

Same instructions as Mission 1. Thanks!

**Problem 55** Your signature below indicates you have:

(a.) I have read much of Cook's Chapter 6 and 8: \_\_\_\_\_.

**Problem 56** Let  $Q(x, y) = 10x^2 - 8xy + 10y^2$ . Find a linear change of coordinates for which  $Q(\bar{x}, \bar{y}) = \lambda_1 \bar{x}^2 + \lambda_2 \bar{y}^2$ .

**Problem 57** Let  $Q(x, y, z) = 31x^2 + 15y^2 + 15z^2 - 22xy - 22xz + 10yz$ . Find the matrix for  $Q$  and use technology to calculate the eigenvalues for  $Q$ . Let  $y_1, y_2, y_3$  denote the eigencoordinates, write the formula for  $Q$  in terms of the eigencoordinates. For the record, I did not design this problem to have that eigenvalue. It just happened.

**Problem 58** Let  $Q(x, y, z) = 6x^2 - 2xy - 4xz + 5y^2 - 2yz + 6z^2$ . Find the matrix for  $Q$  and use technology to calculate the eigenvalues for  $Q$ . Let  $y_1, y_2, y_3$  denote the eigencoordinates, write the formula for  $Q$  in terms of the eigencoordinates.

**Problem 59** I'll share a little backwards linear algebra with you: if  $v_1, v_2, v_3$  are orthonormal vectors then we can build a symmetric matrix by  $A = \lambda_1 v_1 v_1^T + \lambda_2 v_2 v_2^T + \lambda_3 v_3 v_3^T$ . Let,

$$v_1 = \frac{1}{\sqrt{3}}(1, 1, 1), \quad v_2 = \frac{1}{\sqrt{6}}(1, -2, 1), \quad v_3 = \frac{1}{\sqrt{2}}(1, 0, -1).$$

and  $\lambda_1 = 3, \lambda_2 = 6$  and  $\lambda_3 = 8$ . **Calculate  $A$  and verify  $Av_1 = 3v_1$  and  $Av_2 = 6v_2$  and  $Av_3 = 8v_3$ .**

**Problem 60** Consider  $f(x, y) = 3 + 3(x - 1) + 4(y + 2) + 2(x - 1)^2 + 6(x - 1)(y + 2) + 7(y + 2)^2 + \dots$ . Find the values of  $f, f_x, f_y, f_{xx}, f_{xy}, f_{yy}$  at the point  $(1, -2)$ .

**Problem 61** Calculate the multivariate Taylor series centered about  $(0, 0, 0)$  for  $f(x, y, z) = \frac{1 + y^2}{1 - 2xz}$  to order 4. Analyze: is  $(0, 0, 0)$  a critical point? If so, analyze if it yields a min/max/saddle or if the second derivative test is not applicable for the given problem.

**Problem 62** Find and classify the critical points of  $f(x, y) = (x^2 + y^2)e^{x^2 - y^2}$ .

**Problem 63** Consider  $\int \cos(tx) dx = \frac{1}{t} \sin(tx) + C$ . Use differentiation with respect to  $t$  to derive a new integral or two from the given integral. Set  $t = 1$  or some other fun value once you've completed the differentiation.

**Problem 64** Follow §4 of Professor Conrad's blurb to derive  $\int_{-\infty}^{\infty} e^{-x^2/2} dx = \sqrt{2\pi}$

**Problem 65** Read §9 of Professor Conrad's blurb and summarize his argument in your own words.

**Problem 66** Find the geodesics on the cone  $\phi = \pi/3$  where  $\phi$  denotes the usual spherical angle.

**Problem 67** Find a differential equation whose solutions are geodesics on the surface  $x^2 + y^3 + z^4 = 1$ . **Bonus: numerically generate a particular solution and plot it on the surface using some C.A.S.**

**Problem 68** Let  $L = \frac{m}{2}(\dot{x}^2 + \dot{y}^2) - \frac{k}{2}(x^2 + y^2)$  denote the Lagrangian of a particle with mass  $m$  under the force a spring with potential energy  $U(x, y) = \frac{k}{2}(x^2 + y^2)$ . Notice  $L = T - U$  where  $T$  is the kinetic energy. **Calculate the Euler-Lagrange equations and show energy  $E = T + U$  is conserved along the solution to the Euler-Lagrange equation**

**Problem 69** Show that the geodesics to a sphere are the great circles.

**Problem 70** Let  $L = \frac{m}{2}(\dot{r}^2 + r^2\dot{\theta}^2) + g(r)$  where  $g$  is a differentiable function of the polar radius  $r$ . Find the Euler Lagrange equations. Also, suppose we define angular momentum  $J = \frac{\partial L}{\partial \dot{\theta}}$ , show  $J$  is conserved.

**Problem 71** A marble slides without friction on a bowl of radius  $R$ . If the marble has mass  $m$  and the force of gravity is given by  $-mg\hat{z}$  then find the equations of motion for the marble (differential equations suffice as an answer here).

**Problem 72** Imagine a pendulum of length  $l_1$  which consists of a very light rod which does not flex and a bob of mass  $m_1$ . Next, a second pendulum of length  $l_2$  which consists of a very light rod which does not flex and a bob of mass  $m_2$  is attached so that  $l_2$  hangs freely off  $m_1$ . All of this is attached to point and allowed to swing back and forth under the influence of gravity. Assume this is near the surface of the earth where  $F = mg$  applies. Find the equations of motion for this double pendulum. Let  $\theta_1$  and  $\theta_2$  be the angles which  $l_2$  and  $l_1$  make with respect to  $-\hat{z}$ . Write the equations of motion in terms of these angular variables.