec{u}_+ = \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} v e^{\pi i/4} \\ v \end{bmatrix}$$

$$\text{Next, the 2's cancel,} \quad \underbrace{u - e^{\pi i/4} v = 0} \quad \therefore \underline{\vec{u}_+ = \begin{bmatrix} e^{\pi i/4} \\ 1 \end{bmatrix}}$$

$$A - \lambda_- I = \begin{bmatrix} e^{\pi i/4} & i \\ 1 & e^{\pi i/4} \end{bmatrix} \Rightarrow \underline{\vec{u}_- = \begin{bmatrix} -e^{\pi i/4} \\ 1 \end{bmatrix}}$$

$$\langle \vec{u}_+, \vec{u}_- \rangle = [e^{\pi i/4}, 1] \begin{bmatrix} -e^{-\pi i/4} \\ 1 \end{bmatrix} = -(e^{\pi i/4})(e^{-\pi i/4}) + 1 = -1 + 1 = 0.$$

It remains to normalize $\vec{u}_{\pm}$,

$$\langle \vec{u}_+, \vec{u}_+ \rangle = |e^{\pi i/4}|^2 + |1|^2 = 2 = \langle \vec{u}_-, \vec{u}_- \rangle$$

$$\beta = \left\{ \frac{1}{\sqrt{2}} \begin{bmatrix} \frac{1}{\sqrt{2}}(1+i) \\ 1 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} \frac{1}{\sqrt{2}}(1-i) \\ 1 \end{bmatrix} \right\}$$

$$\beta = \left\{ \left(\frac{1}{2}(1+i), 1/\sqrt{2} \right), \left(-\frac{1}{2}(1+i), 1/\sqrt{2} \right) \right\}$$

$$\lambda_+ = 2 + \frac{1+i}{\sqrt{2}}$$

$$\lambda_- = 2 - \frac{1+i}{\sqrt{2}}$$

P82 continued

(d.) $V = P_2(\mathbb{R})$ define $T(f) = f'$ with $\langle f(x), g(x) \rangle = \int_0^1 f(x)g(x)dx$

Let $\beta = \{1, x, x^2\}$ and $A = [T]_{\beta, \beta}$

$$A = \left[[T(1)]_{\beta} \mid [T(x)]_{\beta} \mid [T(x^2)]_{\beta} \right] = \left[[0]_{\beta} \mid [1]_{\beta} \mid [2x]_{\beta} \right] = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$A^*A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 2 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$AA^* = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 2 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$A^*A \neq AA^*$$

A not normal.

$A \neq A^*$
not self-adjoint

It follows, T is likewise neither self-adjoint or normal.

(e.) $V = \mathbb{R}^{2 \times 2}$ and $T(A) = A^T$

$\beta = \{E_{11}, E_{12}, E_{21}, E_{22}\}$ and $[T]_{\beta, \beta} = M$

$$M = \left[[E_{11}]_{\beta} \mid [E_{12}]_{\beta} \mid [E_{21}]_{\beta} \mid [E_{22}]_{\beta} \right] = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} = M^T \Rightarrow \boxed{T \text{ is self-adjoint}}$$

Note $A^T = A \Rightarrow T(A) = A \therefore \lambda = 1$ (symmetric matrices)

Likewise $A^T = -A \Rightarrow T(A) = -A \therefore \lambda = -1$ (antisymmetric matrices)

$$\gamma = \left\{ \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}}_{\lambda = 1}, \underbrace{\begin{bmatrix} 0 & 1/\sqrt{2} \\ 1/\sqrt{2} & 0 \end{bmatrix}, \begin{bmatrix} 0 & -1/\sqrt{2} \\ 1/\sqrt{2} & 0 \end{bmatrix}}_{\lambda = -1} \right\}$$

(f.) $V = \mathbb{R}^{2 \times 2}$

$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} c & d \\ a & b \end{pmatrix}$ Let $\beta = \{E_{11}, E_{12}, E_{21}, E_{22}\}$ and $[T]_{\beta\beta} = M$

$$\left. \begin{aligned} T(E_{11}) &= E_{21} \\ T(E_{12}) &= E_{22} \\ T(E_{21}) &= E_{11} \\ T(E_{22}) &= E_{12} \end{aligned} \right\} \rightarrow M = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} = M^T \therefore M \text{ is self-adjoint}$$

$$\Rightarrow T \text{ is self-adjoint}$$

$$\det \begin{pmatrix} -\lambda & 0 & 1 & 0 \\ 0 & -\lambda & 0 & 1 \\ 1 & 0 & -\lambda & 0 \\ 0 & 1 & 0 & -\lambda \end{pmatrix} = -\lambda \det \begin{bmatrix} -\lambda & 0 & 1 \\ 0 & -\lambda & 0 \\ 1 & 0 & -\lambda \end{bmatrix} + \det \begin{bmatrix} 0 & -\lambda & 1 \\ 1 & 0 & 0 \\ 0 & 1 & -\lambda \end{bmatrix}$$

$$= -\lambda [-\lambda(\lambda^2) + 1(\lambda)] + \lambda(-\lambda) + 1(1)$$

$$= \lambda^4 - \lambda^2 - \lambda^2 + 1 = \lambda^4 - 2\lambda^2 + 1 = (\lambda^2 - 1)^2 = (\lambda + 1)^2(\lambda - 1)^2$$

$$M - I = \begin{bmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix} \sim \begin{bmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{going back to } V} \begin{bmatrix} u_1 & u_2 \\ u_3 & u_4 \end{bmatrix}$$

$$\begin{aligned} &\rightarrow u_1 = u_3 \\ &\rightarrow u_2 = u_4 \end{aligned}$$

$$M + I = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{going back to } V} \begin{bmatrix} u_1 & u_2 \\ -u_1 & -u_2 \end{bmatrix}$$

$$\begin{aligned} &\rightarrow u_1 = -u_3 \\ &\rightarrow u_2 = -u_4 \end{aligned}$$

Hence,

$$\gamma = \left\{ \underbrace{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}}_{\lambda = 1}, \underbrace{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 0 \\ -1 & 0 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix}}_{\lambda = -1} \right\}$$

Remark: the textbook answers must be for different problems.
sorry.

Let T be self-adjoint on finite dim'l inner-product space V .

Prove $\|T(x) \pm ix\|^2 = \|T(x)\|^2 + \|x\|^2$. Show $T - iI$ is invertible and $(T - iI)^{-1}$ has adjoint $(T + iI)^{-1}$

Suppose $T^* = T$ and let $x \in V$,

$$\langle T(x) \pm ix, T(x) \pm ix \rangle = \langle T(x), T(x) \rangle + \langle T(x), \pm ix \rangle + \langle \pm ix, T(x) \rangle + \langle \pm ix, \pm ix \rangle$$

$$\|T(x) \pm ix\|^2 = \|T(x)\|^2 \mp i \langle T(x), x \rangle \pm i \langle x, T(x) \rangle + \|\pm ix\|^2$$

$$= \|T(x)\|^2 \mp i \langle T(x), x \rangle \pm i \langle T^*(x), x \rangle + | \pm i |^2 \|x\|^2$$

$$= \|T(x)\|^2 \mp i \langle T(x), x \rangle \pm i \langle T(x), x \rangle + \|x\|^2$$

$$= \underline{\|T(x)\|^2 + \|x\|^2}.$$

$T: V \rightarrow V$ is linear on finite dim'l V . Likewise,

$T - iI: V \rightarrow V$ is linear on finite dim'l V . Let

$x \in \text{Ker}(T - iI)$ then $(T - iI)(x) = T(x) - ix = 0 \therefore T(x) = ix$.

But, $\| \underbrace{T(x) - ix}_0 \|^2 = \|T(x)\|^2 + \|x\|^2 = \|ix\|^2 + \|x\|^2 = 2\|x\|^2 = 0$

hence $\|x\| = 0 \Rightarrow x = 0 \Rightarrow \text{Ker}(T - iI) = \{0\} \therefore (T - iI)^{-1}$

exists since $\dim(V) = \dim(\text{Ker}(T - iI)) + \dim(\text{Range}(T - iI))$. implies

$T - iI$ is onto (we can also use Th^m, $T: V \rightarrow V$ onto iff 1-1)

Consider,

$$(T - iI)^{-1} (T - iI) = I$$

$$\Rightarrow (T - iI)^* ((T - iI)^{-1})^* = I^*$$

$$(T^* + iI^*) ((T - iI)^{-1})^* = I$$

$$(T + iI) ((T - iI)^{-1})^* = I \Rightarrow \underline{\left((T - iI)^{-1} \right)^* = (T + iI)^{-1}}$$

Suppose T and U are reflections of $\mathbb{R}^2$ about the respective lines L and L' through origin with angles ϕ and ψ from the positive x -axis to L and L' respectively. By exercise 24, UT is a rotation. Find the angle of UT 's rotation.

From Example 5 we know the standard matrix of the reflection, hence

$$[T] = \begin{bmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{bmatrix} \quad \& \quad [U] = \begin{bmatrix} \cos 2\psi & \sin 2\psi \\ \sin 2\psi & -\cos 2\psi \end{bmatrix}$$

Consider,

$$\begin{aligned} [TU] &= [T][U] \\ &= \begin{bmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{bmatrix} \begin{bmatrix} \cos 2\psi & \sin 2\psi \\ \sin 2\psi & -\cos 2\psi \end{bmatrix} \\ &= \left[\begin{array}{c|c} \cos 2\phi \cos 2\psi + \sin 2\phi \sin 2\psi & \cos 2\phi \sin 2\psi - \sin 2\phi \cos 2\psi \\ \sin 2\phi \cos 2\psi - \cos 2\phi \sin 2\psi & \sin 2\phi \sin 2\psi + \cos 2\phi \cos 2\psi \end{array} \right] \\ &= \left[\begin{array}{c|c} \cos (2\phi - 2\psi) & -\sin (2\phi - 2\psi) \\ \sin (2\phi - 2\psi) & \cos (2\phi - 2\psi) \end{array} \right] \end{aligned}$$

Thus $\boxed{2(\phi - \psi)}$ is the angle of the TU rotation.

Likewise, as I was supposed to calculate, the UT rotation has angle $2(\psi - \phi)$.

P85 Note that $\text{trace}: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$ defines a dual vector in $(\mathbb{R}^{n \times n})^*$. The Riesz vector $\# \text{trace}$ has $\langle x, \# \text{trace} \rangle = \text{trace}(x)$

$$\text{trace}(x (\# \text{trace})^T) = \text{trace}(x) \quad \forall x \in \mathbb{R}^{n \times n}$$

apparently $\boxed{\# \text{trace} = I}$ then

$$\langle x, I \rangle = \text{trace}(x I^T) = \text{trace}(x) \quad \forall x \in \mathbb{R}^{n \times n}$$

P86 Consider $R_3 = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} = \underbrace{R_2(\cos \theta + i \sin \theta)}_{\lambda = \cos \theta \pm i \sin \theta \text{ and } \lambda = 1} \oplus J_1(1)$ (using Real Jordan form discussion)

$$\det(R_3 - \lambda I) = \det \begin{bmatrix} \cos \theta - \lambda & \sin \theta & 0 \\ -\sin \theta & \cos \theta - \lambda & 0 \\ 0 & 0 & 1 - \lambda \end{bmatrix} = [(\lambda - \cos \theta)^2 + \sin^2 \theta](1 - \lambda) = 0$$

$$\Rightarrow \lambda = \cos \theta \pm i \sin \theta = e^{\pm i \theta} \text{ or } \lambda = 1.$$

Observe $R_3 e_3 = e_3$ thus $E_{\lambda=1} = \text{span}\{(0, 0, 1)\}$.

In **P87** we show $R \in SO(3)$ s.t. $R \neq I$ has form R_3 if the transformation has complex e-values. Since $\text{trace}(R) = 0$ is given it follows ^{two} of the eigenvalues are complex hence

$\exists \beta = \{v_1, v_2, v_3\}$ for which $L = L_R$ h.w

$$[L]_{\beta\beta} = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} = [\beta]^T R [\beta]$$

taking the trace of the equation above yields,

$$2 \cos \theta + 1 = \text{trace}([\beta]^T [\beta] R) = \text{tr}(R) = 0$$

Hence $\cos \theta = -1/2$

$$\Rightarrow \boxed{\theta = \frac{2\pi}{3}}$$

P87 Let $SO(3) = \{R \in \mathbb{R}^{3 \times 3} \mid R^T R = I\}$

If $R \in SO(3)$ and $R \neq I$ then show R has only two e -vectors of unit-length with $\lambda = 1$

Let $\lambda \in \mathbb{R}$ be eigenvalue of R then as $R^T R = R R^T = I$ calculate for $Rx = \lambda x$, with $x \neq 0$

$$\langle x, x \rangle = \langle R^T R x, x \rangle = \langle R x, R x \rangle = \langle \lambda x, \lambda x \rangle = \lambda^2 \langle x, x \rangle$$

thus $\lambda^2 = 1$ and so $\lambda = \pm 1$. If we regard $R \in SO(3)$ as the matrix for $L_R: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ then we may complexify and then $R^T R = I = R R^T$ yields normality and hence R is complex diagonalizable. Anyway, we don't need all that. What we do need is to notice

$$\det(R) = \lambda_1 \lambda_2 \lambda_3$$

where either $\lambda_1, \lambda_2, \lambda_3 \in \mathbb{R}$ or $\lambda_1 \in \mathbb{R}$ and $\overline{\lambda_2} = \lambda_3 \in \mathbb{C}$

follows since $\text{char}_R(t)$ is real poly.

① If $\lambda_1 = \lambda_2 = \lambda_3 = 1$ then $[L_R]_{\mathcal{B}, \mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow [\mathcal{B}]^T R [\mathcal{B}] = I$
hence $\lambda_1 = \lambda_2 = \lambda_3 = 1$ cannot happen as $R \neq I$. $\Rightarrow \underline{R = I}$.

② If $\lambda_1 = 1$ and $\lambda_2 = \lambda_3 = -1$ then $\dim(E'_{\lambda=1}) = 1$ and so $\exists$ exactly two unit-vectors with $\lambda = 1$.

③ If $\lambda_1 \in \mathbb{R}$ and $\lambda_2 = b+ic$ and $\lambda_3 = b-ic$. Note $\lambda_1 = \pm 1$ however, as $\det(R) = 1 = \lambda_1 \lambda_2 \lambda_3 = \lambda_1 (b+ic)(b-ic) = \lambda_1 (b^2+c^2)$ we find $\lambda_1 = \frac{1}{b^2+c^2} > 0$ hence $\underline{\lambda_1 = 1}$.

Once more, $\dim(E'_{\lambda=1}) = 1$ and $\exists$ exactly two unit-vectors with $\lambda = 1$.

P88 $Q(x, y) = x^2 + 4xy + y^2$

$$Q(v) = [x, y]^T \underbrace{\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}}_A \begin{bmatrix} x \\ y \end{bmatrix} = v^T A v$$

$$\det(A - \lambda I) = \det \begin{bmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{bmatrix} = (\lambda-1)^2 - 4 = (\lambda-3)(\lambda+1) = 0$$

$$A + I = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \quad \& \quad A - 3I = \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix}$$

$$\text{Null}(A+I) = \text{span} \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\} \quad \text{Null}(A-3I) = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

$$\text{Let } \beta = \left\{ \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\} \text{ then } \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} = [\beta]^{-1} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\text{or better yet } \begin{bmatrix} x \\ y \end{bmatrix} = [\beta] \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} \bar{x} + \bar{y} \\ \bar{y} - \bar{x} \end{bmatrix}$$

$$\text{We find } x = \frac{1}{\sqrt{2}} (\bar{x} + \bar{y}) \text{ whereas } y = \frac{1}{\sqrt{2}} (\bar{y} - \bar{x})$$

hence,

$$\begin{aligned} Q(x, y) &= \left(\frac{1}{\sqrt{2}} (\bar{x} + \bar{y}) \right)^2 + 4 \left(\frac{\bar{x} + \bar{y}}{\sqrt{2}} \right) \left(\frac{\bar{y} - \bar{x}}{\sqrt{2}} \right) + \left(\frac{1}{\sqrt{2}} (\bar{y} - \bar{x}) \right)^2 \\ &= \frac{1}{2} (\bar{x}^2 + 2\bar{x}\bar{y} + \bar{y}^2) + 2(\bar{y}^2 - \bar{x}^2) + \frac{1}{2} (\bar{y}^2 - 2\bar{x}\bar{y} + \bar{x}^2) \\ &= \left(\frac{1}{2} - 2 + \frac{1}{2} \right) \bar{x}^2 + \left(\frac{1}{2} + 2 + \frac{1}{2} \right) \bar{y}^2 \\ &= \boxed{-\bar{x}^2 + 3\bar{y}^2} = 1 \end{aligned}$$

geometrically this is
a hyperbola

No surprise here!

$$\begin{aligned} Q(v) &= v^T A v = v^T [\beta] \underbrace{[\beta]^T A [\beta]}_{\text{diag}(\lambda_1, \lambda_2)} [\beta]^T v \\ &= ([\beta]^T v)^T \text{diag}(\lambda_1, \lambda_2) [\beta]^T v \\ &= [\bar{x}, \bar{y}] \begin{bmatrix} -1 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix}. \end{aligned}$$

$$Q(x, y, z) = 5x^2 + 5y^2 + 2z^2 + 8xy + 4xz + 4yz$$

$$= [x, y, z] \underbrace{\begin{bmatrix} 5 & 4 & 2 \\ 4 & 5 & 2 \\ 2 & 2 & 2 \end{bmatrix}}_A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = Q(v)$$

Find ^{eigen} coordinates $\bar{x}, \bar{y}, \bar{z}$ for which $Q(v) = \bar{x}^2 + \bar{y}^2 + 10\bar{z}^2$

$$A - I = \begin{bmatrix} 4 & 4 & 2 \\ 4 & 4 & 2 \\ 2 & 2 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1/2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow u = -v - \frac{w}{2} \Rightarrow \begin{bmatrix} -v - w/2 \\ v \\ w \end{bmatrix}$$

$$A - 10I = \begin{bmatrix} -5 & 4 & 2 \\ 4 & -5 & 2 \\ 2 & 2 & -8 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{matrix} u = 2w \\ v = 2w \end{matrix} \Rightarrow \begin{bmatrix} 2w \\ 2w \\ w \end{bmatrix}$$

$$\text{Null}(A - I) = \text{span} \left\{ \underbrace{\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}}_{v_1}, \underbrace{\begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}}_{v_2} \right\}$$

$$\text{Null}(A - 10I) = \text{span} \left\{ \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \right\}$$

not orthonormal, need to run G.S.A.

$$v_1' = v_1$$

$$v_2' = v_2 - \frac{\langle v_1, v_2 \rangle}{\langle v_1, v_1 \rangle} v_1 = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1/2 \\ -1/2 \\ 2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 \\ -1 \\ 4 \end{bmatrix}$$

$$\text{Let } \beta = \left\{ \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \frac{1}{\sqrt{18}} \begin{bmatrix} -1 \\ -1 \\ 4 \end{bmatrix}, \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \right\}$$

$$\text{Then } \begin{bmatrix} \bar{x} \\ \bar{y} \\ \bar{z} \end{bmatrix} = [\beta]^{-1} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ define eigen coordinates}$$

$$\begin{aligned} \text{for which } Q(v) &= [x, y, z] A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = [\bar{x}, \bar{y}, \bar{z}] [\beta]^T A [\beta] \begin{bmatrix} \bar{x} \\ \bar{y} \\ \bar{z} \end{bmatrix} \\ &= [\bar{x}, \bar{y}, \bar{z}] \begin{bmatrix} 1 & & \\ & 1 & \\ & & 10 \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \\ \bar{z} \end{bmatrix} \\ &= \bar{x}^2 + \bar{y}^2 + 10\bar{z}^2. \end{aligned}$$

P.90 Suppose $\{u, v, w\}$ forms an orthonormal e-basis for $A \in \mathbb{R}^{3 \times 3}$ with e-values $\lambda_1, \lambda_2, \lambda_3$ respectively ($Au = \lambda_1 u, Av = \lambda_2 v, Aw = \lambda_3 w$)

Define : $E_1 = \lambda_1 u u^T, E_2 = \lambda_2 v v^T, E_3 = \lambda_3 w w^T$

Show : $E_1 + E_2 + E_3 = A$ and $\text{Col}(E_j) = \text{Null}(A - \lambda_j I)$ for $j=1, 2, 3$

Consider $L(x) = (E_1 + E_2 + E_3)x$ and $L_A(x) = Ax$.

If L and L_A agree on a basis for $\mathbb{R}^3$ then $L = L_A$ and thus $E_1 + E_2 + E_3 = A$. Consider,

① $L_A(u) = Au = \lambda_1 u$

$$L(u) = (E_1 + E_2 + E_3)u = (\lambda_1 u u^T + \lambda_2 v v^T + \lambda_3 w w^T)u$$

$$= \lambda_1 u \underbrace{u^T u}_0 + \lambda_2 v \underbrace{v^T u}_0 + \lambda_3 w \underbrace{w^T u}_0$$

thus $L(u) = \lambda_1 u$

Recall $x \cdot y = x^T y$.

and we find $L_A(u) = L(u) = \lambda_1 u$.

② $L_A(v) = Av = \lambda_2 v$

$$L(v) = \lambda_1 u \underbrace{u^T v}_0 + \lambda_2 v \underbrace{v^T v}_1 + \lambda_3 w \underbrace{w^T v}_0 = \lambda_2 v = L_A(v).$$

③ $L_A(w) = Aw = \lambda_3 w$

$$L(w) = \lambda_1 u \underbrace{u^T w}_0 + \lambda_2 v \underbrace{v^T w}_0 + \lambda_3 w \underbrace{w^T w}_1 = \lambda_3 w = L_A(w)$$

Therefore, $A = E_1 + E_2 + E_3$

Observe $E_1 = \lambda_1 u u^T = \begin{bmatrix} * & u / * & u / \otimes u \end{bmatrix} \therefore \text{Col}(E_1) = \text{span}\{u\}$

But, $\text{Null}(A - \lambda_1 I) = \text{span}\{u\}$ since λ_1 has geometric multiplicity 1. (oops! You need $\lambda_1 \neq \lambda_2, \lambda_1 \neq \lambda_3, \lambda_2 \neq \lambda_3$)

Thus $\text{Col}(E_1) = \text{Null}(A - \lambda_1 I)$. Same argument works for 2 & 3.

P91

$$u = \frac{1}{\sqrt{3}} (1, -1, 1)$$

$$v = \frac{1}{\sqrt{2}} (0, 1, 1)$$

$$w = \frac{1}{\sqrt{6}} (2, 1, -1)$$

Construct A for
which u, v, w are
e-vectors with e-values
 $12, 2, 18$

$$A = 12uu^T + 2vv^T + 18ww^T$$

$$= \frac{12}{3} \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix} + \frac{2}{2} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} + \frac{18}{6} \begin{bmatrix} 4 & 2 & -2 \\ 2 & 1 & -1 \\ -2 & -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 & -4 & 4 \\ -4 & 4 & -4 \\ 4 & -4 & 4 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} + \begin{bmatrix} 12 & 6 & -6 \\ 6 & 3 & -3 \\ -6 & -3 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 16 & 2 & -2 \\ 2 & 8 & -6 \\ -2 & -6 & 8 \end{bmatrix}$$

as a check on my calculation,
trace $(A) = 16 + 8 + 8 = 32$

$$\text{and } \lambda_1 + \lambda_2 + \lambda_3 = 12 + 2 + 18 = 32 \checkmark$$

P92 Define $\mathcal{I}: \mathbb{R}^{n \times n} \times \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^{n \times n}$ by $\mathcal{I}(A, B) = AB + BA$

observe $\mathcal{I}(A, B) = AB + BA = BA + AB = \mathcal{I}(B, A) \therefore \mathcal{I}$ is symmetric.

$$\text{Note, } \mathcal{I}(cA_1 + A_2, B) = (cA_1 + A_2)B + B(cA_1 + A_2)$$

$$= c(A_1B + BA_1) + A_2B + BA_2$$

$$= c\mathcal{I}(A_1, B) + \mathcal{I}(A_2, B) \quad (*)$$

for all $c \in \mathbb{R}$ and $A_1, A_2, B \in \mathbb{R}^{n \times n}$ thus $\mathcal{I}$ is linear in its 1st slot.

Likewise, for $c \in \mathbb{R}, A_1, A_2, B \in \mathbb{R}^{n \times n}$,

$$\mathcal{I}(B, cA_1 + A_2) = \mathcal{I}(cA_1 + A_2, B) \quad \text{: by symmetry}$$

$$= c\mathcal{I}(A_1, B) + \mathcal{I}(A_2, B) \quad \text{: using } (*)$$

$$= c\mathcal{I}(B, A_1) + \mathcal{I}(B, A_2) \therefore \underline{\mathcal{I} \text{ is bilinear.}}$$

P:93 $x \otimes y: V^* \times V^* \rightarrow \mathbb{R}$ is defined by

$$(x \otimes y)(\alpha, \beta) = \alpha(x) \beta(y). \text{ Consider,}$$

$$(x \otimes y)(c\alpha_1 + \alpha_2, \beta) = (c\alpha_1 + \alpha_2)(x) \beta(y) = \text{def}^2$$

$$= (c\alpha_1(x) + \alpha_2(x)) \beta(y) = \text{def}^2 \text{ of adding functions}$$

$$= c\alpha_1(x) \beta(y) + \alpha_2(x) \beta(y)$$

$$= c(x \otimes y)(\alpha_1, \beta) + (x \otimes y)(\alpha_2, \beta)$$

Likewise,

$$(x \otimes y)(\alpha, c\beta_1 + \beta_2) = \alpha(x) (c\beta_1 + \beta_2)(y)$$

$$= \alpha(x) (c\beta_1(y) + \beta_2(y))$$

$$= c\alpha(x) \beta_1(y) + \alpha(x) \beta_2(y)$$

$$= c(x \otimes y)(\alpha, \beta_1) + (x \otimes y)(\alpha, \beta_2)$$

Thus $\underbrace{x \otimes y}_{\text{bilinear map on } V^* \times V^*} \in \mathcal{B}(V^*) = \mathcal{B}(V^* \times V^*, \mathbb{R}).$

p94 V has basis $\beta = \{v_1, \dots, v_n\}$ then prove

$\mathcal{T} = \{v_i \otimes v_j \mid 1 \leq i, j \leq n\}$ serves as basis for $\mathcal{B}(V^*)$

Suppose $\sum_{i,j=1}^n c_{ij} v_i \otimes v_j = 0$ then evaluate on (v^k, v^l)

where $v^k, v^l \in \beta^* \subset V^*$ defined as usual $v^k(v_i) = \delta_{ki}$ and $v^l(v_j) = \delta_{lj}$ etc. Thus,

$$\begin{aligned} 0 &= \left(\sum_{i,j} c_{ij} v_i \otimes v_j \right) (v^k, v^l) = \sum_{i,j} c_{ij} (v_i \otimes v_j)(v^k, v^l) \\ &= \sum_{i,j} c_{ij} v^k(v_i) v^l(v_j) \\ &= \sum_{i,j} c_{ij} \delta_{ki} \delta_{lj} \\ &= c_{kl} \Rightarrow c_{ij} = 0 \quad \forall i, j \\ &\Rightarrow \underline{\mathcal{T} \text{ is LI.}} \end{aligned}$$

If $b: V^* \times V^* \rightarrow \mathbb{R}$ is bilinear then

$$b(\alpha, \beta) = b\left(\sum_i \alpha_i v^i, \sum_j \beta_j v^j\right)$$

$$= \sum_{i,j} \alpha_i \beta_j b(v^i, v^j)$$

$$= \sum_{i,j} b(v^i, v^j) \alpha(v_i) \beta(v_j)$$

$$= \left(\sum_{i,j} b(v^i, v^j) v_i \otimes v_j \right) (\alpha, \beta) \quad \forall \alpha, \beta \in V^*$$

$$\therefore b = \sum_{i,j} b(v^i, v^j) v_i \otimes v_j \therefore \underline{\text{span}(\mathcal{T}) = \mathcal{B}(V^*)}$$

(we already showed $\mathcal{T} \subseteq \mathcal{B}(V^*)$ in previous problem hence $\text{span } \mathcal{T} \subseteq \mathcal{B}(V^*)$) (the calculation here shows $\mathcal{B}(V^*) \subseteq \text{span } \mathcal{T}$)