Same instructions as Mission 1. Thanks!

- **Problem 31** Consider  $x, y \in \mathbb{R}^n$ . Define  $Q(t) = ||x ty||^2$  for  $t \in \mathbb{R}$ . Find the minimum value for Q and show how this can be used to derive the inequality  $x \cdot y \leq ||x|| ||y||$ .
- **Problem 32** Let V be a real inner product space with inner product  $\langle, \rangle$ . Suppose  $\beta = \{v_1, \ldots, v_n\}$  is an orthonormal basis for V and let  $x = \sum_i x_i v_i$  and  $y = \sum_j y_j v_j$ . Define  $||x|| = \sqrt{\langle x, x \rangle}$ . Let  $Q(t) = ||x ty||^2$  for  $t \in \mathbb{R}$ . Find the minimum value for Q and show how this can be used to derive the inequality  $\langle x, y \rangle \leq ||x|| ||y||$ .
- **Problem 33** Let  $Q(x,y,z) = 31x^2 + 15y^2 + 15z^2 22xy 22xz + 10yz$ . Find the matrix for Q and use technology to calculate the eigenvalues for Q. Let  $y_1, y_2, y_3$  denote the eigencoordinates, write the formula for Q in terms of the eigencoordinates. For the record, I did not design this problem to have that eigenvalue. It just happened.
- Problem 34 Suppose

$$f(x, y, z) = 9000 + 31(x - 1)^{2} + 15y^{2} + 15(z + 2)^{2} - 22(x - 1)y - 22(x - 1)(z + 2) + 10y(z + 2)$$

Notice (1,0,-2) is a critical point for f. Classify the critical point as min/max or saddle.

- **Problem 35** Calculate the multivariate Taylor series centered about (0,0,0) for  $f(x,y,z) = \frac{1+y^2}{1-2xz}$  to order 4. Analyze: is (0,0,0) a critical point? If so, analyze if it yields a min/max/saddle or if the second derivative test is not applicable for the given problem. *Hint: all the cool kids use geometric series*
- **Problem 36** Find the geodesics in the tunnel given by (x, y, z) for which  $y^2 + z^2 = R^2$ .
- **Problem 37** Find the geodesics on the cone  $\phi = \pi/3$  where  $\phi$  denotes the usual spherical angle.
- **Problem 38** Let  $L = \frac{m}{2}(\dot{x}^2 + \dot{y}^2) \frac{k}{2}(x^2 + y^2)$  denote the Lagrangian of a particle with mass m under the force a spring with potential energy  $U(x,y) = \frac{k}{2}(x^2 + y^2)$ . Notice L = T U where T is the kinetic energy. Calculate the Euler-Lagrange equations and show energy E = T + U is conserved along the solution to the Euler-Lagrange equation
- **Problem 39** Let  $L = \frac{m}{2}(\dot{r}^2 + r^2\dot{\theta}^2) + g(r)$  where g is a differentiable function of the polar radius r. Find the Euler Lagrange equations. Also, suppose we define angular momentum  $J = \frac{\partial L}{\partial \dot{\theta}}$ , show J is conserved.
- **Problem 40** A marble slides without friction on a bowl of radius R. If the marble has mass m and the force of gravity is given by  $-mg\hat{z}$  then find the equations of motion for the marble (differential equations suffice as an answer here). Also, show momentum in the direction of a rotation about the z-axis is conserved.

Bonus 5: Imagine a pendulum of length  $l_1$  which consists of a very light rod which does not flex and a bob of mass  $m_1$ . Next, a second pendulum of length  $l_2$  which consists of a very light rod which does not flex and a bob of mass  $m_2$  is attached so that  $l_2$  hangs freely off  $m_1$ . All of this is attached to point and allowed to swing back and forth under the influence of gravity. Assume this is near the surface of the earth where F = mg applies. Find the equations of motion for this double pendulum. Let  $\theta_1$  and  $\theta_2$  be the angles which  $l_2$  and  $l_2$  make with respect to  $-\hat{z}$ . Write the equations of motion in terms of these anglular variables.

**Bonus 6:** Let  $q_i$  and  $\dot{q}_i$  for  $1 \leq i \leq n$  denote generalized coordinates of a physical system with Lagrangian  $L(q_i, \dot{q}_i)$ . Define the **Hamiltonian** by

$$H(q_i, p_i) = \sum_{i=1}^{n} p_i \dot{q}_i - L(q_i, \dot{q}_i)$$

where  $p_i = \frac{\partial L}{\partial \dot{q}_i}$  defines the *i*-th generalized momenta of the system. Show that the Euler Lagrange equations imply Hamilton's Equations of motion:

$$\frac{dp_i}{dt} = -\frac{\partial H}{\partial q_i} \qquad \& \qquad \frac{dq_i}{dt} = \frac{\partial H}{\partial p_i}.$$

**Bonus 7:** I have in mind a problem where you derive Coriolis effect and such by imposing rotation of the earth on a rotating frame. I lack inspiration to frame the problem properly, but, if you have interest, shoot me an email and I'll put it together as a bonus problem here.